

Anosov Flows and Dynamical Zeta Functions

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Abstract

We study the Ruelle and Selberg zeta functions for C^r Anosov flows, $r > 2$, on a compact smooth manifold. We prove several results, the most remarkable being: (a) for C^∞ flows the zeta function is meromorphic on the entire complex plane; (b) for contact flows satisfying a bunching condition (e.g. geodesic flows on manifolds of negative curvature better than $\frac{1}{9}$ -pinched) the zeta function has a pole at the topological entropy and is analytic in a strip to its left; (c) under the same hypotheses as in (b) we obtain sharp results on the number of periodic orbits. Our arguments are based on the study of the spectral properties of a transfer operator acting on suitable Banach spaces of anisotropic currents.

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1 Introduction

In 1956, Selberg introduced a zeta function for a surface of constant curvature $\kappa = -1$ formally defined to be the complex function

$$\zeta_{\text{Selberg}}(z) = \prod_{\gamma} \prod_{n=0}^{\infty} (1 - e^{-(z+n)\lambda(\gamma)}), z \in \mathbb{C} \quad (1.1)$$

where $\lambda(\gamma)$ denotes the length of a closed geodesic γ . This converges to a non-zero analytic function on the half-plane $\text{Re}(z) > 1$ and Selberg showed that ζ_{Selberg} has an analytic extension to the entire complex plane, by using the trace formula which now bears his name [66]. Moreover, he also showed that the zeros of ζ_{Selberg} correspond to the eigenvalues of the Laplacian. In fact, the trace formula connects the eigenvalues of $-\Delta$ with the information provided by the geodesics, their lengths and their distribution.¹ The definition (1.1) was subsequently adapted to more general settings, including surfaces of variable curvature, thus giving birth to a new class of zeta functions which we refer to as dynamical zeta functions. However, due to the lack of a suitable generalized trace formula, few results are known on their meromorphic extension, the location of their zeros or their relationships with appropriate operators.

In 1976, Ruelle [61] proposed generalizing the definition by replacing the closed geodesics in ζ_{Selberg} by the closed orbits of an Anosov flow $\phi_t : M \rightarrow M$, where M is a C^∞ , d -dimensional Riemannian compact manifold. We recall that an Anosov flow is a flow such that there exists a $D\phi_t$ -invariant continuous splitting $TM = E^s \oplus E^u \oplus E^c$, where E^c is the one-dimensional subspace tangent to the flow, and constants $C_0 \geq 1$ and $\bar{\lambda} > 0$, such that for all $x \in M$

$$\begin{aligned} \|D\phi_t(v)\| &\leq \|v\|C_0e^{-\bar{\lambda}t} && \text{if } t \geq 0, v \in E^s, \\ \|D\phi_{-t}(v)\| &\leq \|v\|C_0e^{-\bar{\lambda}t} && \text{if } t \geq 0, v \in E^u, \\ C_0^{-1}\|v\| &\leq \|D\phi_t(v)\| \leq C_0\|v\| && \text{if } t \in \mathbb{R}, v \in E^c. \end{aligned} \quad (1.2)$$

We will denote by $d_u \doteq \dim(E^u)$ and $d_s \doteq \dim(E^s)$. The geodesic flow on manifolds with negative sectional curvatures are very special examples of mixing Anosov flows (see [67], [59] and references therein).

¹ See [49], and references therein, for a precise, yet friendly, introduction to the Selberg Trace formula and its relationship with the Selberg zeta function.

In this context Ruelle defined a zeta function by

$$\zeta_{\text{Ruelle}}(z) = \prod_{\tau \in \mathcal{T}_p} (1 - e^{-z\lambda(\tau)})^{-1}, z \in \mathbb{C} \quad (1.3)$$

where $\mathcal{T}_p$ denotes the set of prime orbits and $\lambda(\tau)$ denotes the period of the closed orbit τ .² Since it is known that the number of periodic orbits grows at most exponentially in the length [48], it is easy to see that the above zeta functions are well defined for $\Re(z)$ large enough. Also we can relate the Ruelle and Selberg zeta functions by

$$\zeta_{\text{Ruelle}}(z) = \frac{\zeta_{\text{Selberg}}(z+1)}{\zeta_{\text{Selberg}}(z)}, \quad \zeta_{\text{Selberg}}(z) = \prod_{i=0}^{\infty} \zeta_{\text{Ruelle}}(z+i)^{-1}$$

when they are both defined. Here we study ζ_{Ruelle} .

It is known, for weak mixing Anosov flows, that $\zeta_{\text{Ruelle}}(z)$ is analytic and non zero for $\Re(z) \geq h_{\text{top}}(\phi_1)$ apart for a single pole at $z = h_{\text{top}}(\phi_1)$, where by $h_{\text{top}}(\phi_1)$ we mean the topological entropy of the flow (see [15], or [53, Page 143] for more details). Also it is long known that on the left of $h_{\text{top}}(\phi_1)$ there exists a strip in which $\zeta_{\text{Ruelle}}(z)$ is meromorphic ([53] and references therein). It is interesting to notice that the poles of dynamical zeta functions (called also *resonances*) are often computationally accessible and of physical interest (see [18, Chapter 17] for a detailed discussion).

In the very special case of analytic Anosov flows with real analytic stable and unstable foliations, Ruelle already showed that his zeta function has a meromorphic extension to $\mathbb{C}$. This result was generalized first by Rugh [64], for three dimensional manifolds, and then by Fried [27], in arbitrary dimensions, but still assuming an analyticity of the flow. Here we extend such results to the C^∞ setting. More precisely, for C^r flows we obtain a strip in which $\zeta_{\text{Ruelle}}(z)$ is meromorphic of width unboundedly increasing with r . Note that this is consistent with a previous example of Gallavotti [28], where ζ_{Ruelle} is not meromorphic in the entire complex plane.

An additional knowledge of the location of the zeroes of ζ_{Ruelle} allows one to gain information on the distribution of the periodic orbits. For example

² A periodic orbit τ , of period $\lambda(\tau)$, is a closed curve parametrized by the flow, i.e. $\tau : [0, \lambda(\tau)) \rightarrow M$ such that $\tau(t) = \phi_t(\tau(0))$. A periodic orbit τ is prime if it is one-to-one with its image. The range of τ is indicated again by τ . If τ_p is the prime orbit related to τ , then $\mu(\tau)$ is the unique integer such that $\lambda(\tau) = \mu(\tau)\lambda(\tau_p)$.

it is known that if a negatively curved Riemannian manifold has dimension 2 [21] or the sectional curvatures are $\frac{1}{4}$ -pinched [69], then the number $N(T)$ of closed orbits of period less than T satisfies $N(T) = \text{li}(e^{h_{\text{top}}(\phi_1)T}) + O(e^{cT})$ where $c < h_{\text{top}}(\phi_1)$, and $\text{li}(x) = \int_2^x \frac{1}{\ln(s)} ds$. Note that either the assumption that M is two dimensional or that the sectional curvatures are $\frac{1}{4}$ -pinched imply that the horocycle foliation is C^1 . One might then conjecture that such a foliation regularity is necessary in order to obtain the above estimate of the error term. However, we show that this is not the case and, although we cannot prove it in full generality, we conjecture that the above bound holds for all contact Anosov flows. As is usual for number theoretic zeta functions, a key ingredient in this analysis is showing that ζ_{Ruelle} is analytic in a strip to the left of its first pole. This result was stated in ([22]) for geodesic flows for which the sectional curvatures are $\frac{1}{4}$ -pinched, although the proof there was only sketched and is incomplete. An earlier paper ([57]) addressing the same question contains a more serious flaw in the approach.

The general plan of the proof is explained in the next section, here we anticipate a few ideas and give a bit of their history. The basic idea goes back to Ruelle [61] and consists of relating the properties of the zeta function to the *dynamical determinant* of some appropriate operator. Classically such a program has been implemented by first coding the dynamics via Markov partitions and then defining appropriate operators acting on functions of the resulting subshift. As such a coding is, in general, only Hölder, all the properties connected to the smoothness of the dynamics are annihilated in the process. Yet, the work of Ruelle in the case of expanding maps and the seminal work of Kitaev [40] for Anosov diffeomorphisms showed that the smoothness properties of the map are exactly the ones responsible for larger domain of analyticity of the zeta function. The above cited works of Ruelle, Rugh and Fried for analytic flows made this even clearer.

The turning point in overcoming this problem was [12] where it is shown how to construct Banach spaces in which the action of an Anosov map gives rise to a quasi compact operator (often called *Ruelle Transfer operator*) allowing to completely bypass the need of a Markov coding. This opened the door to the possibility of dispensing with the analyticity hypothesis while still retaining the relevant smoothness properties of the dynamical systems. Since then a considerable amount of work has been done to implement such a goal. In particular, [30, 44, 9, 31] and especially [10] have clarified the relation between the smoothness of the map and the essential spectral radii of transfer

operators as well as connected dynamical determinants to appropriate “flat traces”³ of transfer operators (see [6, 7, 10]). On the other hand, [43, 16] illustrated how this approach can be applied also to flows by showing that the resolvent of the generator of the flow is quasi compact on such spaces. More recently some beautiful work, although limited to the case of contact flows, allows one to study directly the transfer operator associated to the time one map of the flow [73, 74, 25, 24]. Note that, for such types of result, some condition on the flow is necessary. Indeed, the quasi compactness of the operator associated to the time one map plus mixing implies exponential mixing, while there are known examples of Axiom A flows, constructed as piecewise constant ceiling suspensions, that are mixing but enjoy arbitrarily slow rates of decay correlations [62, 55]).

Given such a state of the art, it looked like all the ingredients needed to tackle the present problems were present even though quite a lot work remained to be done. It remained to choose a precise line of attack. Given the complexity of the task, we chose to follow the path of least resistance at the cost of obtaining possibly suboptimal results. In particular, here we extend the results of [30, 16] to allow the study of the action of the flow on the space of exterior forms (similarly to the original Ruelle approach for expanding maps [61]). Next, to study the relation between the spectra of such operators and the dynamical determinants we extend to the case of flows a suboptimal, but very efficient, trick introduced in [45] for the case of maps and inspired by the work of Margulis (as explained to Liverani by Dolgopyat). It is likely that, at the price of some more work, one could adapt alternative approaches to the present case. For example defining the operator on different Sobolev-like spaces or replacing the tensor trick by a strategy based on kneading determinants, as in Baladi-Tsujii [10]. Such alternatives might allow one to obtain sharper estimates in the case of finite differentiability.

Next, we show that the zeta function has a pole free strip at the left of the topological entropy and we obtain bounds for the growth of the zeta function on such a strip provided a Dolgopyat type estimate for the action of the flow on d_s -external forms holds true, d_s being the dimension of the strong stable manifold. To do so we use the simple strategy put forward in [44]. Finally, to

³ Such terminology has also been adopted by the dynamical system community, following the work of Atiyah and Bott ([3], [5]), since, as the reader will see, it is morally a regularization, or a flattening, of the trace.

establish the Dolgopyat estimate in the present context we follow the strategy developed in [42, 43, 8] for the action on functions. Note that to look at d_s -forms corresponds, in the old Markov based strategy, to studying the statistical properties of the flow with respect to the measure of maximal entropy. The extension of the geometric part of the original Dolgopyat argument to this situation presents two difficulties. One, well known, related to the lack of regularity of the foliations that is solved, following [43], by restricting the study to the contact flows. The second (here treated in Lemma 7.9), was unexpected (at least to us) and is related to having (morally) the measure of maximal entropy, rather than Lebesgue, as a reference measure. This we can solve only partially, hence the presence of a bunching (or pinching) condition in our results.

The structure of the paper is as follows. In section 2 we present the statements of the main results in this paper. We also explain the strategy of the proofs assuming several Lemmata and constructions detailed in later sections. In section 3 we construct the spaces on which our operators will act. Sections 4, 5 and 6 contain estimates for transfer operators and their “flat traces”. In sections 7 and 8 we restrict ourself to the case of contact flows. In particular, in section 7 we exclude the existence of zeroes in a vertical strip to the left of the topological entropy by the means of a Dolgopyat like estimate. In section 8 we obtain a bound on the growth of ζ_{Ruelle} in this strip.

In Appendix A we collect together, for the reader’s convenience, several facts from differential geometry, while in Appendix B we discuss the orientability of the stable distribution. In Appendix C we relate the topological entropy and the volume growth of manifolds. In Appendix D we detail some facts about mollifiers acting on the Banach spaces of interest. Finally, in Appendix E, we recall some necessary facts concerning holonomies.

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2 Statement of Results

2.1 Some notation

We use $B_d(x, r)$ to designate the open d -dimensional ball with center x and radius r .

We will use $C_{\#}$ to represent a generic constant (depending only on the manifold, the flow, the choice of the charts and the partition of unity made in Section 3) which could change from one occurrence to the next, even within the same equation. We will write $C_{a_1, \dots, a_k}$ for generic constants depending on the parameters $a_1, \dots, a_k$, which could still change at every occurrence. Finally, numbered constants $C_0, C_1, C_2, \dots$ are constants with a fixed value throughout the paper.

2.2 Theorems and Proofs

Our first result applies to all Anosov flows ϕ_t on a connected, compact and orientable C^∞ Riemannian manifold M .⁴

⁴ One could easily extend the result to C^r manifolds, but we avoid it to ease notation.

Theorem 2.1. *For any C^r Anosov flow ϕ_t with $r > 2$, $\zeta_{\text{Ruelle}}(z)$ is meromorphic in the region*

$$\Re(z) > h_{\text{top}}(\phi_1) - \frac{\bar{\lambda}}{2} \left\lfloor \frac{r-1}{2} \right\rfloor$$

where $\bar{\lambda}$, is determined by the Anosov splitting, and $\lfloor x \rfloor$ denotes the integer part of x . Moreover, $\zeta_{\text{Ruelle}}(z)$ is analytic for $\Re(z) > h_{\text{top}}(\phi_1)$ and non zero for $\Re(z) > \max\{h_{\text{top}}(\phi_1) - \frac{\bar{\lambda}}{2} \lfloor \frac{r-1}{2} \rfloor, h_{\text{top}}(\phi_1) - \bar{\lambda}\}$. If the flow is topologically mixing then $\zeta_{\text{Ruelle}}(z)$ has no poles on the line $\{h_{\text{top}}(\phi_1) + ib\}_{b \in \mathbb{R}}$ apart from a single simple pole at $z = h_{\text{top}}(\phi_1)$.

Corollary 2.2. *For any C^∞ Anosov flow the zeta function $\zeta_{\text{Ruelle}}(z)$ is meromorphic in the entire complex plane.*⁵

Note that if the flow is not topologically mixing then the flow can be reduced to a constant ceiling suspension and hence there exists $b > 0$ such that $\zeta_{\text{Ruelle}}(z + ib) = \zeta_{\text{Ruelle}}(z)$ (for more details see [52]).

Corollary 2.3. *$\zeta_{\text{Ruelle}}(z)$ and $\zeta_{\text{Selberg}}(z)$ are meromorphic in the entire complex plane for smooth geodesic flows on any connected compact orientable Riemannian manifold with variable strictly negative sectional curvatures. Moreover, the zeta functions $\zeta_{\text{Ruelle}}(z)$ and $\zeta_{\text{Selberg}}(z)$ have no zeroes or poles on the line $\{h_{\text{top}}(\phi_1) + ib\}_{b \in \mathbb{R}}$, except at $z = h_{\text{top}}(\phi_1)$ where both $\zeta_{\text{Ruelle}}(z)^{-1}$ and $\zeta_{\text{Selberg}}(z)$ have a simple zero.*

Next, we specialize to *contact* Anosov flows. Let $\lambda_+ \geq 0$ such that $\|D\phi_{-t}\|_\infty \leq C_0 e^{\lambda_+ t}$ for all $t \geq 0$.

Theorem 2.4. *For any $C^r, r > 2$, contact flow with $\frac{\bar{\lambda}}{\lambda_+} > \frac{1}{3}$ there exists $\tau_* > 0$ such that the Ruelle zeta function is analytic in $\{z \in \mathbb{C} : \Re(z) \geq h_{\text{top}}(\phi_1) - \tau_*\}$ apart from a simple pole at $z = h_{\text{top}}(\phi_1)$.*

⁵ This provides an answer to an old question of Smale: “Does $\zeta_{\text{Selberg}}(z)$ have nice properties for any general class of flows?” cf. pages 802-803, of [68]. Smale also specifically asked if for suspension flows over Anosov diffeomorphisms close to constant height suspensions the zeta function $\zeta_{\text{Selberg}}(z)$ has a meromorphic extension to all of $\mathbb{C}$. The above corollary answers these questions in the affirmative for C^∞ Anosov flows, despite Smale’s comment “I must admit that a positive answer would be a little shocking”.

Remark 2.5. Note that the bunching condition $\frac{2\bar{\lambda}}{\lambda_+} > \frac{2}{3}$ implies that the invariant foliations are at least $\frac{2}{3}$ -Hölder continuous. Also remember that an a -pinched geodesic flow is $(2\sqrt{a} + \varepsilon)$ -bunched, that is $a \leq \left(\frac{\bar{\lambda}}{\lambda_+}\right)^2 + \varepsilon$, see [33] for more details.

The above facts have several important implications. We begin with some low-hanging fruits. The proof will be obvious once the reader goes over the construction explained later in this section and remembers that the dynamical determinants for 0-forms and d -forms have their first zeros at $\Re(z) = 0$ (since they are exactly the dynamical determinants of the usual Ruelle transfer operator).

Corollary 2.6. For a volume preserving three dimensional Anosov flow we have that the zeta function $\zeta_{\text{Ruelle}}(z)$ is meromorphic in $\mathbb{C}$ and, moreover,

- $\zeta_{\text{Ruelle}}(z)$ is analytic for $\Re(z) \geq h_{\text{top}}(\phi_1) - \tau_*$, except for a pole at $h_{\text{top}}(\phi_1)$;
- $\zeta_{\text{Ruelle}}(z)$ is non-zero for $\Re(z) > 0$.

Theorem 2.4 has the following simple consequence for the rate of mixing with respect to the measure of maximal entropy.

Corollary 2.7. The geodesic flow $\phi_t : T_1M \rightarrow T_1M$ for a compact manifold M with better than $\frac{1}{9}$ -pinched negative sectional curvatures (or more generally any contact Anosov flow satisfying the hypothesis of the Theorem 2.4) is exponentially mixing with respect to the Bowen-Margulis measure μ , i.e., there exists $\alpha > 0$ such that for $f, g \in C^\infty(T_1M)$ there exists $C > 0$ for which the correlation function

$$\rho(t) = \int f \circ \phi_t g d\mu - \int f d\mu \int g d\mu$$

satisfies $|\rho(t)| \leq C_\# e^{-\alpha|t|}$, for all $t \in \mathbb{R}$.

Proof. Consider the Fourier transform $\widehat{\rho}(s) = \int_{-\infty}^{\infty} e^{ist} \rho(t) dt$ of the correlation function $\rho(t)$. By ([56], Theorem 2) and ([63], Theorem 4.1), the analytic extension of $\zeta_{\text{Ruelle}}(z)$ in Theorem 2.4 implies that there exists $0 < \eta \leq \tau_*$ such that $\widehat{\rho}(s)$ has an analytic extension to a strip $|\Im(s)| < \eta$. Moreover, adapting the argument in ([43], proof of Theorem 2.4) we can use the smoothness of

the test functions to allow us to assume without loss of generality that for each fixed value $-\eta < t < \eta$ we have that the function $\sigma \mapsto \widehat{\rho}(\sigma + it)$ is in $L^1(\mathbb{R})$. Finally, we apply the Paley-Wiener theorem ([60], Theorem IX.14) to deduce the result. $\square$

Moreover, Theorem 2.4 allows us to extend results of Huber-Selberg (for constant sectional curvatures), Pollicott-Sharp (for surfaces of negative curvature) and Stoyanov (for $\frac{1}{4}$ -pinched geodesic flows). By a prime closed geodesics we mean an oriented closed geodesic which is a closed curve that traces out its image exactly once.

Theorem 2.8 (Prime Geodesic Theorem with exponential error). *Let M be a manifold better than $\frac{1}{9}$ -pinched, with strictly negative sectional curvature. Let $\pi(T)$ denote the number of prime closed geodesics on M with length at most T , then there exists $\delta > 0$ such that*

$$\pi(T) = \text{li}(e^{h_{\text{top}}(\phi_1)T}) + O(e^{(h_{\text{top}}(\phi_1) - \delta)T}) \text{ as } T \rightarrow +\infty.$$

Remark 2.9. *The above Theorems are most likely not optimal. The $\frac{1}{9}$ -pinching might conceivably be improved with some extra work (one would need to improve, or circumvent the use of, Lemma 7.9) but we do not see how to remove such conditions completely, even though we believe it to be possible.*

Let us start the discussion of the proofs. The basic objects we will study are the *dynamical determinants*, following the approach introduced by Ruelle [61], which arise naturally in the dynamical context and are formally of the general form

$$\mathfrak{D}_\ell(z) = \exp \left(- \sum_{\tau \in \mathcal{T}} \frac{\text{tr} \left(\wedge^\ell (D_{\text{hyp}} \phi_{-\lambda(\tau)}) \right) e^{-z\lambda(\tau)}}{\mu(\tau) \epsilon(\tau) |\det(\mathbf{1} - D_{\text{hyp}} \phi_{-\lambda(\tau)})|} \right), \quad (2.1)$$

where $\epsilon(\tau)$ is 1 if the flow preserves the orientation of E^s along τ and -1 otherwise. The symbol $D_{\text{hyp}} \phi_{-t}$ indicates the derivative of the map induced by two local transverse sections to the orbit (one at x , the other at $\phi_{-t}(x)$) and can be represented as a $(d-1) \times (d-1)$ dimensional matrix. By $\wedge^\ell A$ we mean the matrix associated to the standard ℓ -th exterior product of A . Note that, given any $\tau \in \mathcal{T}$, $\text{tr}(\wedge^\ell (D_{\text{hyp}} \phi_{-\lambda(\tau)}))$, $\det(\mathbf{1} - D_{\text{hyp}} \phi_{-\lambda(\tau)})$, as well as $\det(D\phi_{-\lambda(\tau)}|_{E^s})$ that will be used shortly, when computed at a point $x \in \tau$, depend only on τ (see comments before equation 5.18 for more details).

The sum in (2.1) is well defined provided $\Re(z)$ is large enough.

Note that $\epsilon(\tau) = \text{sign}(\det(D\phi_{-\lambda(\tau)}|_{E^s}))$. Hence, from the hyperbolicity conditions (1.2), we have

$$\begin{aligned} \text{sign}(\det(\mathbb{1} - D_{\text{hyp}}\phi_{-\lambda(\tau)})) &= (-1)^{d_s} \text{sign}(\det(D\phi_{-\lambda(\tau)}|_{E^s})) \\ &= (-1)^{d_s} \epsilon(\tau). \end{aligned} \quad (2.2)$$

Recall the linear algebra identity for a $n \times n$ matrix A (see, for example, [75, Section 3.9] for more details),

$$\det(\mathbb{1} - A) = \sum_{\ell=0}^n (-1)^\ell \text{tr}(\wedge^\ell A). \quad (2.3)$$

Note that

$$\begin{aligned} \zeta_{\text{Ruelle}}(z) &= \prod_{\tau \in T_p} (1 - e^{-z\lambda(\tau)})^{-1} = \exp \left(\sum_{\tau \in T_p} \sum_{m=1}^{\infty} \frac{1}{m} e^{-zm\lambda(\tau)} \right) \\ &= \exp \left(\sum_{\tau \in \mathcal{T}} \frac{1}{\mu(\tau)} e^{-z\lambda(\tau)} \right), \end{aligned} \quad (2.4)$$

where $\mu(\tau)$ is the multiplicity of the associated orbit τ and $\mathcal{T}$ is the whole set of periodic orbits on M . From the equations (2.1), (2.2), (2.3) and (2.4) it follows a product formula analogous to that of Atiyah-Bott for elliptic differential operators [4]:

$$\begin{aligned} \prod_{\ell=0}^{d-1} \mathfrak{D}_\ell(z)^{(-1)^{\ell+d_s+1}} &= \exp \left(\sum_{\ell=0}^{d-1} \sum_{\tau \in \mathcal{T}} \frac{(-1)^{\ell+d_s} \text{tr}(\wedge^\ell(D_{\text{hyp}}\phi_{-\lambda(\tau)})) e^{-z\lambda(\tau)}}{\mu(\tau)\epsilon(\tau) |\det(\mathbb{1} - D_{\text{hyp}}\phi_{-\lambda(\tau)})|} \right) \\ &= \exp \left(\sum_{\tau \in \mathcal{T}} \frac{(-1)^{d_s} \det(\mathbb{1} - D_{\text{hyp}}\phi_{-\lambda(\tau)}) e^{-z\lambda(\tau)}}{\mu(\tau)\epsilon(\tau) |\det(\mathbb{1} - D_{\text{hyp}}\phi_{-\lambda(\tau)})|} \right) \\ &= \exp \left(\sum_{\tau \in \mathcal{T}} \frac{e^{-z\lambda(\tau)}}{\mu(\tau)} \right) = \zeta_{\text{Ruelle}}(z). \end{aligned} \quad (2.5)$$

Thus Theorem 2.1 follows by the analogous statement for the dynamical determinants $\mathfrak{D}_\ell(z)$. To study the region in which the $\mathfrak{D}_\ell(z)$ are meromorphic we will proceed in the following roundabout manner. First we define the following objects.

Definition 2.10. Given $0 \leq \ell \leq d-1$, $\tau \in \mathcal{T}$ let

$$\chi_\ell(\tau) \doteq \frac{\text{tr}(\wedge^\ell(D_{\text{hyp}}\phi_{-\lambda(\tau)}))}{\epsilon(\tau) |\det(\mathbf{1} - D_{\text{hyp}}\phi_{-\lambda(\tau)})|}. \quad (2.6)$$

Moreover, for $\xi, z \in \mathbb{C}$, we let

$$\tilde{\mathfrak{D}}_\ell(\xi, z) \doteq \exp \left(- \sum_{n=1}^{\infty} \frac{\xi^n}{n!} \sum_{\tau \in \mathcal{T}} \frac{\chi_\ell(\tau)}{\mu(\tau)} \lambda(\tau)^n e^{-z\lambda(\tau)} \right). \quad (2.7)$$

Note that the series in (2.7) trivially converges for $|\xi|$ sufficiently small and $\Re(z)$ sufficiently large.

Lemma 2.11. Let $0 \leq \ell \leq d-1$, $\xi, z \in \mathbb{C}$, $\Re(z)$ sufficiently large and $|\xi - z|$ sufficiently small. Then we can write

$$\tilde{\mathfrak{D}}_\ell(\xi - z, \xi) = \frac{\mathfrak{D}_\ell(z)}{\mathfrak{D}_\ell(\xi)}. \quad (2.8)$$

Proof. The proof is by a direct calculation

$$\begin{aligned} \tilde{\mathfrak{D}}_\ell(\xi - z, \xi) &= \exp \left(- \sum_{n=1}^{\infty} \frac{(\xi - z)^n}{n!} \sum_{\tau \in \mathcal{T}} \frac{\chi_\ell(\tau)}{\mu(\tau)} \lambda(\tau)^n e^{-\xi\lambda(\tau)} \right) \\ &= \exp \left(- \sum_{\tau \in \mathcal{T}} \frac{\chi_\ell(\tau)}{\mu(\tau)} (e^{-z\lambda(\tau)} - e^{-\xi\lambda(\tau)}) \right) = \frac{\mathfrak{D}_\ell(z)}{\mathfrak{D}_\ell(\xi)}. \end{aligned}$$

□

Hence Theorem 2.1 is implied by the following.

Proposition 2.12. For any C^r Anosov flow, with $r > 2$, $\xi, z \in \mathbb{C}$, $\mathfrak{D}_\ell(\xi)$ is analytic and non zero in the region $\Re(\xi) > h_{\text{top}}(\phi_1) - \bar{\lambda}|d_s - \ell|$ and, for ξ in such a region, the function $\tilde{\mathfrak{D}}_\ell(\xi - z, \xi)$ is analytic and non zero for z in the region

$$|\xi - z| < \Re(\xi) - h_{\text{top}}(\phi_1) + |d_s - \ell|\bar{\lambda}$$

and analytic in z in the region

$$|\xi - z| < \Re(\xi) - h_{\text{top}}(\phi_1) + |d_s - \ell|\bar{\lambda} + \frac{\bar{\lambda}}{2} \left\lfloor \frac{r-1}{2} \right\rfloor.$$

We can then freely move ξ along the line $\{a + ib\}_{b \in \mathbb{R}}$ and we obtain that $\tilde{\mathfrak{D}}_\ell(\xi - z, \xi)$ is analytic for $\Re(z) > h_{\text{top}}(\phi_1) - |d_s - \ell| \bar{\lambda} - \frac{\bar{\lambda}}{2} \lfloor \frac{r-1}{2} \rfloor$.

Proof of Proposition 2.12. For all $v, \ell \in \mathbb{N}$, let $\Omega_v^\ell(M)$ be the space of ℓ -forms on M , i.e. the C^v sections of $\wedge^\ell(T^*M)$. Let $\Omega_{0,v}^\ell(M) \subset \Omega_v^\ell(M)$ be the subspace of forms null in the flow direction (see (3.5)). In section 3 we construct a family of Banach spaces $\mathcal{B}^{p,q,\ell}$, $p \in \mathbb{N}, q \in \mathbb{R}_+$, as the closure of $\Omega_{0,v}^\ell(M)$ with respect to a suitable anisotropic norm so that the spaces $\mathcal{B}^{p,q,\ell}$ are an extension of the spaces in [30].⁶ Such spaces are canonically embedded in the space of currents (see Lemma 3.10).

In Section 4 we define a family of operators indexed by positive real numbers $t \in \mathbb{R}_+$ as

$$\mathcal{L}_t^{(\ell)}(h) \doteq \phi_{-t}^* h, \quad (2.9)$$

for $h \in \Omega_{0,v}^\ell(M)$. Here we adopt the standard notation where f^* denotes the pullback and f_* indicates the push-forward.

Remark 2.13. *Note that by restricting the transfer operator $\mathcal{L}_t^{(\ell)}$ to the space $\Omega_{0,v}^\ell(M)$ we mimic the action of the standard transfer operators on sections transverse to the flow, in fact we morally project our forms on a Poincaré section.*

Remark 2.14. *In order to simplify a rather involved argument we chose to give full details only for the case in which the invariant foliations are orientable (i.e., $\epsilon(\tau) = 1$ for all τ). Notably, this includes some of the most interesting examples, such as geodesic flows on orientable manifolds with strictly negative sectional curvature (see Lemma B.1). To treat the non orientable case it is often sufficient to slightly modify the definition of the operator (2.9) by introducing an appropriate weight, see equation (B.1), and then repeating almost verbatim the following arguments. Unfortunately, as far as we can see, to treat the fully general case one has to consider more general Banach spaces than the ones used here. This changes very little in the arguments but makes the notation much more cumbersome. The reader can find the essential details in Appendix B.*

The operators (2.9) generalize the action of the transfer operator $\mathcal{L}_t$ on the spaces $\mathcal{B}^{p,q}$ of [30]. We prove in Lemma (4.5) that the operators $\mathcal{L}_t^{(\ell)}$ satisfy a Lasota-Yorke type estimate for sufficiently large times. To take care

⁶ The indexes p, q measure, respectively, the regularity in the unstable and stable direction.

of short times we restrict ourself to a new space $\tilde{\mathcal{B}}^{p,q,\ell}$ which is the closure of $\Omega_{0,s}^\ell(M)$ with respect to a slightly stronger norm $\|\cdot\|_{p,q,\ell}$ (see (4.6)), in this we follow [8]. We easily obtain Lasota-Yorke type estimate for all times in the new norm (Lemma 4.7).

On $\tilde{\mathcal{B}}^{p,q,\ell}$ the operators $\mathcal{L}_t^{(\ell)}$ form a strongly continuous semigroup with generators $X^{(\ell)}$ (see Lemma 4.7). We can then consider the resolvent $R^{(\ell)}(z) \doteq (z\mathbf{1} - X^{(\ell)})^{-1}$. The cornerstone of our analysis is that, although the operator $X^{(\ell)}$ is an unbounded closed operator on $\tilde{\mathcal{B}}^{p,q,\ell}$, we can access its spectrum thanks to the fact that its resolvent $R^{(\ell)}(z)$ is a quasi compact operator on the same space. More precisely, in Proposition 4.9 we show that for $z \in \mathbb{C}$, $\Re(z) > h_{\text{top}}(\phi_1) - |d_s - \ell|\bar{\lambda}$, the operator $R^{(\ell)}(z) \in L(\tilde{\mathcal{B}}^{p,q,\ell}, \tilde{\mathcal{B}}^{p,q,\ell})$, $p+q < r-1$, has spectral radius

$$\rho(R^{(\ell)}(z)) \leq (\Re(z) - h_{\text{top}}(\phi_1) + |d_s - \ell|\bar{\lambda})^{-1}$$

and essential spectral radius

$$\rho_{\text{ess}}(R^{(\ell)}(z)) \leq (\Re(z) - h_{\text{top}}(\phi_1) + |d_s - \ell|\bar{\lambda} + \bar{\lambda} \min\{p, q\})^{-1}.$$

We can then write the spectral decomposition $R^{(\ell)}(z) = P^{(\ell)}(z) + U^{(\ell)}(z)$ where $P^{(\ell)}(z)$ is a finite rank operator and $U^{(\ell)}(z)$ has spectral radius arbitrarily close to $\rho_{\text{ess}}(R^{(\ell)}(z))$. In section 5, we define a “flat trace” denoted by tr^b . In Lemma 5.1 we show that for $\Re(z) > h_{\text{top}}(\phi_1) - |d_s - \ell|\bar{\lambda}$ and $n \in \mathbb{N}$, we have that $\text{tr}^b(R^{(\ell)}(z)^n) < \infty$ and

$$\text{tr}^b(R^{(\ell)}(z)^n) = \frac{1}{(n-1)!} \sum_{\tau \in \mathcal{T}} \frac{\chi_\ell(\tau)}{\mu(\tau)} \lambda(\tau)^n e^{-z\lambda(\tau)}. \quad (2.10)$$

Furthermore, in Lemma 6.10, we prove that, for each $\lambda < \bar{\lambda}$ and $n \in \mathbb{N}$,

$$\begin{aligned} |\text{tr}^b(R^{(\ell)}(z)^n) - \text{tr}(P^{(\ell)}(z)^n)| &\leq C_{z,\lambda} \left(\Re(z) - h_{\text{top}}(\phi_1) + |d_s - \ell|\lambda \right. \\ &\quad \left. + \frac{\lambda}{2} \min\{p, q\} \right)^{-n}. \end{aligned} \quad (2.11)$$

where “tr” is the standard trace.

Remark 2.15. *The loss of a factor 2 in the formula (2.11) is due to an artifact of the method of proof. We live with it since it does not change substantially the result and to obtain a sharper result might entail considerably more work.*

Remark 2.16. *Given the two previous formulae one can have a useful heuristic explanation of the machinery we are using. Indeed, (2.11) shows that $\text{tr}^b(R^{(\ell)}(z))$ is essentially a real trace, then substituting formula (2.10) in (2.1) and performing obvious formal manipulations we have that $\tilde{\mathfrak{D}}_\ell(\xi, z)$ can be interpreted as the “determinant” of $(\mathbb{1} - \xi R^{(\ell)}(z))^{-1}$, while $\mathfrak{D}_\ell(z)$ can be interpreted as the (appropriately renormalized) “determinant” of $z\mathbb{1} - X^{(\ell)}$.*

Note that if $\nu \in \sigma(P^{(\ell)}(z)) \setminus \{0\}$, then $z - \nu^{-1} \in \sigma(X^{(\ell)})$.⁷ Thus, $\nu = (z - \mu)^{-1}$ where $\mu \in \sigma(X^{(\ell)})$. Let $\xi \in \mathbb{C}$ such that $a = \Re(\xi)$ is sufficiently large so that $\mathfrak{D}_\ell(\xi)$ is well defined. Let $\rho_{p,q,\ell} < a - h_{\text{top}}(\phi_1) + |d_s - \ell|\lambda + \frac{\lambda}{2} \min\{p, q\}$. Let $\lambda_{i,\ell}$ be the eigenvalues of $X^{(\ell)}$. For each $z \in B_2(\xi, \rho_{p,q,\ell})$,

$$\begin{aligned} \tilde{\mathfrak{D}}_\ell(\xi - z, \xi) &= \exp \left(- \sum_{n=1}^{\infty} \frac{(\xi - z)^n}{n} \text{tr}^b(R^{(\ell)}(\xi)^n) \right) = \\ &= \exp \left(- \sum_{n=1}^{\infty} \frac{(\xi - z)^n}{n} \left(\sum_{\lambda_i \in B_2(\xi, \rho_{p,q,\ell})} \frac{1}{(\xi - \lambda_{i,\ell})^n} + \mathcal{O}(C_{\xi,\lambda} \rho_{p,q,\ell}^{-n}) \right) \right) \\ &= \exp \left(\sum_{\lambda_i \in B_2(\xi, \rho_{p,q,\ell})} \log \left(1 - \frac{\xi - z}{\xi - \lambda_{i,\ell}} \right) + \sum_{n=1}^{\infty} \frac{(\xi - z)^n}{n} \mathcal{O}(C_{\xi,\lambda} \rho_{p,q,\ell}^{-n}) \right) \\ &= \left(\prod_{\lambda_{i,\ell} \in B_2(\xi, \rho_{p,q,\ell})} \frac{z - \lambda_{i,\ell}}{\xi - \lambda_{i,\ell}} \right) \psi(\xi, z) \end{aligned} \quad (2.12)$$

where $\psi(\xi, z)$ is analytic and non zero for $z \in B_2(\xi, \rho_{p,q,\ell})$. The results follows by optimizing the choice of p, q . $\square$

Once Theorem 2.1 is established we can use the above machinery to obtain more information on the location of the zeros.

Proof of Theorem 2.4. Equation (2.12) and Lemma 2.11 show that the poles of ζ_{Ruelle} are a subset of the eigenvalues of the $X^{(\ell)}$. Proposition 2.12 implies that $\ell = d_s$ is the only term in (2.5) that can contribute a pole in the relevant strip. Thus, it suffices to study the poles of $\mathfrak{D}_{d_s}^{-1}$. In Lemma 7.8 we prove that there exist $\gamma_0, a_0, C_1 > 0$ such that, for $0 < q < \min \left\{ \frac{\bar{\lambda}}{\lambda_+}, \frac{4\bar{\lambda}^2}{\lambda_+^2} \right\}$, $2a_0 > \Re(z) - h_{\text{top}}(\phi_1) > a_0$ and $n \geq C_1 C_{\#} \ln |\Im(z)|$,

$$\|R^{(d_s)}(z)^n\|_{1,q,d_s} \leq C_{\#} (\Re(z) - h_{\text{top}}(\phi_1))^{-n} |\Im(z)|^{-\gamma_0}.$$

⁷ As usual, we denote by σ the spectrum.

In Lemma 4.8 we have, for each $\Re(z) > h_{\text{top}}(\phi_1)$ and $n \in \mathbb{N}$,

$$\|R^{(d_s)}(z)^n\|_{1,q,d_s} \leq C_{\#}(\Re(z) - h_{\text{top}}(\phi_1))^{-n}.$$

Accordingly, the resolvent identity $R^{(d_s)}(z - a) = \sum_{n=0}^{\infty} a^n R^{(d_s)}(z)^n$ yields

$$\begin{aligned} \|R^{(d_s)}(z - a)\| &\leq \sum_{n=0}^{\infty} |a|^n (\Re(z) - h_{\text{top}}(\phi_1))^{-n} [C_{\#} |\Im(z)|^{-\gamma_0}]^{\frac{n}{C_1 C_{\#} \frac{1}{\ln |\Im(z)|}} - 1} \\ &= \frac{C_{\#} |\Im(z)|_0^{\gamma}}{1 - |a| (\Re(z) - h_{\text{top}}(\phi_1))^{-1} C_{\#}^{\frac{1}{C_1 C_{\#} \frac{1}{\ln |\Im(z)|}} e^{-\frac{\gamma_0}{C_{\#} C_1}}}. \end{aligned}$$

From the above we have the statement of Theorem for $\Im(z)$ large enough. The Theorem then follows by the spectral characterization of Proposition 4.9, since smooth contact flows on connected manifolds are mixing. $\square$

Proof of Theorem 2.8. Since there is an obvious bijection between prime closed geodesics and prime closed orbits for the geodesics flow, $\pi(T)$ is precisely the number of prime closed orbits τ for the geodesic flow whose period $\lambda(\tau)$ is at most T . The proof of the Theorem is based on the following estimate, established in Lemma 8.3. For each $z \in \mathbb{C}$, $h_{\text{top}}(\phi_1) \geq \Re(z) > h_{\text{top}}(\phi_1) - \frac{\tau_*}{2}$, $|\Im(z)| \geq 1$, we have that

$$\left| \frac{\zeta'_{\text{Ruelle}}(z)}{\zeta_{\text{Ruelle}}(z)} \right| \leq C_{\#} |z|. \quad (2.13)$$

In particular, on the line $\Re(z) = \sigma_1 := h_{\text{top}}(\phi_1) - \frac{\tau_*}{4}$, say, we have the bound (2.13). Moreover, on the line $\Re(z) = \sigma_2 := h_{\text{top}}(\phi_1) + 1$, say, we have a uniform bound

$$\left| \frac{\zeta'_{\text{Ruelle}}(z)}{\zeta_{\text{Ruelle}}(z)} \right| \leq \left| \frac{\zeta'_{\text{Ruelle}}(\sigma_2)}{\zeta_{\text{Ruelle}}(\sigma_2)} \right| < +\infty. \quad (2.14)$$

By the Phragmén-Lindelöf Theorem ([71], §5.65) the bound on the logarithmic derivative on any intermediate vertical line is an interpolation of those from (2.13) and (2.14). In particular, we have that

$$\left| \frac{\zeta'_{\text{Ruelle}}(z)}{\zeta_{\text{Ruelle}}(z)} \right| \leq C_{\#} |z|^{\gamma_1} \quad (2.15)$$

for $\Re(z) > \sigma_3 := h_{\text{top}}(\phi_1) - \frac{\tau_*}{8}$, say, where $0 < \gamma_1 := \frac{\tau_*}{2\tau_* + 4} < 1$.

Starting from (2.15) we follow a classical approach in number theory. Let

$$\begin{aligned}\psi(T) &\doteq \sum_{e^{nh_{\text{top}}(\phi_1)\lambda(\tau)} \leq T} h_{\text{top}}(\phi_1)\lambda(\tau) \\ \psi_1(T) &\doteq \int_1^T \psi(x)dx = \sum_{e^{nh_{\text{top}}(\phi_1)\lambda(\tau)} \leq T} h_{\text{top}}(\phi_1)\lambda(\tau)(T - e^{nh_{\text{top}}(\phi_1)\lambda(\tau)}) \\ \pi_0(T) &\doteq \sum_{e^{nh_{\text{top}}(\phi_1)\lambda(\tau)} \leq T} 1 \text{ and } \pi_1(T) \doteq \sum_{e^{h_{\text{top}}(\phi_1)\lambda(\tau)} \leq T} 1,\end{aligned}$$

where the finite summation in each case is over prime closed orbits $\tau \in \mathcal{T}_p$ for the associated geodesic flow, and $n \geq 1$, subject to the bound in terms of T . Next we recall the following simple complex integral: For $d_* > 1$ we have that

$$\frac{1}{2\pi i} \int_{d_*-i\infty}^{d_*+i\infty} \frac{y^{z+1}}{z(z+1)} dz = \begin{cases} 0 & \text{if } 0 < y \leq 1 \\ y-1 & \text{if } y > 1 \end{cases}. \quad (2.16)$$

If we denote $\zeta_0(z) = \zeta_{\text{Ruelle}}(h_{\text{top}}(\phi_1)z)$ then we can write

$$\psi_1(T) = \int_{d_*-i\infty}^{d_*+i\infty} \left(-\frac{\zeta'_0(z)}{\zeta_0(z)} \right) \frac{T^{z+1}}{z(z+1)} dz \quad (2.17)$$

for any $d_* > 1$ sufficiently large. This comes by a term by term application of (2.16) to

$$-\frac{\zeta'_0(z)}{\zeta_0(z)} = \sum_{n=1}^{\infty} \sum_{\tau} h_{\text{top}}(\phi_1) e^{-zn h_{\text{top}}(\phi_1)\lambda(\tau)}.$$

(N.B. The summation over the natural numbers in this identity comes from the second expression in (2.4), not non-primitive orbits which are not being included in the counting). Moving the line of integration from $\Re(z) = d_* > 1$ to $\Re(z) = c$ gives

$$\psi_1(T) = \frac{T^2}{2} + \int_{c-i\infty}^{c+i\infty} \left(-\frac{\zeta'_0(z)}{\zeta_0(z)} \right) \frac{T^{z+1}}{z(z+1)} dz \quad (2.18)$$

provided $\sigma_3/h_{\text{top}}(\phi_1) < c < 1$. In particular, we use (2.15) to guarantee convergence of the integral in (2.18). Note that the term $\frac{T^2}{2}$ comes from the line of integration crossing the pole for $\zeta_0(z)$ (now at $z = 1$). Moreover, the integral yields a factor T^{c+1} i.e. $\psi_1(T) = \frac{1}{2}T^2 + O(T^{c+1})$. Next we have the following asymptotic estimates.

Lemma 2.17. *We can estimate, provided $1 > c_1 > c > 0$, that*

$$\begin{aligned}\psi(T) &= T + O(T^{(c+1)/2}); \\ \pi_0(T) &= \text{li}(T) + O\left(\frac{T^{(c+1)/2}}{\log T}\right); \\ \pi_1(T) &= \text{li}(T) + O(T^{(c_1+1)/2}).\end{aligned}$$

Since the proof of the above Lemma is completely analogous to the case of prime numbers, we omit it and refer the reader to [23, Chapter 4, Section 4]. Finally, we can write

$$\pi(T) = \pi_1(e^{h_{\text{top}}(\phi_1)T}) = \text{li}(e^{h_{\text{top}}(\phi_1)T}) + O(e^{[h_{\text{top}}(\phi_1)(c_1+1)/2]T})$$

and the theorem follows with $h_{\text{top}}(\phi_1)(c_1 + 1)/2 = h_{\text{top}}(\phi_1) - \delta$. $\square$

3 Cones and Banach spaces

We want to introduce appropriate Banach spaces of currents⁸ over a d -dimensional smooth compact Riemannian manifold M . We present a general construction of such spaces based only on an abstract cone structure. This is very convenient since later on we will apply this construction twice: once on M to treat certain operators, and once on M^2 to treat some related, but different, operators.

The basic idea, going back to [12], is to consider “appropriate objects” that are “smooth” in the unstable direction while being “distributions” in the stable direction. This is obtained by defining norms in which such objects are integrated, against smooth functions, along manifolds close to the stable direction. Unfortunately, the realization of this program is fairly technical, since we have to define first the class of manifolds on which to integrate, then determine which are the relevant objects and, finally, explain what we mean by “appropriate”.

3.1 Charts and Notation

We start with some assumptions and notation. More precisely, for any $r \in \mathbb{N}$, we assume that there exists $\delta_0 > 0$, such that, for each $\delta \in (0, \delta_0)$ and

⁸ See Federer [26, Sections 4.1.1 - 4.1.7] for a detailed presentation of currents.

$\rho \in (0, 4)$, there exists an atlas $\{(U_\alpha, \Theta_\alpha)\}_{\alpha \in \mathcal{A}}$, where $\mathcal{A}$ is a finite set, such that⁹

$$\begin{cases} \Theta_\alpha(U_\alpha) = B_d(0, 30\delta\sqrt{1+\rho^2}) \\ \cup_\alpha \Theta_\alpha^{-1}(B_d(0, 2\delta)) = M \\ \Theta_\alpha \circ \Theta_\beta^{-1}(\tilde{x}, x_d + t) = \Theta_\alpha \circ \Theta_\beta^{-1}(\tilde{x}, x_d) + (0, t), \quad t \in \mathbb{R} \\ \|(\Theta_\alpha)_*\|_\infty + \|(\Theta_\alpha^{-1})_*\|_\infty \leq 2; \quad \|\Theta_\alpha \circ \Theta_\beta^{-1}\|_{C^r} \leq 2. \end{cases} \quad (3.1)$$

Note that the above is equivalent to the existence of a global C^r vector field V such that Θ_α are flow box charts for the flow generated by V ; i.e. for all $\alpha \in \mathcal{A}$, $(\Theta_\alpha^{-1})_*(\frac{\partial}{\partial x_d}) = V$.¹⁰

Let $\{\psi_\alpha\}_{\alpha \in \mathcal{A}}$ be a smooth partition of unity subordinate to our atlas such that $\text{supp}(\psi_\alpha) \subseteq \Theta_\alpha^{-1}(B_d(0, 2\delta)) \subset U_\alpha$ and $\psi_\alpha|_{\Theta_\alpha^{-1}(B_d(0, \delta))} = 1$. In addition, we assume $d_1 + d_2 = \dim(M)$ are given, and let

$$\mathcal{C}_\rho \doteq \{(s, u) \in \mathbb{R}^{d_1} \times \mathbb{R}^{d_2} : \|u\| \leq \rho\|s\|\}. \quad (3.2)$$

Next, we assume that there exists $4 > \rho_+ > \rho_- > 0$ such that, for all $\alpha, \beta \in \mathcal{A}$,

$$\mathcal{C}_0 \subset (\Theta_\alpha)_* \circ (\Theta_\beta^{-1})_* \mathcal{C}_{\rho_-} \subset \mathcal{C}_{\rho_+}, \quad (3.3)$$

when it is well defined. Note that, by compactness, there must exist $\rho_1 > 0$ such that $\mathcal{C}_{\rho_1} \subset (\Theta_\alpha)_* \circ (\Theta_\beta^{-1})_* \mathcal{C}_{\rho_-}$.

This concludes the hypotheses on the charts and the cones. For each $\ell \in \{0, \dots, d\}$, let $\wedge^\ell(T^*M)$ be the algebra of the exterior ℓ -forms on M . We write $\Omega_r^\ell(M)$ for the space of C^r sections of $\wedge^\ell(T^*M)$. Let $h = \sum_{\alpha \in \mathcal{A}} \psi_\alpha h \doteq \sum_{\alpha \in \mathcal{A}} h_\alpha$ so that $h_\alpha \in \Omega_r^\ell(U_\alpha)$.

Let $\{e_1, \dots, e_d\}$ be the canonical basis of $\mathbb{R}^d$. For all $\alpha \in \mathcal{A}$ and $x \in U_\alpha$ consider the basis of $T_x U_\alpha$ given by $\{(\Theta_\alpha^{-1})_* \frac{\partial}{\partial x_1}, \dots, (\Theta_\alpha^{-1})_* \frac{\partial}{\partial x_d}\}$. Let $\{\hat{e}_{\alpha,1}, \dots, \hat{e}_{\alpha,d}\}$ be the orthonormal basis of $T_x U_\alpha$ obtained from the first one by applying the Gram-Schmidt procedure, setting as first element of the algorithm $\hat{e}_{\alpha,d} = (\Theta_\alpha^{-1})_* \frac{\partial}{\partial x_d} / \left\| (\Theta_\alpha^{-1})_* \frac{\partial}{\partial x_d} \right\|$. Let $\omega_{\alpha,1}, \dots, \omega_{\alpha,d}$ be the dual basis

⁹ The relations are meant to be valid where the composition is defined. The $\|\cdot\|_{C^r}$ norm is precisely defined in (3.6). Note that the explicit numbers used (e.g. 2, 30, ...) are largely arbitrary provided they satisfy simple relations that are implicit in the following constructions.

¹⁰ Indeed, the first, second and last relation can always be satisfied (e.g. consider sufficiently small charts determined by the exponential map). Given V , the third conditions can be satisfied by applying the flow box Theorem.

of 1-forms such that $\omega_{\alpha,i}(\hat{e}_{\alpha,j}) = \delta_{i,j}$. Thus we can define a scalar product on $T_x^*U_\alpha$ by the expression $\langle \omega_{\alpha,i}, \omega_{\alpha,j} \rangle = \delta_{i,j}$. Note that the above construction “respects” the special direction V .

Let $\mathcal{I}_\ell = \{\bar{i} = (i_1, \dots, i_\ell) \in \{1, \dots, d\}^\ell : i_1 < i_2 < \dots < i_\ell\}$ be the set of ℓ -multi-indices ordered by the standard lexicographic order. Let $e_{\bar{i}} \doteq e_{i_1} \wedge \dots \wedge e_{i_\ell}$ in $\wedge^\ell(\mathbb{R}^d)$ and $dx_{\bar{i}} \doteq dx_{i_1} \wedge \dots \wedge dx_{i_\ell} \in \wedge^\ell(\mathbb{R}^d)^*$ so that $dx_{\bar{i}}(e_{\bar{j}}) = \delta_{\bar{i},\bar{j}}$. Let $\{e_{\alpha,\bar{i}}\} \subset \wedge^\ell(T_x U_\alpha)$ and $\{\omega_{\alpha,\bar{i}}\} \subset \wedge^\ell(T_x^* U_\alpha)$ be defined in the same way starting from $\ell_{\alpha,i}, \omega_{\alpha,i}$.

Given $h \in \Omega_r^\ell(U_\alpha)$ and $(\Theta_\alpha^{-1})^* h \in \Omega_r^\ell(B_d(0, 30\delta\sqrt{1+\rho^2}))$ we will write

$$h = \sum_{\bar{i} \in \mathcal{I}_\ell} h_{\alpha,\bar{i}} \omega_{\alpha,\bar{i}}.$$

As usual we define the scalar product

$$\langle h, g \rangle_{\Omega^\ell} \doteq \int_M \langle h, g \rangle_x \omega_M(x) \quad (3.4)$$

where ω_M is the Riemannian volume form on M and $\langle h, g \rangle_x$ is the usual scalar product for forms¹¹ (see (A.1) for a precise definition).

In the sequel we will often restrict ourselves to forms “transversal” to the flow, that is

$$\Omega_{0,r}^\ell(M) \doteq \{h \in \Omega_r^\ell(M) : h(V, \dots) = 0\}. \quad (3.5)$$

Remark 3.1. We use the convention $\Omega_{0,r}^0 = \Omega_r^0$. Note that $\Omega_{0,r}^d = \{0\}$ and, more generally if $h \in \Omega_{0,r}^\ell$, then $h = \sum_{\bar{i} \in \mathcal{I}_\ell} h_{\alpha,\bar{i}} \omega_{\alpha,\bar{i}}$, where $\mathcal{I}_\ell^- = \{\bar{i} = (i_1, \dots, i_\ell) \in \{1, \dots, d-1\}^\ell : i_1 < i_2 < \dots < i_\ell\}$. See Remark 3.9 for further comments.

For $f : B_d(0, \delta) \rightarrow \mathbb{R}^{\bar{d}}$, $\bar{d} \in \mathbb{N}$, we use the following C^r -norm

$$\|f\|_{C^r} = \begin{cases} \sup_x \|f(x)\| & \text{if } r = 0 \\ \|f\|_{C^0} + \sup_{x,y \in B_d(0,\delta)} \frac{\|f(x) - f(y)\|}{\|x - y\|^r} & \text{if } 0 < r < 1 \\ \sum_{i=0}^{\lfloor r \rfloor} 2^{\lfloor r \rfloor - i} \sum_{k_1, \dots, k_i} \left\| \partial_{x_{k_1}} \dots \partial_{x_{k_i}} f \right\|_{C^{r-\lfloor r \rfloor}} & \text{if } r \geq 1. \end{cases} \quad (3.6)$$

Remark 3.2. The reader can check, by induction, that for such a C^r norm, for $r \in \mathbb{R}_+$ and $\bar{d} = 1$, we have $\|fg\|_{C^r} \leq \|f\|_{C^r} \|g\|_{C^r}$ and, for all $\bar{d} \in \mathbb{N}$, $\|f \circ g\|_{C^r} \leq C_\# \sum_{i=0}^r \|f\|_{C^i} \|Dg\|_{C^{r-1}} \dots \|Dg\|_{C^{r-i}}$.

¹¹ In the following we will drop the subscript x in the scalar product and the subindex M in the volume form whenever it does not create confusion.

3.2 Banach Spaces

Given the above setting, we are going to construct several Banach spaces. The strategy is to first define appropriate norms and then close the space of ℓ -forms in the associated topology.

Fix $L_0 > 0$. For each $L > L_0$, let us define

$$\mathcal{F}_r(\rho, L) \doteq \{F : B_{d_1}(0, 6\delta) \rightarrow \mathbb{R}^{d_2} : F(0) = 0; \|DF\|_{C^0(B_{d_1}(0, 6\delta))} \leq \rho; \|F\|_{C^r(B_{d_1}(0, 6\delta))} \leq L\}. \quad (3.7)$$

For each $F \in \mathcal{F}_r(\rho, L)$, $x \in \mathbb{R}^d$, $\xi \in \mathbb{R}^{d_1}$, let $G_{x,F}(\xi) : B_{d_1}(0, 6\delta) \rightarrow \mathbb{R}^d$ be defined by $G_{x,F}(\xi) \doteq x + (\xi, F(\xi))$.

Let us also define $\tilde{\Sigma}(\rho, L) \doteq \{G_{x,F} : x \in B_{d_1}(0, 2\delta), F \in \mathcal{F}_r(\rho, L)\}$.

Remark 3.3. *All the present constructions will depend on the parameters ρ, L . We will often not make it explicit, to ease notation and since many computations hold for any choice of the parameters, but we will state when a particular choice of such parameters is made.*

For each $\alpha \in \mathcal{A}$, and $G \in \tilde{\Sigma}$ we define the leaf¹² $W_{\alpha,G} = \{\Theta_\alpha^{-1} \circ G(\xi)\}_{\xi \in B_{d_1}(0, 3\delta)}$ and the enlarged leaf $W_{\alpha,G}^+ = \{\Theta_\alpha^{-1} \circ G(\xi)\}_{\xi \in B_{d_1}(0, 6\delta)}$. For each $\alpha \in \mathcal{A}$, $G \in \tilde{\Sigma}$ note that $W_{\alpha,G} \subset \hat{U}_\alpha \doteq \Theta_\alpha^{-1}(B_d(0, 6\delta\sqrt{1+\rho^2})) \subseteq U_\alpha$. Finally, we define $\Sigma_\alpha = \cup_{G \in \tilde{\Sigma}_\alpha} \{W_{\alpha,G}\}$. We will be interested in the set of manifolds $\Sigma = \cup_{\alpha \in \mathcal{A}} \Sigma_\alpha$ (our sets of “stable” leaves).

Also, for each $G \in \tilde{\Sigma}_\alpha$ we denote by $\hat{\Gamma}_c^{\ell,s}(\alpha, G)$ the C^s sections of the fiber bundle on $W_{\alpha,G}^+$, with fibers $\wedge^\ell(T^*M)$, which vanish in a neighborhood of $\partial W_{\alpha,G}$. We define the norm

$$\|g\|_{\hat{\Gamma}_c^{\ell,s}(\alpha,G)} \doteq \sup_{\bar{i}} \|g_{\alpha,\bar{i}} \circ \Theta_\alpha^{-1} \circ G\|_{C^s(B_{d_1}(0, 2\delta))}. \quad (3.8)$$

Consistent with this choice, we equip $\Omega_r^\ell(M)$ with the norms, for $s \leq r$,

$$\|h\|_{\Omega_s^\ell} = \sup_{\alpha \in \mathcal{A}, \bar{i} \in \mathcal{I}_\ell} \|h_{\alpha,\bar{i}} \circ \Theta_\alpha^{-1}\|_{C^s(\mathbb{R}^d)}. \quad (3.9)$$

Let $\hat{\mathcal{V}}^s(\alpha, G)$ be the set of $C^s(U_{\alpha,G})$ vector fields, where $U_{\alpha,G}$ is any open set such that $U_\alpha \supset U_{\alpha,G} \supset W_{\alpha,G}^+$.

¹² These $W_{\alpha,G}$ are not to be confused with stable manifolds.

To allow enough flexibility in the previous construction (flexibility that will be essential in Section 6) we introduce the possibility of further choices: we choose sets $\Gamma_c^{\ell,s}(\alpha, G)$ that are dense in $\widehat{\Gamma}_c^{\ell,s}(\alpha, G)$ in the C^s norm for each $s < r$. Also we choose sets $\mathcal{V}^s(\alpha, G) \subseteq \widehat{\mathcal{V}}^s(\alpha, G)$ that contain the push forward of any constant vector field under the coordinate map Θ_α^{-1} and with the property that there exists $C_s > 0$ such that, for each $v, w \in \mathcal{V}^s(\alpha, G)$, $C_s \cdot [v, w] \in \mathcal{V}^{s-1}(\alpha, G)$. Finally, we ask the following extension property: there exists $C_s \in (0, 1)$ such that for each

$$v \in \mathcal{V}^s(\alpha, G) \implies \exists \bar{v} \in \mathcal{V}^s(M) : \begin{cases} \bar{v}|_{U_{\alpha,G}} = v \\ \forall \beta \in \mathcal{A}, G' \in \widetilde{\Sigma}, C_s \bar{v} \in \mathcal{V}^s(\beta, G'), \end{cases} \quad (3.10)$$

where by $\mathcal{V}^s(M)$ we mean the C^s vector fields on M .

Remark 3.4. *The norms and the Banach spaces we are going to define should have an index specifying their dependencies on the choices of $\{\Gamma_c^{\ell,s}(\alpha, G)\}$ and $\{\mathcal{V}^s(\alpha, G)\}$. We choose to suppress them to ease notation, since this creates no confusion.*

Let ω_{vol} be the d_s volume form induced on $W_{\alpha,G}$ by the push forward of Lebesgue measure via the chart Θ_α^{-1} . Write L_v for the Lie derivative along a vector field v . Finally, for all $\alpha \in \mathcal{A}$, $G \in \Sigma_\alpha$, $g \in \Gamma_c^{\ell,0}(\alpha, G)$, $\bar{v}^p = (v_1, \dots, v_p) \in \mathcal{V}^s(\alpha, G)^p$ and $h \in \Omega_r^\ell(M)$ we define

$$J_{\alpha,G,g,\bar{v}^p}(h) \doteq \int_{W_{\alpha,G}} \langle g, L_{v_1} \cdots L_{v_p} h \rangle \omega_{\text{vol}} \in \mathbb{R}. \quad (3.11)$$

Next, for all $p \in \mathbb{N}$, $q \in \mathbb{R}_+$, $p + q < r - 1$, $\ell \in \{0, \dots, d\}$, let

$$\mathbb{U}_{\rho,L,p,q,\ell} \doteq \left\{ J_{\alpha,G,g,\bar{v}^p} \mid \alpha \in \mathcal{A}, G \in \Sigma_\alpha(\rho, L), g \in \Gamma_c^{\ell,p+q}, v_j \in \mathcal{V}^{p+q}, \right. \\ \left. \|g\|_{\Gamma_c^{\ell,p+q}(\alpha,G)} \leq 1, \|v_j\|_{C^{q+p}(U_{\alpha,G})} \leq 1 \right\}, \quad (3.12)$$

where, for $v \in \mathcal{V}^s(\alpha, G)$, $\|v\|_{C^s(U_{\alpha,G})} = \sup_{\alpha,i} \|\langle v, e_{\alpha,i} \rangle \circ \Theta_\alpha^{-1}\|_{C^s}$.

Lastly, for all $\rho \in [\rho_-, \rho_+]$, $L \geq L_0$, $p \in \mathbb{N}$, $q \in \mathbb{R}_+$ and $h \in \Omega_{p+q}^\ell(M)$ we define the following norms

$$\|h\|_{\rho,L,p,q,\ell}^- \doteq \sup_{J \in \mathbb{U}_{\rho,L,p,q,\ell}} J(h) \quad \text{and} \quad \|h\|_{\rho,L,p,q,\ell} \doteq \sup_{n \leq p} \|h\|_{\rho,L,n,q,\ell}^- \quad (3.13)$$

Remark 3.5. Let L_+ be such that $W \in \Sigma_\alpha(\rho_-, L_0)$ and $W \cap \widehat{U}_\beta \neq \emptyset$ imply $W \in \Sigma_\alpha(\rho_+, L_+)$.¹³ We find it convenient to set $\|\cdot\|_{-,p,q,\ell} = \|\cdot\|_{\rho_-,L_0,p,q,\ell}$ and $\|\cdot\|_{+,p,q,\ell} = \|\cdot\|_{\rho_+,L_+,p,q,\ell}$. In the above norms and objects we will suppress systematically the indexes $\rho, L, +, -$, when it does not create confusion. In particular, any statement about a norm without $\pm$ is either meant for each $\rho \in [\rho_-, \rho_+]$, $L \in [L_0, L_+]$ or for the $-$ norm. The introduction of these annoying $\pm$ -norms has the only purpose to allow a simple use of mollifiers, which in general are not bounded operators (see Appendix D for details).

Definition 3.6. For all $p \in \mathbb{N}$, $q \in \mathbb{R}_+$, $\ell \in \{0, \dots, d-1\}$ we define the spaces $\mathcal{B}^{p,q,\ell}$ to be the closures of $\Omega_{0,r}^\ell(M)$ with respect to the norm $\|\cdot\|_{-,p,q,\ell}$ and the spaces $\mathcal{B}_+^{p,q,\ell}$ to be the closures of $\Omega_{0,r}^\ell(M)$ with respect to the norm $\|\cdot\|_{+,p,q,\ell}$.

Remark 3.7. Note that, by definition, the forms in $\mathcal{B}^{p,q,\ell}, \mathcal{B}_+^{p,q,\ell}$ are zero in the flow direction. This retains the relevant properties of Poincaré sections while working directly with the flow.

Remark 3.8. For the norms just defined the reader can easily check that

$$\begin{aligned} \|h\|_{p,q,\ell} &\leq \|h\|_{p+1,q,\ell} \quad \text{and} \quad \|h\|_{p,q+1,\ell} \leq \|h\|_{p,q,\ell} \\ C_{p,q} \|h\|_{p,q,\ell}^- &\leq \sup_{\{v_1, \dots, v_p \in \mathcal{V}^{p+q} : \|v_j\|_{C^{p+q}} \leq 1\}} \|L_{v_1} \cdots L_{v_p} h\|_{0,p+q}^- \leq \|h\|_{p,q,\ell}^- \quad (3.14) \\ \|h\|_{-,p,q,\ell} &\leq \|h\|_{+,p,q,\ell} ; \quad \|h\|_{p,q,\ell} \leq C_\# \|h\|_{\Omega_p^\ell}. \end{aligned}$$

Remark 3.9. The above spaces are the natural extensions of the spaces $\mathcal{B}^{p,q}$ in [30] to the case of ℓ -forms. There the Banach spaces $\mathcal{B}^{p,q}$ were defined as the closure of $C^\infty(M, \mathbb{R})$ with respect to the following norm¹⁴

$$\|h\|_{p,q} = \sup_{0 \leq k \leq p} \sup_{\substack{\alpha \in \mathcal{A} \\ G \in \Sigma}} \sup_{\substack{v_1, \dots, v_k \in \mathcal{V}^{p+k}(\alpha, G) \\ |v_i|_{C^r} \leq 1}} \sup_{\substack{\varphi \in C_0^q(W_{\alpha,G}, \mathbb{R}) \\ |\varphi|_{C^{k+q}} \leq 1}} \int_{W_{\alpha,G}} L_{v_1} \cdots L_{v_k}(h) \cdot \varphi \omega_{\text{vol}}.$$

In particular, we can construct an isomorphism between the Banach space $\mathcal{B}^{p,q}$ in [30] and the present Banach space $\mathcal{B}^{p,q,d-1}$. In fact, let $i_V : \Omega_r^{\ell+1}(M) \rightarrow \Omega_{0,r}^\ell(M)$ be the interior product defined by $i_V(h)(v_1, \dots, v_\ell) = h(V, v_1, \dots, v_\ell)$.

¹³ Such a L_+ exists by the third equation of (3.1).

¹⁴ In [30] the coordinate charts are chosen with slightly different properties. However for our purposes they are equivalent.

If $h \in \Omega_{0,r}^\ell(M)$, then $(-1)^\ell i_V(h \wedge dV) = h$ where dV is any one form such that $dV(V) = 1$. That is $i_V(\Omega_r^{\ell+1}(M)) = \Omega_{0,r}^\ell(M)$. Since $i_V(\Omega_{0,r}^{\ell+1}(M)) = 0$, we can define $i_{V,0} : \Omega_r^{\ell+1}(M)/\Omega_{0,r}^{\ell+1}(M) \rightarrow \Omega_{0,r}^\ell(M)$ and obtain by a standard algebraic construction that $i_{V,0}$ is a natural isomorphism. Next, we define

$$\tilde{\omega} \doteq i_V \omega, \quad (3.15)$$

where ω is the Riemannian volume, and the map $\mathbf{i} : C^r(M) \rightarrow \Omega_{0,r}^{d-1}(M)$ by $\mathbf{i}(f) \doteq f \cdot \tilde{\omega}$. Note that $\mathbf{i}$ is an isomorphism since $\Omega_{0,r}^d = \{0\}$. It is easy to check that $\mathbf{i}$ extends to an isomorphism between $\mathcal{B}^{p,q}$ and $\mathcal{B}^{p,q,d-1}$. It is even easier to construct an isomorphism between $\mathcal{B}^{p,q}$ and $\mathcal{B}^{p,q,0}$. Yet, such an isomorphism is not relevant here, indeed the reader can check that the transfer operators defined in section 4.1 correspond to the transfer operators studied in [30] only when acting on $\mathcal{B}^{p,q,d-1}$.

We now prove some properties of the spaces $\mathcal{B}^{p,q,\ell}$. To this end we will use some estimates on how fast an element of the space can be approximated by smooth forms. Such estimates are proven in Appendix D.

Given a form $h \in \Omega^\ell$, we can define a functional by

$$[j(h)](g) \doteq \langle h, g \rangle_{\Omega^\ell} \quad \text{where} \quad g \in \Omega_s^\ell(M). \quad (3.16)$$

The space of such functionals, equipped with the $*$ -weak topology of $\Omega_s^\ell(M)'$,¹⁵ gives rise to the space $\mathcal{E}_s^\ell$ of currents of regularity s .

The following extends [30, Proposition 4.1] and [30, Lemma 2.1].

Lemma 3.10. *For each $\ell \in \{0, \dots, d-1\}$, there is a canonical injection from the space $\mathcal{B}^{p,q,\ell}$ to a subspace of $\mathcal{E}_{p+q}^\ell$.*

Proof. Since we can foliate M by manifolds in Σ , given the definitions (3.16) and (3.4) we have

$$[j(h)](g) \leq C_\# \|h\|_{p,q,\ell} \|g\|_{\Omega_{p+q}^\ell(M)}. \quad (3.17)$$

Thus j can be extended to a continuous immersion of $\mathcal{B}^{p,q,\ell}$ in $\mathcal{E}_{p+q}^\ell$.

To show injectivity consider a sequence $\{h_n\} \subset \Omega_{0,p+q}^\ell$ that converges to h in $\mathcal{B}^{p,q,\ell}$ such that $j(h) = 0$. Let $W_{\alpha,G} \in \Sigma_\alpha$. In the following it is convenient to introduce the operators $\tilde{\mathbb{M}}_{\alpha,\varepsilon}$ defined as in Definition D.1 with

¹⁵ As usual, given a Banach space $\mathcal{B}$, by $\mathcal{B}'$ we mean the dual space.

$\bar{\Psi}(x, y)_{\bar{i}, \bar{j}} = \tilde{\psi}_\alpha(\Theta_\alpha^{-1}(x))\delta_{\bar{i}, \bar{j}}$, $\tilde{\psi}_\alpha(\xi) = 1$ if $\|\xi\| \leq 3\sqrt{1 + \rho_-^2}$ and $\tilde{\psi}_\alpha(\xi) = 0$ if $\|\xi\| \geq 6\sqrt{1 + \rho_-^2}$. Note that, for each $h' \in \Omega_{0,p+q}^\ell$,

$$\int_{W_{\alpha,G}} \langle g, \tilde{\mathbb{M}}_{\alpha,\varepsilon} h' \rangle \omega_{\text{vol}} = [j(h')](g_\varepsilon) \quad (3.18)$$

where

$$g_\varepsilon(x) \doteq \sum_{\bar{i}} \omega_{\alpha,i}(x) J\Theta_\alpha(x) \int_{W_{\alpha,G}} \omega_{\text{vol}}(y) \tilde{\psi}_\alpha(y) \kappa(\Theta_\alpha(x) - \Theta_\beta(y)) \langle \omega_{\alpha,i}, g \rangle_y \in \Omega_r^\ell.$$

By Lemma D.2 and Remark D.4 we have that

$$\int_{W_{\alpha,G}} \langle g, h_n \rangle \omega_{\text{vol}} = \lim_{\varepsilon \rightarrow 0} \int_{W_{\alpha,G}} \langle g, \tilde{\mathbb{M}}_{\alpha,\varepsilon} h_n \rangle \omega_{\text{vol}} = \lim_{\varepsilon \rightarrow 0} [j(h_n)](g_\varepsilon),$$

Moreover, by equation (3.18), Lemma D.2 and Remark D.4 it follows that

$$\begin{aligned} |[j(h_n)](g_\varepsilon) - [j(h_m)](g_\varepsilon)| &= \left| \int_{W_{\alpha,G}} \langle g, \tilde{\mathbb{M}}_{\alpha,\varepsilon}(h_n - h_m) \rangle \omega_{\text{vol}} \right| \\ &\leq C_\# \|g\|_{\Gamma_c^{\ell,q}(\alpha,G)} \|h_n - h_m\|_{0,q,\ell}. \end{aligned}$$

Thus, we can exchange the limits with respect to n and ε to obtain

$$\begin{aligned} \int_{W_{\alpha,G}} \langle g, h \rangle \omega_{\text{vol}} &= \lim_{n \rightarrow \infty} \int_{W_{\alpha,G}} \langle g, h_n \rangle \omega_{\text{vol}} \\ &= \lim_{\varepsilon \rightarrow 0} \lim_{n \rightarrow \infty} [j(h_n)](g_\varepsilon) = \lim_{\varepsilon \rightarrow 0} [j(h)](g_\varepsilon) = 0. \end{aligned}$$

which implies $\|h\|_{0,q,\ell} = 0$. By similar computations, using equations (D.4) and (D.7) to deal with the derivatives, we obtain $\|h\|_{p,q,\ell} = 0$. Thus j is injective and we obtain the statement of the theorem. $\square$

We conclude this section by proving a compactness result which is essential in the implementation of the usual Lasota-Yorke strategy. The proof is exactly as the proof of [30, Lemma 2.1].

Lemma 3.11. *For each $q, p > 0$, $p + q < r - 1$, the unit ball of $\mathcal{B}^{p,q,\ell}$ is relatively compact in $\mathcal{B}^{p-1,q+1,\ell}$.*

4 Transfer operators and Resolvents

Let $\phi_t : M \rightarrow M$ be a C^r Anosov flow on a smooth Riemannian d -dimensional compact manifold with $r \geq 2$. The flow induces canonically an action ϕ_t^* on ℓ -forms. Such an action has nice spectral properties only when acting on Banach spaces of the type described in section 3. To apply Section 3 to the present context it suffices to specify all the choices involved in the definition of the norms $\|\cdot\|_{p,q,\ell}$.

First of all, the “special” direction is obviously given by the vector field V generating the flow. In addition, we note the following.

Remark 4.1. *Without loss of generality, we can assume*

$$\begin{cases} D_0 \Theta_\alpha^{-1} \{(0, u, 0) : u \in \mathbb{R}^{d_u}\} = E^u(\Theta_\alpha^{-1}(0)) \\ D_0 \Theta_\alpha^{-1} \{(s, 0, 0) : s \in \mathbb{R}^{d_s}\} = E^s(\Theta_\alpha^{-1}(0)) \\ \Theta_\alpha^{-1}((s, u, t)) = \phi_t \Theta_\alpha^{-1}((s, u, 0)). \end{cases} \quad (4.1)$$

Let $d_1 = d_s$ and $d_2 = d_u + 1$. Given the continuity of the stable and unstable distribution we can choose δ so that equations (3.2) and (3.3) are satisfied with $\rho_- = 1, \rho_+ = 2$ and, for all $\alpha \in \mathcal{A}$ and $x \in U_\alpha$, $(\Theta_\alpha)_* E^s(x) \subset \mathcal{C}_{\frac{1}{2}}$. Choose L_0 large enough so that all the stable manifolds belong locally to $\Sigma(1, L_0/2)$. Note that there exists $t_0 > 0$ such that, for all $t \geq t_0$,¹⁶

$$(\Theta_\beta \circ \phi_{-t} \circ \Theta_\alpha^{-1})_*(\mathcal{C}_2) \subset \mathcal{C}_1. \quad (4.2)$$

In addition, for each $v \in (\Theta_\alpha^{-1})_* \mathcal{C}_2$, $t \in \mathbb{R}_+$ we have $\|(\phi_{-t})_*(v)\| > C_\# e^{\bar{\lambda}t} \|v\|$. Finally, we set $\mathcal{V}^s = \widehat{\mathcal{V}}^s$ and $\Gamma_c^{\ell,q} = \widehat{\Gamma}_c^{\ell,q}$.

Lemma 4.2. *With the above choices condition (3.10) is satisfied.*

Proof. To prove the Lemma it suffices to have a uniform estimate on the norm of an extension of a vector field. This is in general a hard problem, but here we can exploit the peculiarities of our situation that allows to give a simple proof based on the well known reflection method that goes back, at least, to [41, 35, 65].

First, notice that, given $W_{\alpha,G}$, we can make a uniformly bounded C^r change of coordinates Ξ such that $\Xi \circ \Theta_\alpha(W_{\alpha,G}^+) = B(0, 6\delta) \times \{0\}$. Given

¹⁶ Indeed, if $x \in U_\alpha$, $v \in \mathbb{R}^d$ and $v = v^u + v^s$, $v^u \in (\Theta_\alpha)_*(E^u(x) \times E^c(x))$, $v^s \in (\Theta_\alpha)_*(E^s(x))$, then $\|(\phi_{-t} \circ \Theta_\alpha^{-1})_*(v^u)\| \leq C_0$ while $\|(\phi_{-t} \circ \Theta_\alpha^{-1})_*(v^s)\| \geq C_0 e^{\lambda t}$ and the result follows by the fourth line of (3.1).

any vector field $v \in \widehat{\mathcal{V}}^s(\alpha, G)$ the domain $\Xi \circ \Theta_\alpha(U_{\alpha, G})$ will always contain a “cylinder” of the type $Y_{\bar{a}} = B(0, 6\delta) \times (\times_{i=1}^{d_2} [-a_i, a_i])$, for some $\bar{a} \in [0, \delta]^{d_2}$, while v will be mapped into the extension of a function $f \in C^s(Y_a, \mathbb{R}^d)$ with $C_\# \|v\|_{C^s(U_{\alpha, G})} \leq \|f\|_{C^s(Y_a)} \leq C_\# \|v\|_{C^s(U_{\alpha, G})}$. Clearly it suffices that we extend f to a fixed, sufficiently large, domain so that, after multiplying it by a function equal one on $Y_{(2\delta, \dots, 2\delta)}$ and supported in the image, under Ξ , of the domain of the chart, we obtain the wanted vector field by the push forward $(\Theta_\alpha^{-1} \circ \Xi^{-1})_*$ and setting it to zero on the rest of M .

Let $I_{\bar{a}, \beta, i, \pm}(x) = (x_1, \dots, x_{i-1}, -\beta(x_i \mp a_i) \pm a_i, x_{i+1}, \dots, x_d)$. Then, given $g \in C^s(Y_{\bar{a}})$, we can define, for $i > d_1$,

$$g^i(x) = \begin{cases} g(x) & \text{for } x \in Y_{\bar{a}} \\ \sum_{k=0}^{\lfloor s \rfloor} b_k f \circ I_{\bar{a}, 2^k, i, +}(x) & \text{for } x \in Y_{\bar{a}^i}, x_i > 0 \\ \sum_{k=0}^{\lfloor s \rfloor} b_k f \circ I_{\bar{a}, 2^k, i, -}(x) & \text{for } x \in Y_{\bar{a}^i}, x_i < 0 \end{cases}$$

where $a_k^i = a_k$ for $k \neq i$ and $a_i^i = [1 + 2^{1-p-\lfloor q \rfloor}]a_i$ and $\sum_{k=0}^{\lfloor s \rfloor} b_k 2^{kn} = 1$ for all $n \in \{0, \dots, \lfloor s \rfloor\}$. Note that the previous condition determines the b_k uniquely since the Vandermonde determinant $\det(2^{ij})$ is well known to be non zero. It is easy to check that $g^i \in C^s(Y_{\bar{a}^i})$ and $\|g^i\|_{C^s(Y_{\bar{a}^i})} \leq C_s \|g\|_{C^s(Y_{\bar{a}})}$. Proceeding in such a way we can extend g to the domain $Y_{(A, \dots, A)}$ for any fixed $A > 0$. We are left with the boundary of the domain determined by $B(0, 6\delta)$, which is smooth. By localizing via a partition of unity and a smooth change of coordinates we can reduce ourselves to the case of extending a function from the half space to the all space, which can be handled as above [65]. This concludes the proof. $\square$

Remark 4.3. By standard hyperbolicity estimates t_0 in (4.2) can be chosen so that, for all $t \geq t_0$, the image of a manifold in Σ can be covered by a collections of manifolds in Σ with a uniformly bounded number of overlaps. The fact that this may be false for small times is a little extra problem present in the study of flows with respect to maps. We will handle such a problem by a further modification of the Banach space, see (4.6).

This concludes the definition of the Banach spaces. Next we define the action of the flow.

4.1 Properties of the transfer operator

Let $h \in \Omega_{0,r-1}^\ell(M)$, then $\forall t \in \mathbb{R}$

$$\phi_t^* h(V, v_2, \dots, v_\ell) = h(V, (\phi_t)_* v_2, \dots, (\phi_t)_* v_\ell) = 0. \quad (4.3)$$

Thus $\phi_t^*(\Omega_{0,r-1}^\ell) = \Omega_{0,r-1}^\ell$ for all $t \in \mathbb{R}$. In (2.9) we defined the operators $\mathcal{L}_t^{(\ell)} : \Omega_{0,r-1}^\ell(M) \rightarrow \Omega_{0,r-1}^\ell(M)$, $t \in \mathbb{R}_+$, by

$$\mathcal{L}_t^{(\ell)} h \doteq \phi_{-t}^* h.$$

Following the Remark 3.9, in the special case of a $d-1$ form, for $h \in \Omega_{0,r-1}^{d-1}(U_\alpha)$ we have $h = \bar{h}\tilde{\omega}$ where $\bar{h} \in C^s(M, \mathbb{R})$ and $\tilde{\omega}$ is defined in (3.15). Then¹⁷

$$\mathcal{L}_t^{(d-1)} h = \bar{h} \circ \phi_{-t} \det(D\phi_{-t}) \tilde{\omega} \doteq (\mathcal{L}_t \bar{h}) \tilde{\omega}. \quad (4.4)$$

Thus we recover the transfer operator acting on densities studied in [16].

We begin with a Lasota-Yorke type inequality for $\mathcal{L}_t^{(\ell)}$.

Definition 4.4. Let $p \in \mathbb{N}$, $q \in \mathbb{R}_+$, $0 \leq \ell \leq d-1$ and $0 < \lambda < \bar{\lambda}$ where $\bar{\lambda}$ is as in the Anosov splitting. Let us define

$$\begin{aligned} \sigma_\ell &\doteq h_{\text{top}}(\phi_1) - \lambda|d_s - \ell| \\ \sigma_{p,q} &\doteq \min\{p, q\} \lambda. \end{aligned}$$

Lemma 4.5. There exists $t_0 > 0$ such that, for each $p \in \mathbb{N}$, $q \in \mathbb{R}_+$, $p+q < r-1$, $\ell \in \{0, \dots, d-1\}$, $\lambda \in (0, \bar{\lambda})$ and $t > t_0$ the linear operators $\mathcal{L}_t^{(\ell)}$ can be uniquely extended to a bounded operator¹⁸ $\mathcal{L}_t^{(\ell)} \in L(\mathcal{B}_-^{p,q,\ell}, \mathcal{B}_+^{p,q,\ell})$. More precisely,

$$\left\| \mathcal{L}_t^{(\ell)} h \right\|_{+,0,q,\ell} \leq C_q e^{\sigma_\ell t} \|h\|_{-,0,q,\ell}.$$

In addition, if $0 < q \leq r-2$,

$$\left\| \mathcal{L}_t^{(\ell)} h \right\|_{+,0,q,\ell} \leq C_{q,\lambda} e^{(\sigma_\ell - \lambda q)t} \|h\|_{-,0,q,\ell} + C_{q,\lambda} e^{\sigma_\ell t} \|h\|_{-,0,q+1,\ell}$$

and, if $p, q > 0$,

$$\begin{aligned} \left\| \mathcal{L}_t^{(\ell)} h \right\|_{+,p,q,\ell} &\leq C_{p,q,\lambda} e^{(\sigma_\ell - \sigma_{p,q})t} \|h\|_{-,p,q,\ell} + C_{p,q,\lambda} e^{\sigma_\ell t} \|h\|_{-,p-1,q+1,\ell} \\ &\quad + C_{p,q,\lambda} e^{\sigma_\ell t} \|X^{(\ell)} h\|_{-,p-1,q+1,\ell}. \end{aligned}$$

¹⁷ Indeed, for $\omega \in \Omega_s^d(M)$ we have $\det(D\phi_t)\omega = \phi_t^* \omega$. Hence by (3.15) we have $\phi_t^* \tilde{\omega}(v_1, \dots, v_{d-1}) = \det(D\phi_t) \tilde{\omega}(v_1, \dots, v_{d-1})$. That is $\phi_t^* \tilde{\omega} = \det(D\phi_t) \tilde{\omega}$.

¹⁸ Which, by a harmless abuse of notation, we still designate by $\mathcal{L}_t^{(\ell)}$.

The proof of this lemma is the content of Subsection 4.3. In particular, note that from the first and last equations of the above Lemma and equation (3.14) we have,

$$\left\| \mathcal{L}_t^{(\ell)} h \right\|_{p,q,\ell} \leq C_{p,q} e^{\sigma_\ell t} \|h\|_{p,q,\ell}. \quad (4.5)$$

Remark 4.6. *Up to now we have extended, yet followed closely, the arguments in [16]. Unfortunately, in Section 7 of [16], the authors did not take into consideration that for $t \leq t_0$, $\phi_t(W_{\alpha,G})$ is not necessarily controlled by the cones defined by (3.2), and thus could be an inadmissible manifold. Such an issue can be easily fixed, in the present context, by introducing a dynamical norm (similarly to [8]) as done below. This however is not suitable for studying perturbation theory, to this end a more radical change of the Banach space is required [17].*

To take care of the $t \leq t_0$, we introduce the dynamical norm $\| \cdot \|_{p,q,\ell}$. For each $h \in \Omega_r^\ell(M)$, we set

$$\|h\|_{p,q,\ell} \doteq \sup_{s \leq t_0} \left\| \mathcal{L}_s^{(\ell)} h \right\|_{p,q,\ell}. \quad (4.6)$$

Thus we can define $\tilde{\mathcal{B}}^{p,q,\ell} \doteq \overline{\Omega_{0,r}^\ell}^{\|\cdot\|_{p,q,\ell}} \subset \mathcal{B}^{p,q,\ell}$.

Lemma 4.7. *For each $p \in \mathbb{N}$, $q \in \mathbb{R}_+$, $p+q < r-1$, $\ell \in \{0, \dots, d-1\}$, $\lambda < \bar{\lambda}$, for each $t \in \mathbb{R}_+$, we have that $\mathcal{L}_t^{(\ell)} \in L(\tilde{\mathcal{B}}^{p,q,\ell}, \tilde{\mathcal{B}}^{p,q,\ell})$ and, more precisely,*

$$\left\| \mathcal{L}_t^{(\ell)} h \right\|_{p,q,\ell} \leq C_{p,q} e^{\sigma_\ell t} \|h\|_{p,q,\ell}.$$

Moreover, if $p, q > 0$,

$$\begin{aligned} \left\| \mathcal{L}_t^{(\ell)} h \right\|_{p,q,\ell} &\leq C_{p,q,\lambda} e^{(\sigma_\ell - \sigma_{p,q})t} \|h\|_{p,q,\ell} + C_{p,q,\lambda} e^{\sigma_\ell t} \|h\|_{p-1,q+1,\ell} \\ &\quad + C_{p,q} e^{\sigma_\ell t} \|X^{(\ell)} h\|_{p-1,q+1,\ell}. \end{aligned}$$

In addition, $\{\mathcal{L}_t\}_{t \in \mathbb{R}_+}$ forms a strongly continuous semigroup.

Proof. For $h \in \Omega_{0,r}^\ell$ equations (4.5), (4.6) imply, for $t < t_0$,

$$\left\| \mathcal{L}_t^{(\ell)} h \right\|_{p,q,\ell} \leq \max \left\{ \|h\|_{p,q,\ell}, C_{p,q} e^{|\sigma_\ell|t_0} \|h\|_{p,q,\ell} \right\} \leq C_{p,q} \|h\|_{p,q,\ell},$$

while for $t \geq t_0$ the required inequality holds trivially. The boundedness of $\mathcal{L}_t^{(\ell)}$ follows.

The second inequality follows directly from the above, for small times, and from Lemma 4.5 for larger times.

To conclude, note that $\mathcal{L}_t^{(\ell)}$ is strongly continuous on $\Omega_r^\ell(M)$ in the C^r topology. Let $\{h_n\} \subset \Omega_{0,p}^\ell$ such that $\lim_{n \rightarrow \infty} \|h_n - h\|_{p,q,\ell} = 0$, then, by the boundedness of $\mathcal{L}_t^{(\ell)}$,

$$\left\| \mathcal{L}_t^{(\ell)} h - h \right\|_{p,q,\ell} \leq C_\# \|h - h_n\|_{p,q,\ell} + \|\mathcal{L}_t^{(\ell)} h_n - h_n\|_{\Omega_p^\ell}$$

which can be made arbitrarily small by choosing n large and t small. $\square$

4.2 Properties of the Resolvent

By standard results, see for example [19], the semigroups $\mathcal{L}_t^{(\ell)}$ have generators $X^{(\ell)}$ which are closed operators on $\tilde{\mathcal{B}}^{p,q,\ell}$ such that $X^{(\ell)} \mathcal{L}_t^{(\ell)} = \frac{d}{dt} \mathcal{L}_t^{(\ell)}$. Setting $R^{(\ell)}(z) = (z\mathbb{1} - X^{(\ell)})^{-1}$ we have, for $\Re(z) > \sigma_\ell$, the following identity

$$R^{(\ell)}(z)^n = \frac{1}{(n-1)!} \int_0^\infty t^{n-1} e^{-zt} \mathcal{L}_t^{(\ell)} dt, \quad (4.7)$$

that can be easily verified by computing $X^{(\ell)} R^{(\ell)}(z)^n$ and $R^{(\ell)}(z)^n X^{(\ell)}$. The next Lemma, whose proof can be found at the end of Section 4.3, gives an effective Lasota-Yorke inequality for the resolvent.

Lemma 4.8. *Let $p \in \mathbb{N}$, $q \in \mathbb{R}_+$, $p+q < r-1$, $z \in \mathbb{C}$ such that $a = \Re(z) > \sigma_\ell$ then we have*

$$\|R^{(\ell)}(z)^n\|_{p,q,\ell} \leq C_{p,q,\lambda} (a - \sigma_\ell)^{-n},$$

and, for $p, q > 0$,

$$\|R^{(\ell)}(z)^n h\|_{p,q,\ell} \leq C_{p,q,a,\lambda} \left\{ (a - \sigma_\ell + \sigma_{p,q})^{-n} \|h\|_{p,q,\ell} + \frac{(|z| + 1)}{(a - \sigma_\ell)^n} \|h\|_{p-1,q+1,\ell} \right\}.$$

The operator $R^{(\ell)}(z)$ has essential spectral radius bounded by $(a - \sigma_\ell + \sigma_{p,q})^{-1}$.

We are now in the position to obtain the required spectral properties.

Proposition 4.9. *For $p + q \leq r - 1$ the spectrum of the generator $X^{(\ell)}$ of the semigroup $\mathcal{L}_t^{(\ell)}$ acting on $\tilde{\mathcal{B}}^{p,q,\ell}$ lies on the left of the line $\{\sigma_\ell + ib\}_{b \in \mathbb{R}}$ and in the strip $\sigma_\ell \geq \Re(z) > \sigma_\ell - \sigma_{p,q}$ consists of isolated eigenvalues of finite multiplicity. Moreover, for $\ell = d_s$, $h_{\text{top}}(\phi_1)$ is an eigenvalue of X . If the flow is topologically transitive $h_{\text{top}}(\phi_1)$ is a simple eigenvalue. If the flow is topologically mixing, then $h_{\text{top}}(\phi_1)$ is the only eigenvalue on the line $\{h_{\text{top}}(\phi_1) + ib\}_{b \in \mathbb{R}}$.*

Proof. The first part of the Lemma is proven exactly as in [43, Proposition 2.10, Corollary 2.11]. Next, let us analyze the case $\ell = d_s$. As explained in Remark 2.14, we restrict ourselves to the case in which E^s is orientable. Indeed, in the non orientable case we must study a slightly different operator (see Section B for more details). We can then choose in each $E^s(x)$ a volume form $\tilde{\omega}_s$ on E^s normalized so that $\|\tilde{\omega}_s\| = 1$ and it is globally continuous. Also let $\pi_s(x) : T_x M \rightarrow E^s(x)$ be the projections on $E^s(x)$ along $E^u(x) \oplus E^c(x)$. Remember that π_s is ϖ -Hölder (see Appendix E). Next, define $\omega_s(v_1, \dots, v_{d_s}) \doteq \tilde{\omega}_s(\pi_s v_1, \dots, \pi_s v_{d_s})$, by construction $\omega_s \in \Omega_{0,\varpi}^{d_s}$. Note that $\phi_{-t}^* \omega_s = J_s \phi_{-t} \omega_s$, where $J_s \phi_{-t}$ is the Jacobian restricted to the stable manifold. Note that, setting $\omega_{s,\varepsilon} = \mathbb{M}_\varepsilon \omega_s$, for ε small enough, we have $\langle \omega_{s,\varepsilon}, \omega_s \rangle \geq \frac{1}{2}$. Hence,

$$\int_{W_{\alpha,G}} \langle \omega_{s,\varepsilon}, \mathcal{L}_t \omega_s \rangle \geq \int_{W_{\alpha,G}} \frac{J_s \phi_{-t}}{2} \geq C_\# \int_{W_{\alpha,G}} J_W \phi_{-t} \geq C_\# \text{vol}(\phi_{-t} W_{\alpha,G}). \quad (4.8)$$

Taking the sup on the manifolds and integrating in time, Appendix C (see in particular Remark C.4) implies that the spectral radius of $R^{(d_s)}(a)$ on $\tilde{\mathcal{B}}^{q,\varpi,d_s}$ is exactly $(a - \sigma_{d_s})^{-1}$.

By Lemma 4.8 $R^{(d_s)}(a)$ is quasicompact on $\tilde{\mathcal{B}}^{p,q,d_s}$ and its peripheral spectrum does not contain Jordan blocks.¹⁹ In turn, this implies that

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=0}^{n-1} (a - \sigma_{d_s})^k R^{(d_s)}(a)^k = \begin{cases} \Pi & \text{if } (a - \sigma_{d_s})^{-1} \in \sigma_{\tilde{\mathcal{B}}^{p,q,d_s}}(R^{(d_s)}(a)) \\ 0 & \text{otherwise,} \end{cases}$$

where Π is the eigenprojector on the associated eigenspace and the convergence takes place in the strong operator topology of $L(\tilde{\mathcal{B}}^{p,q,d_s}, \tilde{\mathcal{B}}^{p,q,d_s})$. Also

¹⁹ A Jordan block would imply that $\|R^{(d_s)}(a)^n\|_{p,q,d_s}$ grows at least as $C_\# n(a - \sigma_{d_s})^{-n}$ contrary to the first inequality in Lemma 4.8.

by the second inequality in the statement of Lemma 4.8 it follows that Π extends naturally to an operator in $L(\tilde{\mathcal{B}}^{p-1,q+1,d_s}, \tilde{\mathcal{B}}^{p,q,d_s})$. Since, by (4.8),

$$\int_{W_{\alpha,G}} \langle \omega_{s,\varepsilon}, \Pi \omega_s \rangle > 0$$

we have that $\Pi \neq 0$ and $(a - \sigma_{d_s})^{-1}$ belongs to the spectrum. The other claimed properties follow by arguing as in [31, Section 6.2]. $\square$

4.3 Proof of the Lasota-Yorke inequality

Proof of Lemma 4.5. For each $\mathbf{a} \in (0, 1)$, we introduce the norms

$$\|h\|_{\rho,L,p,q,\ell,\mathbf{a}} \doteq \sum_{\wp=0}^p \mathbf{a}^{\wp} \|h\|_{\rho,L,\wp,q,\ell}^-$$

From now on we will suppress the indexes ρ, L as their values will be clear from the context. As the above norms are equivalent to $\|\cdot\|_{p,q,\ell}$, it suffices to prove the required inequality for some fixed $\mathbf{a}$ (to be chosen later).

For any $\wp, q \in \mathbb{N}$, $\alpha \in \mathcal{A}$, $G \in \tilde{\Sigma}(\rho_+, L_+)$, $v_i \in \mathcal{V}^{\wp+q}(\alpha, G)$, $g \in \Gamma_c^{\ell,\wp+q}(\alpha, G)$ such that $\|g\|_{\Gamma_c^{\ell,\wp+q}(\alpha, G)} \leq 1$, we must estimate

$$\int_{W_{\alpha,G}} \langle g, L_{v_1} \cdots L_{v_{\wp}} \mathcal{L}_t^{(\ell)} h \rangle \omega_{\text{vol}}. \quad (4.9)$$

First of all, we consider the atlas introduced at the beginning of Section 3. For $\beta \in \mathcal{A}$ and for each $t \in \mathbb{R}_+$, let $\{V_{k,\beta}\}_{k \in K_\beta}$, $K_\beta \subset \mathbb{N}$, be the collection of connected components of $\Theta_\beta(\phi_{-t}(W_{\alpha,G}) \cap U_\beta)$. Let $\tilde{K}_\beta \doteq \{k \in K_\beta : V_{k,\beta} \cap B(0, 2\delta) \neq \emptyset\}$. For all $V_{k,\beta}$, let $\tilde{V}_{k,\beta}$ be the connected component of $\Theta_\beta(\phi_{-t}(W_{\alpha,G}^+ \cap U_\beta)$ which contains $V_{k,\beta}$. Next, for each $k \in \tilde{K}_\beta$ choose $x_{k,\beta} \in (V_{k,\beta} \cap B(0, 2\delta))$. We choose t_0 as in Remark 4.3. Then, for all $t \geq t_0$, there exists $F_{k,\beta} \in \mathcal{F}_r(1, L_0)$ (see definition (3.7)) such that $G_{x_{k,\beta}, F_{k,\beta}}(\xi) = x_{k,\beta} + (\xi, F_{k,\beta}(\xi))$, $\xi \in B(0, 6\delta)$, and the graph of $G_{x_{k,\beta}, F_{k,\beta}}$ is contained in $\tilde{V}_{k,\beta}$. Next we consider the manifolds

$$\{W_{\beta, G_{x_{k,\beta}, F_{k,\beta}}}\}_{k \in \tilde{K}_\beta} \subset U_\beta. \quad (4.10)$$

From now on let us write W_{β, G_k} for $W_{\beta, G_{x_{k,\beta}, F_{k,\beta}}}$. By the above construction $W_{\beta, G_k} \in \Sigma_-$. Note that the above construction provides an explicit analogue

of Lemma 7.2 in [16]. In particular, $\cup_{\beta \in \mathcal{A}} \cup_{k \in \tilde{K}_\beta} W_{\beta, G_k} \supset \phi_{-t} W_{\alpha, G}$ with a uniformly bounded number of overlaps.

In the following it will be convenient to use the *Hodge operator* “ $*$ ”, see Appendix A for details. Let us start with the case $\wp = 0$. By using formula (A.4), changing variables we obtain²⁰

$$\int_{W_{\alpha, G}} \langle g, \mathcal{L}_t^{(\ell)} h \rangle \omega_{\text{vol}} = \sum_{\substack{\beta \in \mathcal{A} \\ k \in \tilde{K}_\beta}} \int_{W_{\beta, G_k}} (-1)^{(d-\ell)\ell} \psi_\beta \frac{J_W \phi_t}{J \phi_t} \langle * \phi_t^* (*g), h \rangle \omega_{\text{vol}}, \quad (4.11)$$

where $J_W \phi_t$ is the Jacobian of the change of variable $\phi_t : W_{\beta, G_k} \mapsto W_{\alpha, G}$. Note that

$$\begin{aligned} * \phi_t^* (*g) &= \sum_{\bar{i}, \bar{j} \in \mathcal{I}_\ell} \langle \omega_{\beta, \bar{i}}, * \phi_t^* \omega_{\alpha, \bar{j}} \rangle g_{\bar{j}} \circ \phi_t \cdot \omega_{\beta, \bar{i}} \\ &= (-1)^{(d-\ell)\ell} J \phi_t \sum_{\bar{i}, \bar{j} \in \mathcal{I}_\ell} \langle \phi_{-t}^* \omega_{\beta, \bar{i}}, \omega_{\alpha, \bar{j}} \rangle \circ \phi_t \cdot g_{\bar{j}} \circ \phi_t \cdot \omega_{\beta, \bar{i}}, \end{aligned}$$

where we have used (A.4) again. Letting

$$\tilde{g}_t = (-1)^{(d-\ell)\ell} J \phi_t \sum_{\bar{i} \in \mathcal{I}_\ell^-} \sum_{\bar{j} \in \mathcal{I}_\ell} \langle \phi_{-t}^* \omega_{\beta, \bar{i}}, \omega_{\alpha, \bar{j}} \rangle \circ \phi_t \cdot g_{\bar{j}} \circ \phi_t \cdot \omega_{\beta, \bar{i}},$$

by Remark 3.1 it follows that $\langle * \phi_t^* (*g), h \rangle = \langle \tilde{g}_t, h \rangle$. Accordingly, we have

$$\begin{aligned} \|[J \phi_t^{-1} J_W \phi_t \cdot \psi_\beta \cdot \tilde{g}_t] \circ \Theta_\beta^{-1} \circ G_k\|_{C^q} &\leq C_\# \sup_{\bar{j}, \bar{i}} \|g_{\bar{j}} \circ \phi_t \circ \Theta_\beta^{-1} \circ G_k\|_{C^q} \\ &\times \|[J_W \phi_t \cdot \langle \phi_{-t}^* \omega_{\beta, \bar{i}}, \omega_{\alpha, \bar{j}} \rangle \circ \phi_t] \circ \Theta_\beta^{-1} \circ G_k\|_{C^q}. \end{aligned} \quad (4.12)$$

Next, we estimate the factors of the above product. Note that there exist maps $\Xi_t \in C^r(\mathbb{R}^d, \mathbb{R}^d)$ such that

$$\Theta_\alpha \circ \phi_t \circ \Theta_\beta^{-1} \circ G_k = G \circ \Xi_t. \quad (4.13)$$

Moreover, by the contraction properties of the Anosov flow, $\|D\Xi_t\|_{C^{r-1}} \leq C_\# e^{-\bar{\lambda}t}$.²¹ Thus, by the properties of r -norms (see Remark 3.2),

$$\|g_{\bar{j}} \circ \phi_t \circ \Theta_\beta^{-1} \circ G_k\|_{C^q} \leq C_\# \|g \circ \Theta_\alpha^{-1} \circ G\|_{C^q}. \quad (4.14)$$

²⁰ Since $\langle g, h \rangle$ can be seen as a function on M , we will often use the notation $F^* \langle g, h \rangle$ for $\langle g, h \rangle \circ F$. Also, will use interchangeably the notations $\det(D\phi_t)$ and $J\phi_t$, since, for all $t \in \mathbb{R}$, $\det(D\phi_t) > 0$.

²¹ See the Appendix in [16] for details.

Next, note that $|\langle \phi_{-t}^* \omega_{\beta, \bar{i}}, \omega_{\alpha, \bar{j}} \rangle|$ is bounded by the growth of ℓ -volumes while $J_W \phi_t$ gives the contraction of d_s volumes in the stable direction. Clearly, the latter is simply the inverse of the maximal growth of $|\langle \phi_{-t}^* \omega_{\beta, \bar{i}}, \omega_{\alpha, \bar{j}} \rangle|$ which takes place for d_s forms. By the Anosov property and Remark 3.1 follow that

$$\|J_W \phi_t \circ \Theta_\beta^{-1} \circ G_k \cdot \langle \phi_{-t}^* \omega_{\beta, \bar{i}}, \omega_{\alpha, \bar{j}} \rangle \circ \phi_t \circ \Theta_\beta^{-1} \circ G_k\|_{C^0} \leq C_\# e^{-|d_s - \ell| \bar{\lambda} t}. \quad (4.15)$$

To compute the C^q norm, for $q \geq 1$, we begin by computing the Lie derivative with respect to the vector fields $Z_i = \partial_{\xi_i}$, $i \in \{1, \dots, d_s\}$. Let us set $\Upsilon_t \doteq \phi_t \circ \Theta_\beta^{-1} \circ G_k$. By (A.5) and (A.6) we have

$$\begin{aligned} L_{Z_i}[\langle \phi_{-t}^* v, w \rangle \circ \Upsilon_t] &= \Upsilon_t^* L_{\Upsilon_{t*} Z_i} \langle \phi_{-t}^* v, w \rangle \\ &= -\Upsilon_t^* [\text{div}(\Upsilon_{t*} Z_i) \langle \phi_{-t}^* v, w \rangle] + (-1)^{\ell(d-\ell)} \Upsilon_t^* \langle *L_{\Upsilon_{t*} Z_i} * w, \phi_{-t}^* v \rangle \\ &\quad + \Upsilon_t^* \langle w, L_{(\Theta_\beta^{-1} \circ G_k)_* Z_i} v \rangle. \end{aligned} \quad (4.16)$$

Hence, recalling again (3.6) and its properties, for $q \in \mathbb{N}$,

$$\begin{aligned} \|\langle \phi_{-t}^* v, w \rangle \circ \Upsilon_t\|_{C^q} &\leq C_\# \sup_i \|L_{Z_i}[\langle \phi_{-t}^* v, w \rangle \circ \Upsilon_t]\|_{C^{q-1}} \\ &\quad + 2^{[q]+1} \|\langle \phi_{-t}^* v, w \rangle \circ \Upsilon_t\|_{C^0} \\ &\leq C_q \{ \|\text{div}(\Upsilon_{t*} Z_i) \langle \phi_{-t}^* v, w \rangle\|_{C^{q-1}} + \| \langle L_{(\Theta_\beta^{-1} \circ G_k)_* Z_i} v, w \rangle \|_{C^{q-1}} \\ &\quad + \|\langle \phi_{-t}^* v, *L_{\Upsilon_{t*} Z_i} * w \rangle\|_{C^{q-1}} + \|\langle \phi_{-t}^* v, w \rangle\|_{C^0} \}, \end{aligned}$$

which can be used inductively to show that the C^q norm is bounded by the C^0 norm. The case $q \in (0, 1)$ can be computed directly as well, but is also follow by interpolation theory (e.g., see [72, (2),(4) page 201]). The computation for the case $q \in \mathbb{R}_+$ easily follows. Finally, by (4.15), (4.14), and (4.12) we have that

$$\|\psi_\beta J \phi_t^{-1} J_W \phi_t * \phi_t * g\|_{\Gamma_c^{\ell, q}} \leq C_\# e^{-\bar{\lambda} |d_s - \ell| t}. \quad (4.17)$$

This provides an estimate for each term in (4.11). We are left with the task of estimating the number of manifolds. Note that such number at time t is bounded by a constant times the volume of the manifold $\phi_{-t}(W_{\alpha, G})$. Moreover, it turns out that such volumes grow proportionally to $e^{h_{\text{top}}(\phi_1)t}$ (see Appendix C). Thus

$$\left\| \mathcal{L}_t^{(\ell)} h \right\|_{0, q, \ell}^- \leq C_q e^{-\bar{\lambda} |d_s - \ell| t} e^{h_{\text{top}}(\phi_1)t} \|h\|_{0, q, \ell}^-. \quad (4.18)$$

To establish the second inequality note that, by analogy with [30, Lemma 6.6], for each $\varepsilon > 0$ there exists $g_\varepsilon \in \Gamma_0^{\ell,r}(W_{\alpha,G})$ such that, setting $q' = \max\{0, q-1\}$,

$$\|g_\varepsilon - g\|_{\Gamma_c^{\ell,q'}} \leq C_q \varepsilon^{q-q'} ; \|g_\varepsilon\|_{\Gamma_c^{\ell,q}} \leq C_q ; \|g_\varepsilon\|_{\Gamma_c^{\ell,q+1}} \leq C_q \varepsilon^{-1}.$$

Thus, writing $g = (g - g_\varepsilon) + g_\varepsilon$ we can estimate to the two pieces separately. For g_ε we apply all the above computations using $q+1$ instead of q . To estimate the equivalent of (4.14) for the first piece, set $\psi_{t,k} = \phi_t \circ \Theta_\beta^{-1} \circ G_k$. For $q \notin \mathbb{N}$, we have²²

$$\begin{aligned} \|(g - g_\varepsilon)_{\bar{j}} \circ \psi_{t,k}\|_{C^q} &\leq C_q \varepsilon^{q-q'} + \sup_{i_1, \dots, i_{[q]}} H^{q-[q]} \left(L_{Z_{i_1}} \dots L_{Z_{i_{[q]}}} [(g - g_\varepsilon)_{\bar{j}} \circ \psi_{t,k}] \right) \\ &\leq C_q (\varepsilon^{\min\{1,q\}} + e^{-\bar{\lambda}qt}), \end{aligned}$$

the case $q \in \mathbb{N}$ being easier. Choosing ε depending on t yields the inequality

$$\left\| \mathcal{L}_t^{(\ell)} h \right\|_{0,q,\ell}^- \leq C_q e^{(h_{\text{top}}(\phi_1) - \bar{\lambda}|d_s - \ell| - \bar{\lambda}q)t} \|h\|_{0,q,\ell}^- + C_{q,t} \|h\|_{0,q+1,\ell}^-. \quad (4.19)$$

The second inequality of the Lemma follows then by iterating (4.19) for time steps $t_* > t_0$ such that $C_q e^{(\sigma_\ell - \bar{\lambda}q)t_*} \leq e^{(\sigma_\ell - \bar{\lambda}q)t_*}$ and using (4.18).

We are left with the case $\wp > 0$. We can apply Lemma 7.4 in [16] to decompose each $v \in \mathcal{V}^{\wp+q}(\phi_t(W_{\beta,G_{x_k,F_k}}))$ as $v = v^s + v^u + v^V$ where v^s is tangent to $\phi_t(W_{\beta,G_{x_k,F_k}})$, v^u is “close” to the unstable direction and v^V is the component in the flow direction. Let $\sigma \in \{s, u, V\}^\wp$, then (4.9) reads

$$\sum_{\sigma \in \{s,u,V\}^\wp} \int_{W_{\alpha,G}} \langle g, L_{v_1^{\sigma_1}} \dots L_{v_\wp^{\sigma_\wp}} \mathcal{L}_t^{(\ell)} h \rangle \omega_{\text{vol}}. \quad (4.20)$$

Since $L_v L_w h = L_w L_v h + L_{[v,w]} h$, we can reorder the derivatives so as to have first those with respect to the stable components, then those with respect to the unstable, and then finally those in the flow direction. By permuting the Lie derivative in such a way we introduce extra terms with less than $\wp$ derivatives, and these extra terms contribute only to weaker norms. For each $\sigma \in \{s, u, V\}^\wp$ let $p_s(\sigma) = \#\{i \mid \sigma_i = s\}$, $p_u(\sigma) = \#\{i \mid \sigma_i = u\}$ and $p_V(\sigma) = \#\{i \mid \sigma_i = V\}$. For each $\bar{p} = (p_s, p_u, p_V) \in \mathbb{N}^3$, $p_s + p_u + p_V = \wp$, let

²² By $H^\eta(f)$ we mean the Hölder constant of f , i.e. $\sup_{\|x-y\| \leq \delta} \frac{\|f(x) - f(y)\|}{\|x-y\|^\eta}$.

$\Sigma_{\bar{p}} = \{\sigma : p_s = p_s(\sigma), p_u = p_u(\sigma), p_V = p_V(\sigma)\}$. Next, for each $\sigma \in \Sigma_{\bar{p}}$ we define the permutation π_σ by $\pi_\sigma(i) < \pi_\sigma(i+1)$ for $i \notin \{p_s, p_s + p_u\}$; $\sigma_{\pi(i)} = s$ for $i \in \{1, \dots, p_s\}$; $\sigma_{\pi(i)} = u$ for $i \in \{p_s + 1, \dots, p_s + p_u\}$ and $\sigma_{\pi(i)} = V$ for $i \in \{\wp - p_V + 1, \dots, \wp\}$. We can then bound the absolute value of (4.20) by

$$\begin{aligned} & \sum_{p_s + p_u + p_V = \wp} \sum_{\sigma \in \Sigma_{\bar{p}}} \left| \int_{W_{\alpha, G}} \langle g, L_{v_{\pi_\sigma(1)}^s} \cdots L_{v_{\pi_\sigma(p_s)}^s} L_{v_{\pi_\sigma(p_s+1)}^u} \cdots L_{v_{\pi_\sigma(p_s+p_u)}^u} \right. \\ & \quad \times L_{v_{\pi_\sigma(p_s+p_u+1)}^V} \cdots L_{v_{\pi_\sigma(\wp)}^V} \mathcal{L}_t^{(\ell)} h \rangle \omega_{\text{vol}} \Big| + \mathfrak{a}^{-\wp+1} C_{\wp, q} \left\| \mathcal{L}_t^{(\ell)} h \right\|_{\wp-1, q, \ell, \mathfrak{a}}. \end{aligned} \quad (4.21)$$

To simplify the notation we define²³

$$\tilde{v}_i = \begin{cases} v_{\pi_\sigma(i)}^s & \text{for } i \leq p_s \\ v_{\pi_\sigma(i)}^u & \text{for } p_s + 1 \leq i \leq p_s + p_u \\ v_{\pi_\sigma(i)}^V & \text{for } i \geq p_s + p_u + 1. \end{cases}$$

We will analyze the terms of (4.21) one by one. First of all, suppose $p_V \neq 0$, then $v_i = \gamma_i V$ for $i > p_s + p_u$. Using equation (A.7),

$$\begin{aligned} & \left| \int_{W_{\alpha, G}} \langle g, L_{\tilde{v}_1} \cdots L_{\tilde{v}_\wp} \mathcal{L}_t^{(\ell)} h \rangle \omega_{\text{vol}} \right| \\ &= \left| \int_{W_{\alpha, G}} \langle g, L_{\tilde{v}_1} \cdots L_{\tilde{v}_{\wp-1}} (\gamma_\wp \mathcal{L}_t^{(\ell)} X^{(\ell)} h) \rangle \omega_{\text{vol}} \right| \\ &\leq C_{\wp, q} \left\| \mathcal{L}_t^{(\ell)} X^{(\ell)} h \right\|_{\wp-1, q+1, \ell}^- + \mathfrak{a}^{-\wp+1} C_{\wp, q} \left\| \mathcal{L}_t^{(\ell)} h \right\|_{\wp-1, q, \ell, \mathfrak{a}}. \end{aligned} \quad (4.22)$$

Next, suppose $p_V = 0$ but $p_s \neq 0$. By (A.5),

$$\begin{aligned} & \left| \int_{W_{\alpha, G}} \langle g, L_{\tilde{v}_1} \cdots L_{\tilde{v}_\wp} \mathcal{L}_t^{(\ell)} h \rangle \omega_{\text{vol}} \right| \\ &\leq \left| \int_{W_{\alpha, G}} L_{\tilde{v}_1} \langle g, L_{\tilde{v}_2} \cdots L_{\tilde{v}_\wp} \mathcal{L}_t^{(\ell)} h \rangle \omega_{\text{vol}} \right| + C_{\wp, q} \left\| \mathcal{L}_t^{(\ell)} h \right\|_{\wp-1, q, \ell}^-. \end{aligned}$$

Then, by intrinsic differential calculus in the manifold $W_{\alpha, G}$,

$$d(fi_v \omega_{\text{vol}}) = L_v(f \omega_{\text{vol}}) = (-1)^{d_s+1} (L_v f) \omega_{\text{vol}} + f d(i_v \omega_{\text{vol}}). \quad (4.23)$$

²³ We should write $\tilde{v}_{\sigma, i}$. However, since the following arguments are done at fixed σ , we drop the subscripts to ease the notation.

Thus, by Stokes theorem, the integral is bounded by $C_{\wp,q} \left\| \mathcal{L}_t^{(\ell)} h \right\|_{\wp-1,q,\ell}^-$ and

$$\left| \int_{W_{\alpha,G}} \langle g, L_{\tilde{v}_1} \cdots L_{\tilde{v}_{\wp}} \mathcal{L}_t^{(\ell)} h \rangle \omega_{\text{vol}} \right| \leq C_{\wp,q} \left\| \mathcal{L}_t^{(\ell)} h \right\|_{\wp-1,q,\ell}^-. \quad (4.24)$$

Finally, suppose $p_u = \wp$. Recalling (A.6) yields

$$\int_{W_{\alpha,G}} \langle g, L_{\tilde{v}_1} \cdots L_{\tilde{v}_{\wp}} \mathcal{L}_t^{(\ell)} h \rangle \omega_{\text{vol}} = \int_{W_{\alpha,G}} \langle g, \mathcal{L}_t^{(\ell)} L_{\phi_{-t*} \tilde{v}_1} \cdots L_{\phi_{-t*} \tilde{v}_{\wp}} h \rangle \omega_{\text{vol}}.$$

By construction we have $\|\phi_{-t*} \tilde{v}_i\|_{C^{\wp+q}} \leq C_{\#} e^{-\bar{\lambda}t}$. Hence, using (4.19) and (3.14) yields, for $\wp < p$,²⁴

$$\begin{aligned} \left| \int_{W_{\alpha,G}} \langle g, L_{\tilde{v}_1} \cdots L_{\tilde{v}_{\wp}} \mathcal{L}_t^{(\ell)} h \rangle \omega_{\text{vol}} \right| &\leq C_{\wp,q,t} \|L_{\phi_{-t*} \tilde{v}_1} \cdots L_{\phi_{-t*} \tilde{v}_{\wp}} h\|_{0,q+\wp+1,\ell}^- \\ &\quad + C_{\wp,q} e^{(h_{\text{top}}(\phi_1) - \bar{\lambda}|d_s - \ell| - q\bar{\lambda})t} \|L_{\phi_{-t*} \tilde{v}_1} \cdots L_{\phi_{-t*} \tilde{v}_{\wp}} h\|_{0,q+\wp,\ell}^- \\ &\leq C_{\wp,q} e^{(h_{\text{top}}(\phi_1) - \bar{\lambda}|d_s - \ell| - (q+\wp)\bar{\lambda})t} \|h\|_{\wp,q,\ell}^- + C_{\wp,q,t} \|h\|_{\wp,q+1,\ell}^-. \end{aligned} \quad (4.25)$$

Note that the last term can be estimated by the $\|\cdot\|_{p-1,q+1,\ell,\mathfrak{a}}$ norm, except in the case $\wp = p$. In such a case we use instead (4.18) which yields, for each $\wp \leq p$,

$$\left| \int_{W_{\alpha,G}} \langle g, L_{\tilde{v}_1} \cdots L_{\tilde{v}_{\wp}} \mathcal{L}_t^{(\ell)} h \rangle \omega_{\text{vol}} \right| \leq C_{\wp,q} e^{(h_{\text{top}}(\phi_1) - \bar{\lambda}|d_s - \ell| - \wp\bar{\lambda})t} \|h\|_{\wp,q,\ell}^-. \quad (4.26)$$

Collecting together (4.19), (4.22), (4.24), (4.25) and (4.26) we have, for $t > t_0$,

$$\begin{aligned} \|\mathcal{L}_t^{(\ell)} h\|_{p,q,\ell,\mathfrak{a}} &\leq C_q e^{(h_{\text{top}}(\phi_1) - \bar{\lambda}|d_s - \ell| - q\bar{\lambda})t} \|h\|_{0,q,\ell}^- + C_{q,t} \|h\|_{0,q+1,\ell}^- \\ &\quad + C_{p,q} \mathfrak{a} \left\| \mathcal{L}_t^{(\ell)} h \right\|_{p-1,q,\ell,\mathfrak{a}} + \sum_{\wp=1}^p \mathfrak{a}^{\wp} C_{\wp,q} \left\| \mathcal{L}_t^{(\ell)} X^{(\ell)} h \right\|_{\wp-1,q+1,\ell}^- \\ &\quad + \sum_{\wp=1}^{p-1} \mathfrak{a}^{\wp} C_{\wp,q} e^{(h_{\text{top}}(\phi_1) - \bar{\lambda}|d_s - \ell| - \bar{\lambda}(q+\wp)t)} \|h\|_{\wp,q,\ell}^- + C_{p,q,\mathfrak{a},t} \|\mathcal{L}_t^{(\ell)} h\|_{p-1,q+1,\ell,\mathfrak{a}} \\ &\quad + \mathfrak{a}^p C_{p,q} e^{(h_{\text{top}}(\phi_1) - \bar{\lambda}|d_s - \ell| - \bar{\lambda}p)t} \|h\|_{p,q,\ell}^-. \end{aligned}$$

²⁴ By an abuse of notation we use $\tilde{v}_i$ also for the extensions of the vector fields.

Then

$$\begin{aligned} \|\mathcal{L}_t^{(\ell)} h\|_{p,q,\ell,\mathbf{a}} &\leq C_{p,q} e^{(h_{\text{top}}(\phi_1) - \bar{\lambda}|d_s - \ell| - \min\{p,q\}\bar{\lambda})t} \|h\|_{p,q,\ell,\mathbf{a}} \\ &\quad + C_{p,q,\mathbf{a},t} \|h\|_{p-1,q+1,\ell,\mathbf{a}} + C_{p,q,\mathbf{a},t} \|\mathcal{L}_t^{(\ell)} h\|_{p-1,q+1,\ell,\mathbf{a}} \\ &\quad + C_{p,q} \mathbf{a} \left\| \mathcal{L}_t^{(\ell)} X^{(\ell)} h \right\|_{p-1,q+1,\ell,\mathbf{a}} + C_{p,q} \mathbf{a} \left\| \mathcal{L}_t^{(\ell)} h \right\|_{p,q,\ell,\mathbf{a}}. \end{aligned} \quad (4.27)$$

While, if we do not use (4.19) and (4.25), we have, for $\mathbf{a} \in (0, 1)$,

$$\begin{aligned} \|\mathcal{L}_t h\|_{p,q,\ell,\mathbf{a}} &\leq C_{p,q} e^{(h_{\text{top}}(\phi_1) - \bar{\lambda}|d_s - \ell|)t} \|h\|_{p,q,\ell,\mathbf{a}} \\ &\quad + C_{p,q} \mathbf{a} \left\| \mathcal{L}_t^{(\ell)} X^{(\ell)} h \right\|_{p-1,q+1,\ell,\mathbf{a}} + C_{p,q} \mathbf{a} \left\| \mathcal{L}_t^{(\ell)} h \right\|_{p-1,q,\ell,\mathbf{a}}. \end{aligned}$$

By induction, for which (4.18) is the initial step, it follows that, for all $t \in \mathbb{R}_+$,

$$\|\mathcal{L}_t h\|_{p,q,\ell,\mathbf{a}} \leq C_{p,q} e^{(h_{\text{top}}(\phi_1) - \bar{\lambda}|d_s - \ell|)t} \|h\|_{p,q,\ell,\mathbf{a}}. \quad (4.28)$$

Next, we choose t_* such that, for a given $\lambda < \bar{\lambda}$, we have that²⁵

$$C_{p,q} e^{(h_{\text{top}}(\phi_1) - \bar{\lambda}|d_s - \ell|)t_*} \leq e^{(h_{\text{top}}(\phi_1) - \lambda|d_s - \ell|)t_*}.$$

Finally, choosing $\mathbf{a} = e^{-\min\{p,q\}\bar{\lambda}t_*}$, from (4.27) and (4.28) we have

$$\begin{aligned} \|\mathcal{L}_{t_*} h\|_{p,q,\ell,\mathbf{a}} &\leq e^{(h_{\text{top}}(\phi_1) - \lambda|d_s - \ell| - \min\{p,q\}\lambda)t_*} \|h\|_{p,q,\ell,\mathbf{a}} \\ &\quad + C_{p,q,\mathbf{a},t_*} \|h\|_{p-1,q+1,\ell,\mathbf{a}} + C_{p,q} \mathbf{a} \left\| \mathcal{L}_{t_*}^{(\ell)} X^{(\ell)} h \right\|_{p-1,q+1,\ell,\mathbf{a}}. \end{aligned} \quad (4.29)$$

Iterating (4.29), recalling (4.28), and using (4.27) for the remaining $t - \lfloor t/t_* \rfloor t_*$ time interval, the Lemma follows. $\square$

Proof of Lemma 4.8. By Lemma 4.7 and equation (4.7) we have²⁶

$$\|R^{(\ell)}(z)^n h\|_{p,q,\ell} \leq \frac{C_{p,q,\lambda}}{(n-1)!} \|h\|_{p,q,\ell} \int_0^\infty dt e^{-at + \sigma_\ell t} t^{n-1} = \frac{C_{p,q,\lambda}}{(a - \sigma_\ell)^n} \|h\|_{p,q,\ell}.$$

Thus, provided $\Re(z) > \sigma_\ell$, we have that $R^{(\ell)}(z)^n \in L(\tilde{\mathcal{B}}^{p,q,\ell}, \tilde{\mathcal{B}}^{p,q,\ell})$.

Let us introduce a truncated resolvent

$$R_{n,\ell}(z) \doteq \frac{1}{(n-1)!} \int_{t_0}^\infty t^{n-1} e^{-zt} \mathcal{L}_t^{(\ell)}.$$

²⁵ In this case $C_{p,q}$ refers exactly to the first constant in (4.27).

²⁶ Note that for each $a > 0, \alpha \geq 0$, we have $\int_\alpha^\infty x^n e^{-ax} dx = e^{-a\alpha} \sum_{k=0}^n \frac{n!}{k!} \frac{\alpha^k}{a^{n-k+1}}$.

Then

$$\begin{aligned} \|R^{(\ell)}(z)^n - R_{n,\ell}(z)\|_{p,q,\ell} &\leq \int_0^{t_0} \frac{C_{p,q,\lambda} t^{n-1} e^{-(a-\sigma_\ell)t}}{(n-1)!} \\ &\leq C_{p,q,\lambda} \frac{t_0^n}{n!} \leq C_{p,q,\lambda} (a - \sigma_\ell + \sigma_{p,q})^{-n}, \end{aligned} \quad (4.30)$$

provided $n \geq t_0 e(a - \sigma_\ell + \sigma_{p,q})$.²⁷ To prove the second inequality of the Lemma it suffices to estimate $R_{n,\ell}(z)$. To this end we follow the same computation used to estimate the norm $\|\cdot\|_{p,q,\ell}$ in Lemma 4.5. The only difference being in the treatment of (4.22). Indeed, since $X\mathcal{L}_t = \frac{d}{dt}\mathcal{L}_t$, integration by parts yields

$$\begin{aligned} &\left| \int_{W_{\alpha,G}} \int_{t_0}^{\infty} \frac{t^{n-1} e^{-zt}}{(n-1)!} \langle \gamma_{\wp} g, L_{\tilde{v}_1} \cdots L_{\tilde{v}_{\wp-1}} (\mathcal{L}_t^{(\ell)} X^{(\ell)} h) \rangle \omega_{\text{vol}} \right| \\ &\leq C_{\wp,q} |z| \|h\|_{\wp-1,q+1,\ell}. \end{aligned}$$

Hence

$$\|R_n(z)h\|_{p,q,\ell} \leq \frac{C_{p,q,a,\lambda} \|h\|_{p,q,\ell}}{(a - \sigma_\ell + \sigma_{p,q})^n} + \frac{C_{p,q,a,\lambda} (|z| + 1)}{(a - \sigma_\ell)^n} \|h\|_{p-1,q+1,\ell}. \quad (4.31)$$

The first part of the Lemma then follows as in Lemma 4.7.

To prove the bound on the essential spectral radius of $R^{(\ell)}(z)^n$ we argue by analogy with [43, Proposition 2.10, Corollary 2.11]. Nussbaum's formula [51] asserts that if r_n is the infimum of the r such that $\{R^{(\ell)}(z)^n h\}_{\|h\| \leq 1}$ can be covered by a finite number of balls of radius r , then the essential spectral radius of $R^{(\ell)}(z)^n$ is given by $\liminf_{n \rightarrow \infty} \sqrt[n]{r_n}$. Let

$$B_1 \doteq \{h \in \tilde{\mathcal{B}}^{p,q,\ell} \mid \|h\|_{p,q,\ell} \leq 1\} \subset \{h \in \mathcal{B}^{p,q,\ell} \mid \|h\|_{p,q,\ell} \leq 1\} \doteq B_2.$$

By Lemma 3.11, B_2 is relatively compact in $\mathcal{B}^{p-1,q+1,\ell}$. Thus, for each $\epsilon > 0$ there are $h_1, \dots, h_{N_\epsilon} \in B_2$ such that $B_2 \subseteq \bigcup_{i=1}^{N_\epsilon} U_\epsilon(h_i)$, where $U_\epsilon(h_i) = \{h \in \mathcal{B}^{p-1,q+1,\ell} \mid \|h - h_i\|_{p-1,q+1,\ell} < \epsilon\}$. For $h \in B_1 \cap U_\epsilon(h_i)$, computing as in (4.31) we have

$$\|R_n(z)(h - h_i)\|_{p,q,\ell} \leq \frac{C_{p,q,a,\lambda}}{(a - \sigma_\ell + \sigma_{p,q})^n} \|h - h_i\|_{p,q,\ell} + \frac{C_{p,q,a,\lambda} e^{at_0} |z|}{(a - \sigma_\ell)^n} \epsilon.$$

Choosing ϵ appropriately and recalling (4.30) we conclude that for each $n \in \mathbb{N}$ the set $R^{(\ell)}(z)^n(B_1)$ can be covered by a finite number of $\|\cdot\|_{p,q,\ell}$ -balls of radius $C_{p,q,a,\lambda} (a - \sigma_\ell + \sigma_{p,q})^{-n}$, which implies the statement. $\square$

²⁷ Since $n! \geq n^n e^{-n}$.

5 Flat Traces

In this section we define a flat trace and we prove some of its relevant properties. Formally, for $A \in L(\mathcal{B}^{p,q,\ell}, \mathcal{B}^{p,q,\ell})$ we would like to define a trace by

$$\int_M \sum_{\alpha, \bar{i}} \langle \omega_{\alpha, \bar{i}}, A \delta_{x, \bar{i}} \rangle_x \quad (5.1)$$

where, for $x \in U_\alpha$, $\delta_{x, \bar{i}}(f) = \langle \omega_{\alpha, \bar{i}}, f \rangle_x \omega_{\alpha, \bar{i}}(x)$, for each $f \in \Omega_r^\ell$. Unfortunately, the $\delta_{x, \bar{i}}$ do not belong to the space $\mathcal{B}^{p,q,\ell}$. We are thus forced to employ an indirect strategy. For each $x \in M$, $\bar{i} \in \mathcal{I}_\ell$, $\alpha \in \mathcal{A}$ and $\varepsilon > 0$ small enough, let²⁸

$$j_{\varepsilon, \alpha, \bar{i}, x}(y) \doteq \begin{cases} J\Theta_\alpha(x)\psi_\alpha(x)\kappa_\varepsilon(\Theta_\alpha(x) - \Theta_\alpha(y))\omega_{\alpha, \bar{i}}(y) & \text{if } y \in U_\alpha \\ 0 & \text{if } y \notin U_\alpha, \end{cases} \quad (5.2)$$

where $\kappa_\varepsilon(x) = \varepsilon^{-d}\kappa(\varepsilon^{-1}x)$. At this stage we choose a particular κ (this refers also to Definition D.1). Let κ be $\kappa(x_1, \dots, x_d) = \kappa^{d-1}(x_1, \dots, x_{d-1})\kappa^1(x_d)$. Given an operator $A \in L(\mathcal{B}^{p,q,\ell}, \mathcal{B}^{p,q,\ell})$ we define the *flat trace* by

$$\mathrm{tr}^b(A) \doteq \lim_{\varepsilon \rightarrow 0} \int_M \sum_{\alpha, \bar{i}} \langle \omega_{\alpha, \bar{i}}, A(j_{\varepsilon, \alpha, \bar{i}, x}) \rangle_x \omega_M(x), \quad (5.3)$$

provided the limit exists. To get a feeling for what we are doing, consider the operator A acting on $h \in \Omega^\ell$ defined by

$$Ah(x) \doteq \int_M a(x, y)[h(y)] \quad (5.4)$$

where $a(x, y) \in L(\wedge^\ell T_y^* M, \wedge^\ell T_x^* M)$ depends continuously on x, y . A direct computation shows that

$$\mathrm{tr}^b(A) = \int_M \mathrm{tr}(a(x, x)).$$

Also, one can verify directly that for a finite rank operator A we have $\mathrm{tr}^b(A) = \mathrm{tr}(A)$, although we will not require this fact.

²⁸ Note that the definition is, given the freedom in the choice of κ , quite arbitrary. We are not interested in investigating the equivalence of the various possible definitions.

Lemma 5.1. *For each $s \in \mathbb{R}_+$, $0 \leq \ell \leq d-1$, $\Re(z) > \sigma_\ell$ and $n \in \mathbb{N}$, we have that $\mathrm{tr}^b(R^{(\ell)}(z)^n \mathcal{L}_s^{(\ell)})$ is well defined. Moreover,*

$$\mathrm{tr}^b(R^{(\ell)}(z)^n \mathcal{L}_s^{(\ell)}) = \frac{1}{(n-1)!} \sum_{\tau \in \mathcal{T}(s)} \frac{\chi_\ell(\tau)}{\mu(\tau)} [\lambda(\tau) - s]^{n-1} \lambda(\tau) e^{-z(\lambda(\tau)-s)},$$

where $\mathcal{T}(s) \doteq \{\tau \in \mathcal{T} ; \lambda(\tau) > s\}$, provided $s \notin \{\lambda(\tau)\}_{\tau \in \mathcal{T}}$.

Proof. By definitions (4.7), (5.2) and (5.3) we have

$$\begin{aligned} \mathrm{tr}^b(R(z)^n \mathcal{L}_s) &= \lim_{\varepsilon \rightarrow 0} \int_{M \times \mathbb{R}_+} \omega_M(x) dt \sum_{\alpha, \bar{i}} \frac{t^{n-1} e^{-zt}}{(n-1)!} \langle \omega_{\alpha, \bar{i}}, \phi_{-t-s}^* j_{\varepsilon, \alpha, \bar{i}, x} \rangle_x \\ &= \lim_{\varepsilon \rightarrow 0} \sum_{\alpha, \bar{i}} \int_{U_\alpha \times \mathbb{R}_+} \omega_M(x) dt \frac{t^{n-1} e^{-zt}}{(n-1)!} J\Theta_\alpha(x) \psi_\alpha(x) \\ &\quad \times \kappa_\varepsilon(\Theta_\alpha(x) - \Theta_\alpha(\phi_{-t-s}(x))) \langle \omega_{\alpha, \bar{i}}, \phi_{-t-s}^* \omega_{\alpha, \bar{i}} \rangle_x. \end{aligned}$$

We find convenient to rewrite the above as

$$\begin{aligned} \mathrm{tr}^b(R(z)^n \mathcal{L}_s) &= \lim_{\varepsilon \rightarrow 0} \sum_{\alpha, \bar{i}} \int_{U_\alpha \times [s, \infty)} F_{\alpha, \bar{i}, z}(x, t-s) \frac{\kappa_\varepsilon(\Theta_\alpha(x) - \Theta_\alpha(\phi_{-t}(x)))}{J\Theta_\alpha(x)^{-1}} \\ F_{\alpha, \bar{i}, z}(x, t) &\doteq \frac{t^{n-1}}{(n-1)!} e^{-zt} \psi_\alpha(x) \langle \omega_{\alpha, \bar{i}}, \phi_{-t-s}^* \omega_{\alpha, \bar{i}} \rangle_x. \end{aligned} \tag{5.5}$$

Note that the integrand is non zero only for $\kappa_\varepsilon(\Theta_\alpha(x) - \Theta_\alpha(\phi_{-t}(x))) \neq 0$, that is for $d(x, \phi_{-t}(x)) < \varepsilon$.

Our next step is to break up the domain of the above integral in a convenient way. To this end for each closed orbit $\tau \in \mathcal{T}$ and $\epsilon > 0$ we define

$$\begin{aligned} \Omega_\tau^\epsilon &\doteq \{(x, t) \in M \times \mathbb{R}_+ \mid |t - \lambda(\tau)| \leq C_4 \epsilon, \\ &\quad d(\phi_{-t_1}(x), \tau) \leq C_3 \epsilon \quad \forall t_1 \in (0, t)\}, \end{aligned}$$

where C_3, C_4 are constant to be specified shortly.

Sub-Lemma 5.2. *There exists $\varepsilon_0 > 0$ such that, for all $\varepsilon < \varepsilon_0$, the support of the integrand in (5.5) is contained in $\cup_{\tau \in \mathcal{T}} \Omega_\tau^\varepsilon$. In addition, if $\Omega_\tau^\varepsilon \cap \Omega_{\tau'}^\varepsilon \neq \emptyset$, then $\tau = \tau'$.*

Proof. Let us recall the shadowing theorem for flows (Bowen [14]), in the formulation explicitly given by Pilyugin in [54, Theorem 1.5.1], adapted to our case. First of all we define the (ε, T) -pseudo-orbits $\mathbf{t}(t) : \mathbb{R} \rightarrow M$ to be maps such that for any $t' \in \mathbb{R}$ we have $d(\phi_t(\mathbf{t}(t')), \mathbf{t}(t+t')) \leq \varepsilon$ if $|t| < T$.²⁹ Then we have the following theorem.

Theorem 5.3 ([54]). *Let M be a smooth manifold and ϕ_t a C^2 Anosov flow. There exists $\varepsilon_0 > 0, C_3 \geq 1$ such that given a $(\varepsilon, 1)$ -pseudo orbit $\mathbf{t}(t)$ with $\varepsilon < \varepsilon_0$ there exists an orbit τ , a point $p \in \tau$ and a reparametrization $\sigma(t)$ such that, for all $t, s \in \mathbb{R}$,*

$$d(\mathbf{t}(t), \phi_{\sigma(t)}(p)) \leq C_3\varepsilon \text{ where } |\sigma(t) - \sigma(s) - t + s| \leq C_3\varepsilon|t - s|.$$

Now we can start our proof. Given $x \in M$ and $t \in \mathbb{R}$ such that $d(x, \phi_{-t}(x)) < \varepsilon$, we can construct a closed $(\varepsilon, 1)$ -pseudo orbit. Let S be a codimension one manifold containing x and transversal to the flow. Then, by Theorem 5.3, there exists a $p \in S \cap \tau$ and a σ such that $d(\phi_{\sigma(t_1)}(p), \phi_{-t_1+nt}(x)) \leq C_3\varepsilon$ for all $t_1 \in [nt, (n+1)t]$, $n \in \mathbb{Z}$. Next, let t_* be the time of first return to S : i.e. $\phi_{\sigma(t_*)}(p) = q \in S$. Since, for all $t_1 \in \mathbb{R}$, $\phi_{t_1}(p), \phi_{t_1}(q)$ are always $C_3\varepsilon$ close to the $(\varepsilon, 1)$ -pseudo orbit, then they must belong to each other's weak stable and unstable manifolds, which implies $p = q$. Accordingly, there exists a prime periodic orbit $\tau_p \in \mathcal{T}_p$ that shadows the pseudo orbit. Also, by the same argument, such an orbit is unique. It follows that

$$|\sigma(t) - \lambda(\tau_p)| \leq 2C_3\varepsilon. \quad (5.6)$$

Moreover, for each $t_1 \in [0, t]$, the trajectory of $\phi_{-t_1}(x)$ is $C_3\varepsilon$ close to τ for a time at least $\min\{t_1, t - t_1\}$ both backward and forward in time. By the hyperbolicity this implies that $d(\phi_{-t_1}(x), \tau) \leq C_0C_3\varepsilon e^{-\lambda \min\{t_1, t-t_1\}}$. If $q \in \tau$ is the closest point to $z = \phi_{-\frac{t}{2}}(x)$, let $\xi(t_1) = \phi_{\bar{\sigma}(t_1)}(q) - \phi_{t_1}(z)$ where $\bar{\sigma}$ is defined by³⁰

$$\langle \xi(t_1), V(\phi_{\bar{\sigma}(t_1)}(q)) \rangle = 0,$$

where V is the vector field generating the flow. Differentiating we have

$$|1 - \bar{\sigma}'| \|V(\phi_{\bar{\sigma}(t_1)}(q))\|^2 \leq C_{\#} \|\xi(t_1)\|$$

²⁹ Note that we do not require $\mathbf{t}(t)$ to be continuous.

³⁰ Here we are really working in charts and using the euclidean structure, we do not write this explicitly since it is obvious (but a bit notationally unpleasant) how to proceed.

which, by the integral Gronwald inequality, yields $|\bar{\sigma}(t_1) - t_1| \leq C_{\#}\varepsilon$. Hence, for each $t_1 \in [0, t]$,

$$\begin{aligned} |\phi_{\sigma(-t_1)}(p) - \phi_{\frac{t}{2}-t_1}(q)| &\leq |\phi_{\sigma(-t_1)}(p) - \phi_{\bar{\sigma}(\frac{t}{2}-t_1)}(q)| + C_{\#}\varepsilon \\ &\leq |\phi_{\frac{t}{2}-t_1}(z) - \phi_{\bar{\sigma}(\frac{t}{2}-t_1)}(q)| + C_{\#}\varepsilon \leq C_{\#}\varepsilon. \end{aligned}$$

Accordingly, there exists $C_4 > 0$ such that $|\sigma(t) - t| \leq C_4\varepsilon$ whereby improving the bound in Theorem 5.3. Recalling (5.6) it follows that $(x, t) \in \Omega_{\tau}^{\varepsilon}$.

The above proves the first part of the Sub-Lemma, to prove the second suppose $(x, t) \in \Omega_{\tau}^{\varepsilon} \cap \Omega_{\tau'}^{\varepsilon}$. Let $z \in \tau$ be the closest point to x . Then,

$$d(x, \phi_t(x)) \leq 2C_3\varepsilon + d(z, \phi_t(z)) \leq (2C_3 + C_4)\varepsilon.$$

We can then construct a closed $((2C_3 + C_4)\varepsilon, 1)$ pseudo orbit. If ε is chosen small enough, by the arguments above such a pseudo orbit can shadow a unique prime orbit τ_p . Hence both τ and τ' are multiples of the same orbit, but $|\lambda(\tau) - \lambda(\tau')| \leq 2C_4\varepsilon$. Hence if $2C_4\varepsilon$ is smaller than the period of the shortest periodic orbit, then $\tau = \tau'$. $\square$

We can then rewrite (5.5) as

$$\sum_{\alpha, \bar{i}, \tau \in \mathcal{T}_{\varepsilon}(s)} \int_{\Omega_{\tau}^{\varepsilon}} \kappa_{\varepsilon}(\Theta_{\alpha}(x) - \Theta_{\alpha}(\phi_{-t}(x))) J\Theta_{\alpha}(x) F_{\alpha, \bar{i}, z}(x, t-s) \omega_M(x), \quad (5.7)$$

where we have introduced the notation $\mathcal{T}_{\varepsilon}(s) \doteq \mathcal{T}(s - C_4\varepsilon)$. Next, it is convenient to pass to charts, $(\xi, t) \doteq \tilde{\Theta}_{\alpha}(x, t) \doteq (\Theta_{\alpha}(x), t)$, $\phi_{-t}^{\alpha} \doteq \Theta_{\alpha} \circ \phi_{-t} \circ \Theta_{\alpha}^{-1}$. Thus, part of the expression (5.7) can be rewritten as,

$$\sum_{\alpha, \bar{i}, \tau \in \mathcal{T}_{\varepsilon}(s)} \int_{\tilde{\Theta}_{\alpha}(\Omega_{\tau} \cap (U_{\alpha} \times \mathbb{R}))} \kappa_{\varepsilon}(\xi - \phi_{-t}^{\alpha}(\xi)) F_{\alpha, \bar{i}, z} \circ \tilde{\Theta}_{\alpha}^{-1}(\xi, t-s). \quad (5.8)$$

Note that $\tilde{\Theta}_{\alpha}(\Omega_{\tau} \cap (U_{\alpha} \times \mathbb{R}_+))$ is contained in the ε -neighborhood of a finite number of lines (the connected pieces of $\Theta_{\alpha}(\tau \cap U_{\alpha})$). Let us call $\{\bar{\Omega}_{\tau, \alpha, m}\}$ the collection of such connected components.

Let us set $\xi = (\xi, \xi_d)$ and the map $\Xi_{\tau, \alpha, m} : \bar{\Omega}_{\tau, \alpha, m} \rightarrow \mathbb{R}^{d+1}$ given by

$$\begin{aligned} \Xi_{\tau, \alpha, m}(\xi, t) &\doteq (\xi_1 - \phi_{-t}^{\alpha}(\xi)_1, \dots, \xi_{d-1} - \phi_{-t}^{\alpha}(\xi)_{d-1}, \xi_d, t) \\ &\doteq (\zeta_1, \dots, \zeta_{d-1}, \xi_d, t) \doteq (\zeta, \xi_d, t). \end{aligned} \quad (5.9)$$

Note that, if $\xi \in M$ belongs to a periodic orbit τ , then $\det(D\Xi_{\tau, \alpha, m}(\xi, \lambda(\tau))) \neq 0$ by the hyperbolicity of the flow. Thus the map $\Xi_{\tau, \alpha, m}$ is locally invertible. What is not clear is if it is invertible on all $\bar{\Omega}_{\tau, \alpha, m}$.

Sub-Lemma 5.4. *There exists $\varepsilon_0 > 0$ such that, for all $\varepsilon \leq \varepsilon_0$ and α, m, τ , the map $\Xi_{\tau, \alpha, m}$ is a diffeomorphism from $\overline{\Omega}_{\tau, \alpha, m}$ onto its image.*

Proof. Suppose there exist $(z, \xi, t), (y, \eta, t') \in \overline{\Omega}_{\tau, \alpha, m}$ such that $\Xi_{\tau, \alpha, m}(z, \xi, t) = \Xi_{\tau, \alpha, m}(y, \eta, t')$. Then $t = t'$ and $\xi = \eta$ and

$$z - y = f(z) - f(y) \quad (5.10)$$

where $f = \phi_{-r_{\tau, \alpha, m}(z)}^\alpha$ is the return map to the zero section. Let $W^s(v), W^u(v)$ be the local stable and unstable manifolds of f at v and $E^s(v), E^u(v)$ be the stable and unstable spaces. For $v \in \mathbb{R}^{d-1}$ let $\Pi(v)$ be the projector on $E^s(v)$ along $E^u(v)$. Let $x = W^s(z) \cap W^u(y)$, then $w = f(x) = W^s(f(z)) \cap W^u(f(y))$. By hyperbolicity,

$$\|f(z) - f(x)\| \leq C_0 e^{-\bar{\lambda}t} \|z - x\|; \quad \|y - x\| \leq C_0 e^{-\bar{\lambda}t} \|f(y) - f(x)\|. \quad (5.11)$$

By the uniform bounds on the curvature of the invariant manifolds (see Appendix E),

$$\begin{aligned} \|\Pi(x)(z - x) - (z - x)\| &\leq C_\# \|z - x\|^2; \\ \|(1 - \Pi(f(x)))(f(z) - f(x)) - (f(z) - f(x))\| &\leq C_\# \|f(z) - f(x)\|^2, \end{aligned} \quad (5.12)$$

and the analogous for y . Indeed, we can argue in the plane containing the triangle of vertices x, z and $q = x + \Pi(x)(z - x)$. Let p be the orthogonal projection of z on the x, q line. Since the side x, q is tangent to $W^s(x)$, and the stable and unstable manifolds are uniformly transversal, at x , $\|z - q\| + \|z - p\| \leq C_\# \|x - z\|^2$. Thus $\|z - x\| - \|x - p\| \leq C_\# \|z - x\|^3$. On the other hand $\|p - q\| \leq C_\# \|z - x\|^2$.

By the Hölder continuity of the foliations we have, for some $\varpi \in (0, 1]$,

$$\|\Pi(x)(1 - \Pi(f(x)))\| + \|(1 - \Pi(f(x)))\Pi(x)\| \leq C_\# \varepsilon^\varpi. \quad (5.13)$$

Accordingly, by (5.12), (5.10), (5.11) and (5.13),

$$\begin{aligned} \|z - x\| &\leq \|\Pi(x)(z - x)\| + C_\# \|z - x\|^2 \\ &= \|\Pi(x)[(y - x) + (f(z) - f(x)) - (f(y) - f(x))]\| + C_\# \varepsilon \|z - x\| \\ &\leq C_\# [e^{-\bar{\lambda}t} + \varepsilon^\varpi] (\|z - x\| + \|f(y) - f(x)\|). \end{aligned}$$

If $\lambda(\tau)$ is large enough and ε small, then $\|z - x\| \leq \frac{1}{2} \|f(y) - f(x)\|$. By a similar argument we have $\|f(y) - f(x)\| \leq \frac{1}{2} \|z - x\|$. This proves the Lemma for all the periodic orbits with period larger than a fixed constant. For the finitely many remaining orbits the statement follows trivially from the local invertibility of the map by choosing ε_0 small enough. $\square$

Having established that (5.9) is a good change of coordinates, we can consider some more of its properties. For each α, m , there exists a unique $p_{\tau, \alpha, m} \in \mathbb{R}^{d-1}$ such that $(p_{\tau, \alpha, m}, 0) \in \Theta_\alpha(\tau \cap U_\alpha)$ and $(p_{\tau, \alpha, m}, 0, \lambda(\tau)) \in \overline{\Omega}_{\tau, \alpha, m}$, note that $\Xi_{\tau, \alpha, m}(p_{\tau, \alpha, m}, 0, t) = (0, 0, t)$. Next, define the (smooth) return time function $r_{\tau, \alpha, m}(\tilde{\xi})$ by $[\phi_{-r_{\tau, \alpha, m}(\tilde{\xi})}^\alpha(\tilde{\xi}, 0)]_d = 0$ such that $r_{\tau, \alpha, m}(p_{\tau, \alpha, m}) = \lambda(\tau)$. Note that $\phi_{-\lambda(\tau)}^\alpha(p_{\tau, \alpha, m}, 0) = (p_{\tau, \alpha, m}, 0)$, moreover, for t close to $\lambda(\tau)$, we have

$$\phi_{-t}^\alpha(\tilde{\xi}, \xi_d) = \phi_{-r_{\tau, \alpha, m}(\tilde{\xi})}^\alpha(\tilde{\xi}, 0) + (0, -t + r_{\tau, \alpha, m}(\tilde{\xi}) + \xi_d).$$

Also $r_{\tau, \alpha, m} \circ \Xi_{\tau, \alpha, m}^{-1}(\zeta, \xi_d, t) = \tilde{r}_{\tau, \alpha, m}(\zeta)$. It is then natural to define the return map to the zero section $K_{\tau, \alpha, m} = \phi_{r_{\tau, \alpha, m}(\tilde{\xi})}^\alpha(\tilde{\xi}, 0)$. Clearly such a map is hyperbolic. It is convenient to set $\Lambda_{\tau, \alpha, m}(\zeta) = [DK_{\tau, \alpha, m}] \circ \Xi_{\tau, \alpha, m}^{-1}(\zeta, 0, \tilde{r}_{\tau, \alpha, m}(\zeta))$. In the sequel we will need several estimates on the regularity of the above object that we summarize in the next result.³¹

Sub-Lemma 5.5. *There exists $\varepsilon_0 > 0$ such that, for all $\varepsilon < \varepsilon_0$, $\tau \in \mathcal{T}$, $\alpha \in \mathcal{A}$ and $m \in \mathbb{N}$, we have*

$$\begin{aligned} \|(1 - \Lambda_{\tau, \alpha, m})^{-1}\|_\infty &\leq C_\# \\ \|\partial_\zeta \tilde{r}_{\tau, \alpha, m}\|_\infty &\leq C_\# \\ \|\partial_\zeta \det(1 - \Lambda_{\tau, \alpha, m})^{-1}\|_\infty &\leq C_\# \|\det(1 - \Lambda_{\tau, \alpha, m})\|_\infty. \end{aligned}$$

Proof. Note that

$$D\phi_{-t}^\alpha(\xi) = \begin{pmatrix} \Lambda_{\tau, \alpha, m} \circ \Xi_{\tau, \alpha, m}(\tilde{\xi}, \xi_d, t) & 0 \\ g_{\tau, \alpha, m} \circ \Xi_{\tau, \alpha, m}(\tilde{\xi}, \xi_d, t) & 1 \end{pmatrix}$$

where the left entries do not depend on ξ_d, t (hence $\Lambda_{\tau, \alpha, m}, g_{\tau, \alpha, m}$ depend only on ζ). The first inequality of the Sub-Lemma follows by hyperbolicity. In addition, $g_{\tau, \alpha, m}$, by the existence of an invariant cone field, satisfies, for each $\eta \in \mathbb{R}^{d-1}$, $|\langle g_{\tau, \alpha, m}, \eta \rangle| \leq C_\# \|\Lambda_{\tau, \alpha, m} \eta\|$. That is

$$\|[\Lambda_{\tau, \alpha, m}^{-1}]^* g_{\tau, \alpha, m}\| \leq C_\#. \quad (5.14)$$

Also, we have

$$[D\Xi_{\tau, \alpha, m}] \circ \Xi_{\tau, \alpha, m}^{-1}(\zeta, \xi_d, t) = \begin{pmatrix} 1 - \Lambda_{\tau, \alpha, m}(\zeta) & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}. \quad (5.15)$$

³¹ In fact, Sub-Lemma 5.5 contains much more than what is presently needed (a rough bound of the type $e^{C_\# \lambda(\tau)}$ would suffice), yet its full force will be necessary in Lemma 8.2.

Hence $\det([D\Xi_{\tau,\alpha,m}] \circ \Xi_{\tau,\alpha,m}^{-1}(\zeta, \xi_d, t)) = \det(\mathbb{1} - \Lambda_{\tau,\alpha,m}(\zeta)) \neq 0$ by hyperbolicity. By applying the implicit function theorem we then have

$$\partial_\zeta \tilde{r}_{\tau,\alpha,m} = [\Lambda_{\tau,\alpha,m}(\mathbb{1} - \Lambda_{\tau,\alpha,m})^{-1}]^* [\Lambda_{\tau,\alpha,m}^{-1}]^* g_{\tau,\alpha,m}.$$

The above formula and (5.14) imply the second inequality of the Lemma. To prove the last we adapt the arguments in [44, Sub-Lemma 3.2] (see also [58]).

We divide $\lambda(\tau)$ in l time intervals long enough so that the Poincaré map is hyperbolic. Let $\{t_i\}_{i=1}^{l-1}$ be the times at which we insert a Poincaré section while the first and last are our zero section. In each new section we can choose coordinates so that the periodic orbit is at $(0, 0)$ and, at such a point, $\{(\xi, 0)\}$ corresponds to the stable manifold and $\{(0, \eta)\}$ to the unstable one. Let Λ_i be the derivative of the map between the i and $i+1$ section. By hypothesis each Λ_i expands vectors close to the $\{(\xi, 0)\}$ subspace and contracts vectors close to the $\{(0, \eta)\}$ subspace. Also

$$\Lambda_{\tau,\alpha,m} = \prod_{i=0}^{l-1} \Lambda_i.$$

Given a point $\tilde{\xi}$ in the zero section, let $\tilde{\xi}^i$ be its image in the i -th section. With this notation we can write

$$\begin{aligned} \partial_{\zeta_m} \Lambda_{\tau,\alpha,m} &= \sum_{p=1}^{d-1} \frac{\partial \tilde{\xi}_p^j}{\partial \zeta_m} \sum_{j=0}^{l-1} P_j \Gamma_{j,p} Q_j \\ P_j &= \prod_{i>j} \Lambda_i \quad ; \quad Q_j = \prod_{i\leq j} \Lambda_i \quad ; \quad \Gamma_{j,p} = \partial_{\tilde{\xi}_p^j} \Lambda_j \Lambda_j^{-1}. \end{aligned}$$

Note that

$$\frac{\partial \tilde{\xi}_p^j}{\partial \zeta_m} = Q_j (\mathbb{1} - \Lambda_{\tau,\alpha,m})^{-1} = Q_j (\mathbb{1} - P_j Q_j)^{-1} = (Q_j^{-1} - P_j)^{-1}$$

and, by the hyperbolicity, it follows that $\|\frac{\partial \tilde{\xi}_p^j}{\partial \zeta_m}\| \leq C_\#$. On the other hand

$$\partial_{\zeta_m} \det(\mathbb{1} - \Lambda_{\tau,\alpha,m}) = -\text{tr}(\partial_{\zeta_m} \Lambda_{\tau,\alpha,m} (\mathbb{1} - \Lambda_{\tau,\alpha,m})^{-1}) \cdot \det(\mathbb{1} - \Lambda_{\tau,\alpha,m}).$$

We can then compute

$$\begin{aligned} |\text{tr}(\partial_{\zeta_m} \Lambda_{\tau,\alpha,m} (\mathbb{1} - \Lambda_{\tau,\alpha,m})^{-1})| &\leq C_\# \sup_p \sum_{j=0}^{l-1} |\text{tr}(P_j \Gamma_{j,p} Q_j (\mathbb{1} - P_j Q_j)^{-1})| \\ &= C_\# \sup_p \sum_{j=0}^{l-1} |\text{tr}(\Gamma_{j,p} (P_j^{-1} Q_j^{-1} - \mathbb{1})^{-1})| \leq C_\# \end{aligned}$$

where we have used the hyperbolicity again. The last inequality of the Sub-Lemma is thus proven. $\square$

By first performing the change of variables $\Xi_{\tau,\alpha,m}$, then using the properties of the chosen κ , and finally using the change of coordinates $\eta = \varepsilon^{-1}\zeta$, $v = \varepsilon^{-1}(t - \tilde{r}_{\tau,\alpha,m}(\zeta))$, we can write (5.8) as

$$\sum_{\alpha,\bar{i},m,\tau \in \mathcal{T}_\varepsilon(s)} \int_{\mathbb{R}^{d+1}} F_{\alpha,\bar{i},z} \circ \tilde{\Theta}_\alpha^{-1} \circ \Xi_{\tau,\alpha,m}^{-1}(\varepsilon\eta, \xi_d, \varepsilon v + \tilde{r}_{\tau,\alpha,m}(\varepsilon\eta) - s) \times \kappa^{d-1}(\eta) \kappa^1(v) |\det(\mathbb{1} - \Lambda_{\tau,\alpha,m}(\varepsilon\eta))|^{-1}. \quad (5.16)$$

To continue we need to estimate the ε dependence in the integrand. Remembering the definition (5.5), we see that the derivative of F is, in general, of order $C_\# e^{C_\#|t|}$. Then, setting $a = \Re(z)$, Sub-Lemma 5.5 yields

$$\sum_{\alpha,\bar{i},m,\tau \in \mathcal{T}_\varepsilon(s)} \int_{-\delta}^{\delta} \frac{F_{\alpha,\bar{i},z} \circ \tilde{\Theta}_\alpha^{-1} \circ \Xi_{\tau,\alpha,m}^{-1}(0, \xi_d, \lambda(\tau) - s)}{|\det(\mathbb{1} - \Lambda_{\tau,\alpha,m}(0))|} + \mathcal{O}\left(\varepsilon|z| \frac{[\lambda(\tau) - s]^{n-1} e^{C_\# \lambda(\tau) - a[\lambda(\tau) - s]}}{(n-1)!}\right). \quad (5.17)$$

Define $D_{\text{hyp}}\phi_{\lambda(\tau)} = \Lambda_{\tau,\alpha,m}(0)$. If we compute this matrix in a different chart or at another point in the orbit we simply obtain a matrix conjugated to $D_{\text{hyp}}\phi_{\lambda(\tau)}$. Thus $|\det(\mathbb{1} - D_{\text{hyp}}\phi_{\lambda(\tau)})|$ depends only on τ . In addition, we have³²

$$\begin{aligned} \text{tr}(\wedge^\ell D\phi_{-\lambda(\tau)}^\alpha) &= \sum_{\bar{k} \in \mathcal{I}_\ell} \det(D\phi_{-\lambda(\tau)}^\alpha)_{\bar{k},\bar{k}} = \sum_{\bar{k} \in \mathcal{I}_\ell^-} \det(D_{\text{hyp}}\phi_{-\lambda(\tau)})_{\bar{k},\bar{k}} \\ &= \text{tr}(\wedge^\ell (D_{\text{hyp}}\phi_{-\lambda(\tau)})), \end{aligned} \quad (5.18)$$

which, again, depends only on the orbit τ . Accordingly,

$$\sum_{\bar{i}} \langle \omega_{\alpha,\bar{i}}, \phi_{-\lambda(\tau)}^* \omega_{\alpha,\bar{i}} \rangle_{p_{\tau,\alpha,m}} = \text{tr}(\wedge^\ell (D_{\text{hyp}}\phi_{-\lambda(\tau)})).$$

³² Given a vector space V^d over $\mathbb{R}$ and a matrix representation of a linear operator $A : V^d \rightarrow V^d$, we can construct, by the standard external product, a matrix representation of $\wedge^\ell A : \wedge^\ell(V^d) \rightarrow \wedge^\ell(V^d)$ with elements $a_{\bar{i},\bar{j}} = \det(A_{\bar{i},\bar{j}})$ (see definition (A.1) or [11]). By $\det(A)_{\bar{k},\bar{k}}$ we mean the determinant of the matrix (A_{k_i,k_j}) . Note that $\det(D\phi_{-\lambda(\tau)}^\alpha)_{\bar{k},\bar{k}} = 0$ unless $k_\ell = d$. See Remark 3.1 for the definition of $\mathcal{I}_\ell^-$.

To conclude, remember that the number of closed orbits with period between t and $t+1$ is bounded by $C_{\#}e^{h_{\text{top}}(\phi_1)t}$ (see [39, Theorem 18.5.7]). In fact, there exists an asymptotic formula, see [48], which we are substantially improving in Theorem 2.8. Hence the error term in (5.17) is bounded by

$$\sum_{k \geq s} \varepsilon |z| \frac{[k-s]^{n-1} e^{C_{\#}k-a[k-s]}}{(n-1)!} \leq C_{\#} \varepsilon |z| (a - C_{\#})^{-n} e^{C_{\#}s}$$

provided $a > C_{\#}$. By summing over the connected components of $\bar{\Omega}_{\tau, \alpha, m}$, taking into account the multiplicity of orbits, resumming on α and recalling (2.6) we finally obtain that there exists $C_2, \varepsilon_0 > 0$ such that, for all $\varepsilon \leq \varepsilon_0$ and $a > C_2$,

$$\left| \int_M \sum_{\alpha, \bar{i}} \langle \omega_{\alpha, \bar{i}}, R^{(\ell)}(z)^n \mathcal{L}_s^{(\ell)}(j_{\epsilon, \alpha, \bar{i}, x}) \rangle_x - \sum_{\tau \in \mathcal{T}(s)} \frac{\chi_{\ell}(\tau) [\lambda(\tau) - s]^{n-1} \lambda(\tau)}{(n-1)! \mu(\tau) e^{z(\lambda(\tau)-s)}} \right| \quad (5.19)$$

$$\leq C_{\#} \varepsilon |z| (a - C_2)^{-n} e^{\frac{a}{2}s}.$$

Taking the limit $\varepsilon \rightarrow 0$ yields the Lemma for $a > C_2$. On the other hand the above estimates show that both sides of the equation in the statement of the Lemma are well defined analytic functions for $a > \sigma_{\ell}$. Indeed, equation (5.16) shows that the approximations to the flat trace, which are analytic, are uniformly bounded in any region $a \geq a_0 > \sigma_{\ell}$ hence they have analytic accumulation points that must agree since they agree for large a . The statement of the Lemma follows. $\square$

By a direct computation using Lemma 5.1 we have the natural formula³³

$$\int_0^{\infty} e^{-zs} \frac{s^{n-1}}{(n-1)!} \text{tr}^b(R(z) \mathcal{L}_s) = \text{tr}^b(R(z)^{n+1}). \quad (5.20)$$

6 Tensorial Transfer Operators

In this section we extend the methods of Liverani-Tsujii [45] to the case of flows. The goal is to provide a setting in which a formula of the type (5.1)

³³ Indeed,

$$\int_0^{\infty} e^{-zs} \frac{s^{n-1}}{(n-1)!} \text{tr}^b(R(z) \mathcal{L}_s) = \sum_{\tau \in \mathcal{T}} \int_0^{\lambda(\tau)} \frac{s^{n-1}}{(n-1)!} \frac{\chi_{\ell}(\tau)}{\mu(\tau)} \lambda(\tau) e^{-z\lambda(\tau)}.$$

makes sense and can be used to compute the trace (see Lemma 6.8 for the exact implementation). The first step is to note that, by equation (A.4), the adjoint (with respect to $\langle \cdot, \cdot \rangle_{\Omega^\ell}$) of $\mathcal{L}_t^{(\ell)}$ is given by, for $g \in \Omega_{0,r}^\ell$,

$$\overline{\mathcal{L}}_t^{(\ell)} g \doteq (-1)^{\ell(d-\ell)} * (\phi_t^*(*g)). \quad (6.1)$$

Next we would like to take the tensor product of $\mathcal{L}_t^{(\ell)}$ times $\overline{\mathcal{L}}_t^{(\ell)}$, and define a Banach space, connected to the product space $\Omega_r^{2\ell}(M^2)$,³⁴ on which it acts naturally. Note that, contrary to the discrete case, in the continuous setting this procedure naturally yields a $\mathbb{R}_+$ action in the variables $s, t \geq 0$ (rather than a flow). We start with the construction of the Banach space.

6.1 Spaces and Operators

We use the construction developed in Section 3 applied to the manifold M^2 .

First of all consider the atlas $\{U_\alpha, \Theta_\alpha\}_{\alpha \in \mathcal{A}}$ chosen at the beginning of Section 4. We define the map $I(u, s, t, u', s', t') = (s, u', u, s', t, t')$, $u, u' \in \mathbb{R}^{d_u}$, $s, s' \in \mathbb{R}^{(d_s)}$, $t, t' \in \mathbb{R}$, the atlas $\{U_\alpha \times U_\beta, I \circ (\Theta_\alpha \times \Theta_\beta)\}_{\alpha, \beta \in \mathcal{A}}$ and the partition of unity $\{\psi_{\alpha, \beta}\}_{\alpha, \beta \in \mathcal{A}}$, where $\psi_{\alpha, \beta}(x, y) = \psi_\alpha(x)\psi_\beta(y)$. We are thus in the situation of Section 3 with $d_1 = d_u + d_s = d - 1$ and $d_2 = d + 1$. Note that the conditions (3.1) are automatically satisfied.³⁵ We choose the cones given by the choice $\rho_+ = 2, \rho_- = 1$ and L_0 as in Section 4 to define the set of “stable” leaves, which we denote by Σ_2 .

Remark 6.1. *From now on we will ignore the map I since it is just a trivial permutation of the coordinates.*

By appendix A we can consider the exterior forms $\Omega_r^{2\ell}(M^2)$ and the related scalar product. We define the projections $\pi_i : M^2 \rightarrow M$, $i \in \{1, 2\}$, such that $\pi_1(x, y) = x$ and $\pi_2(x, y) = y$. For each pair of ℓ -forms f, g in $\Omega_r^\ell(M)$ we have that $\pi_1^* f \wedge \pi_2^* g \in \Omega_r^{2\ell}(M^2)$. In addition, given $a, b, f, g \in \Omega_r^\ell(M)$, by equation (A.1), we have

$$\langle \pi_1^* a \wedge \pi_2^* b, \pi_1^* f \wedge \pi_2^* g \rangle_{(x,y)} = \langle a, f \rangle_x \langle b, g \rangle_y. \quad (6.2)$$

Moreover, by (A.2), it follows that

$$* (\pi_1^* f \wedge \pi_2^* g) = (-1)^{\ell(d-\ell)} \pi_1^*(*f) \wedge \pi_2^*(*g). \quad (6.3)$$

³⁴ By M^2 we mean the Riemannian manifold with the product metric.

³⁵ Note that the third condition holds both for x_{2d} and x_{2d-1} .

Next we define the vector space $\Omega_{2,r}^\ell(M) \doteq \text{span}\{\pi_1^* f \wedge \pi_2^* g : f, g \in \Omega_{0,r}^\ell(M)\}$ on which we intend to base our spaces. Note that locally the C^s closure of $\Omega_{2,s}^\ell(M)$ contains all the forms h such that $i_{(V,0)} h = i_{(0,V)} h = 0$ and that can be written as

$$h = \sum_{\alpha,\beta} h_{\alpha,\beta} = \sum_{\alpha,\beta,\bar{i},\bar{j}} \psi_{\alpha,\beta}(x,y) h_{\bar{i},\bar{j}}^{\alpha,\beta}(x,y) \omega_{\alpha,\bar{i}}(x) \wedge \omega_{\beta,\bar{j}}(y), \quad (6.4)$$

where $h_{\alpha,\beta} \doteq \psi_{\alpha,\beta} h$, and $h_{\bar{i},\bar{j}}^{\alpha,\beta} \in C^{\bar{s}}(M^2)$, for each $\bar{s} > s$.³⁶

Lastly, we must choose an appropriate set of test functions and vector fields. For the set of test functions we choose $\Gamma_{2,c}^{\ell,s}(\alpha, \beta, G)$, defined by the restriction of $\text{span}\{\pi_1^* f \wedge \pi_2^* g : f, g \in \Omega_s^\ell(M), \pi_1^* f \wedge \pi_2^* g|_{\partial W_{\alpha,\beta,G}} = 0\}$ to $W_{\alpha,\beta,G}$. The set of vector fields have only the restriction that³⁷

$$\begin{aligned} (\pi_1)_*(v) = 0 &\implies w \in \mathcal{V}^s(M^2) \text{ and } (\pi_2)_*(w) = 0 \implies [w, v] = 0 \\ (\pi_2)_*(w) = 0 &\implies v \in \mathcal{V}^s(M^2) \text{ and } (\pi_1)_*(v) = 0 \implies [v, w] = 0. \end{aligned} \quad (6.5)$$

Note that this implies

$$[v, w] = [(\pi_1)_* v, (\pi_1)_* w], [(\pi_2)_* v, (\pi_2)_* w]. \quad (6.6)$$

The reader can easily check that the above choices satisfy all the conditions specified in Section 3. In particular, Lemma 4.2 holds also in the present context, since the arguments in its proof respects the property (6.5). Thus we can apply the construction in Section 3 and call $\|\cdot\|_{p,q,\ell,2}$ the resulting norms and $\mathcal{B}_2^{p,q,\ell} \doteq \overline{\Omega_{2,r}^\ell(M)}^{\|\cdot\|_{p,q,\ell,2}}$ the corresponding Banach spaces.

Finally, we define the required operators $\mathcal{L}_{t,s}^{(\ell)}$. For each $f, g \in \Omega_r^\ell(M)$

$$\mathcal{L}_{t,s}^{(\ell)}(\pi_1^* f \wedge \pi_2^* g) \doteq (\pi_1^*(\mathcal{L}_t^{(\ell)} f)) \wedge (\pi_2^*(\mathcal{L}_s^{(\ell)} g)) \quad (6.7)$$

which extends by linearity to an operator $\mathcal{L}_{t,s}^{(\ell)} : \Omega_{2,r}^\ell(M) \rightarrow \Omega_{2,r}^\ell(M)$.

To avoid the problem of small times, for which the cone contraction might fail, we apply the same strategy used in the previous section: we define

$$\|h\|_{p,q,\ell,2} = \sup_{t,s \leq t_0} \left\| \mathcal{L}_{t,s}^{(\ell)} h \right\|_{p,q,\ell,2},$$

³⁶ This follows since C^∞ is dense in $C^{\bar{s}}$ in the C^s topology and smooth functions can be approximated by tensor functions, e.g. by Fourier series, in any C^s norm. Note that if $s \in \mathbb{N}$, then one can choose $s = \bar{s}$ (for a more refined description, not used here, see the theory of *little Hölder spaces*).

³⁷ Let $(x, y) \in M^2$, then we are requiring $v(x, y) = (v_1(x), v_2(y))$.

and we define the spaces $\tilde{\mathcal{B}}_2^{p,q,\ell} \doteq \overline{\Omega_{2,r}^\ell}^{\|\cdot\|_{p,q,\ell,2}} \subset \mathcal{B}_2^{p,q,\ell}$.

Following Remark 3.9, equation (A.4), setting $\omega_2 = \pi_1^* \tilde{\omega} \wedge \pi_2^* \tilde{\omega}$, yields

$$\mathcal{L}_{t,t}^{(d-1)}(f\omega_2) = f \circ (\phi_{-t} \times \phi_t) J\phi_{-t}\omega_2.$$

That is, we recover the same type of operators studied in [45].

6.2 Lasota-Yorke inequalities

We can now obtain several results parallel to those in Sections 4.1, 4.2. As the proofs are almost identical to those in Section 4.3 we will not give full details and highlight only the changes that need to be made.

Lemma 6.2. *For each $0 < p + q < r - 1$, $t, s \in \mathbb{R}_+$, $\mathcal{L}_{t,s}^{(\ell)} \in L(\tilde{\mathcal{B}}_2^{p,q,\ell}, \tilde{\mathcal{B}}_2^{p,q,\ell})$. More precisely $\mathcal{L}_{t,s}^{(\ell)}$ is an $\mathbb{R}_+^2$ action over $\tilde{\mathcal{B}}_2^{p,q,\ell}$. Moreover, $\mathcal{L}_{t,0}^{(\ell)}$ and $\mathcal{L}_{0,s}^{(\ell)}$ are strongly continuous semigroups with generators X_1, X_2 , respectively. In addition, we have³⁸*

$$\begin{aligned} \left\| \mathcal{L}_{t,s}^{(\ell)} h \right\|_{p,q,\ell,2} &\leq C_{p,q} e^{\sigma_\ell(t+s)} \|h\|_{p,q,\ell,2} \\ \left\| \mathcal{L}_{t,s}^{(\ell)} h \right\|_{p,q,\ell,2} &\leq C_{p,q} e^{\sigma_\ell(t+s)} e^{-\sigma_{p,q} \min\{t,s\}} \|h\|_{p,q,\ell,2} + C_{p,q} e^{\sigma_\ell(t+s)} \|h\|_{p-1,q+1,\ell,2} \\ &\quad + \sum_{j=1}^2 e^{\sigma_\ell(t+s)} \|X_j h\|_{p-1,q+1,\ell,2}. \end{aligned}$$

Proof. As in Section 4, we first prove an analogue of Lemma 4.5, and then we prove a stronger version of it, as in Lemma 4.7.

The proof contained in Subsection 4.3 can be followed almost verbatim. By the same construction one obtains the equivalent of (4.11), that is

$$\begin{aligned} \int_{W_{\alpha,\alpha',G}} \langle g, \mathcal{L}_{t,s}^{(\ell)} h \rangle \omega_{\text{vol}} &= \sum_{\substack{\beta, \beta' \in \mathcal{A} \\ k \in \tilde{K}_{\beta, \beta'}}} \sum_{\tilde{i}, \tilde{j}, \tilde{i}', \tilde{j}'} \int_{W_{\beta, \beta', G_k}} (-1)^{(d-\ell)\ell} \psi_{\beta, \beta'} J\phi_{t-s}^{-1} \\ &\quad \times J_W(\phi_t \times \phi_{-s}) g_{\tilde{i}', \tilde{j}'} \circ (\phi_t \times \phi_{-s}) \cdot \langle \omega_{\beta, \tilde{i}}, * \phi_t^* * \omega_{\alpha, \tilde{j}} \rangle \langle \omega_{\beta, \tilde{i}'}, \phi_{-s}^* \omega_{\alpha, \tilde{j}'} \rangle \omega_{\text{vol}}. \end{aligned}$$

³⁸ Here and in the sequel we suppress the λ dependence in the constants to simplify the notation.

For the case $\wp = 0$, the argument is exactly the same as in Section 4.3, apart from the estimate of the volume of $\phi_{-t} \times \phi_s(W_{\alpha,\alpha',G})$ to which Appendix C cannot be applied directly. To estimate such a volume, after setting $(z_1, z_2) = (\Theta_\alpha \times \Theta_{\alpha'})^{-1}(G(0))$, let us consider $W(z) \doteq W_{6\delta}^s(z_1) \times W_{6\delta}^u(z_2)$ and the holonomy from $W_{\alpha,\alpha',G}$ to $W(z)$ determined by the weak unstable foliation in the first coordinate and the weak stable in the second. Clearly the distance between the corresponding points in the images of $W_{\alpha,\alpha',G}$ and $W(z)$ is uniformly bounded; hence the required volume is proportional to the volume of $\phi_{-t} \times \phi_s(W(z))$, which is bounded by $e^{h_{\text{top}}(\phi_1)(t+s)}$.

For the case $\wp > 0$, by equations (6.6), we can reorder the vector fields so as to have first the vector fields tangent to W_{β,β',G_k} , then the vector fields in the unstable direction of $\phi_t \times \phi_{-s}$ and then the two neutral directions. We can then proceed as in equation (4.21). All the following computations hold verbatim apart from two issues.

First, in equation (4.23) the last term yields a multiplicative factor that does not produce a new legal test function. Indeed, such a factor is the sum of the a divergence of the vector field (which gives no problems) and the scalar product of the vector field time a C^{r-1} vector, call it A . As A comes from taking derivatives of G , it follows that it may not be of the required product structure. The problem is easily solved: since $r-1 > p+q$, we can approximate A in the $\wp-1+q$ topology by vectors $A_n \in \Gamma_{2,c}^{\ell,\wp-1+q}(\alpha, \beta, G)$ with the appropriate tensor product structure. The required inequality follows.

Second, the weakest contraction is now given by the case in which all the vector fields act on the component with the smallest time, hence the $\min\{t, s\}$ factor. $\square$

Lemma 6.3. *For each $0 < p+q < r-1$, $\ell \in \{0, \dots, d-1\}$, and for each $\Re(z) \doteq a > \sigma_\ell$, the operator*

$$R_2^{(\ell)}(z)^n = \frac{1}{(n-1)!^2} \int_0^\infty \int_0^\infty (ts)^{n-1} e^{-z(t+s)} \mathcal{L}_{t,s}^{(\ell)} dt ds \quad (6.8)$$

satisfies

$$\begin{aligned} \left\| R_2^{(\ell)}(z)^n \right\|_{p,q,\ell,2} &\leq C_{p,q} (a - \sigma_\ell)^{-2n} \\ \left\| R_2^{(\ell)}(z)^n h \right\|_{p,q,\ell,2} &\leq C_{p,q,a} \left\{ \frac{\|h\|_{p,q,\ell,2}}{(a - \sigma_\ell + \frac{\sigma_{p,q}}{2})^{2n}} + \frac{(|z| + 1)}{(a - \sigma_\ell)^{2n}} \|h\|_{p-1,q+1,\ell,2} \right\}. \end{aligned}$$

Hence $R^{(\ell)}(z)$ is a linear operator on $\tilde{\mathcal{B}}_2^{p,q,\ell}$ with spectral radius bounded by $(\Re(z) - \sigma_\ell)^{-2}$ and essential spectral radius bounded by $(\Re(z) - \sigma_\ell + \frac{\sigma_{p,q}}{2})^{-2}$.

Proof. Again the proof follows closely Subsection 4.2, and more precisely Lemma 4.8. The only difference rests in the need to decompose the domain of integration of (6.8) into four pieces: $A_1 = \{(t, s) \in \mathbb{R}_+^2 : t \leq t_0, s \leq t_0\}$, $A_2 = \{(t, s) \in \mathbb{R}_+^2 : t \leq t_0, s > t_0\}$, $A_3 = \{(t, s) \in \mathbb{R}_+^2 : t > t_0, s \leq t_0\}$ and $A_4 = \{(t, s) \in \mathbb{R}_+^2 : t > t_0, s > t_0\}$.

The estimate of the integration over A_4 follows verbatim the argument in Lemma 4.8, except that one then obtains (instead of equation (4.31))

$$\begin{aligned} & \int_{t_0}^{\infty} \int_{t_0}^{\infty} \frac{C_{p,q}(ts)^{n-1}}{(n-1)!^2 e^{[a-\sigma_\ell](t+s)+\min\{t,s\}\sigma_{p,q}}} \|h\|_{p,q,\ell,2} dt ds \\ & + \frac{C_{p,q}(|z|+1)}{(a-\sigma_\ell)^{2n}} \|h\|_{p-1,q+1,\ell,2}. \end{aligned} \quad (6.9)$$

The integral in (6.9) is estimated as follows.

$$\begin{aligned} & \int_{t_0}^{\infty} \int_{t_0}^{\infty} \frac{e^{-[a-\sigma_\ell](t+s)-\min\{t,s\}\sigma_{p,q}} (ts)^{n-1}}{(n-1)!^2} = 2 \int_{t_0}^{\infty} dt \int_t^{\infty} ds \frac{e^{-[a-\sigma_\ell](t+s)-t\sigma_{p,q}} (ts)^{n-1}}{(n-1)!^2} \\ & \leq \sum_{k=0}^{n-1} \frac{2}{(n-1)!k!} \int_0^{\infty} dt \frac{t^{n+k-1} e^{-(2a-2\sigma_\ell+\sigma_{p,q})t}}{(a-\sigma_\ell)^{n-k}} \\ & = 2 \sum_{k=0}^{n-1} \binom{n+k-1}{n-1} \frac{1}{(a-\sigma_\ell)^{n-k} (2a-2\sigma_\ell+\sigma_{p,q})^{n+k}} \\ & \leq 2(2a-2\sigma_\ell+\sigma_{p,q})^{-n} (a-\sigma_\ell)^{-n} \sum_{k=0}^{n-1} \binom{n+k-1}{n-1} \frac{(a-\sigma_\ell)^k}{(2a-2\sigma_\ell+\sigma_{p,q})^k} \\ & \leq (a-\sigma_\ell + \frac{\sigma_{p,q}}{2})^{-n} (a-\sigma_\ell)^{-n}. \end{aligned}$$

Similarly, the integrals over A_2, A_3 are bounded by

$$2 \int_0^{\infty} dt \int_0^{t_0} ds \frac{e^{-[a-\sigma_\ell](t+s)-s\sigma_{p,q}} (ts)^{n-1}}{(n-1)!^2} \leq \frac{C_{p,q} t_0^n}{(a-\sigma_\ell)^n n!} \leq \frac{C_{p,q}}{(a-\sigma_\ell + \frac{\sigma_{p,q}}{2})^{2n}},$$

provided $n \geq \frac{(a-\sigma_\ell + \frac{\sigma_{p,q}}{2})^2 t_0 e}{(a-\sigma_\ell)}$, by analogy with (4.30). The estimate of the integral over A_1 is treated similarly. $\square$

6.3 Tensor representation of the trace

Following the scheme of [45], we define a suitable delta like functional acting on $\tilde{\mathcal{B}}_2^{p,q,\ell}$ and we construct an approximation scheme for such a functional.

For each $f, g \in \Omega_r^\ell(M)$, we define

$$\delta_2^\ell(\pi_1^* f \wedge \pi_2^* g) \doteq \int_M \langle f, g \rangle_x \omega_M(x). \quad (6.10)$$

Such a definition extends by linearity and density to all sections in the closure of $\Omega_{2,r}^\ell(M)$ with respect to the C^r topology. Thus we obtain

$$\begin{aligned} \delta_2^\ell(h) &= \sum_{\alpha, \beta} \sum_{\bar{i}, \bar{j}} \int_M \psi_{\alpha, \beta}(x, x) h_{\bar{i}, \bar{j}}^{\alpha, \beta}(x, x) \langle \omega_{\alpha, \bar{i}}(x), \omega_{\beta, \bar{j}}(x) \rangle \omega_M(x) \\ &= \sum_{\alpha, \bar{i}} \int_M \psi_\alpha(x) h_{\bar{i}, \bar{i}}^{\alpha, \alpha}(x, x) \omega_M(x). \end{aligned} \quad (6.11)$$

Given κ_ε as in Definition D.1, we set $J_\varepsilon(x, y) = 0$ if $d(x, y) > \delta$, otherwise we set

$$J_\varepsilon(x, y) \doteq \sum_{\alpha, \bar{i}} \psi_\alpha(y) \cdot J\Theta_\alpha(y) \cdot \kappa_\varepsilon(\Theta_\alpha(x) - \Theta_\alpha(y)) \omega_{\alpha, \bar{i}}(x) \wedge \omega_{\alpha, \bar{i}}(y). \quad (6.12)$$

Lemma 6.4. *For each $h \in \Omega_{2,s}^\ell(M)$, $s < r$, we have that*

$$\lim_{\varepsilon \rightarrow 0} \langle J_\varepsilon, h \rangle_{\Omega(2\ell)} = \delta_2^\ell(h). \quad (6.13)$$

Proof. For $f, g \in \Omega_\infty^\ell(M)$, let $h = \pi_1^* f \wedge \pi_2^* g$, then

$$\begin{aligned} \lim_{\varepsilon \rightarrow 0} \langle J_\varepsilon, h \rangle_{\Omega(2\ell)} &= \int_{M^2} \langle J_\varepsilon, \pi_1^* f \wedge \pi_2^* g \rangle_{(x,y)} \omega_M(x) \wedge \omega_M(y) \\ &= \lim_{\varepsilon \rightarrow 0} \int_{M^2} \sum_{\alpha} \psi_\alpha(y) J\Theta_\alpha(y) \cdot \kappa_\varepsilon(\Theta_\alpha(x) - \Theta_\alpha(y)) \langle f, g \rangle_x \omega_M(x) \wedge \omega_M(y). \end{aligned}$$

The result follows, for h of the above form, by integrating with respect to y . We can extend this result to a generic h by linearity of the scalar product and by density (see footnote 36). $\square$

Next we need the equivalent of Lemma 3.10, the proof is omitted since it is exactly the same as before, starting from the space $\Omega_{2,r}^\ell(M)$ and choosing k appropriately.

Lemma 6.5. *There exists an injective immersion $j_2 : \tilde{\mathcal{B}}_2^{p,q,\ell} \rightarrow (\Omega_{2,r}^\ell(M))'$.*

Lemma 6.6. *The current δ_2^ℓ extends uniquely to an element of $(\tilde{\mathcal{B}}_2^{p,q,\ell})'$.*

Proof. Since $\tilde{\mathcal{B}}_2^{p,q,\ell}$ is defined by the closure of the sections in $\Omega_{2,r}^\ell$, it suffices to prove that there exists $c > 0$ such that $\delta_2^\ell(h) \leq c \|h\|_{p,q,\ell,2}$ for each $h \in \Omega_{2,r}^\ell$.

Let $W_D \doteq \{(x, y) \in M^2 : x = y\}$ and recall that δ_2^ℓ corresponds to integrating on such a manifold by (6.11). If $x \in U_\alpha$ we can foliate W_D , in the local chart V_α , with the manifolds $W_{\alpha, G_\varsigma} \in \tilde{\Sigma}$ given by the graph of the functions $G_\varsigma(x^s, y^u) = (x^s, y^u, \varsigma, x^s, y^u, \varsigma)$. Accordingly,

$$\delta_2^\ell(h) \leq \sum_{\alpha, \bar{i}} \int d\varsigma \left| \int_{W_{\alpha, G_\varsigma}} \langle \psi_\alpha(x) \omega_{\alpha, \bar{i}} \wedge \omega_{\alpha, \bar{i}}, h \rangle \right| \leq C_\# \|h\|_{0,q,\ell,2}. \quad \square$$

At this point, we would like to make sense of the limit of J_ε in $\tilde{\mathcal{B}}_2^{p,q,\ell}$. Unfortunately, this can be done only at a price.

Lemma 6.7. *For $\Re(z)$ sufficiently large, the sequence $R_2^{(\ell)}(z) \mathcal{L}_{t_0, t_0} J_\varepsilon$ is a Cauchy sequence in $\tilde{\mathcal{B}}_{+,2}^{p,q,\ell}$. We call $\bar{\delta}_2^\ell(z)$ the limit of such a sequence.*

Proof. Let us start by showing that the sequence is bounded in $\tilde{\mathcal{B}}_{+,2}^{0,q,\ell}$. Let $W_{\alpha, \beta, G} \in \Sigma_2(2, L_+)$ and $g \in \Gamma_{2,c}^{\ell,r}$, then by equations (A.4), (6.2) and (6.3) we have that

$$\begin{aligned} \int_{W_{\alpha, \beta, G}} \langle g, R_2^{(\ell)}(z) \mathcal{L}_{t_0, t_0} J_\varepsilon \rangle &= \int_{\mathbb{R}_+^2} ds dt e^{-z(t+s)} \int_{W_{\alpha, \beta, G}} J\phi_{-t-t_0}(x) \\ &\quad \times J\phi_{s+t_0}(y) \langle (*\phi_{t+t_0}^* \times \phi_{-s-t_0}^*)g, J_\varepsilon \rangle \circ \phi_{-t-t_0}(x) \times \phi_{s+t_0}(y). \end{aligned} \quad (6.14)$$

Note that, provided t_0 has been chosen large enough, the tangent spaces of the manifold $\phi_{-t-t_0} \times \phi_{s+t_0}(W_{\alpha, \beta, G})$ can be covered by manifolds in $\Sigma_2(1, L_0)$.

Let $\tilde{p} \in C^\infty(\mathbb{R}, \mathbb{R}_+)$, $\text{supp}(\tilde{p}) \subset (-\delta, \delta)$, $\tilde{p}(-t) = \tilde{p}(t)$, be such that $\sum_{n \in \mathbb{Z}} \tilde{p}(t + n\delta) = 1$ for all $t \in \mathbb{R}$. Let

$$\begin{aligned} F_{n,m}(x, y, t, s) &\doteq J\phi_{-t-t_0}(\phi_{n\delta+t_0}(x)) J\phi_{s+t_0}(\phi_{-m\delta-t_0}(y)) \\ &\quad \times \det \left(D(\phi_{-n\delta-t_0} \times \phi_{m\delta+t_0})|_{TW_{\alpha, \beta, G}} \right)^{-1} \circ \phi_{n\delta+t_0} \times \phi_{-m\delta-t_0}(x, y). \end{aligned}$$

By the change of variable $(x', y') \doteq \phi_{-n\delta-t_0} \times \phi_{m\delta+t_0}(x, y)$, (6.14) becomes

$$\begin{aligned} &\sum_{n,m \in \mathbb{N}} \int_{\mathbb{R}_+^2} ds dt \tilde{p}(-t + n\delta) \tilde{p}(s - m\delta) e^{-z(t+s)} \\ &\quad \times \int_{\phi_{-n\delta-t_0} \times \phi_{m\delta+t_0}(W_{\alpha, \beta, G})} F_{n,m} \cdot \langle (*\phi_{t+t_0}^* \times \phi_{-s-t_0}^*)g, J_\varepsilon \rangle \circ \phi_{-t+n\delta} \times \phi_{s-m\delta}. \end{aligned}$$

Note that if $(x, y) \in \phi_{-n\delta-t_0} \times \phi_{m\delta+t_0}(W_{\alpha,\beta,G})$ and $y \in \text{supp } \psi_\gamma$, then the integrand is different from zero only if $x \in U_\gamma$. Let $\{W_{\gamma,\gamma,k}\}_{K_{\gamma,n,m}} \subset \Sigma_2(1, L_0)$ be a covering of $\phi_{-n\delta-t_0} \times \phi_{m\delta+t_0}(W_{\alpha,\beta,G})$. Recalling equation (6.12), we can then rewrite the previous formula³⁹ by setting $t' = t - n\delta$, $s' = s - m\delta$. Thus we obtain

$$\begin{aligned} & \sum_{n,m \in \mathbb{N}} \sum_{\gamma \in \mathcal{A}, \bar{i} \in \mathcal{I}} \sum_{k \in K_{\gamma,n,m}} \int_{\mathbb{R}^2} ds' dt' \tilde{p}(t') \tilde{p}(s') e^{-z(t'+s'+(n+m)\delta)} \\ & \times \int_{W_{\gamma,\gamma,k}} F_{n,m}(x, y, t' + n\delta, s' + m\delta) \cdot \psi_\gamma \circ \phi_{s'}(y) J\Theta_\gamma \circ \phi_{s'}(y) \\ & \times \kappa_\varepsilon(\Theta_\gamma(\phi_{-t'}(x)) - \Theta_\gamma(\phi_{s'}(y))) \\ & \times \langle (*\phi_{t'+t_0+n\delta}^* \times \phi_{-s'-t_0-m\delta}^*)g, \omega_{\gamma,\bar{i}} \wedge \omega_{\gamma,\bar{i}} \rangle \circ \phi_{-t'} \times \phi_{s'}. \end{aligned} \quad (6.15)$$

Recall that the manifolds $\Theta_\gamma(W_{\gamma,\gamma,k})$ are graphs of the type⁴⁰

$$G_k(x^s, y^u) \doteq (x^s + \hat{x}^s, H^u(x^s, y^u), H^s(x^s, y^u), y^u + \hat{y}^u, H_1^0(x^s, y^u), H_2^0(x^s, y^u))$$

where, since $T\Theta_\gamma^{-1}(W_{\gamma,\gamma,k}) \in \mathcal{C}_{\frac{1}{2}}$, $\max\{\|\partial_x H^u\| + \|\partial_x H^s\|, \|\partial_y H^u\| + \|\partial_y H^s\|\} \leq \frac{1}{2}$. It is then natural to set $\bar{G}_k = \Theta_\gamma^{-1} \circ G_k$ and

$$\begin{aligned} \widehat{F}_{\gamma,n,m,k,\bar{i}}(x^s, y^u, s', t') &= F_{\gamma,n,m}(\bar{G}_k(x^s, y^u), t' + n\delta, s' + m\delta) \\ &\times [J\Theta_\gamma \cdot \psi_\gamma] \circ \Theta_\gamma^{-1}(G_k(x^s, y^u) + (0, 0, 0, s')) \\ &\times \langle (*\phi_{t'+t_0+n\delta}^* \times \phi_{-s'-t_0-m\delta}^*)g, \omega_{\gamma,\bar{i}} \wedge \omega_{\gamma,\bar{i}} \rangle \circ \Theta_\gamma^{-1}(G_k(x^s, y^u) + (0, 0, -t', s')). \end{aligned}$$

We can then continue our computation and write

$$\begin{aligned} & \sum_{n,m \in \mathbb{N}} \sum_{\gamma \in \mathcal{A}, \bar{i} \in \mathcal{I}} \sum_{k \in K_{\gamma,n,m}} \int_{\mathbb{R}^2} ds' dt' \tilde{p}(t') \tilde{p}(s') e^{-z(t'+s'+(n+m)\delta)} \\ & \times \int_{\mathbb{R}^{d-1}} dx^s dy^u \widehat{F}_{\gamma,n,m,k,\bar{i}}(x^s, y^u, t', s') \\ & \times \varepsilon^{-d} \kappa^{d-1}(\varepsilon^{-1}(x^s - H^s(x^s, y^u) + \hat{x}^s, H^u(x^s, y^u) - y^u - \hat{y}^u)) \\ & \times \kappa^1(\varepsilon^{-1}(H^{0,1}(x^s, y^u) - H^{0,2}(x^s, y^u) - t' - s')). \end{aligned} \quad (6.16)$$

³⁹ To be precise we should treat separately the terms with $n = 0$ or $m = 0$, but we leave this as an exercise for the reader since it is quite simple to handle, although a bit cumbersome.

⁴⁰ We drop the subscript n, m, γ, k from $\hat{x}, \hat{y}, H^u, H^s, H^{0,1}, H^{0,2}$ in the following equation since it is clear that such graphs depend on all these choices. Moreover we drop n, m, γ from G_k since it will always be clear which open set we are considering.

Note that we have $\|\widehat{F}\|_{C^0} \leq C_{\#}\|g\|_{C^0}$ as in equation (4.15). In addition, the map Ξ defined by

$$\begin{aligned}\xi &= x^s - H^s(x^s, y^u) + \hat{x}^s, \\ \eta &= H^u(x^s, y^u) - y^u - \hat{y}^u, \\ \tau &= -H^{0,1}(x^s, y^u) + H^{0,2}(x^s, y^u) + t' + s', \\ \varsigma &= s'\end{aligned}\tag{6.17}$$

is locally invertible, hence it can be used as a change of variables. Thus, setting $a = \Re(z)$, we can bound (6.16) by

$$\begin{aligned}\sum_{n,m \in \mathbb{N}} \sum_{\gamma \in \mathcal{A}} \sum_{k \in K_{\gamma,n,m}} C_z e^{-a(n+m)\delta} \|g\|_{C^0} &\leq C_z \sum_{n,m \in \mathbb{N}} e^{(h_{\text{top}}(\phi_1) - a)(n+m)\delta} \|g\|_{C^0} \\ &\leq C_z (a - h_{\text{top}}(\phi_1))^{-2} \|g\|_{C^0}.\end{aligned}$$

Which, taking the sup on the manifolds and test forms, yields

$$\left\| R_2^{(\ell)}(z) \mathcal{L}_{t_0, t_0}^{(\ell)} J_{\varepsilon} \right\|_{0, q, \ell, 2} \leq C_z (a - h_{\text{top}}(\phi_1))^{-2}.$$

Next, given $\varepsilon > \varepsilon' > 0$, by using equation (6.16), (6.17) and the intermediate value theorem we have, for $\Re(z)$ large enough,

$$\begin{aligned}&\left| \int_{W_{\alpha, \beta, G}} \langle g, R_2^{(\ell)}(z) \mathcal{L}_{t_0, t_0}^{(\ell)} J_{\varepsilon} - R_2^{(\ell)}(z) \mathcal{L}_{t_0, t_0}^{(\ell)} J_{\varepsilon'} \rangle \right| \\ &\leq C_{\#} \sum_{n,m \in \mathbb{N}} \sum_{\gamma \in \mathcal{A}, \bar{i} \in \mathcal{I}} \sum_{k \in K_{\gamma,n,m}} \int_{\mathbb{R}^{d+1}} d\xi d\eta d\tau d\varsigma e^{-z\{\tau + [H^{0,1} - H^{0,2}] \circ \Xi^{-1}(\xi, \eta, \tau, \varsigma) + (n+m)\delta\}} \\ &\quad \times [\mathbb{F}_{\gamma,n,m,k,\bar{i}}(\xi, \eta, t', s') - \mathbb{F}_{\gamma,n,m,k,\bar{i}}(0, 0, 0, s')] \cdot [\kappa_{\varepsilon}((\xi, \eta, t')) - \kappa_{\varepsilon'}((\xi, \eta, t'))] \\ &\leq C_{z,q} \varepsilon^{\min\{q,1\}} \|g\|_{C^q} (a - h_{\text{top}}(\phi_1))^{-2}\end{aligned}$$

where $\mathbb{F}_{\gamma,n,m,k,\bar{i}} = \widehat{F} \circ \Xi^{-1} \cdot J \Xi^{-1}$. Note that, as in (4.17), $\|\mathbb{F}_{\gamma,n,m,k,\bar{i}}\|_{C^q} \leq C_q$. This proves the Lemma for $\widetilde{\mathcal{B}}_2^{0,q,\ell}$. The extension to $\widetilde{\mathcal{B}}_2^{p,q,\ell}$ is treated similarly after integrating by parts p times. $\square$

We can finally present a description of the trace that does not involve any limit (although, unfortunately, not yet for the operators we are interested in).

Lemma 6.8. *For each $z \in \mathbb{C}$, $\Re(z)$ large enough, $n \in \mathbb{N}$ and $s, t \in \mathbb{R}_+$, we have that*

$$\delta_2^{(\ell)} \left(R_2^{(\ell)}(z)^n \mathcal{L}_{t,s}^{(\ell)} \bar{\delta}_2^{(\ell)}(z) \right) = \text{tr}^b(R^{(\ell)}(z)^{2n} \mathcal{L}_{t+s+2t_0}^{(\ell)}). \quad (6.18)$$

Proof. Let $\Re_n(z, s, t) \doteq \delta_2^{(\ell)} \left(R_2^{(\ell)}(z)^n \mathcal{L}_{t,s}^{(\ell)} \bar{\delta}_2^{(\ell)}(z) \right)$. From Lemmata 6.6, 6.7 and equation (6.11) we obtain

$$\begin{aligned} \Re_n(z, s, t) &= \lim_{\varepsilon \rightarrow 0} \sum_{\alpha, \bar{i}} \int_M \omega_M(x) \psi_\alpha(x) \left(R_2^{(\ell)}(z)^n \mathcal{L}_{t+t_0, s+t_0}^{(\ell)} J_\varepsilon \right)_{\bar{i}, \bar{i}}^{\alpha, \alpha}(x, x) \\ &= \lim_{\varepsilon \rightarrow 0} \sum_{\alpha, \beta, \bar{i}, \bar{j}} \int_{\mathbb{R}_+^2} ds' dt' \frac{(t' s')^{n-1} e^{-z(t'+s')}}{[(n-1)!]^2} \int_M \omega_M(x) \psi_\alpha(x) [\psi_\beta J \Theta_\beta] \circ \phi_{s'+s+t_0}(x) \\ &\quad \times \kappa_\varepsilon(\Theta_\beta(\phi_{-t'-t-t_0}(x)) - \Theta_\beta(\phi_{s'+s+t_0}(x))) \\ &\quad \times (-1)^{\ell(d-\ell)} \langle \phi_{-t'-t-t_0}^* \omega_{\beta, \bar{j}}, \omega_{\alpha, \bar{i}} \rangle_x \langle \omega_{\alpha, \bar{i}}, * \phi_{s'+s+t_0}^* * \omega_{\beta, \bar{j}} \rangle_x. \end{aligned}$$

Next, we sum over $\bar{i}$, α and use (A.4) to obtain

$$\begin{aligned} \Re(z, s, t) &= \lim_{\varepsilon \rightarrow 0} \sum_{\beta, \bar{j}} \int_{\mathbb{R}_+^2} ds' dt' \frac{(t' s')^{n-1} e^{-z(t'+s')}}{[(n-1)!]^2} \int_M [\psi_\beta J \Theta_\beta] \circ \phi_{s'+s+t_0}(x) \\ &\quad \times \kappa_\varepsilon(\Theta_\beta(\phi_{s'+s+t_0}(x)) - \Theta_\beta(\phi_{-t'-t-t_0}(x))) \\ &\quad \times J \phi_{s'+s+t_0} \langle \phi_{-t'-t-s'-s-2t_0}^* \omega_{\beta, \bar{j}}, \omega_{\beta, \bar{j}} \rangle \circ \phi_{s'+s+t_0}(x) \\ &= \lim_{\varepsilon \rightarrow 0} \sum_{\beta, \bar{j}} \int_{\mathbb{R}_+^2} ds' dt' \frac{(t' s')^{n-1} e^{-z(t'+s')}}{[(n-1)!]^2} \int_M \langle \omega_{\beta, \bar{j}}, \mathcal{L}_{t'+s'+t+s+2t_0}^{(\ell)} j_{\varepsilon, \beta, \bar{j}, x} \rangle, \end{aligned}$$

where, in the last line, we have changed variables and used (5.2). Next, after the change of variables $v = t' + s'$, $u = t'$, we integrate in u (the integral is given by the β -function) and recall (5.3) to obtain the statement of the Lemma. $\square$

At last we can start harvesting the benefits of the previous results. For fixed $p, q > 0$, $p+q < r-1$, by Lemma 6.3 we have $R_2^{(\ell)}(z) = P_2^{(\ell)}(z) + U_2^{(\ell)}(z)$ where $P_2^{(\ell)}(z)$ is a finite rank operator and the spectral radius of $U_2^{(\ell)}(z)$ is bounded by $(\Re(z) - \sigma_\ell + \frac{\sigma_{p,q}}{2})^{-2}$. Recall that by Lemma 4.8 we have $R^{(\ell)}(z) = P^{(\ell)}(z) + U^{(\ell)}(z)$ where $P^{(\ell)}(z)$ is a finite rank operator and the spectral radius of $U^{(\ell)}(z)$ is bounded by $(\Re(z) - \sigma_\ell + \sigma_{p,q})^{-1}$. In addition,

$$P^{(\ell)}(z)U^{(\ell)}(z) = U^{(\ell)}(z)P^{(\ell)}(z) = 0; \quad P_2^{(\ell)}(z)U_2^{(\ell)}(z) = U_2^{(\ell)}(z)P_2^{(\ell)}(z) = 0.$$

Lemma 6.9. *There exists $C_5 > 0$ such that, for each $t, s \in \mathbb{R}_+$, $n \in \mathbb{N}$ and $z \in \mathbb{C}$, $a = \Re(z) \geq C_5$, we have that*

$$\delta_2^{(\ell)} \left(P_2^{(\ell)}(z)^n \mathcal{L}_{t,s}^{(\ell)} \bar{\delta}_2^{(\ell)}(z) \right) = \text{tr} \left(P^{(\ell)}(z)^{2n} \mathcal{L}_{t+s+2t_0}^{(\ell)} \right). \quad (6.19)$$

Proof. Recalling (6.7) and (A.4) we can write, for $\Re(z)$ sufficiently large,

$$\begin{aligned} & \langle R_2^{(\ell)}(z)^n \mathcal{L}_{t+t_0, s+t_0}^{(\ell)} J_\varepsilon, \pi_1^*(f) \wedge \pi_2^*(g) \rangle_{\Omega(2\ell)} \\ &= \int_{\mathbb{R}_+^2 \times M^2} ds' dt' \frac{(t's')^{n-1}}{(n-1)!^2 e^{z(t'+s')}} \langle J_\varepsilon, \pi_1^*(\phi_{t'+t+t_0}^* f) \wedge \pi_2^*(\phi_{-s-s'-t_0}^* g) \rangle. \end{aligned} \quad (6.20)$$

By taking the limit $\varepsilon \rightarrow 0$, since the integrals are uniformly convergent with respect to time (as in equation (5.7), by a rough bound on the growth of the number of orbits), using Lemma 6.4 we obtain

$$\begin{aligned} R_2^{(\ell)}(z)^n \mathcal{L}_{t,s}^{(\ell)} \bar{\delta}_2^{(\ell)}(\pi_1^*(f) \wedge \pi_2^*(g)) &= \int_{\mathbb{R}_+^2 \times M} \frac{(t's')^{n-1} \langle \phi_{t'+t+t_0}^* f, \phi_{-s-s'-t_0}^* g \rangle}{(n-1)!^2 e^{z(t'+s')}} \\ &= (-1)^{\ell(d-\ell)} \int_{\mathbb{R}_+^2} ds dt \frac{(t's')^{n-1} e^{-z(t'+s')}}{(n-1)!^2} \int_M \langle f, \phi_{-s-t-s'-t'-2t_0}^* g \rangle \\ &= (-1)^{\ell(d-\ell)} \int_{\mathbb{R}_+} d\tau \int_0^1 d\eta \frac{\tau^{2n-1} \eta^{n-1} (1-\eta)^{n-1}}{(n-1)!^2 e^{z\tau}} \int_M \langle f, \phi_{-\tau-t-s-2t_0}^* g \rangle \\ &= (-1)^{\ell(d-\ell)} \int_{\mathbb{R}_+ \times M} d\tau \frac{\tau^{2n-1} \langle f, \phi_{-\tau-t-s-2t_0}^* g \rangle}{(2n-1)! e^{z\tau}} \\ &= (-1)^{\ell(d-\ell)} \langle f, R(z)^{2n} \mathcal{L}_{t+s+2t_0}^{(\ell)} g \rangle_{\Omega^\ell}, \end{aligned} \quad (6.21)$$

since the $d\eta$ integral in the third line is given by the β -function. By the von Neumann expansion, for $\Re(z)$ and $\Re(\xi)$ large enough, we have

$$(\xi \mathbb{1} - R_2^{(\ell)}(z))^{-1} \mathcal{L}_{t,s}^{(\ell)} \bar{\delta}_2^{(\ell)}(\pi_1^*(f) \wedge \pi_2^*(g)) = (-1)^{\ell(d-\ell)} \langle f, (\xi \mathbb{1} - (R(z)^{(\ell)})^2)^{-1} \mathcal{L}_{t+s+2t_0}^{(\ell)} g \rangle_{\Omega^\ell}.$$

Since both expressions are meromorphic in the region $\{|\xi| > (a - \sigma_\ell + \frac{\sigma_{p,q}}{2})^{-2}\}$, it follows that they must agree on such a region. Given a curve γ surrounding the region $\{|\xi| \leq (a - \sigma_\ell + \frac{\sigma_{p,q}}{2})^{-2}\}$, we can use standard functional analytic calculus (e.g., [37]) and recall Lemma 6.5 to obtain, for $h = \pi_1^* f \wedge \pi_2^* g$,

$$\begin{aligned} & \left\{ \left[U_2^{(\ell)}(z) \right]^m \mathcal{L}_{t,s}^{(\ell)} \bar{\delta}_2^{(\ell)} \right\} (h) = \frac{1}{2\pi i} \int_\gamma \xi^m \left(\xi \mathbb{1} - R_2^{(\ell)}(z) \right)^{-1} \mathcal{L}_{t,s}^{(\ell)} \bar{\delta}_2^{(\ell)}(h) d\xi \\ &= \frac{(-1)^{\ell(d-\ell)}}{2\pi i} \int_\gamma \xi^m \langle f, (\xi \mathbb{1} - R^{(\ell)}(z)^2)^{-1} \mathcal{L}_{t+s+2t_0}^{(\ell)} g \rangle_{\Omega^\ell} d\xi \\ &= \langle f, U^{(\ell)}(z)^{2m} \mathcal{L}_{t+s+2t_0}^{(\ell)} g \rangle_{\Omega^\ell}. \end{aligned}$$

Hence, we have

$$\left\{ \left[P_2^{(\ell)}(z) \right]^m \mathcal{L}_{t,s}^{(\ell)} \bar{\delta}_2^\ell \right\} (h) = \langle f, P^{(\ell)}(z)^{2m} \mathcal{L}_{t+s+2t_0}^{(\ell)} g \rangle_{\Omega^\ell}. \quad (6.22)$$

Since $P^{(\ell)}(z)^{2m}$ is a finite rank operator, it follows that $P^{(\ell)}(z)^{2m} \mathcal{L}_{t+s+2t_0}^{(\ell)} = \mathcal{L}_{t_0}^{(\ell)} P^{(\ell)}(z)^{2m} \mathcal{L}_{t+s+t_0}^{(\ell)}$ is also finite rank on $\mathcal{B}_{p,q,\ell}$. Thus there exist $u_{m,k} \in \mathcal{B}'_{-,p,q,\ell}$, $v_{m,k} \in \mathcal{B}_{+,p,q,\ell}$, $k \in \{1, \dots, L\}$ (see Lemma 4.5), such that

$$\langle f, P^{(\ell)}(z)^{2m} \mathcal{L}_{t+s+2t_0}^{(\ell)} g \rangle_{\Omega^\ell} = \sum_{k=1}^L \langle f, v_{m,k} \rangle_{\Omega^\ell} u_{m,k}(g).$$

Next, we define the mollification of an element $h \in \Omega_{2,s}^\ell$ by

$$\begin{aligned} \mathbb{M}_{2,\varepsilon}(h)(x, y) &= \sum_{\alpha, \beta} \sum_{\bar{i}, \bar{j}} \psi_\alpha(x, y) \psi_\beta(x, y) \omega_{\alpha, \bar{i}}(x) \wedge \omega_{\beta, \bar{j}}(y) \\ &\times \varepsilon^{-2d} \int_{\mathbb{R}^{2d}} \kappa_\varepsilon(\Theta_\alpha(x) - \xi) \kappa_\varepsilon(\Theta_\beta(y) - \eta) h_{\bar{i}, \bar{j}}^{\alpha, \beta}(\Theta_\alpha^{-1}(\xi), \Theta_\beta^{-1}(\eta)). \end{aligned} \quad (6.23)$$

By duality, we can define the mollificator $\mathbb{M}'_{2,\varepsilon}$ on the currents. Following the same reasoning as in Lemma D.2 we have that $\mathbb{M}'_{2,\varepsilon}$, restricted to $\mathcal{B}_2^{p,q,\ell}$, is a bounded operator which converges, in the sense of Lemma D.2, to the identity when $\varepsilon \rightarrow 0$.

A direct computation shows that $\mathbb{M}_{2,\varepsilon}(\pi_1^*(f) \wedge \pi_2^*(g)) = \pi_1^*(\mathbb{M}_\varepsilon f) \wedge \pi_2^*(\mathbb{M}_\varepsilon g)$, hence (6.22) implies

$$\mathbb{M}'_{2,\varepsilon} \left\{ \left[P_2^{(\ell)}(z) \right]^m \mathcal{L}_{t,s}^{(\ell)} \bar{\delta}_2^\ell \right\} (h) = \langle \mathbb{M}_\varepsilon f, P^{(\ell)}(z)^{2m} \mathcal{L}_{t+s+2t_0}^{(\ell)} \mathbb{M}_\varepsilon g \rangle_{\Omega^\ell}.$$

Note that the $\mathbb{M}'_{2,\varepsilon} \left\{ \left[P_2^{(\ell)}(z) \right]^m \mathcal{L}_{t,s}^{(\ell)} \bar{\delta}_2^\ell \right\} \in \mathcal{E}_s^{2\ell}$ for $s \leq p + q$. Thus its value on the product sections determines it uniquely as a $\mathcal{E}_{p+q}^{2\ell}$ current (see footnote 36). Accordingly, since $\mathbb{M}'_{2,\varepsilon} [P_2^{(\ell)}(z)]^m \mathcal{L}_{t,s}^{(\ell)} \bar{\delta}_2^\ell$ and $\sum_{k=1}^L \pi_1^*(\mathbb{M}'_\varepsilon v_{m,k}) \wedge \pi_2^*(\mathbb{M}'_\varepsilon u_{m,k})$ agree on each element of the type $\pi_1^*(f) \wedge \pi_2^*(g)$, they agree as currents. Thus, by Lemma 6.5, they are the same element of $\mathcal{B}_2^{p,q,\ell}$. Accord-

ingly, by Lemmata D.2, 6.6 and equation (6.10), we finally obtain that

$$\begin{aligned}
\delta_2 \left(P_2^{(\ell)}(z)^m \mathcal{L}_{t,s}^{(\ell)} \bar{\delta}_2^{(\ell)} \right) &= \lim_{\varepsilon \rightarrow 0} \delta_2 \left(\mathbb{M}'_{2,\varepsilon} P_2^{(\ell)}(z)^m \mathcal{L}_{t,s}^{(\ell)} \bar{\delta}_2^{(\ell)} \right) \\
&= \lim_{\varepsilon \rightarrow 0} \sum_{k=1}^L \delta_2 \left(\pi_1^* (\mathbb{M}'_{\varepsilon} v_{m,k}) \wedge \pi_2^* (\mathbb{M}'_{\varepsilon} u_{m,k}) \right) \\
&= \lim_{\varepsilon \rightarrow 0} \sum_{k=1}^L \langle \mathbb{M}'_{\varepsilon} v_{m,k}, \mathbb{M}'_{\varepsilon} u_{m,k} \rangle = \sum_{k=1}^L u_{m,k}(v_{m,k}). \quad \square
\end{aligned}$$

Thus we have reduced the computation of certain “flat trace” to that of a trace of a matrix. This suffices to obtain the same type of result for the operators we are interested in, at last.

Lemma 6.10. *For each $p + q < r - 1$, $z = a + ib \in \mathbb{C}$ with $a > C_5$, $\mu > (a - \sigma_{\ell} + \frac{\sigma_{p,q}}{2})^{-1}$, we have, for each $n \in \mathbb{N}$, that*

$$|\mathrm{tr}^b(R^{(\ell)}(z)^n) - \mathrm{tr}(P^{(\ell)}(z)^n)| \leq C_{p,q,z,\mu} \mu^n. \quad (6.24)$$

Proof. Lemma 6.8 yields, for all $n, m, k \in \mathbb{N}$, $|m - k| \leq C_{\#}$, the following ugly, but useful, formula

$$\begin{aligned}
&\int_{t_0}^{\infty} dt \int_{t_0}^{\infty} ds \frac{s^{m-1} t^{k-1} e^{-z(t+s)}}{(m-1)!(k-1)!} \delta_2^{(\ell)} \left(R_2^{(\ell)}(z)^n \mathcal{L}_{t-t_0, s-t_0}^{(\ell)} \bar{\delta}_2^{(\ell)} \right) \\
&= \int_{2t_0}^{\infty} dt \int_{t_0}^{t-t_0} ds \frac{s^{m-1} (t-s)^{k-1} e^{-zt}}{(m-1)!(k-1)!} \mathrm{tr}^b(R^{(\ell)}(z)^{2n} \mathcal{L}_t^{(\ell)}) \\
&= \mathrm{tr}^b(R^{(\ell)}(z)^{2n+m+k}) - \int_0^{2t_0} dt \frac{t^{m+k-1}}{(m+k-1)!} e^{-zt} \mathrm{tr}^b(R^{(\ell)}(z)^{2n} \mathcal{L}_t^{(\ell)}) \\
&\quad - 2 \int_{2t_0}^{\infty} dt \int_0^{t_0} ds \frac{s^{m-1} (t-s)^{k-1} e^{-zt}}{(m-1)!(k-1)!} \mathrm{tr}^b(R^{(\ell)}(z)^{2n} \mathcal{L}_t^{(\ell)}). \quad (6.25)
\end{aligned}$$

On the other hand by the spectral decomposition of R_2 , as in Lemma 6.3, and Lemma 6.9 it follows that, for each $\mu > \mu_1 > (a - \sigma_{\ell} + \frac{\sigma_{p,q}}{2})^{-1}$,

$$\begin{aligned}
&\int_{t_0}^{\infty} dt \int_{t_0}^{\infty} ds \frac{s^{m-1} t^{k-1} e^{-z(t+s)}}{(m-1)!(k-1)!} \delta_2^{(\ell)} \left(R_2^{(\ell)}(z)^n \mathcal{L}_{t-t_0, s-t_0}^{(\ell)} \bar{\delta}_2^{(\ell)} \right) \\
&= \int_{t_0}^{\infty} dt \int_{t_0}^{\infty} ds \frac{s^{m-1} t^{k-1} e^{-z(t+s)}}{(m-1)!(k-1)!} \delta_2^{(\ell)} \left(P_2^{(\ell)}(z)^n \mathcal{L}_{t-t_0, s-t_0}^{(\ell)} \bar{\delta}_2^{(\ell)} \right) + \mathcal{O} \left(\frac{C_{p,q,z,\mu_1} \mu_1^{2n}}{(a - \sigma_{\ell})^{m+k}} \right) \\
&= \int_{t_0}^{\infty} dt \int_{t_0}^{\infty} ds \frac{s^{m-1} t^{k-1} e^{-z(t+s)}}{(m-1)!(k-1)!} \mathrm{tr} \left(P^{(\ell)}(z)^{2n} \mathcal{L}_{t+s}^{(\ell)} \right) + \mathcal{O} \left(\frac{C_{p,q,z,\mu_1} \mu_1^{2n}}{(a - \sigma_{\ell})^{m+k}} \right)
\end{aligned}$$

Finally, recall again that the number of periodic orbits of length t grows at most exponentially. Hence, by Lemma 5.1, there exists $A \geq \sigma_\ell$ such that $|\mathrm{tr}^b(R^{(\ell)}(z)^{2n}\mathcal{L}_t^{(\ell)})| \leq C_\#(a-A)^{-2n}e^{At}$ while $|\mathrm{tr}(P^{(\ell)}(z)^{2n}\mathcal{L}_{t+s}^{(\ell)})| \leq C_\#(a-\sigma_\ell)^{-2n}e^{\sigma_\ell t}$. We can use such estimates to evaluate the integrals in (6.25) and obtain,

$$\begin{aligned} |\mathrm{tr}^b(R^{(\ell)}(z)^{2n+m+k}) - \mathrm{tr}(P^{(\ell)}(z)^{2n+m+k})| &\leq \frac{C_{p,q,z,\mu_1}\mu_1^{2n}}{(a-\sigma_\ell)^{m+k}} + \frac{C_\#t_0^m}{(a-A)^{2n+k}m!} \\ &\quad + \frac{C_\#(2t_0)^{m+k}}{(a-A)^{2n}(m+k)!}. \end{aligned}$$

To conclude we choose $m = \varsigma n$, $|m-k| \leq 1$. Note that the last two terms are smaller than μ^{2n+m+k} provided $n \geq \frac{C_\#et_0}{\varsigma(a-A)^{1+\frac{2}{\varsigma}}\mu^{2+\frac{2}{\varsigma}}}$, while the first term on the left is bounded by $C_\#\mu^{2n+m+k}$ provided we choose $\varsigma = \frac{\ln \mu \mu_1^{-1}}{\mu^{-1}(a-\sigma_\ell^{-1})}$. $\square$

7 Contact flows

The results of the previous sections suffice to prove that the ζ_{Ruelle} is meromorphic, yet they provide very little information on the location of its zeroes and poles. Such a knowledge is fundamental to extract information from the ζ functions (e.g. counting results or statistical properties of the flow). In section 8 we provide an approach to gain such information, partially inspired by [44], based on a Dolgopyat type estimate on the norm of the resolvent. We are not aware of a general approach to gain such estimates apart for the case of C^1 or Lipschitz foliations [21, 69, 70] and the case of *contact flows* ([42, 73]). In the following we will restrict to the latter since it covers the geometrically relevant case of geodesic flows in negative curvature. Our approach follows roughly [42, Section 6] but employs several simplifying ideas, some from [8], some new.

In the case of contact flows d must be odd, $d_u = d_s$ and we can, and will, assume that the contact form $\bar{\alpha}$ in coordinates reads (see [8, section 3.2, Appendix A] for details)

$$(\Theta_\beta^{-1})^*\bar{\alpha} = dx_d - \langle x^s, dx^u \rangle \doteq \alpha_0$$

where $(x^s, x^u, x_d) \in \mathbb{R}^{(d_s)} \times \mathbb{R}^{(d_s)} \times \mathbb{R} = \mathbb{R}^d$ is a point in the chart.

Remark 7.1. *The extra information that we need, and that can be gained in the contact flow case, are bounds on the size of the resolvent $R^{(d_s)}(z)$ for $\Im(z)$ large. See Lemma 8.3 for an explanation of why $\ell \neq d_s$ need not be studied. Since in the rest of this section we discuss only the case $\ell = d_s$ we will often drop the scripts d_s in the relevant objects.*

7.1 Dolgopyat's estimate

Let $a = \Re(z) > \sigma_{d_s}$ be fixed once and for all. For a fixed $C_6 \in (0, e^{-4})$, define $c_a \doteq C_6(a - \sigma_{d_s})^{-1}e^{-1}$ and

$$\widehat{R}_n(z)h = \int_{c_a n}^{\infty} dt e^{-zt} \frac{t^{n-1}}{(n-1)!} \mathcal{L}_t^{(d_s)} h.$$

Then, bounding $e^{-\sigma_{d_s} t} \|\mathcal{L}_t\|_{0,q,d_s}$ by one, integrating and using Stirling formula we have, for each $q > 0$,

$$\left\| (R^{(d_s)}(z)^n - \widehat{R}_n(z))h \right\|_{0,q,d_s} \leq C_{\#}(a - \sigma_{d_s})^{-n} C_6^n \|h\|_{0,q,d_s}. \quad (7.1)$$

Moreover, for $c_a n > t_0$, by Lemma 4.5 it follows that

$$\left\| \widehat{R}_n(z)h \right\|_{0,q,d_s} \leq C_{\#}(a - \sigma_{d_s})^{-n} \|h\|_{0,q,d_s}. \quad (7.2)$$

Thus, it is natural to start estimating the latter norm.

In the following arguments it turns out to be convenient to introduce norms similar to the one used in [42]. We did not use them in the previous sections since they do not allow to keep track of the higher regularity of the flow.

Definition 7.2. *We define norms $\|\cdot\|_q^s$ as with the norms $\|\cdot\|_{0,q,d_s}$ with the only difference that the set Σ is replaced by the set Σ^s , defined as the elements of Σ which are subsets of a strong stable manifold. Also, let $\mathcal{V}^u$ be the set of continuous vector fields tangent to the strong unstable direction, of C^0 -norm one, and C^1 when restricted to any unstable manifold.⁴¹ We then define $\|h\|^u \doteq \sup_{v \in \mathcal{V}^u} \|L_v h\|_{0,0,d_s}$. To conclude we define the norm $\|\cdot\|_q^* \doteq \|\cdot\|_q^s + \|\cdot\|^u$.*

⁴¹Note that such vector fields determine a unique flow on each unstable manifold, hence a unique global flow, even if they are only continuous on the manifold. Thus the corresponding Lie derivative is well defined.

Note that the unstable foliation can be trivialized by a Hölder continuous change of variables that is C^1 when restricted to any leaf. In such coordinates one can easily verify that (3.10) holds also in the present case by arguing as in Lemma 4.2.

Before starting the real work let us fix some notation and recall some facts. Let ϖ be the Hölder regularity of the strong foliations and ϖ^* the Hölder regularity of the Jacobian of the associated holonomy. Then, in the contact flow case, $\varpi \geq \frac{2\bar{\lambda}}{\lambda_+}$ and $\varpi^* \geq \frac{\bar{\lambda}}{\lambda_+}$ (see Appendix E for more details).

For a manifold $W \in \Sigma$ let $\widetilde{W} = \cup_{|t| \leq \delta} \phi_t W$, $\widetilde{W}_+ = \cup_{|t| \leq 2\delta} \phi_t W_+$. For each two sufficiently nearby manifolds $W, W' \in \Sigma$, let $H_{W,W'} : \widetilde{W}_+ \rightarrow \widetilde{W}'_+$ be the strong unstable holonomy, then $\|JH_{W,W'}\|_{C^{\varpi^*}} + \|H_{W,W'}\|_{C^{\varpi}} \leq C_{\#}$. We set $\hat{\varpi} = \frac{2\bar{\lambda}}{\lambda_+}$, $\varpi' = \min\{1, \hat{\varpi}\}$ and $\varpi_* = \min\{\bar{\lambda}/\lambda_+, \hat{\varpi}^2\}$.

Lemma 7.3. *For each $q \geq 1$, $\alpha \in \mathcal{A}$, $W, W' \in \Sigma_{\alpha}$ such that $H_{W,W'}(\widetilde{W}) \subset \widetilde{W}'_+$, $g \in \Gamma_c^{d_s, q}(\widetilde{W}')$, there exists $\bar{g} \in \Gamma_c^{d_s, \varpi_*}(\widetilde{W}'_+)$, $\|\bar{g}\|_{\Gamma_c^{d_s, \varpi_*}(\widetilde{W}')} \leq C_{\#} \|g\|_{\Gamma_c^{d_s, q}(\widetilde{W})}$, such that for all $h \in \Omega_r^{d_s}$ we have*

$$\left| \int_{\widetilde{W}} \langle g, h \rangle - \int_{\widetilde{W}'_+} \langle \bar{g}, h \rangle \right| \leq C_{\#} d(W, W') \|h\|^u \|g\|_{\Gamma_c^{d_s, q}(\widetilde{W})}.$$

Proof. Let $\{W_{\tau}^*\}_{\tau \in [0,1]}$ be a smooth foliation interpolating between $\widetilde{W}$ and $\widetilde{W}'$. Also let H_{τ} be the strong unstable holonomy from $\widetilde{W}$ to W_{τ}^* . Note that, by performing the interpolation in the chart Θ_{α} , one can ensure that there exists $W_{\tau} \in \Sigma_{\alpha}$ such that $W_{\tau}^* \subset \widetilde{W}_{\tau,+}$. Next, let φ_{τ} be a one parameter family of forms, then

$$\int_{W_{\tau}^*} \langle \varphi_{\tau}, h \rangle = \int_{\widetilde{W}} \langle \varphi_{\tau}, h \rangle \circ H_{\tau} JH_{\tau} = \sum_{\bar{i}} \int_{\widetilde{W}} \bar{\varphi}_{\tau, \bar{i}} h_{\bar{i}} \circ H_{\tau}.$$

where $\bar{\varphi}_{\tau, \bar{i}} = \varphi_{\tau, \bar{i}} \circ H_{\tau} JH_{\tau}$. By the implicit function theorem it follows that $\partial_{\tau} h_{\bar{i}} \circ H_{\tau} = (L_v h_{\bar{i}}) \circ H_{\tau}$ for some $v \in \mathcal{V}^u$, $\|v\|_{\infty} \leq C_{\#} d(W, W')$. In addition,

$$(L_v h)_{\bar{i}} = L_v h_{\bar{j}} + \sum_{\bar{j}} \langle \omega_{\alpha, \bar{i}}, L_v \omega_{\alpha, \bar{j}} \rangle h_{\bar{j}}.$$

Let $A_{\bar{i}, \bar{j}}(\tau) = \langle \omega_{\alpha, \bar{i}}, L_v \omega_{\alpha, \bar{j}} \rangle \circ H_{\tau}$ and note that A is C^r in τ .

$$\partial_{\tau} \int_{W_{\tau}^*} \langle \varphi_{\tau}, h \rangle = \sum_{\bar{i}} \int_{\widetilde{W}} \left\{ \partial_{\tau} \bar{\varphi}_{\tau, \bar{i}} - \sum_{\bar{j}} A_{\bar{j}, \bar{i}} \bar{\varphi}_{\tau, \bar{j}} \right\} h_{\bar{i}} \circ H_{\tau} + \bar{\varphi}_{\tau, \bar{i}} (L_v h)_{\bar{i}} \circ H_{\tau}.$$

We can then choose $\bar{\varphi}_{\tau,\bar{i}}$ as the solution of the ordinary differential equation (the variables on $\widetilde{W}$ are treated as parameters)

$$\begin{aligned}\frac{d}{d\tau}\bar{\varphi}_{\tau,\bar{i}} &= \sum_{\bar{j}} A_{\bar{j},\bar{i}}(\tau)\bar{\varphi}_{\tau,\bar{j}} \\ \bar{\varphi}_{0,\bar{i}} &= g_{\bar{i}}.\end{aligned}$$

By the dependence on the parameters of the solution of an ODE we have, for each $\tau \in [0, 1]$, $\|\bar{\varphi}_{\tau,\bar{i}}\|_{C^{\varpi'}} \leq C_{\#}\|g\|_{\Gamma_c^q}$. Hence, $\|\varphi_{\tau}\|_{\Gamma_c^{\varpi*}(W_{\tau}^*)} \leq C_{\#}\|g\|_{\Gamma_c^q(\widetilde{W})}$.

$$\begin{aligned}\left| \int_{\widetilde{W}'} \langle \varphi_1, h \rangle - \int_{\widetilde{W}} \langle g, h \rangle \right| &\leq \int_0^1 d\tau \left| \sum_{\bar{i}} \int_{\widetilde{W}} \bar{\varphi}_{\tau,\bar{i}}(L_v h)_{\bar{i}} \circ H_{\tau} \right| \\ &= \int_0^1 d\tau \left| \int_{W_{\tau}^*} \langle \varphi_{\tau}, L_v h \rangle \right| \leq C_{\#} d(W, W') \|h\|^u \|g\|_{\Gamma_c^{d_s,q}(\widetilde{W})}.\end{aligned}\tag{7.3}$$

□

Lemma 7.4. *For each $\eta \in (0, \varpi_*)$, $t \in (t_0, \infty)$ and $h \in \Omega_r^{d_s}$ we have*

$$\begin{aligned}\|h\|_{0,\eta,d_s} &\geq \|h\|_{\eta}^s, \\ \left\| \widehat{R}_n(z)h \right\|_{0,1+\eta,d_s} &\leq \frac{C_{\#}}{a - \sigma_{d_s}} \|h\|_{\eta}^*.\end{aligned}$$

Proof. The first inequality is obvious since the sup in the definition of the norm is taken on a larger set. To prove the second note that

$$\int_{W_{\alpha,G}} \langle g, \widehat{R}_n(z)h \rangle = \int_{c_a n}^{\infty} dt \int_{W_{\alpha,G}} \frac{t^{n-1} e^{-zt}}{(n-1)!} \langle g, \mathcal{L}_t^{d_s} h \rangle$$

which, by introducing a partition of unity in time as in (6.15) and changing variables as in (4.11), can be seen as an integral on $d_s + 1$ dimensional manifolds close to the weak stable foliation. If we consider the integral on a strong stable leaf close to $W_{\alpha,G}$ we can split it similarly and apply Lemma 7.3 to compare the integral on each manifold. The Lemma readily follows. □

We can now state the main estimate of this section. As the proof is a bit involved we postpone it at the end of the section so as not to break the flow of the argument.

Proposition 7.5 (Dolgopyat type estimate). *Let ϕ_t be a contact flow such that $\varpi' > \frac{2}{3}$. Then for each $\eta \in (0, \varpi_*)$, there exist constants $C_1, a_0, b_0 \geq 1$, $\lambda C_1 C_6 > 2ea_0$, and $\gamma_0 \in (0, 1)$ such that, for each $h \in \Omega_{0,1}^{d_s}(M)$, $z = a + ib$ with $2a_0 + \sigma_{d_s} \geq a \geq a_0 + \sigma_{d_s}$, $|b| \geq b_0$ and $n \geq C_1 \ln |b|$, we have*

$$\begin{aligned} \left\| \widehat{R}_n(z)h \right\|_{\eta}^* &\leq \frac{C_{\eta}}{(a - \sigma_{d_s})^n} \|h\|_{\eta}^*, \\ \left\| \widehat{R}_n(z)^3 h \right\|_{\eta}^* &\leq \frac{C_{\eta}}{(a - \sigma_{d_s})^{3n}} |b|^{-3\gamma_0} \|h\|_{\eta}^*. \end{aligned}$$

Remark 7.6. *The bunching condition in the statement of Proposition 7.5 arises as follows: in the Dolgopyat estimate one reduces the problem to comparing certain integrals over a multitude of nearby manifolds. They are usually broken into two sets: the one that are sufficiently far apart to allow for cancellations due to the non integrability of the foliations (this is the basic Dolgopyat cancellation mechanism) and the ones that are too close for the cancellation mechanism to be effective. The latter are shown to be too few to contribute to the total estimate. In Lemma 7.10 we give explicit meaning to “sufficiently far apart”, we believe this to be optimal. The remaining “too close” manifolds are handled in Lemma 7.9. The estimate is reduced to the growth rate of certain unstable disks that we can handle only if “too close” is small enough. This is due to the possibility for a disk to grow in an extremely elongated ellipses because of different expansion rates in the unstable directions. The two different meaning of “too close” are consistent only under the above mentioned bunching conditions. This is the only place where such a condition is used. It might be possible to improve Lemma 7.9, and hence remove the bunching condition, by cleverly using some distortion estimate but at the moment we do not see how.*

Remark 7.7. *The choice of stating the Lemma in terms of the norm $\|\cdot\|_{\eta}^*$ is a bit arbitrary but very convenient in the present context. The estimate is largely norm-independent as better shown in [8].*

The goal of this section easily follows.

Lemma 7.8. *If ϕ_t is a contact Anosov flow with $\varpi' > \frac{2}{3}$, then for each $\eta \in (0, \varpi_*)$, there exist constants $C_1, a_0, b_0 \geq 1$, $\lambda C_1 C_6 > 2ea_0$, such that for each $h \in \mathcal{B}^{1,\eta,d_s}$, $z = a + ib$ with $2a_0 + \sigma_{d_s} > a \geq a_0 + \sigma_{d_s}$, $|b| \geq b_0$, and $n \geq C_{\#} C_1 \ln |b|$, holds true*

$$\|R(z)^n h\|_{1,\eta,d_s} \leq C_{\eta} (a - \sigma_{d_s})^{-n} b^{-\gamma_0} \|h\|_{1,\eta,d_s}.$$

Proof. By Lemma 4.8 we have, for $m = \lceil C_1 \ln |b| \rceil$ where C_1 is given by Proposition 7.5,

$$\begin{aligned} \| \| R(z)^{(k+2)m} h \| \|_{1,\eta,d_s} &\leq \frac{C_{\#}}{(a - \sigma_{d_s})^{(k+1)m} (a - \sigma_{d_s} + \lambda)^m} \| \| h \| \|_{1,\eta,d_s} \\ &\quad + \frac{C_{\#} |b|}{(a - \sigma_{d_s})^m} \| \| R(z)^{(k+1)m} h \| \|_{0,1+\eta,d_s}. \end{aligned}$$

The first term is already small enough. By equations (7.1), (7.2)

$$\| \| R(z)^{(k+1)m} h \| \|_{0,1+\eta,d_s} \leq \frac{C_{\#} k C_6^m \| \| h \| \|_{0,1+\eta,d_s}}{(a - \sigma_{d_s})^{(k+1)m}} + \frac{C_{\#}}{a - \sigma_{d_s}} \| \| \widehat{R}_m(z)^k h \| \|_{0,1+\eta,d_s}.$$

The first term is small enough provided $\gamma_0 \leq C_1 \ln C_6^{-1} - 1 - \frac{\ln k}{\ln b_0}$. Accordingly, to establish the Lemma it suffices to prove, for some $k \in \mathbb{N}$,

$$\| \| \widehat{R}_m(z)^k h \| \|_{0,1+\eta,d_s} \leq C_{\eta} (a - \sigma_{d_s})^{-km} b^{-1-\gamma_0} \| \| h \| \|_{1,\eta,d_s}. \quad (7.4)$$

Note that $\| \| \widehat{R}_m(z) h \| \|_{+,1,\eta,d_s} \leq \frac{C_{\eta}}{a - \sigma_{d_s}} \| \| h \| \|_{-,1,\eta,d_s}$. Hence, by Lemmata D.2, 7.4 and Proposition 7.5 we have

$$\begin{aligned} \| \| \widehat{R}_m(z)^k h \| \|_{0,1+\eta,d_s} &\leq \frac{C_{\#} \varepsilon \| \| h \| \|_{1,\eta,d_s}}{(a - \sigma_{d_s})^{kn}} + C_{\#} \| \| \widehat{R}_m(z)^{k-1} \mathbb{M}_{\varepsilon} \widehat{R}_m(z) h \| \|_{0,1+\eta,d_s} \\ &\leq \frac{C_{\#} \varepsilon \| \| h \| \|_{1,\eta,d_s}}{(a - \sigma_{d_s})^{km}} + \frac{C_{\#}}{a - \sigma_{d_s}} \| \| \widehat{R}_m(z)^{k-2} \mathbb{M}_{\varepsilon} \widehat{R}_m(z) h \| \|_{\eta}^* \\ &\leq \frac{C_{\#} \varepsilon \| \| h \| \|_{1,\eta,d_s}}{(a - \sigma_{d_s})^{km}} + C_{\#} (a - \sigma_{d_s})^{-(k-1)m} |b|^{-(k-1)\gamma_0} \| \| \mathbb{M}_{\varepsilon} \widehat{R}_m(z) h \| \|_{\eta}^* \\ &\leq \frac{C_{\#} \varepsilon \| \| h \| \|_{1,\eta,d_s}}{(a - \sigma_{d_s})^{kn}} + C_{\#} (a - \sigma_{d_s})^{-km} |b|^{-(k-1)\gamma_0} \varepsilon^{-1-\eta-d_s} \| \| h \| \|_{1,\eta,d_s}, \end{aligned}$$

which, after choosing $\varepsilon = |b|^{-1-\gamma_0}$ and $k = C_{\#} \gamma_0^{-1}$, proves equation (7.4) and hence the Lemma. Indeed, the condition $\gamma_0 \leq C_1 \ln C_6^{-1} - 1 - \frac{\ln k}{\ln b_0}$ can be satisfied by choosing b_0 large enough. $\square$

We conclude with the missing proof.

Proof of Proposition 7.5. First note that, for each $v \in \mathcal{V}^u$, $L_v \phi_{-t}^* h = \phi_{-t}^* L_{(\phi_{-t})^* v} h$ and, by the Anosov property, $\| (\phi_{-t})^* v \|_{C^0} \leq C_{\#} e^{-\bar{\lambda} t} \| v \|_{C^0}$.

$$\| \mathcal{L}_t h \| ^u \leq C_{\#} e^{-\bar{\lambda} t} \sup_{v \in \mathcal{V}^u} \| \mathcal{L}_t (L_v h) \|_{0,0,d_s} \leq C_{\#} e^{(h_{\text{top}}(\phi_1) - \bar{\lambda}) t} \| h \| ^u. \quad (7.5)$$

Thus

$$\left\| \widehat{R}_n(z)h \right\|^u \leq C_{\#}(a - \sigma_{d_s} + \bar{\lambda})^{-n} \|h\|^u. \quad (7.6)$$

To continue note that the proof of Lemma 4.5 holds for the set of manifolds Σ^s , indeed the only required property of the set of manifolds is the fact that the image under the flow can be covered by manifolds in the set. Thus the first two inequalities of Lemma 4.5 hold for the norms $\|\cdot\|_{\eta}^s$. By the first

$$\left\| \widehat{R}_n(z)h \right\|_{\eta}^s \leq C_{\#}(a - \sigma_{d_s})^{-n} \|h\|_{\eta}^s,$$

which suffices to prove the first inequality of the Lemma. To prove the second is much harder. The second inequality in Lemma 4.5 can be used, as in Lemma 4.8, to yield

$$\left\| \widehat{R}_n(z)h \right\|_{\eta}^s \leq \frac{C_{\eta}}{(a - \sigma_{d_s} + \lambda\eta)^n} \|h\|_{\eta}^s + \frac{C_{\eta}}{(a - \sigma_{d_s})^n} \|h\|_{1+\eta}^s. \quad (7.7)$$

It is then sufficient to consider the case $h \in \Omega_{0,r}^{d_s}$, $g \in \Gamma_c^{\ell,1+\eta}$. In the following we will set $h_s = \mathcal{L}_s^{(\ell)} h$. It is convenient to proceed by small time steps of size $r > 0$, to be fixed later. Let $p(t) = \tilde{p}(\delta t)$ where $\tilde{p}$ is as in the proof of Lemma 6.7. For $n \in \mathbb{N}$ large enough, we must estimate (see (4.11))

$$\begin{aligned} \int_{c_{an}}^{\infty} dt \int_{W_{\alpha,G}} \frac{t^{n-1} e^{-zt}}{(n-1)!} \langle g, \phi_{-t}^* h_s \rangle &= \sum_{k \in \mathbb{N}} \int_{c_{an}}^{\infty} dt \frac{t^{n-1} e^{-zt} p(k - tr^{-1})}{(-1)^{\ell(d-\ell)} (n-1)!} \\ &\times \int_{\phi_{-kr} W_{\alpha,G}} \langle * \phi_t^* * g, h_s \rangle \circ \phi_{-t+kr} J_W \phi_{kr} J \phi_{-t} \circ \phi_{kr}. \end{aligned} \quad (7.8)$$

Next, it is convenient to localize in space as well. To this end we need to define a sequence of smooth partitions of unity.

For each $\mathbf{i} \in \mathbb{Z}^d$, let us define $x^{\mathbf{i}} = r d^{-\frac{1}{2}} \mathbf{i}$. We then introduce the partition of unity $\Phi_{r,\mathbf{i}}(x) = \prod_{l=1}^d p(d^{\frac{1}{2}} r^{-1} x_{i_l} - \mathbf{i}_l)$ (limited to the set $B_d(0, 30\delta)$). Note that it enjoys the following properties

- (i) $\Phi_{r,\mathbf{i}}(z) = 0$ for all $z \notin B_d(x_{\mathbf{i}}, r)$;
- (ii) the collection $\{B_d(x^{\mathbf{i}}, r)\}_{\mathbf{i} \in B_d(0, 10\delta)}$ covers $B_d(0, 30\delta)$ with a uniformly bounded number of overlaps;
- (iii) for each $r, \mathbf{i}$ we have $\|\nabla \Phi_{r,\mathbf{i}}\|_{L^\infty} \leq C_{\#} r^{-1}$.

Note that the collection in **(ii)** has a number of elements bounded by $C_{\#}r^{-d}$.

For each $k \in \mathbb{N}$ let $\mathcal{W}_{\alpha,G,\beta,kr}$ be the family of manifolds defined in (4.10), with $t = kr$, and set $\mathcal{W}_{\alpha,G,\beta,kr,\mathbf{i}} = \{W \in \mathcal{W}_{\alpha,G,\beta,kr} : \Theta_{\beta}(W) \cap B_d(x^{\mathbf{i}}, r) \neq \emptyset\}$. For simplicity, let us adopt the notation $\mathcal{W}_{k,\beta,\mathbf{i}} \doteq \mathcal{W}_{\alpha,G,\beta,kr,\mathbf{i}}$. For $W \in \mathcal{W}_{k,\beta,\mathbf{i}}$ let $\tau_W : \widetilde{W} \doteq \cup_{t \in [-2r, 2r]} \phi_t W \rightarrow \mathbb{R}$ be defined by $\phi_{\tau_W(x)}(x) \in W$. Also set

$$\varphi_{k,\beta,\mathbf{i}}(x) = \psi_{\beta}(x) \Phi_{r,\mathbf{i}}(\Theta_{\beta}(x)) p(r^{-1} \tau_W(x)) \|V(x)\|^{-1}. \quad (7.9)$$

Letting

$$\hat{g}_{k,\beta,\mathbf{i}} = \varphi_{k,\beta,\mathbf{i}} \frac{(kr + \tau_W)^{n-1} J_W \phi_{kr} \circ \phi_{\tau_W}}{(-1)^{\ell(d-\ell)} e^{-z(kr + \tau_W)} J \phi_{kr + \tau_W} (n-1)!} * \phi_{kr + \tau_W}^* * g, \quad (7.10)$$

we can rewrite (7.8) as⁴²

$$\int_{cn}^{\infty} dt \int_{W_{\alpha,G}} \frac{t^{n-1} \langle g, \phi_{-t}^* h_s \rangle}{e^{zt} (n-1)!} = \sum_{k,\beta,\mathbf{i}} \sum_{W \in \mathcal{W}_{k,\beta,\mathbf{i}}} \int_{\widetilde{W}} \langle \hat{g}_{k,\beta,\mathbf{i}}, h_s \rangle. \quad (7.11)$$

Recalling (4.17) and since the derivative of $\hat{g}_{k,\beta,\mathbf{i}}$ in the flow direction is uniformly bounded, we have

$$\|J_W \phi_{kr} \circ \phi_{\tau_W} (J \phi_{kr + \tau_W})^{-1} * \phi_{kr - \tau_W}^* * g\|_{\Gamma_c^{1+\eta}(\widetilde{W})} \leq C_{\#}. \quad (7.12)$$

For each $\beta, \mathbf{i}$ we choose the reference manifold $W_{\delta}^s(\Theta_{\beta}^{-1}(x^{\mathbf{i}})) \doteq \overline{W}_{\beta,\mathbf{i}} \in \Sigma^s$, and define $W_{\beta,\mathbf{i}} = \overline{W}_{\beta,\mathbf{i}} \cap \Theta_{\beta}^{-1}(B_d(x^{\mathbf{i}}, 2r))$ and $\widetilde{W}_{\beta,\mathbf{i}} = \cup_{t \in [-4r, 4r]} \phi_t(W_{\beta,\mathbf{i}})$. Let us set $H_{\widetilde{W}_{\beta,\mathbf{i}}, \widetilde{W}} \doteq H_{\beta,\mathbf{i},W}$. We can then rewrite the right hand side of (7.11) multiplied by $(-1)^{\ell(d-\ell)}$ as

$$\sum_{k,\beta,\mathbf{i}} \sum_{W \in \mathcal{W}_{k,\beta,\mathbf{i}}} \int_{\widetilde{W}_{\beta,\mathbf{i}}} \langle \hat{g}_{k,\beta,\mathbf{i},W}, h_s \rangle + \mathcal{O} \left(\frac{r^{1-\eta} (kr)^{n-1} e^{(\sigma_{d_s} - \lambda)s} \|h\|^u}{(n-1)! e^{(a - \sigma_{d_s})kr}} \right), \quad (7.13)$$

where $\hat{g}_{k,\beta,\mathbf{i},W}$ is given by Lemma 7.3 and we have used (7.5).⁴³ Then Lemma 7.3 and equations (7.9), (7.10), (7.12) imply

$$\|\hat{g}_{k,\beta,\mathbf{i},W}\|_{\Gamma_c^{\eta}(\widetilde{W}_{\beta,\mathbf{i}})} \leq C_{\#} r^{-\eta} \frac{(kr)^{n-1} e^{-akr}}{(n-1)!}. \quad (7.14)$$

⁴² First, for each $k \in \mathbb{N}$, perform the change change of variables $L_k : \mathbb{R} \times W \rightarrow \widetilde{W}$ defined by $L_k(t, y) = \phi_{-t+kr}(y)$ and then introduce the partition of unity in space. Note that this implies $t = kr - \tau_W(x)$. Also, note that the same manifold $\widetilde{W}$ appears several times. Yet, given the support of the functions, the value of the integral is the correct one.

⁴³ More precisely, rather than Lemma 7.3, we have used equation (7.3) and the fact that, in the present case, the support of φ_{τ} , in the flow direction, is contained in a strip of size $C_{\#}r$, which provides the extra factor r .

It is then natural to define

$$\mathfrak{g}_{k,\beta,\mathbf{i}} \doteq \sum_{W \in \mathcal{W}_{k,\beta,\mathbf{i}}} \hat{g}_{k,\beta,\mathbf{i},W}. \quad (7.15)$$

To conclude we need a sharp estimate for the sup norm of $\mathfrak{g}_{k,\beta,\mathbf{i}}$, this will follow from an L^2 estimate and the inequality⁴⁴

$$\int_{\widetilde{W}_{\beta,\mathbf{i}}} \|\mathfrak{g}_{k,\beta,\mathbf{i}}\|^2 \geq C_{\#} \|\mathfrak{g}_{k,\beta,\mathbf{i}}\|_{\Gamma_c^0}^{2+\frac{d_s+1}{\eta}} \|\mathfrak{g}_{k,\beta,\mathbf{i}}\|_{\Gamma_c^\eta}^{-\frac{d_s+1}{\eta}}.$$

Hence

$$\|\mathfrak{g}_{k,\beta,\mathbf{i}}\|_{\Gamma_c^0} \leq C_{\#} \|\mathfrak{g}_{k,\beta,\mathbf{i}}\|_{L^2(\widetilde{W}_{\beta,\mathbf{i}})}^{\mathfrak{p}} \|\mathfrak{g}_{k,\beta,\mathbf{i}}\|_{\Gamma_c^\eta}^{1-\mathfrak{p}}. \quad (7.16)$$

where we have set $\mathfrak{p} = \frac{2\eta}{2\eta+d_s+1}$. To compute the L^2 norm it is convenient to proceed as follows. Given $W \in \mathcal{W}_{k,\beta,\mathbf{i}}$ let $\{x_W\} \doteq \widetilde{W} \cap \Theta_\beta^{-1}(\{x^{\mathbf{i}} + (0, \eta)\}_{\eta \in B_{d_u}(0,r)})$ be its “central” point. Also, for each $\rho > 0$, consider the disks $\widetilde{D}_\rho^u(W) = \{\Theta_\beta(x_W) + (0, u, 0)\}_{u \in B_{d_u}(0,\rho)}$. Then, for a fixed $\varrho \in (0, r)$ to be chosen later, let $A_{k,\beta,\mathbf{i}}(W) = \{W' \in \mathcal{W}_{k,\beta,\mathbf{i}} : \Theta_\beta(\widetilde{W}') \cap \widetilde{D}_\varrho^u(W) \neq \emptyset\}$ and $B_{k,\beta,\mathbf{i}}(W) = \mathcal{W}_{k,\beta,\mathbf{i}} \setminus A_{k,\beta,\mathbf{i}}(W)$ and set

$$\begin{aligned} \mathfrak{G}_{k,\beta,\mathbf{i},A} &\doteq \sum_{W \in \mathcal{W}_{k,\beta,\mathbf{i}}} \sum_{W' \in A_{k,\beta,\mathbf{i}}(W)} \langle \hat{g}_{k,\beta,\mathbf{i},W}, \hat{g}_{k,\beta,\mathbf{i},W'} \rangle \\ \mathfrak{G}_{k,\beta,\mathbf{i},B} &\doteq \sum_{W \in \mathcal{W}_{k,\beta,\mathbf{i}}} \sum_{W' \in B_{k,\beta,\mathbf{i}}(W)} \langle \hat{g}_{k,\beta,\mathbf{i},W}, \hat{g}_{k,\beta,\mathbf{i},W'} \rangle, \end{aligned}$$

note that $\langle \mathfrak{g}_{k,\beta,\mathbf{i}}, \mathfrak{g}_{k,\beta,\mathbf{i}} \rangle = \mathfrak{G}_{k,\beta,\mathbf{i},A} + \mathfrak{G}_{k,\beta,\mathbf{i},B}$. We will estimate the two terms by separate arguments, the first being similar to [43, Lemma 6.2], the second being the equivalent of [43, Lemma 6.3].

To simplify the notation we set: $D_{k,\beta,\mathbf{i}} = \frac{(kr)^{n-1}e^{-ark}}{(n-1)!} \#\mathcal{W}_{k,\beta,\mathbf{i}}$, where by $\#A$ we mean the cardinality of the set A . Also, we assume

$$n \geq C_1 \ln |b| \quad (7.17)$$

where C_1 is a constant to be chosen large enough.

⁴⁴ To prove the inequality note that if $f : \mathbb{R}^\nu \rightarrow \mathbb{R}_+$ is a η -Hölder function and x_0 satisfies $f(x_0) = \|f\|_{C^0}$, then $f(x) \geq \|f\|_{C^0} - \|f\|_{C^\eta} |x_0 - x|^\eta$, thus $f(x) \geq \frac{1}{2}\|f\|_\infty$ for all $x \in B_\nu(x_0, \rho)$ where $\rho = [\|f\|_{C^0}(2\|f\|_{C^\eta})^{-1}]^{\frac{1}{\eta}}$.

Lemma 7.9. *If $C_{\#}|b|^{-\frac{\bar{\lambda}C_1C_6}{2ea_0}} \leq \varrho < \delta r^{(1+\varsigma)\frac{2}{\varpi}}$, for some $\varsigma > 0$, then there exists $\varsigma_0 > 0$ s.t.*

$$\|\mathfrak{G}_{k,\beta,\mathbf{i},A}\|_{\infty} \leq C_{\#} D_{k,\beta,\mathbf{i}}^2 r^{\varsigma_0}. \quad (7.18)$$

Proof. Note that the number of elements in $A_{k,\beta,\mathbf{i}}(W)$ must correspond to the number of intersections between $\cup_{t \in [-3\delta, 3\delta]} W_{\alpha,G}$ and $\phi_{kr}(D_{\varrho}^u(W))$. Since each intersection has a δ -neighborhood in $\phi_{kr}(D_{\varrho}^u(W))$ that cannot contain any other intersection we have $\#A_{k,\beta,\mathbf{i}}(W) \leq C_{\#} \text{vol}(\phi_{kr}(D_{2\varrho}^u(W)))$, provided that each point in $\phi_{kr}(D_{\varrho}^u(W))$ has a δ neighbourhood contained in $\phi_{kr}(D_{2\varrho}^u(W))$.

The latter condition is satisfied provided $C_{\#}|b|^{\frac{\bar{\lambda}C_6C_1}{2ea_0}} \varrho \geq \delta$, which is implied by the first hypothesis in the Lemma. On the other hand, by the mixing property,⁴⁵ a disk in $\phi_{kr}(D_r^u(W))$ with diameter larger than $C_{\#}$ must intersect $\cup_{t \in [-3\delta, 3\delta]} W_{\alpha,G}$, thus $\#\mathcal{W}_{k,\beta,\mathbf{i}} \geq C_{\#} \text{vol}(\phi_{kr}(D_{r/2}^u(W)))$. We are thus reduced to estimating the ratio of two volumes.

The simplest possible estimate is as follows: let $\bar{t} \in \mathbb{R}_+$ be such that $C_0 e^{\bar{\lambda}\bar{t}} r = r^{-\varsigma}$, now assume that $2e^{\lambda+\bar{t}} \varrho \leq \delta$. It follows that at time $\bar{t}$ the image of $D_{2\varrho}^u(W)$ is contained in a disk of radius δ while the image of $D_{r/2}^u(W)$ contains at least $C_{\#} r^{-\varsigma d_u}$ such disks. By Lemmata C.1 and C.3 such a ratio will persist at later times. Note that the above assumptions are verified only if $\varrho < \delta r^{(1+\varsigma)\frac{2}{\varpi}}$. $\square$

Lemma 7.10. *Setting $|b| = \varrho^{-2+\varpi'-2\varsigma}$ and $r = \varrho^{1-\varpi'+\varsigma}$, for $\varsigma > 0$, there exists $\gamma > 0$ such that*

$$\left| \int_{\widetilde{W}_{\beta,\mathbf{i}}} \mathfrak{G}_{k,\beta,\mathbf{i},B} \right| \leq C_{\#} b^{-6\gamma} r^{d_s+1} D_{k,\beta,\mathbf{i}}^2. \quad (7.19)$$

The proof of the above Lemma is postponed to Subsection 7.2.

Remark 7.11. *Note that the conditions of the two Lemmata can be simultaneously satisfied, by choosing C_1 large and ς small enough, only if $\varpi' > \frac{2}{3}$. In addition, since $\varpi' \leq 1$, ς must always be smaller than $\frac{\sqrt{3}-1}{2}$.*

Substituting in (7.16) the estimates given by (7.14), (7.18) and (7.19), we obtain that there exists $\gamma_0 \in (0, \gamma]$ such that

$$\|\mathfrak{g}_{k,\beta,\mathbf{i}}\|_{\Gamma_c^0} \leq C_{\#} D_{k,\beta,\mathbf{i}} |b|^{-3\gamma_0}. \quad (7.20)$$

⁴⁵Recall that a contact flow on a connected manifold is mixing, [38].

Next, we assume $s \geq c_a n$. Then, by (7.14) and (7.20) and arguing as in the proof of (4.19),⁴⁶ we can write the integral in (7.13) as⁴⁷

$$\left| \sum_{k,\beta,\mathbf{i}} \int_{\widetilde{W}_{\beta,\mathbf{i}}} \langle \mathbf{g}_{k,\beta,\mathbf{i}}, h_s \rangle \right| \leq C_{\#} \sum_{k,\beta,\mathbf{i}} D_{k,\beta,\mathbf{i}} (b^{-3\gamma_0} + e^{-\lambda\eta s} r^{-\eta}) \text{vol}(\phi_{-s} \widetilde{W}_{\beta,\mathbf{i}}) \|h\|_{\eta}^s.$$

Note that $\sum_{\mathbf{i}} \# \mathcal{W}_{k,\beta,\mathbf{i}} |\phi_{-s} \widetilde{W}_{\beta,\mathbf{i}}| \leq C_{\#} r \sum_{W \in \mathcal{W}_{\alpha,G,\beta,kr}} |\phi_{-s} W|$. Thus, by Lemma C.3 and Remark C.4,

$$\begin{aligned} \left| \sum_{k,\beta,\mathbf{i}} \int_{\widetilde{W}_{\beta,\mathbf{i}}} \langle \mathbf{g}_{k,\beta,\mathbf{i}}, h_s \rangle \right| &\leq C_{\#} \sum_k \frac{(kr)^{n-1} (|b|^{-3\gamma_0} + e^{-\lambda\eta s} r^{-\eta})}{(n-1)! e^{ark - \sigma_{d_s}(kr+s)}} r \|h\|_{\eta}^s \\ &\leq C_{\#} (a - \sigma_{d_s})^{-n} (|b|^{-3\gamma_0} + e^{-\lambda\eta s} r^{-\eta}) e^{\sigma_{d_s} s} \|h\|_{\eta}^s. \end{aligned} \quad (7.21)$$

Thus, by (7.11), (7.13), (7.21),

$$\left\| \widehat{R}_n(z)^2 h \right\|_{1+\eta}^s \leq \frac{C_{\#}}{(a - \sigma_{d_s})^{2n}} \left[\frac{r^{-\eta} \|h\|^u (a - \sigma_{d_s})^n}{(a - \sigma_{d_s} + \lambda\eta)^n} + |b|^{-3\gamma_0} \|h\|_{\eta}^s \right]. \quad (7.22)$$

Next, by (7.7), (7.22) and Lemma 7.10,

$$\begin{aligned} \left\| \widehat{R}_n(z)^3 h \right\|_{\eta}^s &\leq \frac{C_{\eta} \left\| \widehat{R}_n(z)^2 h \right\|_{\eta}^s}{(a - \sigma_{d_s} + \lambda\eta)^n} + \frac{C_{\eta}}{(a - \sigma_{d_s})^n} \left\| \widehat{R}_n(z)^2 h \right\|_{1+\eta}^s \\ &\leq \frac{C_{\eta}}{(a - \sigma_{d_s})^{3n}} \left[\frac{(a - \sigma_{d_s})^n |b|^{\frac{n}{2}}}{(a - \sigma_{d_s} + \lambda\eta)^n} + |b|^{-3\gamma_0} \right] \|h\|^*. \end{aligned} \quad (7.23)$$

The above, and (7.6), (7.17) imply the Lemma provided γ_0 has been chosen smaller than 40η . $\square$

7.2 A key (but technical) inequality

We are left with the task of proving (7.19).

⁴⁶ Namely, we use the first line of the equation before (4.19) with $g - g_{\varepsilon} = \mathbf{g}_{k,\beta,\mathbf{i}}$, $\varepsilon = 1$ and $q = \eta$.

⁴⁷ Note that, since $\mathbf{g}_{k,\beta,\mathbf{i}}$ is supported in $\widetilde{W}_{\beta,\mathbf{i}}$, the integral can also be seen as an integral on $\widetilde{W}_{\beta,\mathbf{i}} \in \Sigma^s$.

Proof of Lemma 7.10. This is the heart of Dolgopyat's estimate. Given $W \in \mathcal{W}_{k,\beta,\mathbf{i}}$ and $W' \in B_{k,\beta,\mathbf{i}}(W)$, we must estimate

$$\begin{aligned} \int_{\widetilde{W}_{\beta,\mathbf{i}}} \langle \hat{g}_{k,\beta,\mathbf{i},W}, \hat{g}_{k,\beta,\mathbf{i},W'} \rangle &= \int_{\widetilde{W}_{\beta,\mathbf{i}}} JH_{\beta,\mathbf{i},W} \cdot JH_{\beta,\mathbf{i},W'} \cdot \overline{\hat{g}_{k,\beta,\mathbf{i},\bar{i}}} \circ H_{\beta,\mathbf{i},W} \\ &\quad \times \hat{g}_{k,\beta,\mathbf{i},\bar{i}} \circ H_{\beta,\mathbf{i},W'}. \end{aligned} \quad (7.24)$$

It turns out to be convenient to write the above as an integral over $\widetilde{W}$. More precisely, let $\tilde{\vartheta}_W : B_d(0, \delta) \rightarrow \mathbb{R}^d$ be a flow box coordinate change preserving the contact form α_0 and such that, setting $\vartheta_W = \Theta_\beta^{-1} \circ \tilde{\vartheta}_W$, has the property that $\vartheta_W(\{(\xi, 0)\}_{\xi \in B_{d_s}(0, C_\# r)}) \subset W$ and, moreover, $\widetilde{W}$ contains the support (projected on via the unstable Holonomy) of the integrand.⁴⁸ We can then rewrite (7.24) as⁴⁹

$$\int_{\widetilde{W}_{\beta,\mathbf{i}}} \langle \hat{g}_{k,\beta,\mathbf{i},W}, \hat{g}_{k,\beta,\mathbf{i},W'} \rangle = \int_{B_{d_s+1}(0, 2r)} d\xi e^{-z(\tau_{W'} \circ \tilde{H}_{W'}(\xi) - \xi_d)} \mathcal{G}_{k,\beta,\mathbf{i},W,W',\bar{i}}(\xi), \quad (7.25)$$

where $\xi = (\tilde{\xi}, \xi_d)$, $\tilde{H}_{W'} = H_{\widetilde{W}, \widetilde{W}'} \circ \vartheta_W$, and

$$\begin{aligned} \mathcal{G}_{k,\beta,\mathbf{i},W,W',\bar{i}} &\doteq \left\{ \overline{\varphi_{k,\beta} \frac{(kr + \tau_W)^{n-1} e^{-akr}}{(n-1)!} \frac{J_W \phi_{kr} \circ \phi_{\tau_W}}{J \phi_{kr+\tau_W}} (*\phi_{kr+\tau_W}^* * g)_{\bar{i}}} \right\} \circ \vartheta_W \\ &\quad \times \left\{ \varphi_{k,\beta} \frac{(kr + \tau_{W'})^{n-1} e^{-akr}}{(n-1)!} \frac{J_{W'} \phi_{kr} \circ \phi_{\tau_{W'}}}{J \phi_{kr+\tau_{W'}}} (*\phi_{kr+\tau_{W'}}^* * g)_{\bar{i}} \right\} \circ \tilde{H}_{W'} \\ &\quad \times J\tilde{H}_{\beta,\mathbf{i},W'}. \end{aligned}$$

Let us define

$$\Delta^*(\xi) \doteq \tau_{W'} \circ \tilde{H}_{\beta,\mathbf{i},W'}(\xi) - \xi_d, \quad (7.26)$$

and note that $\Delta^*(\xi + \zeta) - \Delta^*(\xi)$ is exactly the so called *temporal function*.⁵⁰ We let $w(\xi) = (w^s(\xi), w^u(\xi), w_d(\xi)) = \vartheta_W^{-1} \circ \tilde{H}_{W'}(\xi) - (\xi, 0)$. Then by Lemma

⁴⁸ Such a coordinate change always exists, see [8, Lemma A.4].

⁴⁹ By Appendix E it follows that the image of W' on $\widetilde{W}$ by the unstable holonomy is strictly contained in a ball of radius $2r$, provided r is small enough.

⁵⁰ In the language of [43] (in which the role of the stable and unstable manifolds are reversed) $\Delta^*(\xi + \zeta) - \Delta^*(\xi) = \Delta(y, y')$, where $x = \vartheta_W(\xi)$, $y = \tilde{H}_{W'}(\xi)$ and $y' = \vartheta_W(\xi + (\tilde{\zeta}, 0))$ with $\zeta = (\zeta, \zeta_d)$.

E.2 we have⁵¹

$$\begin{aligned} |\Delta^*(\xi + \zeta) - \Delta^*(\xi) - d\alpha_0(w(\xi), \zeta)| &\leq C_{\#} \|w\|^2 \|\tilde{\zeta}\|^{\varpi'} + C_{\#} \|w\|^{\varpi'} \|\tilde{\zeta}\|^2 \\ &\quad + C_{\#} \|w\|^{1+\varpi'} \|\tilde{\zeta}\|^{1+\varpi'}. \end{aligned} \quad (7.27)$$

We are left with the task of performing the integral in the lefthand side of (7.25). The basic idea (introduced in [43]) is to integrate first in the direction $y_{\mathbf{i}} = \|w^u(0)\|^{-1}(w^u(0), 0)$. Note that $d\alpha_0(w(0), y_{\mathbf{i}}) = \|w^u(0)\|$ and, by the cone condition, $\|w^s\| \leq C_{\#} \|w^u\|$. Hence, by the Hölder continuity of the unstable foliation (detailed in Appendix E), for $\xi \in B_{d_s+1}(0, r)$,

$$d\alpha_0(w(\xi), y_{\mathbf{i}}) \geq C_{\#} \|w(\xi)\| \geq C_{\#} \varrho. \quad (7.28)$$

Next, we impose the condition

$$r = \varrho^{1-\varpi'+\varsigma} \quad (7.29)$$

for some, very small, $\varsigma > 0$. By Lemma E.1 we have that

$$\|w(\xi) - w(\xi + \zeta)\| \leq C_{\#} (\|w(\xi)\| \|\tilde{\zeta}\|^{\varpi'} + \|w(\xi)\|^{\varpi'} \|\tilde{\zeta}\|) \leq C_{\#} \varrho. \quad (7.30)$$

For each $\xi \in B_{d_s+1}(0, r)$, $\langle \xi, y_{\mathbf{i}} \rangle = 0$, we define $I_{\mathbf{i}}(\xi) = \{s \in \mathbb{R} : \xi + sy_{\mathbf{i}} \in B_{d_s+1}(0, r)\}$ and consider the integral

$$\left| \int_{I_{\mathbf{i}}(\xi)} ds e^{-z\Delta^*(\xi+sy_{\mathbf{i}})} \mathcal{G}_{k,\beta,\mathbf{i},W,W',\bar{\mathbf{i}}}(\xi + sy_{\mathbf{i}}) \right|. \quad (7.31)$$

It is then natural to divide the interval $I_{\mathbf{i}}(\xi)$ in subintervals $\{s_l, s_{l+1}\}_{l \in \mathbb{Z}}$ such that,

$$(s_{l+1} - s_l) d\alpha_0(w(\xi + s_l y_{\mathbf{i}}), y_{\mathbf{i}}) = 2\pi |b|^{-1}.$$

Let us set $\delta_l = s_{l+1} - s_l$ and $w_l = w(\xi + s_l y_{\mathbf{i}})$, then, recalling (7.28), we have

$$C_{\#} |b|^{-1} \leq \frac{\delta_l \|w_l\|}{2\pi} \leq C_{\#} |b|^{-1}. \quad (7.32)$$

Next, we must assume

⁵¹ It may be possible to improve this estimate by going forward or backward in time to the situation in which the two lengths are equal, but some non-obvious distortion estimate would have to play a role to ensure that the following “preferred” direction does not changes too wildly.

$$|b|^{-1} \leq r \varrho, \quad (7.33)$$

to insure that $I_i(\xi)$ contains at least one interval. Note that Lemma E.1 implies that $\|\tilde{H}_{W'}(\xi + y_i s_{l+1}) - \tilde{H}_{W'}(\xi + y_i s_l)\| \leq C_{\#} \max\{\delta_l, \|w_l\| \delta_l^{\varpi'}\}$. Hence⁵²

$$\begin{aligned} \sup_{|s-s_l| \leq \delta_i} |\mathcal{G}_{k,\beta,i,W,W',\bar{i}}(\xi + s y_i) - \mathcal{G}_{k,\beta,i,W,W',\bar{i}}(\xi + s_l y_i)| &\leq C_{\#} D_{n,k}^2 \\ &\times (r^{-1} \max\{\delta_l, \|w_l\| \delta_l^{\varpi'}\} + \delta_l^{\varpi_*} \|w_l\|) \end{aligned}$$

$$\text{where } D_{n,k} \doteq \frac{(kr)^{n-1} e^{-akr}}{(n-1)!}.$$

We can then bound (7.31) by

$$\begin{aligned} \sum_l \left| \int_{s_l}^{s_{l+1}} e^{-z[\Delta^*(\xi + s y_i) - \Delta^*(\xi + s_l y_i)]} \mathcal{G}_{k,\beta,i,W,W',\bar{i}}(\xi + s_l y_i) \right| \\ + C_{\#} D_{n,k}^2 \left(|b|^{-1} \|w_l\|^{-1} + |b|^{-\varpi'} \|w_l\|^{1-\varpi'} + \frac{\|w_l\|^{1-\varpi_*} r}{|b|^{\varpi_*}} \right). \end{aligned}$$

Next, equations (7.27), (7.32) yield

$$\begin{aligned} |\Delta^*(\xi + s y_i) - \Delta^*(\xi + s_l y_i) - (s - s_l) d\alpha_0(w_l, y_i)| &\leq C_{\#} \frac{\|w_l\|^{2-\varpi'}}{|b|^{\varpi'}} \\ &+ C_{\#} \frac{\|w_l\|^{\varpi'-2}}{|b|^2} + C_{\#} \frac{1}{|b|^{1+\varpi'}}. \end{aligned}$$

Recalling (7.29) and (7.30), we can continue our estimate of (7.31) as

$$\begin{aligned} C_{\#} \sum_l \left| \int_{s_l}^{s_{l+1}} ds e^{-z(s-s_l) d\alpha_0(w_l, y_i)} \mathcal{G}_{k,\beta,i,W,W',\bar{i}}(\xi + s_l y_i) \right| \\ + C_{\#} D_{n,k}^2 r \left(|b|^{-1} \varrho^{-1} r^{-1} + \frac{r^{1-\varpi_*}}{|b|^{\varpi_*}} + \frac{r^{2-\varpi'}}{|b|^{\varpi'-1}} + \frac{\varrho^{\varpi'-2}}{|b|} + \frac{r^{-\varpi'}}{|b|^{\varpi'}} \right). \end{aligned}$$

We remark that the integrals in the first line are all bounded by $C_{\#} |b|^{-1} \delta_l$. By the above equation, integrating in the remaining directions and letting⁵³

$$D_{k,n,\beta,i} \doteq D_{k,n} \# \mathcal{W}_{k,\beta,i} \text{ and } |b|^{-1} = \varrho^{2-\varpi'+2\varsigma}$$

⁵² We remark that $\|J\tilde{H}_{\beta,i,W'}(\xi) - J\tilde{H}_{\beta,i,W'}(\xi + \zeta)\| \leq C_{\#} \|w_l\| \|\zeta\|^{\varpi_*}$, see Appendix E.

⁵³ The choice for ϱ satisfies the constraints (7.33).

equation (7.25) yields

$$\left| \int_{\widetilde{W}_{\beta, \mathbf{i}}} \mathfrak{G}_{k, \beta, \mathbf{i}, B} \right| \leq C_{\#} D_{k, n, \beta, \mathbf{i}}^2 \left[\varrho^{\varpi' \varsigma} + \frac{1}{|b|^{\frac{\varpi'}{2}}} \right] r^{d_s+1} \leq C_{\#} D_{k, n, \beta, \mathbf{i}}^2 |b|^{-\frac{\varpi' \varsigma}{2-\varpi'+2\varsigma}} r^{d_s+1}.$$

which gives the required inequality. $\square$

8 Growth of ζ -functions

We start by showing that the estimates in section 7.1 imply a bound on the growth of the traces. To this end note that the previous results show that $\mathrm{tr}^b(R^{(d_s)}(z)^n)$, which is well defined for $\Re(z)$ large enough, equals a function meromorphic in $\Re(z) > \sigma_{d_s} - \frac{\sigma_{p,q}}{2}$, for each $0 < p + q < r - 1$. Since $\mathrm{tr}^b(R^{(d_s)}(z)^n)$ is independent on p, q , it can be extended as much as the condition $p + q < r - 1$ allows. It is then natural to use $\mathrm{tr}^b(R^{(d_s)}(z)^n)$ to also denote such an extension. Before getting to the point we need a refinement of equation (5.19) which holds only for $\ell = d_s$.

Lemma 8.1. *For each $a = \Re(z) > h_{top}(\phi_1)$ and $n \in \mathbb{N}$*

$$\left| \int_M \sum_{\alpha, \bar{i}} \langle \omega_{\alpha, \bar{i}}, R^{(d_s)}(z)^n j_{\varepsilon, \alpha, \bar{i}, x} \rangle_x - \sum_{\tau \in \mathcal{T}} \frac{\chi_{d_s}(\tau) \lambda(\tau)^{n-1} \lambda(\tau)}{(n-1)! \mu(\tau) e^{z\lambda(\tau)}} \right| \leq \frac{C_{\#} \varepsilon |z| n}{(a - \sigma_{d_s})^{n+1}} + \frac{C_{\#} |z| n}{(a - \sigma_{d_s} + \lambda)^{n+1}}.$$

Proof. We start by equation (5.16) with $s = 0$ and $\ell = d_s$ and then we look more in depth at the derivative of $F_{\alpha, \bar{i}, z}$. By formulae (5.5) and (5.18) we have

$$\sum_{\bar{i}} F_{\alpha, \bar{i}, z}(x, t) = \frac{t^{n-1}}{(n-1)!} e^{-zt} \psi_{\alpha}(x) \mathrm{tr}(\wedge^{d_s}(D_{\mathrm{hyp}} \phi_{-\lambda(\tau)}(x))).$$

To compute the trace is it convenient to do a linear change of variables in the zero section such that the periodic orbit is at zero and its stable and unstable substances are spanned by $e_1, \dots, e_{d_s}$ and $e_{d_s+1}, \dots, e_{d-1}$. Then, calling ω_i the dual base, we have that $\langle \omega_1 \wedge \dots \wedge \omega_{d_s}, D_{\mathrm{hyp}} \phi_{-\lambda(\tau)} \omega_1 \wedge \dots \wedge \omega_{d_s} \rangle$ gives exactly the stable Jacobian J_t^s of the map, while all the other terms in the trace are

smaller than $C_{\#}J_t^s e^{-\bar{\lambda}t}$. Note that this implies that $\sup_{\tau} \chi_{d_s}(\tau) \leq C_{\#}$. By the usual distortion estimates it follows that

$$\|\partial_{\zeta} J_t^s\|_{\infty} \leq C_{\#} \|J_t^s\|_{\infty} \leq C_{\#} |\det(\mathbf{1} - \Lambda_{\tau, \alpha, m}(0))|,$$

where we are using the coordinates defined in (5.9). By the above inequality and Sub-Lemma 5.5 we can obtain from equation (5.16) the improved estimated (with respect to equation (5.17))

$$\begin{aligned} \sum_{\alpha, \bar{i}, m, \tau \in \mathcal{T}_{\varepsilon}} \int_{-\delta}^{\delta} \frac{F_{\alpha, \bar{i}, z} \circ \tilde{\Theta}_{\alpha}^{-1} \circ \Xi_{\tau, \alpha, m}^{-1}(0, \xi_d, \lambda(\tau))}{|\det(\mathbf{1} - \Lambda_{\tau, \alpha, m}(0))|} \\ + \frac{\lambda(\tau)^{n-1}}{(n-1)!} \mathcal{O} \left(\varepsilon |z| e^{-a\lambda(\tau)} + |z| e^{-(a+\bar{\lambda})\lambda(\tau)} \right). \end{aligned} \quad (8.1)$$

Using [39, Theorem 18.5.7] we can bound the total error term in the above equation by

$$C_{\#} \varepsilon |z| n (a - h_{\text{top}}(\phi_1))^{-n-1} + C_{\#} |z| n (a + \bar{\lambda} - h_{\text{top}}(\phi_1))^{-n-1}.$$

The Lemma is then proven arguing exactly as at the end of Lemma 5.1. $\square$

Lemma 8.2. *There exists $a_0 \geq 1$ and $\tau_* > 0$ such that, for each $n \in \mathbb{N}$, $z \in \mathbb{C}$, $h_{\text{top}}(\phi_1) + 2a_0 \geq a = \Re(z) \geq h_{\text{top}}(\phi_1) + a_0$, $b = \Im(z) \notin [-1, 1]$,*

$$|\text{tr}^b(R^{(d_s)}(z)^n)| \leq C_{\#} |b| (a - \sigma_{d_s} + \tau_*)^{-n}.$$

Proof. Choose $\eta \in (0, \varpi_*)$ and consider $R^{(d_s)}(z) \in L(\tilde{\mathcal{B}}^{1, \eta, d_s}, \tilde{\mathcal{B}}^{1, \eta, d_s})$. Next, we establish the analogue of [44, Lemma 3.1]. By Lemmata 5.1 and 8.1 it follows, for each $\varepsilon < \varepsilon_0$,

$$\begin{aligned} |\text{tr}^b(R^{(d_s)}(z)^n)| &\leq C_{\#} \| \|R^{(d_s)}(z)^n\| \|_{1, \eta, d_s} \sup_{x \in M} \| \|j_{\varepsilon, \alpha, \bar{i}, x}\| \|_{1, \eta, d_s} + \frac{C_{\#} |z| \varepsilon n}{(a - \sigma_{d_s})^{n+1}} \\ &\quad + \frac{C_{\#} |z| n}{(a + \lambda - \sigma_{d_s})^{n+1}} \\ &\leq C_{\#} \varepsilon^{-C_{\eta}} \| \|R^{(d_s)}(z)^n\| \|_{1, \eta, d_s} + \frac{C_{\#} |z| \varepsilon n}{(a - \sigma_{d_s})^{n+1}} + \frac{C_{\#} |z| n}{(a + \lambda - \sigma_{d_s})^{n+1}} \end{aligned}$$

where, in the first line, we have used the usual trick of seeing, locally, the integral over M as an integral over a foliation made of elements of Σ . Next,

given $b \in \mathbb{R}$, $|b| \geq B$, let $z = a + ib$, $a = a_0 + \sigma_{d_s}$ and $c > 0$. Also, let $n_b = \lceil C_1 C_\# \ln |b| \rceil$ and write, for any $n \in \mathbb{N}$, $n = k_n n_b + r_n$, $r_n < n_b$. Lemmata 7.8, 4.8 imply

$$\begin{aligned} \|R^{(d_s)}(z)^n\|_{1,\eta,d_s} &\leq \frac{C_\eta^{k_n+1} |b|^{-\gamma_0 k_n}}{(a - \sigma_{d_s})^n} \leq \frac{|b|^{\gamma_0} e^{\frac{n}{C_1 C_\# \ln |b|} (\ln C_\eta - \gamma_0 \ln |b|)}}{(a - \sigma_{d_s})^n} \\ &\leq \frac{C_\eta |b|^{\gamma_0} e^{-\frac{n \gamma_0}{2 C_1 C_\#}}}{(a - \sigma_{d_s})^n}, \end{aligned} \quad (8.2)$$

where we have assumed $|b| \geq C_\eta^{\frac{2}{\gamma_0}} =: B$. Choosing ε depending on n by requiring $\varepsilon^{-C_\eta} e^{-\frac{n \gamma_0}{2 C_\# C_1}} = \varepsilon$ yields

$$|\mathrm{tr}^b(R^{(d_s)}(z)^n)| \leq C_\# (a - \sigma_{d_s})^{-n} |b| e^{-\frac{n \gamma_0}{3 C_1 C_\# (1+C_\eta)}} + C_\# |b| n (a + \lambda - \sigma_{d_s})^{-n}$$

implying the result for $|b| \geq B$. On the other hand, by Proposition 4.9, in the region $\{z \in \mathbb{C} : |\Im(z)| \leq B, h_{\mathrm{top}}(\phi_1) - 1 \leq \Re(z) \leq h_{\mathrm{top}}(\phi_1)\}$ there are only finitely many eigenvalues of $X^{(d_s)}$ and $h_{\mathrm{top}}(\phi_1)$ is the only eigenvalue on the line $\Re(z) = h_{\mathrm{top}}(\phi_1)$. Accordingly, there exists $\tau_0 > 0$ such that $\sigma(X^{(d_s)}) \cap \{z \in \mathbb{C} : |\Im(z)| \leq B, h_{\mathrm{top}}(\phi_1) - \tau_0 \leq \Re(z) < h_{\mathrm{top}}(\phi_1)\} = \emptyset$. By standard spectral theory it follows that, for $\tau_1 < \min\{\tau_0, \frac{1}{2a_0}\}$,

$$\|R^{(d_s)}(z)^n\|_{1,\eta,d_s} \leq C_\# (a + \tau_1 - \sigma_{d_s})^{-n}.$$

Using the above instead of (8.2) yields the results in the remaining region. $\square$

Lemma 8.3. *In the region $\{z \in \mathbb{C} : \Re(z) \in [h_{\mathrm{top}}(\phi_1) - \tau_*, \infty)\}$ ζ_{Ruelle} is non zero and has only a simple pole at $z = h_{\mathrm{top}}(\phi_1)$. Moreover, setting $D = \{z \in \mathbb{C} : \Re(z) \in [h_{\mathrm{top}}(\phi_1) - \tau_*, A] ; |\Im(z)| \geq 1\}$ we have*

$$\begin{aligned} |\zeta_{\mathrm{Ruelle}}(z)| &\leq C_\# e^{C_\# |z|} \quad \text{for all } z \in D \\ \left| \frac{d}{dz} \ln \zeta_{\mathrm{Ruelle}}(z) \right| &\leq C_\# |z| \quad \text{for all } z \in D. \end{aligned}$$

Proof. If τ_* is chosen small enough, then Proposition 2.12 implies that the determinants $\mathfrak{D}_\ell$, $\ell \neq d_s$, are analytic, bounded and non zero in the regions considered and hence, recalling equation (2.5), it suffices to study $\mathfrak{D}_{d_s}(z)$.

In view of Lemma 2.11 we start by studying $\tilde{\mathfrak{D}}_{d_s}(\xi - z, \xi)$. Fix $z_0 \in D$ and consider $\xi = a_0 + h_{\text{top}}(\phi_1) + i\Im(z_0)$. Then, recalling Lemma 5.1

$$\mathfrak{D}_{d_s}(z) = \mathfrak{D}_{d_s}(\xi) \tilde{\mathfrak{D}}_{d_s}(\xi - z, \xi) = \mathfrak{D}_{d_s}(\xi) \exp \left(- \sum_{n=1}^{\infty} \frac{(\xi - z)^n}{n} \text{tr}^b(R(\xi)^n) \right).$$

Note that $\mathfrak{D}_{d_s}(\xi)$ is uniformly bounded in z_0 . By Lemma 8.2 it follows that

$$|\mathfrak{D}_{d_s}(z_0)| \leq C_{\#} \exp \left(\sum_{n=1}^{\infty} \frac{|\Im(z_0)|(a_0 + h_{\text{top}}(\phi_1) - \Re(z_0))^n}{n(a_0 + \tau_*)^n} \right)$$

which is convergent provided $\Re(z_0) > h_{\text{top}}(\phi_1) - \tau_*$.

Next, by the same argument as above, the logarithmic derivative

$$\frac{d}{dz} \ln \mathfrak{D}_{d_s}(z) = \sum_{n=1}^{\infty} (\xi - z)^{n-1} \text{tr}^b(R(\xi)^n)$$

is bounded as claimed in the required domain. □

Appendices

A External Forms: a toolbox

In this appendix we collect, for the reader's convenience, some useful formulae. More details can be found in [36, Section 2]).

Given a Riemannian d dimensional manifold M , for each $x \in M$, $\ell \in \{0, \dots, d\}$ and $v_1, \dots, v_\ell, w_1, \dots, w_\ell \in T_x^*M$ we define⁵⁴

$$\langle v_1 \wedge \dots \wedge v_\ell, w_1 \wedge \dots \wedge w_\ell \rangle = \det(\langle v_i, w_j \rangle). \quad (\text{A.1})$$

Assuming bilinearity, the above formula defines uniquely a scalar product among ℓ -forms.

Let ω_M be the Riemannian volume form on M . We define a duality from ℓ to $d - \ell$ forms via (see [36, (2.1.6)])

$$\langle v, w \rangle \omega_M = (-1)^{\ell(d-\ell)} v \wedge *w = (-1)^{\ell(d-\ell)} w \wedge *v = *v \wedge w. \quad (\text{A.2})$$

⁵⁴ By duality the scalar product in T_x^*M induces a canonical scalar product in T_x^*M .

Since such a formula must hold for all ℓ -forms, the $(d - \ell)$ -forms $*w, *v$ are uniquely defined. The operator “ $*$ ” is the so called *Hodge operator*.

Note that if $\{dx_i\}$ is an orthogonal base of T_x^*M , then $\{dx_{\bar{i}} = dx_{i_1} \wedge \cdots \wedge dx_{i_\ell}\}$ is an orthonormal base of $\wedge^\ell T^*M$, where $\bar{i} = (i_1, \dots, i_\ell)$ is an ordered multi-index (i.e. $i_k < i_{k+1}$). Then

$$*dx_{\bar{i}} = \varepsilon(\bar{i}^c) dx_{\bar{i}^c}$$

where $\bar{i}^c$ is the ordered $(d - \ell)$ -multiindex such that $dx_{\bar{i}} \wedge dx_{\bar{i}^c} = \varepsilon(\bar{i}) \omega_M$ and $\varepsilon(\bar{i})$ is the sign of the permutation $\pi(1, \dots, d) = (i_1, \dots, i_\ell, i_1^c, \dots, i_{d-\ell}^c)$.

The above definitions and considerations imply the following equalities

$$\langle v, *w \rangle = (-1)^{\ell(d-\ell)} \langle *v, w \rangle ; \quad **v = (-1)^{\ell(d-\ell)} v ; \quad \langle *v, *w \rangle = \langle v, w \rangle. \quad (\text{A.3})$$

Note also that, for any smooth function f , $*(fw) = f * w$. It is also natural to define the scalar product

$$\langle v, w \rangle_{\Omega_\ell} \doteq \int_M \langle v, w \rangle_x \omega_M(x).$$

Next, consider a smooth diffeomorphism $F : M \rightarrow N$, for M, N Riemannian manifolds. Let $\det(DF)$ be determined by $F^* \omega_N = \det(DF) \omega_M$, then

$$\langle F^* v, w \rangle = (-1)^{(d-\ell)\ell} \det(DF) \cdot F^* \langle v, *(F^{-1})^* * w \rangle. \quad (\text{A.4})$$

To prove this, we just compute

$$\begin{aligned} \langle F^* v, w \rangle \omega_M &= ** F^* v \wedge *w = F^*(v \wedge ** (F^{-1})^* * w) \\ &= (-1)^{\ell(d-\ell)} F^*(\langle v, *(F^{-1})^* * w \rangle \omega_N) \\ &= (-1)^{\ell(d-\ell)} \det(DF) \cdot \langle v, *(F^{-1})^* * w \rangle \circ F \cdot \omega_M. \end{aligned}$$

In particular, letting $(F^*)'$ be defined by $\langle F^* f, g \rangle_{\Omega_\ell} = \langle f, (F^*)' g \rangle_{\Omega_\ell}$, we have

$$*(F^*)' = (F^{-1})^* *.$$

The above formulae yield a formula for the Lie derivative: let Z be a vector field and F_t the flow generated by Z . Then, by differentiating $F_t^* \langle v, w \rangle = \det(DF)^{-1} \langle F_t^* * v, * F_t^* w \rangle$ with respect to t at $t = 0$. It follows that

$$\begin{aligned} L_Z \langle v, w \rangle &= -\langle v, w \rangle \operatorname{div} Z + \langle L_Z(*v), *w \rangle + \langle v, L_Z w \rangle \\ &= -\langle v, w \rangle \operatorname{div} Z + (-1)^{d(d-\ell)} \langle *L_Z(*v), w \rangle + \langle v, L_Z w \rangle. \end{aligned} \quad (\text{A.5})$$

We will also be using the relation (see [1, Proposition 2.2.19] for the details)

$$L_Z F^* w = F^* L_{F_* Z} w. \quad (\text{A.6})$$

Let γV be a rescaling of the vector field V . Recall that, by definition, $X^{(\ell)} h \doteq \frac{d}{dt} \phi_{-t}^* h \big|_{t=0} = -L_V h$ for $h \in \Omega_s^\ell$. Hence for all $t \in \mathbb{R}$ and $h \in \Omega_{0,s}^\ell$, by the properties of Lie derivatives (for i_V as in Remark 3.9),

$$\begin{aligned} L_{\gamma V}(\mathcal{L}_t^{(\ell)} h) &= \gamma L_V(\mathcal{L}_t^{(\ell)} h) + d\gamma \wedge i_V(\mathcal{L}_t^{(\ell)} h) \\ &= -\gamma \frac{d}{ds} \phi_{-s}^*(\phi_{-t}^* h) \bigg|_{s=0} = -\gamma \mathcal{L}_t^{(\ell)}(X^{(\ell)} h). \end{aligned} \quad (\text{A.7})$$

B Orientability

Here we prove some simple facts about orientability of the invariant distributions for Anosov flows and discuss how to modify the arguments of this paper in the non orientable case. We believe some of the following results to be well known but we could not locate a simple reference, so we add them for the reader's convenience.

Lemma B.1. *For each geodesic flow on an orientable compact Riemannian manifold M_0 of negative sectional curvature, the unstable and stable distribution are orientable.*

Proof. We present the proof for the unstable distribution, the proof for the stable distribution being exactly the same by reversing time. Remember that the geodesic flow takes place in $M \doteq T_1 M$, the unitary tangent bundle. If we assume that M_0 is d dimensional, then M is $2d - 1$ dimensional and the unstable space is $d - 1$ dimensional.

Given a geodesic γ , let $(J, J') \in T(TM)$ be a Jacobi fields along it. We have then [20, Chapter 5.2]

$$\frac{D^2 J}{dt^2} + R(\gamma'(t), J(t))\gamma'(t) = 0$$

where $\frac{D}{dt}$ is the covariant derivative and R is the curvature tensor. Recall that $\frac{D}{dt} J = J'$ and that we can assume that both $J(t)$ and $J'(t)$ are perpendicular

to $\frac{d}{dt}\gamma(t)$. If we then define the quadratic form $Q(J, J') = \langle J, J' \rangle$, we have [20, chapter 3.3],⁵⁵

$$\begin{aligned} \frac{d}{dt}Q(J, J') &= \langle J', J' \rangle - \langle J, R(\gamma'(t), J(t))\gamma'(t) \rangle \\ &= \langle J', J' \rangle - K(\gamma'(t), J(t)) \|\gamma'(t) \wedge J(t)\|^2 > 0. \end{aligned}$$

This means that the cone $\{(J, J') \in T(TM) : Q(J, J') > 0\}$ is invariant under the flow, thus the unstable vectors must belong to such a cone. Given a point $q \in M_0$ and $(q, p) \in M$, let us consider the tangent space $T_{(q,p)}M$. Let $(\delta q, \delta p) \in E^u(q, p) \subset T_{(q,p)}M$. By the above discussion we have $\langle \delta q, p \rangle = \langle \delta p, p \rangle = 0$ and that $(0, \delta p) \in E^u$ implies $\delta p = 0$. Finally, let $E^{cu}(q, p) = \text{span}\{E^u(q, p), V\}$, where $V = (p, 0)$ is the vector field generating the geodesic flow. Accordingly, if we denote the canonical projection $\pi : M \rightarrow M_0$ defined by $\pi(q, p) = q$, we have that $\pi_* : E^{cu}(q, p) \rightarrow T_q M$ is an isomorphism. Indeed, if $(\delta q, \delta p) \in E^{cu}$, then we can write $\delta q = \beta p + \xi$ and $\delta p = \eta$, where $\beta \in \mathbb{R}$, and $(\xi, \eta) \in E^u$. Accordingly, if $\delta q = \pi_*(\delta q, \delta p) = 0$, then $\beta = 0$ and $\xi = 0$, which in turns imply $\eta = 0$.

To conclude note that since M_0 is orientable, then there exists a volume form ω on M_0 . But then $\bar{\omega} = i_V(\pi^*\omega)$ is a volume form on each E^u , therefore the bundle is orientable. $\square$

The above arguments remain true for more general flows (see [47, 46] for a discussion of appropriate invariant cones associated to contact flows or [76] for a slightly more general setting) but the result is false for some Anosov flows.⁵⁶ Yet, it is often possible to keep track of the orientation of an orbit by a simple multiplicative factor as follows.

Lemma B.2. *If the torsion of the first homology group of M does not contain factors of the type $\mathbb{Z}_{2^m}$, then there exists a smooth function $A : M \times \mathbb{R}_+ \rightarrow \mathbb{R}$ such that, for each closed orbit τ and $x \in \tau$,*

$$e^{\pi i A(x, \lambda(\tau))} = \epsilon(\tau).$$

⁵⁵ We let K denote the sectional curvature.

⁵⁶ For example consider the map $f : \mathbb{T}^2 \rightarrow \mathbb{T}^2$ defined by $f(x, y) = -A(x, y) \bmod 1$ where

$$A = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}.$$

One can then define a ceiling function τ and the associated suspension, and clearly the resulting flows is Anosov but the invariant distribution are non orientable.

Moreover, $A_t(\cdot) = A(\cdot, t)$ is a cocycle.

Proof. Consider the line bundle $\pi : \mathcal{F} \rightarrow M$ such that the fiber at $x \in M$ consists of the volume forms on $E^u(x)$. Let $\mathcal{F}_0 = \mathcal{F} \setminus \{(x, 0)\}_{x \in M}$, i.e. we have taken out the zero section. Hence, for each $x \in M$, $\pi^{-1}(x)$ has two connected component. Thus, for each $x \in M$, there exists a neighborhood $\mathcal{F}_0 \supset U \ni \pi^{-1}x$ and a continuous map $F : U \rightarrow \pi(U) \times \mathbb{Z}_2$ such that, for each $\bar{x} \in U$, $p \circ F(\bar{x}) = \pi(\bar{x})$, where $p(x, i) = x$, and $q(F(U)) = \mathbb{Z}_2$, where $q(x, i) = i$. This construction defines a double covering M_{or} of M . Given a cycle $\gamma : [0, 1] \rightarrow M$ we can then consider any lift $\tilde{\gamma}$ to M_{or} . Locally $\tilde{\gamma}$ will have the form $\tilde{\gamma}(t) = (\gamma(t), i(t))$, $i \in \mathbb{Z}_2$. We define then the degree map $\bar{d}(\gamma) = i(0) + i(1)$ which is well known to be a homotopy invariant. Accordingly, $\bar{d}$ depends only on the homology class of γ . In other words $\bar{d} \in H^1(M, \mathbb{Z}_2)$. We would like to show that $\bar{d} \in H^1(M, \mathbb{R})$.

Since $H_1(M, \mathbb{Z})$ is finitely generated it is isomorphic to $\mathbb{Z}^n \oplus \text{Tor}$. By the universal coefficient Theorem $H_1(M, \mathbb{R})$ is isomorphic to $\mathbb{R}^n$ while $H_1(M, \mathbb{Z}_2)$ is isomorphic to $\mathbb{Z}_2^{n+m}$ where m is the number of $\mathbb{Z}_{2^k}$ that are present in the torsion part. Thus by hypothesis $m = 0$. Next, it is known that the closed orbits of an Anosov map generate all $H_1(M, \mathbb{Z})$, [2]. Consider a set of closed periodic orbits $\Gamma = \{\gamma_i\}_{i \in \mathbb{N}}$ that generate $H_1(M, \mathbb{Z})$, hence they generate $H_1(M, \mathbb{Z}_2)$. We can thus consider a base $\Gamma_0 \subset \Gamma$ of $H_1(M, \mathbb{Z}_2)$. By the above discussion it is a base in $H_1(M, \mathbb{R})$ as well. We can then consider the dual base in $H^1(M, \mathbb{R})$. By De Rham cohomology such a base can be represented in terms of 1-forms. In conclusion, there exist closed 1-forms $\{w_\gamma\}_{\gamma \in \Gamma_0}$ such that, for each $\gamma, \gamma' \in \Gamma_0$, $\int_0^{\lambda(\gamma')} \phi_t^* w_\gamma(V)$ is one if $\gamma = \gamma'$ and zero otherwise. Finally, let

$$A(x, t) = \sum_{\gamma \in \Gamma_0} \bar{d}(\gamma) \int_0^t \phi_s^* w_\gamma(V(x)) ds.$$

Note that A is an additive cocycle with respect to the flow ϕ_t . Moreover, if τ is a closed orbit and $x \in \tau$, $A(x, \lambda(\tau)) \bmod 2 = \bar{d}(\tau)$. The Lemma follows since $\epsilon(\tau) = e^{\pi i \bar{d}(\tau)}$. $\square$

In the hypothesis of the above Lemma we can define, instead of (2.9), the operator

$$\mathcal{L}_t^{(\ell)}(h) = e^{\pi i A_t} \phi_{-t}^* h. \quad (\text{B.1})$$

The study of such an operator can be carried out in complete analogy with

what we have done in sections 4, 5, 6 (at the price of slightly heavier notation).⁵⁷

If the hypothesis of Lemma B.2 does not apply, then one can still introduce an appropriate weight, but this creates some difficulties that can be solved only by introducing a more sophisticated Banach space. The basic idea is to consider the action of ϕ_t^* also on an orientation bundle. This would be simple enough, but in so doing the action of the flows on such a bundle produces a multiplicative factor proportional to the stable Jacobian. To eliminate such an unwanted multiplicative factor it is then necessary to consider a transfer operator with a weight given exactly by the inverse of the stable Jacobian.⁵⁸ Yet, this solution produces another problem: in general such a weight is only Hölder, hence the resulting operator does not act properly on spaces of smooth functions, a property essential to obtain large domains of analyticity for the zeta function. To overcome this last obstacle in the present setting one has to change the Banach space. This can be done as in [31].

Let $\mathcal{G}$ be the Grassmannian of d_s dimensional subspaces of the tangent bundle. Next, consider the fiber bundle $\mathcal{E} := \{(x, E, h, \omega) : (x, E) \in \mathcal{G}, h \in \bigwedge^\ell \mathcal{T}_x^* M, \omega \in \bigwedge^{d_s} E'\}$, $\pi : \mathcal{E} \rightarrow \mathcal{G}$ given by $\pi(x, E, h, \omega) = (x, E)$. The fibers consist of an ℓ -form times a volume form (hence an orientation) on the subspace. We can then consider the vector space $\mathcal{S}$ of the C^{r-1} sections of the bundle $\mathcal{E}$. This generalizes the space Ω_r^ℓ . Given $(h, \omega) \in \mathcal{S}$, $g \in \Omega_r^\ell$ and $W_{\alpha, G} \in \Sigma$ we can then define the integral

$$\int_{W_{\alpha, G}} \langle g, h \rangle \omega = \int_{\mathbb{R}^{(d_s)}} \langle g(G_\alpha(\xi)), h(G_\alpha(\xi), E_{G_\alpha}) \rangle G_\alpha^* \omega$$

where $G_\alpha \doteq \Theta_\alpha^{-1} \circ G$ and $E_{G_\alpha} = DG_\alpha(\mathbb{R}^{(d_s)})$. We can then use the above to define the analogue of the functional $J_{\alpha, G, g, v_1, \dots, v_p}$ in section (3.11) and then construct the norms in the same way. The transfer operator is then the canonical action of the flow on $\mathcal{S}$ with a weight given by the Jacobian of the flow restricted to the element of the Grassmanian. Note that one obtains an operator of the type considered in [31, equation (3.1)]. Accordingly, all the present arguments can be repeated in complete analogy, although one must

⁵⁷ The computations are essentially the same. In Section 4, 6, 7 one obtains the same bounds for the spectrum, while in Section 5 keeping track of the cocycle yields the required factor $\epsilon(\tau)$.

⁵⁸ The interested reader can consult Fried [27, Section 6] for a thorough explanation.

compute in the more sophisticated way explained in [31].⁵⁹

As the present paper is already quite technical, we decided not to go into such a more sophisticated construction as, on the one hand, it does not add any new idea, and on the other it would make the presentation much harder to follow. Nevertheless, all the results presented here can be generalized by using such an approach.

C Topological Entropy and volume growth

It is well known that there is a relation between asymptotic volume growth of manifolds and the topological entropy (see [77, 29, 50] and references therein). Unfortunately, here we need a uniform upper and lower bound for all times. We are not aware of such bounds for flows in the literature. For Axiom A diffeomorphisms they can be obtained in great generality from the results in [31].⁶⁰ It is clear that applying the same strategy to the present setting of flows similar results can be obtained. Yet, since we are interested only in the topological entropy and not in an arbitrary potential, a more elementary approach is available.

Let us proceed in slightly greater generality than needed, since it can be done at no extra cost. Let M be a Riemannian manifold and (M, f) a partially hyperbolic diffeomorphism. Call E^s, E^u, E^c the stable, unstable and central distribution respectively. Let d_s be the dimension of E^s .

Assume that, for each $n \in \mathbb{N}$, $\|Df^n|_{E^c}\| + \|Df^{-n}|_{E^c}\| \leq C_\#$.

A set $S \subset M$ is called (ε, n) -separated if for each $x, y \in S$ we have that $d_{f,n}(x, y) > \varepsilon$ where $d_{f,n}(x, y) = \max_{0 \leq k \leq n} d(f^k(x), f^k(y))$. Let $\mathcal{S}(f, \varepsilon, n)$ be the set of all (ε, n) -separated sets. We then define $N(f, \varepsilon, n) = \sup_{S \in \mathcal{S}(f, \varepsilon, n)} \#S$.

It is well known that, [39],

$$h_{\text{top}}(f) = \lim_{\varepsilon \rightarrow 0} \lim_{n \rightarrow \infty} \frac{\ln N(f, \varepsilon, n)}{n}.$$

⁵⁹ To be precise, in [31] there are no ℓ -forms, but the point of the present paper is exactly that functions and ℓ -forms can be handled by essentially the same computations once the proper machinery has been set up.

⁶⁰ Indeed, in [31] it is shown in particular that, given a mixing Axiom A diffeomorphism (M, f) , the spectral radius of a transfer operator with potential $\bar{\phi}$ satisfies, for each manifold $W \in \Sigma$, $C_\# e^{P(\bar{\phi})n} \leq \left| \int_W e^{\sum_{k=0}^{n-1} \bar{\phi} \circ f^k} \right| \leq C_\# e^{P(\bar{\phi})n}$, where $P(\bar{\phi})$ is the pressure associated to the potential, see [31, equations (3.3), (4.10), Lemma 4.7, Theorem 5.1.].

Moreover since if $\varepsilon' > \varepsilon$, then $N(f, \varepsilon, n) \geq N(f, \varepsilon', n)$. Thus, for each $\delta > 0$,

$$h_{\text{top}}(f) \geq \lim_{n \rightarrow \infty} \frac{\ln N(f, \delta, n)}{n}. \quad (\text{C.1})$$

Fix $\delta > 0$ and let $\widehat{\Sigma}$ be the set of all C^1 , d_s -dimensional manifolds of radius δ and tangent space close to E^s . Let us define

$$\rho_n^+ = \sup_{W \in \widehat{\Sigma}} \text{vol}(f^n W) \quad ; \quad \rho_n^- = \inf_{W \in \widehat{\Sigma}} \text{vol}(f^n W).$$

Lemma C.1. *For all $n, m \in \mathbb{N}$,*

$$\rho_{n+m}^- \geq C_{\#} \rho_n^- \rho_m^-; \quad \rho_{n+m}^+ \leq C_{\#} \rho_n^+ \rho_m^+.$$

In addition, if f is topologically transitive,

$$\rho_n^+ \leq C_{\#} \rho_n^-.$$

Proof. To prove the first equation consider $f^n(W)$ and chose a set $\mathcal{W}_n \doteq \{W_i\} \in \widehat{\Sigma}$ such that $W_i \subset f^n(W)$, $W_i \cap W_j = \emptyset$ and the cardinality of $\mathcal{W}_n$ is maximal. Then $\#\mathcal{W}_n \geq C_{\#} \text{vol}(f^n(W))$. Thus

$$\text{vol}(f^{n+m}(W)) \geq \sum_{W' \in \mathcal{W}_n} \text{vol}(f^m(W')) \geq C_{\#} \rho_n^- \rho_m^-$$

and the result follows taking the inf on W . The second inequality is proven similarly by taking a minimal cover of $f^n(W)$.

Let us prove the last inequality. By topological transitivity for each $\varepsilon > 0$ there exists $n_{\varepsilon} \in \mathbb{N}$ such that given any two ball B, B' of radius ε , there exists $n \leq n_{\varepsilon}$ such that $f^n(B) \cap B' \neq \emptyset$.⁶¹ Let $\bar{n} = n_{\delta}$.

Next, for each $n \in \mathbb{N}$ there exists $W_n \in \widehat{\Sigma}$ such that $\text{vol}(f^{n-\bar{n}}(W_n)) \geq \frac{1}{2} \rho_{n-\bar{n}}^+$. Let $x \in W_n$ and B an open ball centered at x and of radius $c\delta$ for some fixed $c \in (0, 1)$ to be chosen later. Given any $W \in \widehat{\Sigma}$ let $z \in W$ and B' a ball of radius $c\delta$ centered at z . By the above arguments there exists $m \leq \bar{n}$, such that $f^m(B') \cap B \neq \emptyset$. Given that the stable and unstable

⁶¹ Take $S \in \mathcal{S}(f, 0, \varepsilon/4)$ with maximal cardinality. Then $\cup_{x \in S} B(x, \varepsilon) \supset M$, where $B(x, \varepsilon)$ is a ball (in the Riemannian metric) of radius ε and center x . Then for each $x, y \in S$ there exists $n_{x,y} \in \mathbb{N}$ such that $f^{n_{x,y}}(B(x, \varepsilon/4)) \cap B(y, \varepsilon/4) \neq \emptyset$. The claim follows since any ball B of radius ε must contain a point $x \in S$ such that $B(x, \varepsilon/4) \subset B$.

manifolds are uniformly transversal, it is possible to choose c such that, for each point in $y \in W_n$, $W_\delta^{cu}(y) \cap f^m W \neq \emptyset$.⁶² By the hypothesis on the central bundle it follows that the point related by the holonomy will never have a distance larger than δ in the future, then $\text{vol}(f^k(W_n)) \leq C_\# \text{vol}(f^{k+m}(W))$. Accordingly

$$\text{vol}(f^n(W)) \geq C_\# \text{vol}(f^{n-m}(W_n)) \geq C_\# \rho_{n-\bar{n}}^+ \geq C_\# \rho_n^+,$$

and the result follows again by taking the inf on the W . $\square$

Lemma C.2. *If (M, f) is topologically transitive, then, for each $n \in \mathbb{N}$, $\varepsilon > 0$,*

$$C_\varepsilon \rho_n^+ \leq N(f, \delta, n) \leq C_\varepsilon \rho_n^+.$$

Proof. Let $W \in \widehat{\Sigma}$ and consider a ε separated set S_n on $f^n(W)$.⁶³ Since the manifold contracts backward, points that are far away in $f^n(W)$ but close in M will separate backward. Thus $f^{-n}S_n \in \mathcal{S}(f, \varepsilon, n)$. Since $\#S_n \geq C_\# \text{vol}(f^n(W))$, it follows that $N(f, \varepsilon, n) \geq C_\varepsilon \rho_n^+$.

To prove the second inequality we use the notation introduced in the proof of Lemma C.1. Fix $W \in \widehat{\Sigma}$. Let $S \in \mathcal{S}(f, \varepsilon, n)$ be a set with maximal cardinality. Cover M with balls of radius $c\varepsilon$. By transitivity, for each ball B there exists a time $n_B \leq \bar{n}$ such that $f^{n_B}W \cap B \neq \emptyset$. Let $W_B \subset f^{n_B}W$, $W_B \in \widehat{\Sigma}$ be a manifold that intersects the ball B and project all the point in $S \cap B$ to W_B via the weak unstable holonomy. If we consider the images of such points we note that two points can be (ε, n) separated only if their corresponding points on W_B are $(C_\# \varepsilon, n)$ separated. Finally, note again that the $(C_\# \varepsilon, n)$ separated points on W_B must have a distance larger than $C_\# \varepsilon$ in the manifold $f^n(W_B)$. Thus there can be at most $C_\varepsilon \text{vol}(f^n(W_B))$ such points. Accordingly,

$$N(f, \varepsilon, n) \leq \sum_B C_\varepsilon \text{vol}(f^{n+n_B}(W)) \leq C_\varepsilon \rho_n^+.$$

$\square$

Using the above results the required bound follows.

⁶² By $W_\delta^{cu}(y)$ we mean a disk of radius δ in the weak unstable manifold.

⁶³ That is the distance among the points is larger than ε when measured on the manifold $f^n(W)$.

Lemma C.3. *If (M, f) is topologically transitive, then for all $n \in \mathbb{N}$ we have*

$$e^{h_{\text{top}}(f)n} \leq \rho_n^+ \leq C_{\#} e^{h_{\text{top}}(f)n}.$$

Proof. By Lemmata C.2, C.1

$$\frac{\ln N(f, \varepsilon, kn)}{kn} \leq \frac{\ln C_{\varepsilon} \rho_{kn}^+}{kn} \leq \frac{\ln C_{\varepsilon}}{kn} + \frac{\ln \rho_n^+}{n}.$$

Taking first the limit for $k \rightarrow \infty$ and then the limit $\varepsilon \rightarrow 0$, the first inequality of the Lemma follows.

By Lemma C.1, it follows that $\rho_{n+m}^+ \geq C_{\#} \rho_n^+ \rho_m^+$. Then $\rho_{kn}^+ \geq C_{\#}^k (\rho_n^+)^k$ and

$$\ln[C_{\#} \rho_n^+] \leq m \lim_{k \rightarrow \infty} \frac{\ln \rho_{kn}^+}{km} \leq n \lim_{k \rightarrow \infty} \frac{\ln N(f, \delta, kn)}{kn} \leq n h_{\text{top}}(\phi_1)$$

where we have used Lemma C.2 and equation (C.1). $\square$

Remark C.4. *Note that if f is the time one map of a hyperbolic flow, then by the spectral decomposition Theorem [13, Section 1.1], the manifold can be decomposed into finitely many isolated topologically transitive sets. Hence applying Lemma C.3 to each isolating neighborhood we obtain $C_{\#} e^{h_{\text{top}}(\phi_1)n} \leq \rho_n^+ \leq C_{\#} e^{h_{\text{top}}(\phi_1)n}$ for each Anosov flow.*

D Averaging operators

The following operators are used extensively in this paper.

Definition D.1. *Let $\kappa \in C^\infty(\mathbb{R}^d, \mathbb{R}_+)$ such that $\int \kappa(x) dx = 1$, $\text{supp } \kappa \subset \{x \in \mathbb{R}^d : \|x\| \leq 1\}$ and let $\kappa_\varepsilon(x) \doteq \varepsilon^{-d} \kappa(\varepsilon^{-1}x)$. For each $\alpha \in \mathcal{A}$, $\ell \in \{0, \dots, d\}$, let $\Psi \in C_0^\infty(\mathbb{R}^{2d}, GL(\binom{d}{\ell}, \mathbb{R}))$ with $\text{supp } \Psi \subset B_d(0, 2\delta)^2$. We define⁶⁴ the operator $\mathbb{M}_{\alpha, \Psi, \varepsilon} : \Omega_r^\ell \rightarrow \Omega_r^\ell$ by*

$$\mathbb{M}_{\alpha, \Psi, \varepsilon}(h)(x) \doteq \begin{cases} 0 & \text{if } x \notin U_\alpha \\ \sum_{\bar{i}, \bar{j} \in \mathcal{I}_\ell} \left[\int_{\mathbb{R}^d} \Psi(\Theta_\alpha(x), y)_{\bar{i}, \bar{j}} \kappa_\varepsilon(\Theta_\alpha(x) - y) \right. \\ \quad \left. \times \langle \omega_{\alpha, \bar{j}}, h \rangle_{\Theta_\alpha^{-1}(y)} dy \right] \omega_{\alpha, \bar{i}} & \text{if } x \in U_\alpha. \end{cases}$$

⁶⁴ Obviously our definition depends on the choice of the function κ , and in the future some special choice of κ will be made. However, we choose not to explicitly show the dependence as a subscript to simplify the notation.

Given the particular choice $\bar{\Psi}(x, y)_{\bar{i}, \bar{j}} \doteq \psi_\alpha(\Theta_\alpha^{-1}(x))\delta_{\bar{i}, \bar{j}}$ we define

$$\mathbb{M}_\varepsilon \doteq \sum_\alpha \mathbb{M}_{\alpha, \varepsilon} \doteq \sum_\alpha \mathbb{M}_{\alpha, \bar{\Psi}, \varepsilon}.$$

Lastly, given the duality induced by (3.4), we define the operators $\mathbb{M}'_{\alpha, \varepsilon}, \mathbb{M}'_\varepsilon$, as those such that for all $h, g \in \Omega_r^\ell$ we have⁶⁵

$$\langle \mathbb{M}'_{\alpha, \varepsilon} h, g \rangle_{\Omega_r^\ell} = \langle h, \mathbb{M}_{\alpha, \varepsilon} g \rangle_{\Omega_r^\ell} \quad \text{and} \quad \langle \mathbb{M}'_\varepsilon h, g \rangle_{\Omega_r^\ell} = \langle h, \mathbb{M}_\varepsilon g \rangle_{\Omega_r^\ell}.$$

Lemma D.2. *There exists $\varepsilon_0 > 0$ such that, for each $\varepsilon \in (0, \varepsilon_0)$, $\ell \in \{1, \dots, d\}$, $q > 0, p \in \mathbb{N}^*$ and $h \in \Omega_{p+q}^\ell$, we can bound*

$$\begin{aligned} \|\mathbb{M}_\varepsilon h\|_{-, p, q, \ell} + \|\mathbb{M}'_\varepsilon h\|_{-, p, q, \ell} &\leq C_{p, q, \kappa} \|h\|_{+, p, q, \ell}, \\ \|\mathbb{M}_\varepsilon h\|_{C^p(\Omega, M)} + \|\mathbb{M}'_\varepsilon h\|_{C^p(\Omega, M)} &\leq C_{p, q, \kappa} \varepsilon^{-d_s - p - q} \|h\|_{-, p, q, \ell}, \\ \|h - \mathbb{M}_\varepsilon h\|_{-, p-1, q+1, \ell} + \|h - \mathbb{M}'_\varepsilon h\|_{-, p-1, q+1, \ell} &\leq C_{p, q, \kappa} \varepsilon \|h\|_{+, p, q, \ell}. \end{aligned}$$

Proof. We will give a proof only for the operator $\mathbb{M}_\varepsilon$, the proof for $\mathbb{M}'_\varepsilon$ being similar. To prove the first inequality we begin by estimating the integral in (3.11) for the case $p = 0$. First of all note that, for each $\alpha, \beta \in \mathcal{A}$, $W_{\beta, G} \in \Sigma_\alpha(\rho, L_0)$ and Ψ , if

$$\int_{W_{\beta, G}} \langle g, \mathbb{M}_{\alpha, \Psi, \varepsilon} h \rangle \omega_{\text{vol}} \neq 0, \quad (\text{D.1})$$

then $W_{\beta, G} \cap \widehat{U}_\alpha \neq \emptyset$. Thus there exists $W_{\alpha, G'} \in \Sigma_\alpha(\rho_+, L_+)$ such that $W_{\beta, G} \cap \widehat{U}_\alpha \subset W_{\alpha, G'}$ (see Remark 3.5). On the other hand, by Definition D.1, the integrand is supported in $\widehat{U}_\alpha$, thus

$$\int_{W_{\beta, G}} \langle g, \mathbb{M}_{\alpha, \Psi, \varepsilon} h \rangle \omega_{\text{vol}} = \int_{W_{\alpha, G'}} \langle g, \mathbb{M}_{\alpha, \Psi, \varepsilon} h \rangle \omega_{\text{vol}}.$$

Thus, it suffices to compute

$$\begin{aligned} \int_{W_{\alpha, G_{x, F}}} \langle g, \mathbb{M}_{\alpha, \Psi, \varepsilon} h \rangle \omega_{\text{vol}} &= \sum_{\bar{i}, \bar{j} \in \mathcal{I}_\ell} \int_{B_{d_s}(0, 2\delta)} d\xi \int_{\mathbb{R}^d} dy \Psi(G_{x, F}(\xi), y)_{\bar{i}, \bar{j}} \\ &\quad \times g_{\alpha, \bar{i}} \circ \Theta_\alpha^{-1} \circ G_{x, F}(\xi) h_{\alpha, \bar{j}} \circ \Theta_\alpha^{-1}(y) \kappa_\varepsilon(G_{x, F}(\xi) - y), \end{aligned}$$

⁶⁵ By the duality relation $\mathbb{M}'$ is then also defined on currents. In addition, note that $\mathbb{M}_{\alpha, \varepsilon} \Omega_{0, r}^\ell \cup \mathbb{M}'_{\alpha, \varepsilon} \Omega_{0, r}^\ell \subset \Omega_{0, r}^\ell$.

where $h_{\alpha,\bar{i}}(z) = \langle h, \omega_{\alpha,\bar{i}} \rangle_z$ and $g_{\alpha,\bar{i}}(z) = \langle g, \omega_{\alpha,\bar{i}} \rangle_z$ for each $z \in U_\alpha$.

Next, we keep $\xi \in B_{d_s}(0, 2\delta)$ fixed and we consider the change of variables $\zeta = G_{x,F}(\xi) - y$. By Fubini-Tonelli theorem and the definition of $G_{x,F}$ we can exchange the integrals and obtain

$$\begin{aligned} \int_{W_{\alpha,G_{x,F}}} \langle g, \mathbb{M}_{\alpha,\Psi,\varepsilon} h \rangle \omega_{\text{vol}} &= \sum_{\bar{i}, \bar{j} \in \mathcal{I}_\ell} \int_{\mathbb{R}^d} d\zeta \kappa_\varepsilon(\zeta) \int_{B_{d_s}(0, 2\delta)} d\xi \Psi(G_{x,F}(\xi), G_{x-\zeta,F}(\xi))_{\bar{i}, \bar{j}} \\ &\quad \times g_{\alpha,\bar{i}} \circ \Theta_\alpha^{-1} \circ G_{x,F}(\xi) h_{\alpha,\bar{j}} \circ \Theta_\alpha^{-1} \circ G_{x-\zeta,F}(\xi). \end{aligned} \quad (\text{D.2})$$

Now given our admissible test function g and a leaf $W_{\alpha,G_{x,F}}$, we can define admissible elements $g_{\zeta,\Psi}$ and $W_{\alpha,G_{x_\zeta,F}}$, as follows. Let $x_\zeta \doteq x - \zeta$, $g_{\zeta,\Psi,\bar{j}} \circ \Theta_\alpha^{-1}(z) \doteq \sum_{\bar{i}} \Psi(z + \zeta, z)_{\bar{i}, \bar{j}} g_{\alpha,\bar{i}} \circ \Theta_\alpha^{-1}(z + \zeta)$ and $g_{\zeta,\Psi} = \sum_{\bar{i}} g_{\zeta,\Psi,\bar{i}} \omega_{\alpha,\bar{i}}$, so that

$$\sum_{\bar{i}} \Psi(G_{x,F}(\xi), G_{x-\zeta,F}(\xi))_{\bar{i}, \bar{j}} g_{\alpha,\bar{i}} \circ \Theta_\alpha^{-1} \circ G_{x,F}(\xi) = g_{\zeta,\Psi,\bar{j}} \circ \Theta_\alpha^{-1} \circ G_{x_\zeta,F}(\xi).$$

Then

$$\int_{W_{\alpha,G_{x,F}}} \langle g, \mathbb{M}_{\alpha,\Psi,\varepsilon} h \rangle \omega_{\text{vol}} = \int_{\mathbb{R}^d} d\zeta \kappa_\varepsilon(\zeta) \int_{W_{\alpha,G_{x_\zeta,F}}} \langle g_{\zeta,\Psi}, h \rangle \omega_{\text{vol}}. \quad (\text{D.3})$$

Note that, since the cones are constant in the charts, $G_{x_\zeta,F} \in \Sigma(\rho_+, L_+)$ for each ζ small enough. Since, $\|g_{\zeta,\Psi}\|_{\Gamma_c^{\ell,q}(\alpha, G_{x_\zeta,F})} \leq C_q \|\Psi\|_{C^q} \|g\|_{\Gamma_c^{\ell,p+q}(\alpha, G_{x,F})}$ we have

$$\|\mathbb{M}_{\alpha,\Psi,\varepsilon} h\|_{-,0,q} \leq C_q \|\Psi\|_{C^q} \|h\|_{+,0,q}.$$

The first inequality of the Lemma, for $p = 0$, follows.

Next we treat the case $p > 0$. Let $v \in C^{p+q}$. We need to compute $L_v \mathbb{M}_{\alpha,\Psi,\varepsilon}$. To do so note that $L_v(\omega_{\alpha,\bar{i}}) = \sum_{\bar{j}} \rho_{\bar{i},\bar{j}}(v) \omega_{\alpha,\bar{j}}$. Moreover by equation (A.6) there exists Ψ'_v such that we have $L_v(\Psi(\Theta_\alpha(x), y))_{\bar{i}, \bar{j}} \doteq \Psi'_v(\Theta_\alpha(x), y)_{\bar{i}, \bar{j}}$. Next, we deal with $L_v(\kappa_\varepsilon(\Theta_\alpha(x) - y))$ using integration by parts with respect to y . Lastly, we apply (A.5) to $L_v \langle \omega_{\alpha,\bar{j}}, h \rangle_{\Theta_\alpha^{-1}(y)}$.

By using all the remarks above, we obtain that there exists vectors $w_1(v), \dots, w_l(v) \in C^{p+q}$, and functions $\Psi_v, \Psi_{v,1}, \dots, \Psi_{v,l}$ such that $\|\Psi_v\|_{C^{p+q-1}+} + \sum_l \|\Psi_{v,l}\|_{C^{p+q}} \leq C_\# \|\psi\|_{C^{p+q}}$ and for which we have

$$L_v \mathbb{M}_{\alpha,\Psi,\varepsilon} h = \mathbb{M}_{\alpha,\Psi_v,\varepsilon} h + \sum_l \mathbb{M}_{\alpha,\Psi_{v,l},\varepsilon} (L_{w_l} h). \quad (\text{D.4})$$

By iterating the above equality, using the previous bound for $p = 0$ and equation (3.14), we obtain the first inequality of the Lemma.

To prove the second inequality, given definition (3.9), we must evaluate

$$\begin{aligned} \langle \omega_{\alpha, i}, \mathbb{M}_{\alpha, \varepsilon} h \rangle_{\Theta_{\alpha}^{-1}(z)} &= \psi_{\alpha} \circ \Theta_{\alpha}^{-1}(z) \left[\int_{\mathbb{R}^d} \kappa_{\varepsilon}(z - y) \langle \omega_{\alpha, \bar{i}}, h \rangle_{\Theta_{\alpha}^{-1}(y)} dy \right] \\ &= \int_{\mathbb{R}^{d_u+1}} dy_{d_s+1} \dots dy_d \int_{W_{\alpha, G(0, y_{d_s+1}, \dots, y_d), 0}} \langle g_{\varepsilon, z, y}, h \rangle \omega_{\text{vol}}. \end{aligned} \quad (\text{D.5})$$

where $\hat{g}_{\varepsilon, z, y, \bar{i}} \circ \Theta_{\alpha}^{-1}(\xi) = \psi_{\alpha} \circ \Theta_{\alpha}^{-1}(z) \kappa_{\varepsilon}(z - (\xi, y_{d_s+1}, \dots, y_d))$ and $g_{\varepsilon, z, y} = \hat{g}_{\varepsilon, z, y, \bar{i}} \omega_{\alpha, \bar{i}}$. Then, differentiating (D.5) with respect to z and integrating by parts yields the desired result since $\|g_{\varepsilon, z, y}\|_{\Gamma_c^{\ell, p+q}} \leq C_{\#} \varepsilon^{-p-q}$.

Finally note that by construction

$$\lim_{\varepsilon \rightarrow 0} [\mathbb{M}_{\alpha, \Psi, \varepsilon} h](x) = \Psi(\Theta_{\alpha}(x), \Theta_{\alpha}(x)) h(x) \doteq \widehat{\Psi}_{\alpha}(x) h(x).$$

Thus, by (D.4), we have that $\lim_{\varepsilon \rightarrow 0} L_v \mathbb{M}_{\alpha, \Psi, \varepsilon} h$ exists. On the other hand, for all $g \in C^r$, we have (see (4.23))

$$\lim_{\varepsilon \rightarrow 0} \int_M g L_v \mathbb{M}_{\alpha, \Psi, \varepsilon} h \omega = \lim_{\varepsilon \rightarrow 0} (-1)^d \int_M \mathbb{M}_{\alpha, \Psi, \varepsilon} h d(i_v(g\omega)) = \int_M g L_v [\widehat{\Psi}_{\alpha} h].$$

Thus,

$$\lim_{\varepsilon \rightarrow 0} L_v \mathbb{M}_{\alpha, \Psi, \varepsilon} h = L_v [\widehat{\Psi}_{\alpha} h]. \quad (\text{D.6})$$

Hence, by (D.3) and the explicit representation of (D.2), we can write

$$\begin{aligned} &\int_{W_{\alpha, G_{x, F}}} \omega_{\text{vol}} \left[\langle g, \widehat{\Psi}_{\alpha} h \rangle - \langle g, \mathbb{M}_{\alpha, \Psi, \varepsilon} h \rangle \right] \\ &= \int d\zeta \kappa_{\varepsilon}(\zeta) \int_0^1 dt \frac{d}{dt} \int_{W_{\alpha, G_{x_t \zeta, F}}} \omega_{\text{vol}} \langle g_{t\zeta, \Psi}, h \rangle \\ &= \int d\zeta \kappa_{\varepsilon}(\zeta) \int_0^1 dt \int_{W_{\alpha, G_{x_t \zeta, F}}} \omega_{\text{vol}} \langle g_{t\zeta, \Psi}, L_{v_{\zeta}} h \rangle - \sum_{\bar{i}} \langle g_{t\zeta, \Psi}, \hat{h}_{\alpha, \bar{i}} L_{v_{\zeta}} \omega_{\alpha, \bar{i}} \rangle \end{aligned} \quad (\text{D.7})$$

where $v_{\zeta} = -(\Theta_{\alpha}^{-1})_* \zeta$. The last inequality, for $p = 0$, follows since $\|v_{\zeta}\|_{C^{p+q}} \leq C_{\#} \varepsilon$. To obtain the result for $p > 0$, one can use (D.4) and (D.6) repeatedly. $\square$

The above Lemma has a useful corollary.

Corollary D.3. *Both $\mathbb{M}_\varepsilon$ and $\mathbb{M}'_\varepsilon$ extend to operators in $L(\mathcal{B}_+^{p,q,\ell}, \mathcal{B}_-^{p,q,\ell})$ and $L((\mathcal{B}_-^{p,q,\ell})', (\mathcal{B}_+^{p,q,\ell})')$. In addition, if $h \in \mathcal{B}_+^{p,q,\ell}$, then*

$$\lim_{\varepsilon \rightarrow 0} \|h - \mathbb{M}_\varepsilon h\|_{-,p,q,\ell} + \|h - \mathbb{M}'_\varepsilon h\|_{-,p,q,\ell} = 0. \quad (\text{D.8})$$

Proof. By definition, there exists a sequence $\{h_n\} \subset \Omega_s^\ell$ that converges to h in $\mathcal{B}_+^{p,q,\ell}$. Hence

$$\begin{aligned} \|h - \mathbb{M}_\varepsilon h\|_{-,p,q,\ell} &\leq \|h - h_n\|_{-,p,q,\ell} + \|h_n - \mathbb{M}_\varepsilon h_n\|_{-,p,q,\ell} + \|\mathbb{M}_\varepsilon(h_n - h)\|_{-,p,q,\ell} \\ &\leq C_\# \|h - h_n\|_{+,p,q,\ell} + C_\# \varepsilon \|h_n\|_{+,p+1,q-1,\ell} \end{aligned}$$

implies the result. $\square$

Remark D.4. *The loss related to the $\pm$ norms is due to the need of viewing a manifold of Σ_α in a different chart. If we would consider a Ψ supported in U_α and be interested only in the semi-norms arising from Σ_α , such a loss would disappear.*

E Holonomies

Here we recall some known facts concerning the invariant foliations of an Anosov flow and prove some useful estimates. Concerning the issue of regularity, more details can be found in [32, 33, 34].

The strong unstable foliation can be locally trivialized by a change of coordinates of the form $\mathbb{H}(\xi, \eta) = (H(\xi, \eta), \eta)$, $\eta \in B_{d_u}(0, \delta)$, $\xi \in B_{d_s+1}(0, \delta)$, such that for each ξ , $\{\mathbb{H}(\xi, \eta)\}_{\eta \in B_{d_u}(0, \delta)}$ is a strong unstable manifold. In addition, without loss of generality, we can require that $H(0, \eta) = 0$ and $H(\xi, 0) = \xi$. The results on the regularity of the foliation can be summarized by considering the map $\tilde{H} : B_{d_s+1}(0, \delta) \rightarrow C^0(B_{d_u}(0, \delta), \mathbb{R}^{d_s+1})$ defined by $[\tilde{H}(\xi)](\cdot) = H(\xi, \cdot)$. Then $\tilde{H}$ has range in $C^r(B_{d_u}(0, \delta), \mathbb{R}^{d_s+1})$ and $\|\tilde{H}\|_{C^\varpi(B_{d_s+1}(0, \delta), C^r(B_{d_u}(0, \delta), \mathbb{R}^{d_s+1}))} \leq C_\#$. Moreover for each η , the function $H(\cdot, \eta)$ is absolutely continuous and has Jacobian $JH(\xi, \eta)$. Again, we can define $J\tilde{H} : B_{d_s+1}(0, \delta) \rightarrow C^0(B_{d_u}(0, \delta), \mathbb{R})$ by $[J\tilde{H}(\xi)](\cdot) = JH(\xi, \cdot)$. Then $J\tilde{H}$ has range in $C^r(B_{d_u}(0, \delta), \mathbb{R})$ and $\|J\tilde{H}\|_{C^\varpi^*(B_{d_s+1}(0, \delta), C^r(B_{d_u}(0, \delta), \mathbb{R}))} \leq C_\#$.⁶⁶

⁶⁶ See [34] and references therein for the proofs of these statements.

In this paper the holonomies are often used as follows: given $W_1, W_2 \in \Sigma$ and $x, y \in W_1$ estimate $d(H_{\widetilde{W}_1, \widetilde{W}_2}(x), H_{\widetilde{W}_1, \widetilde{W}_2}(y))$.⁶⁷ Although it is clear how to proceed, we give the details for the benefit of the lazy reader.

Note that, without loss of generality we can assume that $x = 0$, $y = (a, 0)$ and $H_{\widetilde{W}_1, \widetilde{W}_2}(0) = (0, z)$, $\widetilde{W}_1 = \{(\xi, 0)\}_{\xi \in \mathbb{R}^{d_s+1}}$. Then $\widetilde{W}_2$ will have the form $\{(\xi, z + G(\xi)), G(0) = 0$, and $\|D_\xi G\| \leq 2$. Also let $H_{\widetilde{W}_1, \widetilde{W}_2}(a, 0) = (\xi, \eta)$,

Lemma E.1. *We have that*

$$\|(\xi, \eta) - (a, z)\| \leq C_\# \left[\|a\|^{\varpi'} \|z\| + \|\partial_\xi G\|_{C^0} \|a\| \right]. \quad (\text{E.1})$$

Proof. The intersection point (ξ, η) satisfies $(\xi, \eta) = (H(a, \eta), z + G(\xi))$. Thus

$$\begin{aligned} \xi - a &= H(a, \eta) - H(a, 0) \\ &= H(a, z + G(\xi)) - H(a, z + G(a)) + H(a, z + G(a)) - H(a, 0) \\ &= A(\xi - a) + H(a, z + G(a)) - H(a, 0). \end{aligned}$$

where the last line is an application of the intermediate value theorem and $\|A(\xi)\| \leq \|\partial_\eta H(a, \cdot)\|_{C^0} \|\partial_\xi G\|_{C^0} \leq C_\# \|a\|^{\varpi'} \|\partial_\xi G\|_{C^0}$. Then

$$\|\xi - a\| \leq \|(\mathbf{1} - A)^{-1}(H(a, z + G(a)) - H(a, 0))\| \leq C_\# \|a\|^{\varpi'} (\|z\| + \|\partial_\xi G\|_{C^0} \|a\|).$$

Analogously,

$$\eta - z = G(H(a, \eta)) - G(H(a, z)) + G(H(a, z)) = A_1(\eta - z) + G(H(a, z)),$$

where $\|A_1(\eta)\| \leq \|\partial_\xi G\|_{C^0} \|\partial_\eta H(a, \cdot)\|_{C^0} \leq C_\# \|a\|^{\varpi'} \|\partial_\xi G\|_{C^0}$. Thus

$$\|\eta - z\| \leq \|(\mathbf{1} - A_1)^{-1}G(H(a, z))\| \leq C_\# \|\partial_\xi G\|_{C^0} (\|a\| + \|a\|^{\varpi'} \|z\|).$$

□

Next, we need a small improvement of [43, Lemma B.7]. We use the same notation established before (7.27), a part from the fact that the points ξ, ζ are fixed to some value ξ_*, ζ_* .

Lemma E.2. *For $\xi_*, \zeta_* \in B_{d_s+1}(0, \delta)$ and Δ^* as in (7.26) we have that*

$$\begin{aligned} |\Delta^*(\xi_* + \zeta_*) - \Delta^*(\xi_*) - d\alpha_0(z(\xi_*), \zeta_*)| &\leq C_\# (\|z\|^2 \|\tilde{\zeta}_*\|^{\varpi'} + \|z\|^{\varpi'} \|\tilde{\zeta}_*\|^2) \\ &\quad + C_\# \|z\|^{1+\varpi'} \|\tilde{\zeta}_*\|^{1+\varpi'}. \end{aligned}$$

⁶⁷ Remember that $\widetilde{W} = \cup_{t \in I} \phi_t W$, for some appropriate interval I .

Proof. We use the same coordinates defined before Lemma E.1 with $W = W_1$, $W' = W_2$; so that $\xi_* = 0$, $\zeta_* = (\tilde{\zeta}, 0)$.⁶⁸ Thus $\widetilde{W}$ is a flat manifold and $\widetilde{W}'$ is the graph of $(\xi, G(\tilde{\xi}))$, where $\tilde{\xi} = (\xi_1, \dots, \xi_{d_s})$, ξ_{d_s+1} being the flow direction. Also $W = \{(\xi, 0)\}$ while W' is the graph of $(\xi, G(\tilde{\xi}), L(\tilde{\xi}))$ with $L(0) = 0$, $G(0) = \bar{z} = z^u(\xi_*)$. Let $H(\xi, \eta) = (H_s(\xi, \eta), H_0(\xi, \eta))$, $H_s : \mathbb{R}^d \rightarrow \mathbb{R}^{(d_s)}$, $H_0 : \mathbb{R}^d \rightarrow \mathbb{R}$, and $\{(I_u(\zeta), I_s(\zeta), I_0(\zeta))\} = \{\mathbb{H}(\zeta, \eta)_{\eta \in \mathbb{R}^{d_u}}\} \cap \{(\xi, G(\xi))_{\xi \in \mathbb{R}^{d_s+1}}\}$. Then $\Delta^*(\xi_* + \zeta_*) - \Delta^*(\xi_*) = I_0(\tilde{\zeta}) - L(I_s(\tilde{\zeta}))$. Define $\Xi : [0, 1]^2 \rightarrow \mathbb{R}^d$ by

$$\Xi(t, s) = (sH_s(\tilde{\zeta}, tI_u(\tilde{\zeta})), tG(sI_s(\tilde{\zeta})), s[H_0(\tilde{\zeta}, tI_u(\tilde{\zeta})) - tI_0(\tilde{\zeta})] + tL(sI_s(\tilde{\zeta})))$$

and set $\Xi([0, 1]^2) \doteq \Sigma$. From [43, equations (B.4), (B.5)] it follows that $I_0(\tilde{\zeta}) - L(I_s(\tilde{\zeta}))$ equals the integral of the symplectic form over Σ , hence

$$\begin{aligned} \Delta^*(\xi_* + \zeta_*) - \Delta^*(\xi_*) &= \int_{\Sigma} d\alpha_0 = \int_{[0,1]^2} \Xi^* d\alpha_0 = \int_{[0,1]^2} d\alpha_0(\partial_s \Xi, \partial_t \Xi) dt ds \\ &= \int_{[0,1]^2} \langle H_s(\tilde{\zeta}, tI_u(\tilde{\zeta})), G(sI_s(\tilde{\zeta})) \rangle - ts \langle \partial_{\tilde{\xi}} G(sI_s(\tilde{\zeta})) I_s(\tilde{\zeta}), \partial_{\eta} H_s(\tilde{\zeta}, tI_u(\tilde{\zeta})) I_u(\tilde{\zeta}) \rangle \\ &= \langle \tilde{\zeta}, \bar{z} \rangle + \mathcal{O} \left(\|\tilde{\zeta}\|^{\varpi'} \|\bar{z}\| \|I_u\| + \|\tilde{\zeta}\| \|\bar{z}\|^{\varpi'} \|I_s\| + \|\tilde{\zeta}\|^{\varpi'} \|\bar{z}\|^{\varpi'} \|I_u\| \|I_s\| \right). \end{aligned}$$

Since, by Lemma E.1, $\|I_u - \bar{z}\| + \|I_s - \tilde{\zeta}\| \leq C_{\#}(\|\bar{z}\|^{\varpi'} \|\tilde{\zeta}\| + \|\bar{z}\| \|\tilde{\zeta}\|^{\varpi'})$, the Lemma follows. $\square$

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⁶⁸ This can be done without loss of generality since the general case follows by a trivial translation.

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