

KAM Theory and Applications in Celestial Mechanics – First Lecture: Chaotic Motions in Hamiltonian Systems

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Integrability *à la* Liouville

Theorem (Liouville):

Let $H = H(\mathbf{p}, \mathbf{q})$ be the Hamiltonian of a system with n degrees of freedom. **If** there are n constant of motions J_1, \dots, J_n such that

- they are in **involution**, i.e. $\{J_i, J_j\} = 0 \forall i, j = 1, \dots, n$;
- they are **independent**, i.e.

$$\text{rank} \left(\frac{\partial(J_1, \dots, J_n)}{\partial(p_1, \dots, p_n, q_1, \dots, q_n)} \right) \neq 0 ;$$

then there is a canonical transformation $(\mathbf{p}, \mathbf{q}) = \Psi(\mathbf{J}, \boldsymbol{\alpha})$, such that in the new coordinates $H = H(\mathbf{J})$.

Let us recall that the Poisson bracket $\{\cdot, \cdot\}$ with respect to the canonical coordinates (\mathbf{p}, \mathbf{q}) is defined so that $\{f, g\} = \sum_{j=1}^n \left(\frac{\partial f}{\partial q_j} \frac{\partial g}{\partial p_j} - \frac{\partial f}{\partial p_j} \frac{\partial g}{\partial q_j} \right)$.

- The proof of Liouville's theorem is **constructive** and Hamilton's equations are **integrable** in the new coordinates, i.e. $J_i(t) = J_i(0)$ and $\alpha_i(t) = \alpha_i(0) + \frac{\partial H}{\partial J_i} t, \forall i = 1, \dots, n$.

Integrability *à la* Arnold–Jost

Theorem (Arnold–Jost):

Let $H = H(\mathbf{p}, \mathbf{q})$ be a Hamiltonian satisfying the hypotheses of Liouville's theorem. Moreover, **if**

- there are n constant values c_1, \dots, c_n such that each equation $J_1(\mathbf{p}, \mathbf{q}) = c_1, \dots, J_n(\mathbf{p}, \mathbf{q}) = c_n$ implicitly defines a **regular** and **compact** manifold in the phase-space,

then there is a local canonical transformation $(\mathbf{p}, \mathbf{q}) = \Psi(\mathbf{I}, \vartheta)$ defined on **action-angle coordinates** (i.e. Ψ is defined on $\mathcal{G} \times \mathbb{T}^n$, with \mathcal{G} open subset of \mathbb{R}^n), such that in the new coordinates $H = H(\mathbf{I})$.

Remark:

The proof of Arnold–Jost theorem is **constructive** and Hamilton's equations are **integrable** in the new coordinates, i.e. $I_i(t) = I_i(0)$ and $\vartheta_i(t) = \vartheta_i(0) + \omega_i t$, with **angular velocities** $\omega_i = \frac{\partial H}{\partial I_i}$, $\forall i = 1, \dots, n$. Thus, some regions of the phase space are filled by **invariant tori** and the motion over them is related to the **frequencies** $\omega_i / (2\pi) \forall i = 1, \dots, n$.

Integrability *à la* Arnold–Jost (an example with 1 d.o.f.)

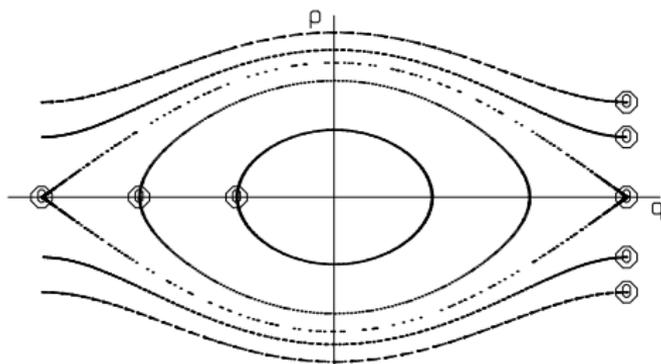


Figure: Eight orbits of the Poincaré map for the simple pendulum equation, i.e. $\ddot{x} = -\sin x$. All the initial conditions are marked with the symbol 0 (in a “○”). For each orbit, 400 points are plotted at regular interval of time equal to $2\pi/\sqrt{2}$ in the phase space with $(q, p) = (x, \dot{x})$ coordinates, being $q \in [-\pi, \pi]$.

- the orbits lie on the energy level $H(p, q) = \frac{p^2}{2} - \cos q = E$.
- Two separatrices (meeting in the hyperbolic point $(p, q) = (0, \pm\pi)$) are between the **“librational tori”** (with $E \in (-1, 1)$) and the **“rotational tori”** ($E > 1$).

A first example of chaotic motion in a Poincaré map

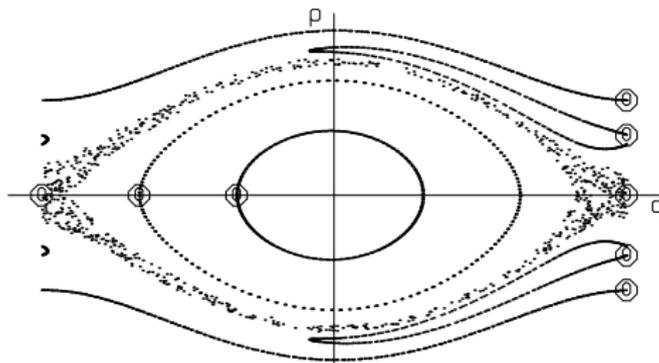


Figure: Eight orbits of the Poincaré map for the forced pendulum equation $\ddot{x} = -\sin x - \varepsilon \cos(\Omega t)$ with $\varepsilon = 0.05$ and $\Omega = \sqrt{2}$. All the initial conditions (marked with the symbol 0 (in a “○”)) are the same as in the previous figure. For each orbit, the points are plotted at regular interval of time equal to $2\pi/\Omega$.

Remark:

After having added a **small perturbation depending on time**, orbits starting close to an hyperbolic point **do not lie on a regular 1D-curve**.

A first example of chaotic motion in a Poincaré map

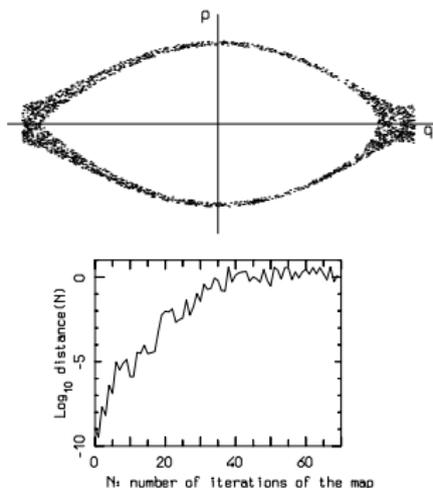


Figure: Same Poincaré map as before. Behavior of the distance between two chaotic orbits as a function of the number of iterations of the map.

- Definition:** a region of the phase space is said to be **chaotic**, when it is **very sensitive to the initial conditions**; i.e. $d(t) \simeq e^{\lambda t} d(0)$, where d is the distance between two motions and $\lambda > 0$.

Stable and unstable manifolds

- **Definition:** the sets $W_{(\bar{p}, \bar{q})}^+$ and $W_{(\bar{p}, \bar{q})}^-$, such that

$$W_{(\bar{p}, \bar{q})}^{\pm} = \{ (p, q) : \lim_{k \rightarrow \infty} \mathcal{M}^{\pm k}(p, q) = (\bar{p}, \bar{q}) \},$$

are said to be the stable and unstable manifold, respectively, for the hyperbolic point (\bar{p}, \bar{q}) of the map \mathcal{M} .

Theorem:

The stable and unstable manifolds $W_{(\bar{p}, \bar{q})}^{\pm}$ are tangent to the eigenspaces \mathcal{E}^{\pm} , respectively. Moreover, *locally*, $W_{(\bar{p}, \bar{q})}^{\pm}$ are regular graphs of \mathcal{E}^{\pm} , resp.

Corollary:

The stable manifold $W_{(\bar{p}, \bar{q})}^+$ cannot intersect itself; the same holds true for the unstable manifold $W_{(\bar{p}, \bar{q})}^-$.

Stable and unstable manifolds: the integrable case ($\varepsilon = 0$)

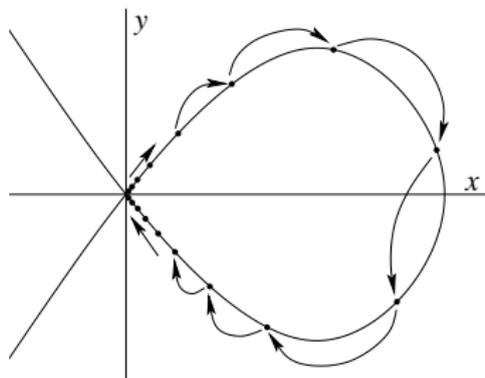


Figure: Stable and unstable manifolds for the Poincaré map $\Phi_H^{2\pi}$ related to the Hamiltonian $H(x, y, t) = (y^2 - x^2)/2 + (1 + \varepsilon \cos t)x^3/3$ when $\varepsilon = 0$.

Both the stable manifold and the unstable one lie on the separatrix given by the implicit equation $H = (y^2 - x^2)/2 + x^3/3 = 0$.

- **Definition:** an orbit (point) is said to be **homoclinic** if it is included in the intersection of the stable manifold with the unstable one.

Splitting of the stable and unstable manifolds (case $\varepsilon \neq 0$)

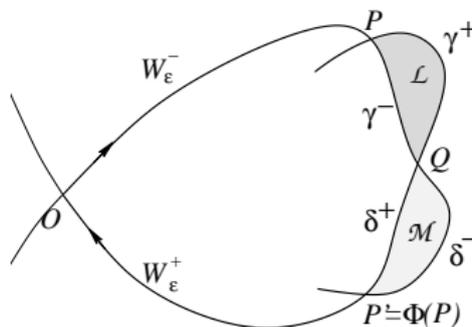


Figure: Schematic representation of the intersections between the stable and unstable manifolds for the Poincaré map $\Phi = \Phi_H^{2\pi}$ related to the Hamiltonian $H(x, y, t) = (y^2 - x^2)/2 + (1 + \varepsilon \cos t)x^3/3$ in the perturbed case, i.e. with $\varepsilon \neq 0$. The consecutive lobes \mathcal{L} and \mathcal{M} have the same area.

- **Remark:** if $\varepsilon \neq 0$ the stable manifold W_ε^+ do not superpose to the unstable one W_ε^- ; they cross each other in the homoclinic points.
- **Proposition:** two consecutive lobes (including the regions between the stable and the unstable manifolds) have the same area.

Splitting of the stable and unstable manifolds (case $\varepsilon \neq 0$)

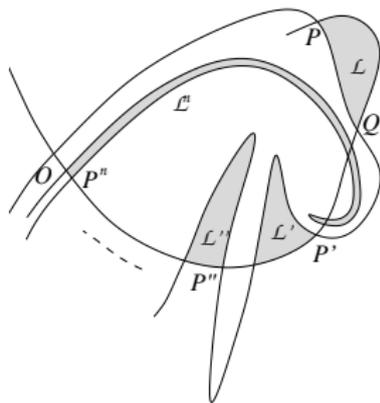


Figure: Schematic representation of the intersections between the stable and unstable manifolds for the same Poincaré map Φ of the previous slide. The lobes \mathcal{L} , \mathcal{L}' , \mathcal{L}'' , \dots , \mathcal{L}^n include the same area.

- Remark:** the hyperbolic point is an accumulation point for the homoclinic orbits. Since all the lobes have the same area and their “bases” are shorter and shorter, they are **stretched in the direction of the stable (unstable) manifold**, which cannot be crossed.

Stable and unstable manifolds for the standard map

- **Definition:** the change of coordinates $\mathcal{M}_\varepsilon : \mathbb{R} \times \mathbb{T} \mapsto \mathbb{R} \times \mathbb{T}$ is called **standard map**, when $(p', q') = \mathcal{M}_\varepsilon(p, q)$ with

$$p' = p + \varepsilon \sin q, \quad q' = q + p' \pmod{2\pi}.$$

- **Remark:** one can easily check that the (standard) map \mathcal{M}_ε is **symplectic** and, then, it is **area-preserving**.
- **Remark:** for all $\varepsilon \neq 0$ the origin is an **hyperbolic point** for \mathcal{M}_ε .
- **Remark:** \mathcal{M}_ε is 2π -periodic also with respect to the action p .
- **Stable [unstable] manifold W_ε^+ [W_ε^-]; drawing “N iterations”:**
 - for the initial iteration with $n = 1$, draw a short segment connecting the hyperbolic point to another point belonging to the eigenspace tangent to W_ε^+ [W_ε^-];
 - for each segment of the $n - 1$ iteration, if its length is $> L$ (being L suitably fixed) split it in a grid of sub-segments shorter than L ; for each (sub)segment, consider both the vertexes, compute the pair of transformed points along the map $\mathcal{M}_\varepsilon^{-1}$ [\mathcal{M}_ε] and connect them;
 - repeat the previous operation while $n \leq N$.

Stable and unstable manifolds for the standard map

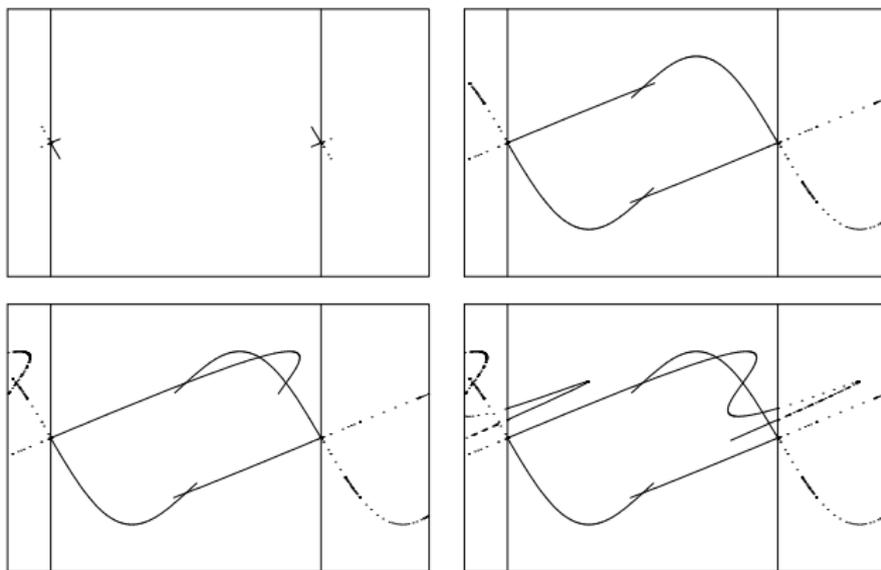


Figure: Stable and unstable manifolds for the standard map \mathcal{M}_ε with $\varepsilon = 2.36$. Each box represents the phase space $[0, 2\pi] \times [-\pi, \pi]$; the shaded parts are reported to make clearer the 2π -periodicity in the angle. Top-left, top-right, bottom-left and bottom-right boxes contain the drawing of the manifolds with 1, 2, 3 and 4 iterations, respectively.

Stable and unstable manifolds for the standard map

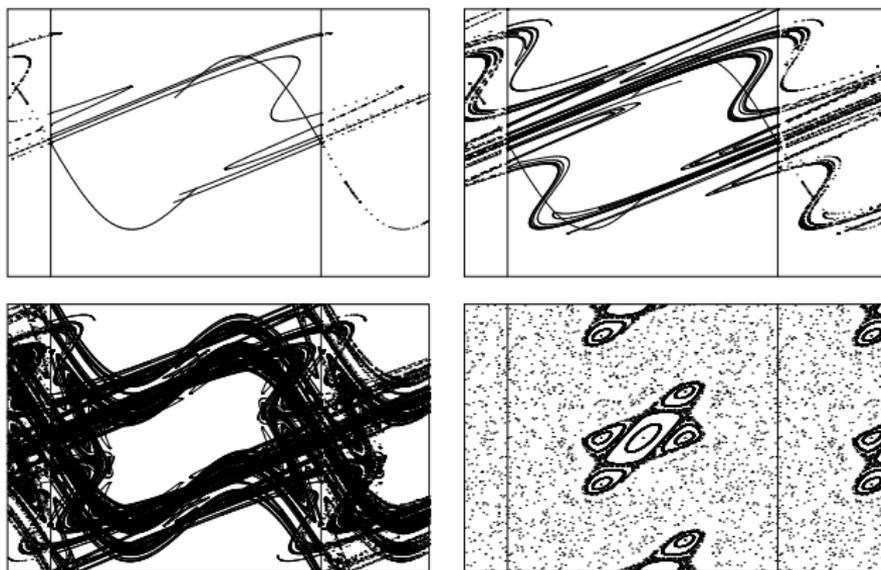


Figure: Stable and unstable manifolds (for the previous standard map \mathcal{M}_ε) are compared to some orbits. Top-left, top-right and bottom-left boxes contain the drawing of the manifolds with 5, 8 and “as many as possible” iterations, resp. In the bottom-right box, some orbits of \mathcal{M}_ε are plotted to highlight that **the manifolds fill the chaotic region.**

Poincaré sections

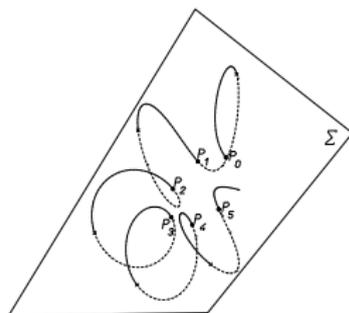


Figure: Schematic representation of a Poincaré section. The flow defines a map Π such that P_0 is related to P_1 , because P_1 is the outgoing intersection (between the orbit and the surface Σ) next to P_0 (ingoing intersections are discarded). For the same reason, $\Pi(P_1) = P_2, \dots, \Pi(P_4) = P_5$.

- Remark:** consider a n degrees of freedom Hamiltonian H and a $(2n - 1)$ D surface Σ , such that for all points $P \in \Sigma$ the flow Φ_H^t is transversal to Σ in P . It is possible to define a Poincaré section, i.e. a map $\Pi : \Sigma \mapsto \Sigma$ as in figure above.

The Hénon–Heiles model

The Hénon–Heiles model is described by the following Hamiltonian:

$$H(\mathbf{p}, \mathbf{q}) = \frac{\omega_1}{2} (p_1^2 + q_1^2) + \frac{\omega_2}{2} (p_2^2 + q_2^2) + q_1^2 q_2 - \frac{1}{3} q_2^3 .$$

Remarks

- For small values of the canonical coordinates (q_1, q_2) , the system is well approximated by a pair of harmonic oscillators, i.e.

$$H(\mathbf{p}, \mathbf{q}) \simeq \omega_1 (p_1^2 + q_1^2)/2 + \omega_2 (p_2^2 + q_2^2)/2, \text{ with } \omega_1 > 0 \text{ e } \omega_2 > 0 .$$
- The section surface Σ is defined so that $q_1 = 0$. When the energy level $H = E > 0$, Σ is obviously transversal to the Hamiltonian flow.
- The Poincaré sections are usually represented for a fixed energy level $H = E > 0$ and on the plane (p_2, q_2) , where each point locates an initial condition (and, so, an orbit), because $q_1 = 0$ and p_1 is given by the equation $H(p_1, p_2, 0, q_2) = E$.
- When the energy level $E < E_e$, where the escape energy value $E_e = \min \{ \omega_1^3/24 + \omega_1^2 \omega_2/8, \omega_2^3/6 \}$, then the points (p_2, q_2) of the Poincaré sections are bounded so that $\omega_2 (p_2^2 + q_2^2)/2 - q_2^3/3 \leq E$.

Poincaré sections for the Hénon–Heiles model

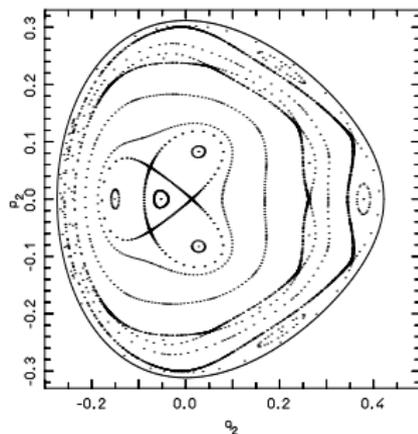


Figure: Poincaré sections for the Hénon–Heiles model in a so called “non-resonant” case ($\omega_1 = 1$ and $\omega_2 = (\sqrt{5} - 1)/2$). The energy level is fixed so that $E = 0.030$. In this case the escape energy value is $E_e = 0.03934466$. The most external curve is the “border” orbit, i.e. $\omega_2(p_2^2 + q_2^2)/2 - q_2^3/3 = E_e$.

- **Remark:** small chaotic regions are visible close to hyperbolic points, but **most of the orbits lie on regular 1D-curves.**

Poincaré sections for the Hénon–Heiles model

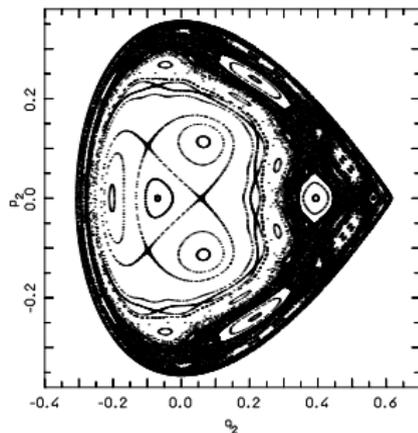


Figure: Poincaré sections for the Hénon–Heiles model with the same values of the angular velocities ω_1 and ω_2 as in the previous slide. The energy level is fixed so that $E = 0.039344$, that is very close to the escape energy value.

- **Remark:** by increasing the energy (and so the perturbation) the chaotic regions gets larger, but (according to the Hénon words) **islands of ordered motion still persist, although they are in a chaotic sea.**

Chaos is everywhere! Does this mean everything is chaotic?

- Poincaré claimed that the **general problem of dynamics** is given by a Hamiltonian system of the type $H(\mathbf{p}, \mathbf{q}) = h(\mathbf{p}) + \varepsilon f(\mathbf{p}, \mathbf{q})$ where ε is a **small parameter** and (\mathbf{p}, \mathbf{q}) are **action–angle coordinates** (that are defined on $\mathcal{G} \times \mathbb{T}^n$, with \mathcal{G} open subset of \mathbb{R}^n). Poincaré proved that a Hamiltonian of the type $H(\mathbf{p}, \mathbf{q}) = h(\mathbf{p}) + \varepsilon f(\mathbf{p}, \mathbf{q})$ is **generically non-integrable**. His proof is based on the fact that **resonances are everywhere dense** when $(\frac{\partial^2 h}{\partial p_i \partial p_j})_{i,j}$ is non-degenerate.
- Each resonance shows **hyperbolic points, homoclinic orbits, stable/unstable manifolds, chaotic regions**.
- Why ordered regions can still be detected in the Hénon–Heiles model? **They cannot be integrable** (according to Poincaré theorem of non-existence of the first integrals for generic Hamiltonians).

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⇒ **KAM THEORY!**