

Lecture 1: The B-spline

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**Splines and PDE's: Recent advances from Approximation
Theory to structured Numerical Linear Algebra**

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The B-spline

Knot sequence

A **knot sequence** ξ is a nondecreasing sequence of real numbers,

$$\xi := \{\xi_i\}_{i=1}^m = \{\xi_1 \leq \xi_2 \leq \cdots \leq \xi_m\}, \quad m \in \mathbb{N}.$$

The elements ξ_i are called **knots**.

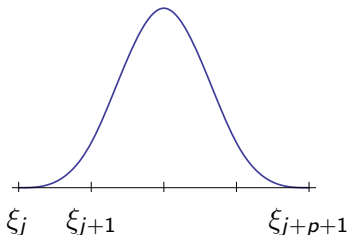
Recursive definition of j th B-splines of degree p on ξ

$$B_{j,0,\xi}(x) := \chi_{[\xi_j, \xi_{j+1})}(x) = \begin{cases} 1, & \text{if } x \in [\xi_j, \xi_{j+1}), \\ 0, & \text{otherwise.} \end{cases}$$

For $p \geq 1$

$$B_{j,p,\xi}(x) := \frac{x - \xi_j}{\xi_{j+p} - \xi_j} B_{j,p-1,\xi}(x) + \frac{\xi_{j+p+1} - x}{\xi_{j+p+1} - \xi_{j+1}} B_{j+1,p-1,\xi}(x), \quad x \in \mathbb{R}$$

term with zero denominator is defined to be zero
(the " $\frac{0}{0} := 0$ " convention)



Alternative notation $B[\xi_j, \xi_{j+1}, \dots, \xi_{j+p+1}](x)$

Right continuity

Note that

$$B_{j,0,\xi}(\xi_j) = 1, \quad B_{j,0,\xi}(\xi_{j+1}) = 0.$$

It follows that any B-spline is **right continuous**, i.e., the value at a point x is obtained by taking limits from the right:

$$B_{j,p,\xi}(\xi) = B_{j,p,\xi}(\xi_+),$$

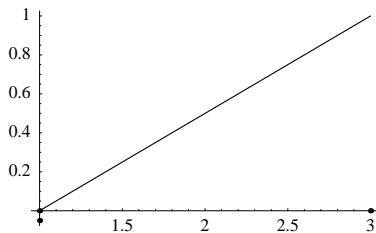
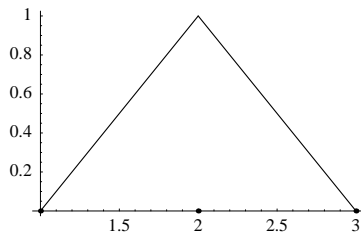
where

$$x_+ := \lim_{\substack{t \rightarrow x \\ t > x}} t, \quad x_- := \lim_{\substack{t \rightarrow x \\ t < x}} t, \quad x \in \mathbb{R}.$$

Multiplicity of a knot

We say that a knot has **multiplicity** μ if it occurs exactly μ times in the knot sequence. A knot is called **simple**, **double**, **triple**, ... if its multiplicity is equal to 1, 2, 3, ..., and a **multiple knot** if $\mu > 1$.

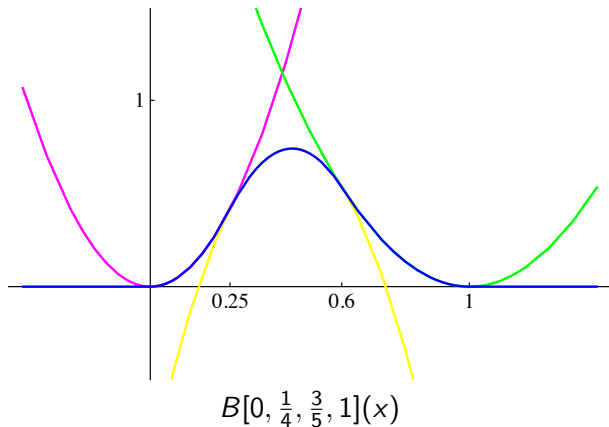
j th B-spline of degree $p = 1$ on ξ



$$B[1, 2, 3](x) := \frac{x-1}{2-1} \chi_{[1,2)}(x) + \frac{3-x}{3-2} \chi_{[2,3)}(x), \quad B[1, 3, 3](x) := \frac{x-1}{2} \chi_{[1,3)}(x) + \frac{0}{0}$$

The linear B-spline is continuous at a simple knot and discontinuous at a double knot.

B-spline of degree 2



The quadratic B-spline consists of pieces of parabolas tied together smoothly.

B-splines, properties

Simple to prove properties (induction on p)

- ▶ **Local support.** $B_{j,p,\xi}(x) = 0, \quad x \notin [\xi_j, \xi_{j+p+1})$.
- ▶ **Piecewise structure.** $B_{j,p,\xi}^{\{m\}} \in \mathbb{P}_p, \quad m = j, \dots, j+p$.
- ▶ **Nonnegativity.** $B_{j,p,\xi}(x) \geq 0, \quad x \in \mathbb{R},$
- ▶ **Positivity.** $B_{j,p,\xi}(x) > 0, \quad x \in (\xi_j, \xi_{j+p+1})$.
- ▶ **Translation and scaling invariance.**

$$B_{j,p,\alpha\xi+\beta}(\alpha x + \beta) = B_{j,p,\xi}(x), \quad \alpha, \beta \in \mathbb{R}, \quad \alpha \neq 0,$$

where $\alpha\xi + \beta := (\alpha\xi_j + \beta, \dots, \alpha\xi_{j+p+1} + \beta)$.

The following identity simplifies many dealings with B-splines.

Theorem (Local Marsden identity)

Suppose

$$\xi_{m-p} \leq \cdots \leq \xi_m < \xi_{m+1} \leq \cdots \leq \xi_{m+p+1}.$$

Then

$$(y - x)^p = \sum_{i=m-p}^m \psi_{i,p,\xi}(y) B_{i,p,\xi}(x), \quad x \in [\xi_m, \xi_{m+1}), \quad y \in \mathbb{R}, \quad (1)$$

where $\psi_{j,0,\xi} := 1$ and

$$\psi_{j,p,\xi}(y) := (y - \xi_{j+1}) \cdots (y - \xi_{j+p}), \quad y \in \mathbb{R}, \quad p \in \mathbb{N}. \quad (2)$$

*We say that $\psi_{j,p,\xi}$ is the polynomial **dual** to $B_{j,p,\xi}$*

Proof

We need to prove

$$(y - x)^p = \sum_{i=m-p}^m (y - \xi_{i+1}) \cdots (y - \xi_{i+p}) B_{i,p,\xi}(x)$$

- ▶ $p = 0$: $1 = 1$
- ▶ $p = 1$

$$\begin{aligned} & (y - \xi_m) B_{m-1,1,\xi}(x) + (y - \xi_{m+1}) B_{m,1,\xi}(x) \\ &= (y - \xi_m) \frac{\xi_{m+1} - x}{\xi_{m+1} - \xi_m} + (y - \xi_{m+1}) \frac{x - \xi_m}{\xi_{m+1} - \xi_m} \\ &= (y - x) \end{aligned}$$

Follows by **linear interpolation** of $\ell_y(x) := y - x$

- ▶ $p > 1$ use recurrence relations for B_j and ψ_j

Local properties

$$(y - x)^p = \sum_{i=m-p}^m (y - \xi_{j+1}) \cdots (y - \xi_{j+p}) B_{i,p,\xi}(x)$$

- **Local partition of unity.** Differentiating p times wrt y and cancelling $p!$ gives

$$1 = \sum_{i=m-p}^m B_{i,p,\xi}(x), \quad x \in [\xi_m, \xi_{m+1}). \quad (3)$$

- **Local linear independence.** The two sets $\{B_{i,p,\xi}\}_{i=m-p}^m$ and $\{\psi_{i,p,\xi}\}_{i=m-p}^m$ form both a basis for the polynomial space \mathbb{P}_p on $[\xi_m, \xi_{m+1})$.

Derivative

The derivative of a B-spline can be expressed by means of a simple difference formula.

Theorem (Differentiation formula)

We have

$$D_+ B_{j,p,\xi}(x) = p \left(\frac{B_{j,p-1,\xi}(x)}{\xi_{j+p} - \xi_j} - \frac{B_{j+1,p-1,\xi}(x)}{\xi_{j+p+1} - \xi_{j+1}} \right), \quad p \geq 1, \quad (4)$$

where fractions with zero denominator have value zero.

Right and left derivatives of a function f are defined by

$$D_+ f(x) := \lim_{\substack{h \rightarrow 0 \\ h > 0}} \frac{f(x+h) - f(x)}{h}, \quad D_- f(x) := \lim_{\substack{h \rightarrow 0 \\ h < 0}} \frac{f(x+h) - f(x)}{h}, \quad (5)$$

provided that the limits exist at the point $x \in \mathbb{R}$.

Proof Differentiation formula

Suppose $x \in [\xi_m, \xi_{m+1})$ for some m with $j \leq m \leq j + p$. Differentiating both sides of Marsden with respect to x gives

$$-p(y-x)^{p-1} = \sum_{i=m-p}^m \psi_{i,p}(y) DB_{i,p,\xi}(x). \quad (6)$$

On the other hand, using Marsden for degree $p-1$

$$\begin{aligned} -p(y-x)^{p-1} &= -p \sum_{i=m-p+1}^m \psi_{i,p-1}(y) B_{i,p-1,\xi}(x) \\ &= p \sum_{i=m-p+1}^m \left(\frac{\psi_{i,p}(y)}{\xi_{i+p} - \xi_i} - \frac{\psi_{i-1,p}(y)}{\xi_{i+p} - \xi_i} \right) B_{i,p-1,\xi}(x) \\ &= \sum_{i=m-p}^m \psi_{i,p}(y) p \left(\frac{B_{i,p-1,\xi}(x)}{\xi_{i+p} - \xi_i} - \frac{B_{i+1,p-1,\xi}(x)}{\xi_{i+p+1} - \xi_{i+1}} \right). \end{aligned}$$

By comparing this with (6) and using the linear independence of the dual polynomials, it follows that (4) holds for $i = m-p, \dots, m$. Since $m-p \leq j \leq m$, (4) holds for $i = j$. □

Continuity

Theorem (Smoothness property)

If ξ is a knot of $B_{j,p,\xi}$ of multiplicity $\mu \leq p + 1$ then

$$B_{j,p,\xi} \in C^{p-\mu}(\xi),$$

i.e., its derivatives of order $0, 1, \dots, p - \mu$ are continuous at ξ .

(The derivative of order $p - \mu + 1$ has a nonzero jump at ξ .)

"continuity + multiplicity = degree"

Integral of a B-spline

Theorem (Integration formula)

We have

$$\gamma_{j,p,\xi} := \int_{\xi_j}^{\xi_{j+p+1}} B_{j,p,\xi}(x) \, dx = \frac{\xi_{j+p+1} - \xi_j}{p+1}. \quad (7)$$

Proof integration formula

We define $p + 1$ extra knots at each end such that

$$\xi := \{\xi_{j-p-1} = \cdots = \xi_{j-1} < \xi_j \leq \cdots \leq \xi_{j+p+1} < \xi_{j+p+2} = \cdots = \xi_{j+2p+2}\}.$$

On this knot sequence we consider $p + 1$ B-splines $B_{i,p+1,\xi}$, $i = j - p - 1, \dots, j - 1$ of degree $p + 1$. These B-splines are continuous on \mathbb{R} . Therefore, we get for $i = j - p - 1, \dots, j - 1$,

$$0 = B_{i,p+1,\xi}(\xi_{i+p+2}) - B_{i,p+1,\xi}(\xi_i) = \int_{\xi_i}^{\xi_{i+p+2}} D_+ B_{i,p+1,\xi}(x) dx = E_i - E_{i+1},$$

where by the local support and the differentiation formula (4),

$$E_i := \frac{p + 1}{\xi_{i+p+1} - \xi_i} \int_{\xi_i}^{\xi_{i+p+1}} B_{i,p,\xi}(x) dx, \quad i = j - p - 1, \dots, j.$$

This means that $E_j = E_{j-1} = \cdots = E_{j-p-1}$. Moreover, since $\xi_{j-p-1} = \cdots = \xi_{j-1}$, we obtain that

$$E_{j-p-1} = \frac{p + 1}{\xi_j - \xi_{j-p-1}} \int_{\xi_{j-p-1}}^{\xi_j} \frac{(\xi_j - x)^p}{(\xi_j - \xi_{j-p-1})^p} dx = 1,$$

and the integration formula (7) follows. □

What does the **B** in B-Splines stand for?

- ▶ Beautiful?
- ▶ Bell shaped?
- ▶ Basic

It started early



Laplace, 1749-1827,



Popoviciu, 1906-1975,



Chakalov, 1886-1963

- ▶ Laplace 1820: Uniform B-splines
- ▶ Popoviciu 1930's B-spline recurrence relation, Marsden identity, knot insertion
- ▶ Chakalov 1930's: B-splines and divided differences, positivity
- ▶ de Boor, Pinkus, J. Approximation Theory, 124(2003), 115-123.
Bojanov, Hakopian, Sahakian 93, Bojanov 96.

Some mathematical works after 1945

- ▶ Schoenberg, 1946, B-splines on uniform knots.
- ▶ Curry, Schoenberg 1966, General B-spline theory
- ▶ Book by Ahlberg, Nilson, Walsh, 1967. Unfortunately they ignored B-splines.
- ▶ Marsden's identity, 1970
- ▶ Cox, de Boor, 1972, recurrence relation
- ▶ Boehm 1980 and Cohen, Lyche, Riesenfeld, 1980, knot insertion.

The Curry Schoenberg paper, 1966

“ The present paper was written in 1945 and completed by 1947, but for no good reason has so far not been published”.

ON POLYA FREQUENCY FUNCTIONS IV:
THE FUNDAMENTAL SPLINE FUNCTIONS
AND THEIR LIMITS

H. B. Curry and I. J. Schoenberg

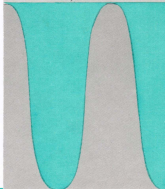
MRC Technical Summary Report #567

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Early industrial applications, France



Paul de Faget de Casteljau (1930-),



Pierre Bézier

Industrial application, variational approach

- ▶ Even Mehlum
- ▶ Autocon, SI, Norway 1960's aimed at ship building industry
- ▶ Autokon had 70% of the world market for ship design systems
- ▶ a form of nonlinear splines (Cornu spirals)