

Ex. 1 | Let $W = L((1, 0, -1, 1), (1, 1, 0, -2))$

Let $R_W: V_4 \rightarrow V_4$ be the reflection of V_4 with respect to W .

Let $P_{W^\perp}: V_4 \rightarrow V_4$ be the projection of V_4 onto W^\perp .

Let $T: V_4 \rightarrow V_4$ denote the composed linear transformation:

$$T = P_{W^\perp} \circ R_W$$

(in practice $T(\underline{v}) = P_{W^\perp}(R_W(\underline{v}))$).

(a) Describe $N(T)$ and $T(V_4)$.

(b) Find a basis of V_4 whose elements are eigenvectors of T .

(c) Compute $m_\mathcal{E}^\mathcal{E}(T)$ (where \mathcal{E} denotes the standard basis of V_4).

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Ex. 2 | Let $T: V_2 \rightarrow V_2$ be the linear transformation.

such that $T(1, 2) = (3, 6)$ and $T(2, 1) = (3, 6)$.

(a) Find $N(T)$.

(b) Compute $m_\mathcal{E}^\mathcal{E}(T)$, where \mathcal{E} is the standard basis of V_2 .

(c) Find a basis \mathcal{B} of V_2 such that $m_\mathcal{B}^\mathcal{B}(T)$ is a diagonal matrix.

SOLUTION

Ex. 1 | Idea: Let $\{\underline{w}_1, \underline{w}_2\}$ be a basis of W

and let $\{\underline{w}_3, \underline{w}_4\}$ be a basis of W^\perp . Then

$\mathcal{B} = \{\underline{w}_1, \underline{w}_2, \underline{w}_3, \underline{w}_4\}$ is a basis of V_4 and we have:

$$T(\underline{w}_1) = P_{W^\perp}(R_W(\underline{w}_1)) = P_{W^\perp}(\underline{w}_1) = \underline{0}$$

$$T(\underline{w}_2) = P_{W^\perp}(R_W(\underline{w}_2)) = P_{W^\perp}(\underline{w}_2) = \underline{0}$$

$$T(\underline{w}_3) = P_{W^\perp}(R_W(\underline{w}_3)) = P_{W^\perp}(-\underline{w}_3) = -\underline{w}_3$$

$$T(\underline{w}_4) = P_{W^\perp}(R_W(\underline{w}_4)) = P_{W^\perp}(-\underline{w}_4) = -\underline{w}_4$$

Therefore B is a basis of eigenvectors of T and $0, -1$ are the eigenvalues.

Specifically:

(a) From the above we have that $N(T) \supseteq W$ and $T(V_4) \supseteq W^\perp$.

But, by the nullity + rank Theorem,

$$\dim(N(T)) + \dim(T(V_4)) = 4.$$

It follows that $N(T) = W$ and $T(V_4) = W^\perp$.

(b) we can take as $\underline{w}_1 = (1, 0, -1, 1)$ and $\underline{w}_2 = (1, 1, 0, -2)$.

To find a basis of W^\perp , recall that W^\perp is the space of solutions of

$$\begin{cases} x - z + t = 0 \\ x + y - z + t = 0 \end{cases} \quad \begin{cases} x = z - t \\ y = -x + z + t = -z + 3t \end{cases}$$

Therefore $W^\perp = \{ (z-t, -z+3t, z, t) \mid z, t \in \mathbb{R} \} = \langle (1, -1, 1, 0), (-1, 3, 0, 1) \rangle$

$$= z(1, -1, 1, 0) + t(-1, 3, 0, 1)$$

Therefore we can take $\underline{w}_3 = (1, -1, 1, 0)$ and $\underline{w}_4 = (-1, 3, 0, 1)$.

Hence $B = \{ \underline{w}_1, \underline{w}_2, \underline{w}_3, \underline{w}_4 \}$ is a basis of V_4 whose elements are eigenvectors of T (of eigenvalues $0, 0, -1, -1$ respectively).

(c) let $C = {}_E^B(id) = \begin{pmatrix} 1 & 1 & 1 & -1 \\ 0 & 1 & -1 & 3 \\ -1 & 0 & 1 & 0 \\ 1 & -2 & 0 & 1 \end{pmatrix}$

By the diagram

$$\begin{array}{ccc} E & & E \\ V_4 & \xrightarrow{T} & V_4 \\ \downarrow id & & \uparrow id \\ V_4 & \xrightarrow{T} & V_4 \\ B & & B \end{array}$$

we have:

$${}_E^E(T) = C \operatorname{diag}(0, 0, -1, -1) C^{-1}$$

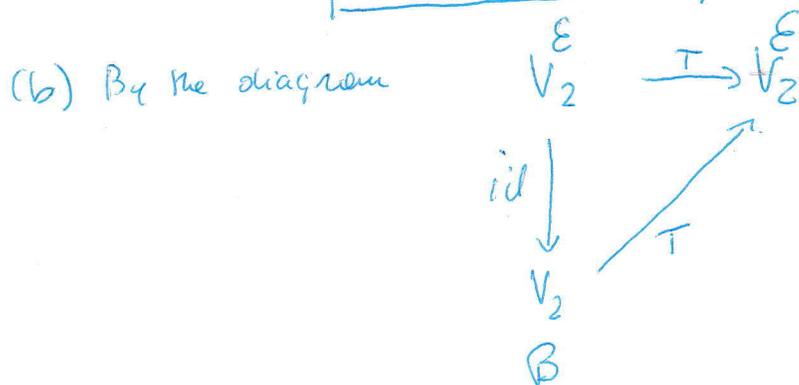
Ex. 2 (a) It is clear that $T(V_2) = L((3, 6))$.

Therefore $\dim(N(T)) = 2 - 1 = 1$.

But $(1, 2) - (2, 1) = (-1, 1)$ belongs to $N(T)$

(indeed $T((1, 2)) - T((2, 1)) = T((1, 2) - (2, 1)) = (3, 6) - (3, 6) = (0, 0)$)

therefore $N(T) = L((-1, 1))$.



We have that $m_{\mathbb{E}}^{\mathbb{E}}(T) = m_{\mathcal{B}}^{\mathcal{B}}(T) m_{\mathcal{B}}^{\mathbb{E}}(\text{id})$

where \mathcal{B} is any basis of V_2 .

Taking as $\mathcal{B} = \{(1, 2), (2, 1)\}$ we have that

$m_{\mathcal{B}}^{\mathcal{B}}(T) = \begin{pmatrix} 3 & 3 \\ 6 & 6 \end{pmatrix}$. On the other hand $m_{\mathcal{B}}^{\mathbb{E}}(\text{id}) = \left(m_{\mathcal{B}}^{\mathcal{B}}(\text{id}) \right)^{-1} = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}^{-1}$

For example, using determinants, we get $\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}^{-1} = -\frac{1}{3} \begin{pmatrix} 1 & -2 \\ -2 & 1 \end{pmatrix}$

therefore $m_{\mathcal{B}}^{\mathbb{E}}(T) = \begin{pmatrix} 3 & 3 \\ 6 & 6 \end{pmatrix} \left(-\frac{1}{3} \right) \begin{pmatrix} 1 & -2 \\ -2 & 1 \end{pmatrix} = -\frac{1}{3} \begin{pmatrix} -3 & -3 \\ -6 & -6 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 2 & 2 \end{pmatrix}$

(c) The basis \mathcal{B} is easily found: since $T((1, 2)) = (3, 6) = 3(1, 2)$

we have that $(1, 2)$ is an eigenvector of eigenvalue $\lambda_1 = 3$.

Since $T((-1, 1)) = (0, 0) = 0(-1, 1)$ we have that $(-1, 1)$ is eigenvector

of eigenvalue $\lambda_2 = 0$. It follows that, with respect to the

basis $\mathcal{E} = \{(1, 2), (-1, 1)\}$ $m_{\mathcal{E}}^{\mathcal{E}}(T) = \begin{pmatrix} 3 & 0 \\ 0 & 0 \end{pmatrix}$.

Otherwise: take as $A = \begin{pmatrix} 1 & 1 \\ 2 & 2 \end{pmatrix}$ $P_A(\lambda) = \det \begin{pmatrix} 1-\lambda & -1 \\ -2 & 1-\lambda \end{pmatrix} =$

$$= (1-\lambda)(1-\lambda) - 2 = \lambda^2 - 3\lambda = \lambda(\lambda - 3).$$

Therefore no eigenvalues are $\lambda_1 = 3$ and $\lambda_2 = 0$. Computing the eigenspaces

one finds $E_3 = L((1, 2))$ and $E_0 = L((-1, 1))$.