

# Advanced topics on Algorithms

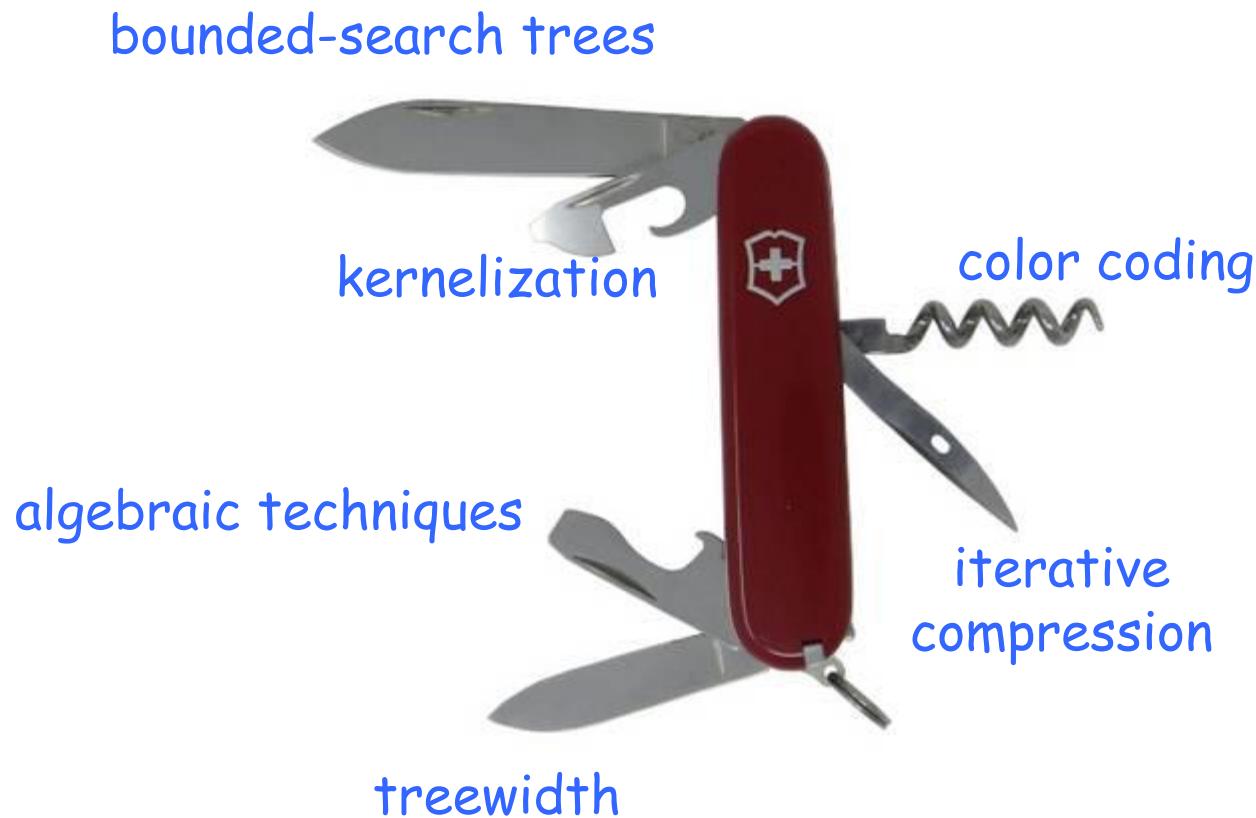
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# Parameterized algorithms

## Episode II

## Toolbox (to show a problem is FPT)



color coding

## k-Path

Input:

- a graph  $G=(V,E)$
- a nonnegative integer  $k$

question:

is there a simple path of  $k$  vertices

parameter:  $k$

obs: NP-hard since it contains the Hamiltonian path as special case

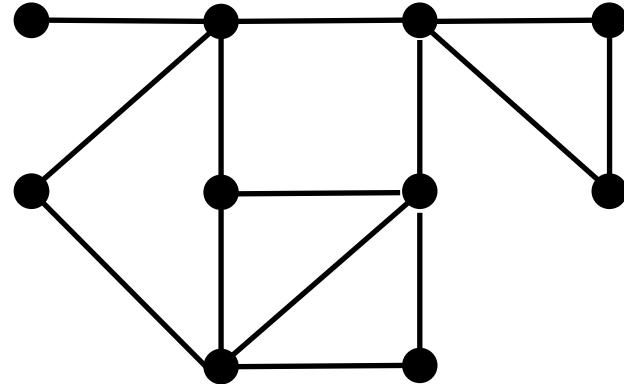
Theorem [Alon, Yuster, Zwick 1994]

k-Path can be solved in time  $2^{O(k)} n^{O(1)}$ .

previous best algorithms had running time  $k^{O(k)} n^{O(1)}$ .

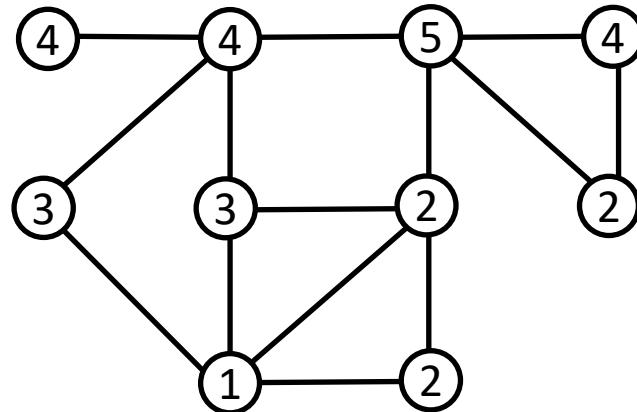
## color coding

- assign colors from  $\{1, \dots, k\}$  to vertices  $V(G)$  uniformly and independently at random.



## color coding

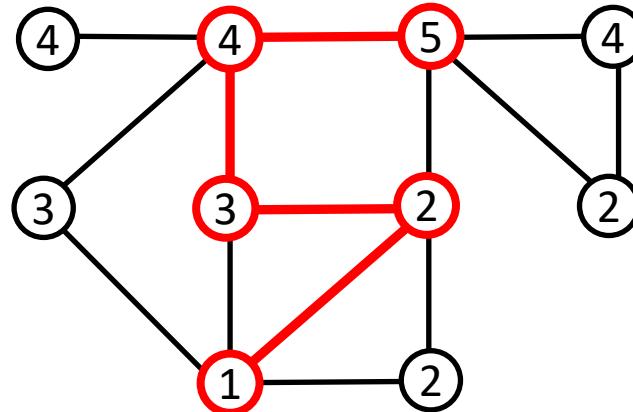
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- check if there is a path colored 1-2-...-k and output YES or NO

## color coding

- assign colors from  $\{1, \dots, k\}$  to vertices  $V(G)$  uniformly and independently at random.



- check if there is a path colored  $1-2-\dots-k$  and output YES or NO

**obs1:** if there is no  $k$ -path: no path colored  $1-2-\dots-k$  exists



NO

**obs2:** if there is a  $k$ -path: there is some probability that this path is colored  $1-2-\dots-k$

probability of success:  $k^{-k}$ .



YES with probability  $k^{-k}$ .

## boosting the probability of success: independent repetitions

### Useful fact

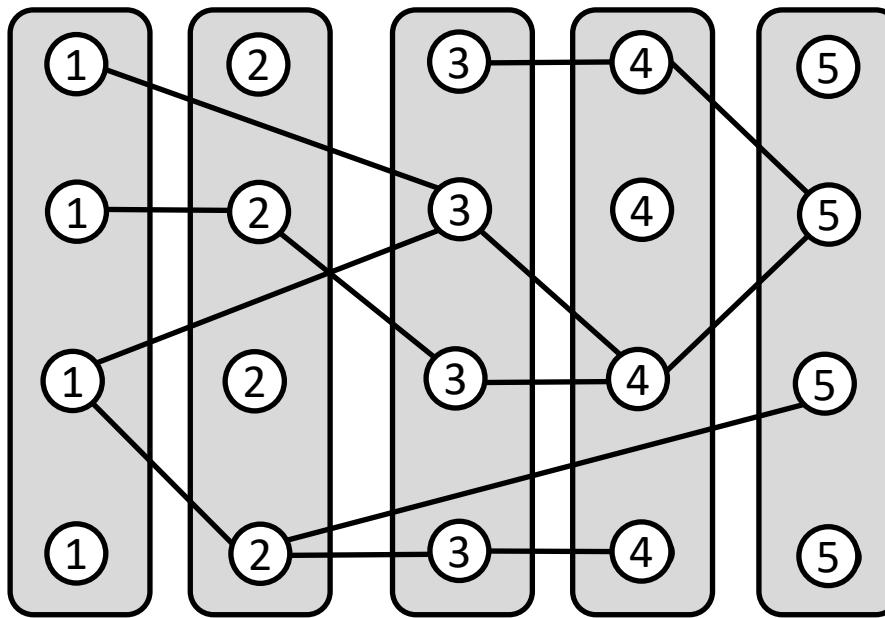
If the probability of success is at least  $p$ , then the probability that the algorithm does not say "YES" after  $1/p$  repetitions is at most

$$(1-p)^{1/p} \leq (e^{-p})^{1/p} = 1/e \approx 0.38$$

- Thus, if  $p \geq k^{-k}$  then error probability is at most  $1/e$  after  $k^k$  repetitions
- repeating the whole algorithm a constant number of times can make the error probability an arbitrary small constant

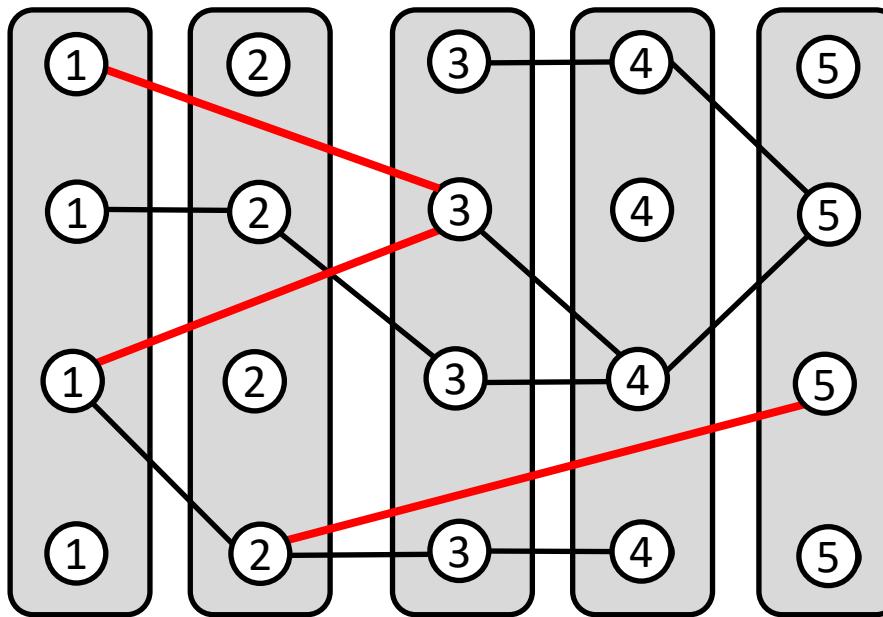
**example:** trying  $100 k^k$  random colorings, the probability of a wrong answer is at most  $(1/e)^{100}$ .

## Finding a path colored 1-2-...-k



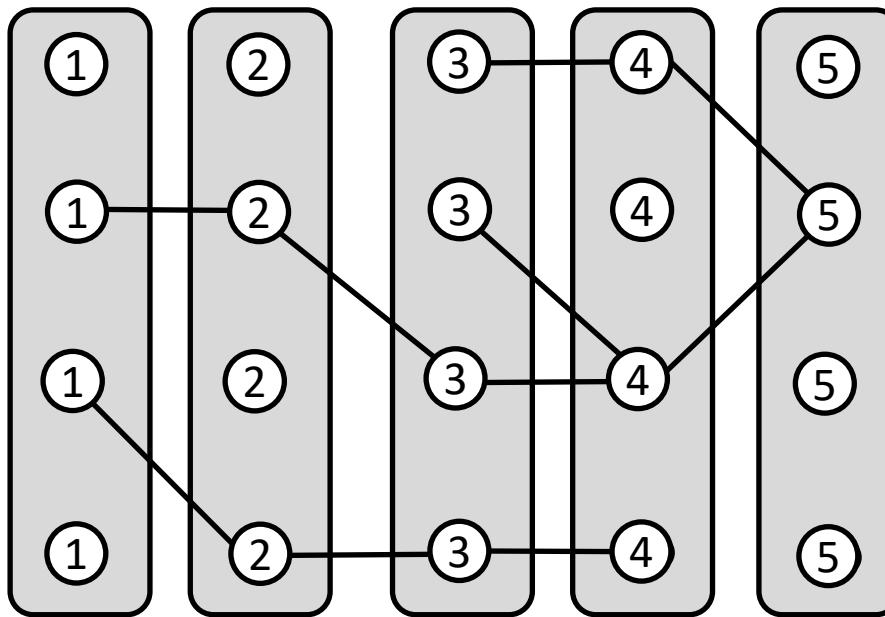
- edges connecting nonadjacent color classes are removed
- the remaining edges are directed towards the larger class
- all we need to check if there is a directed path from class 1 to class k

## Finding a path colored 1-2-...-k



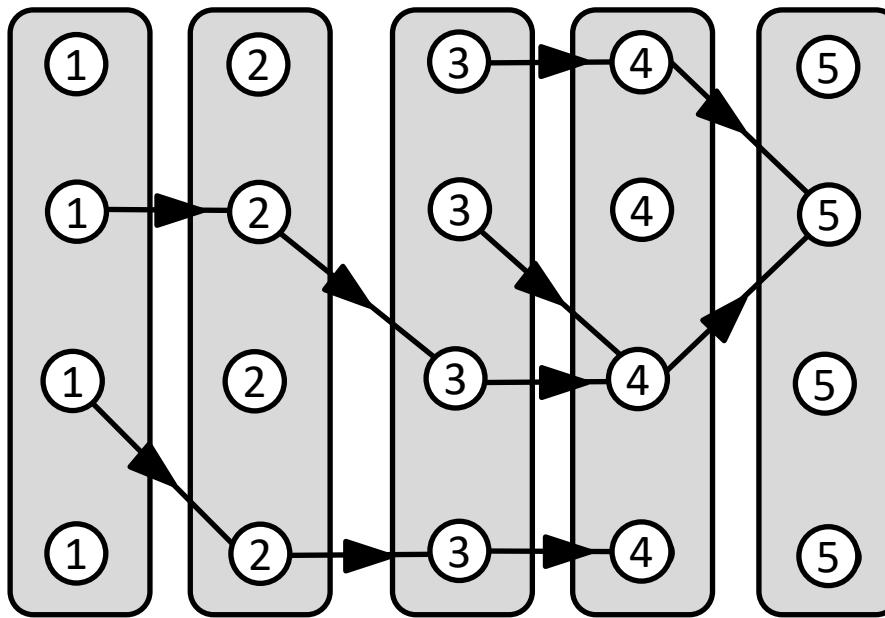
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# Finding a path colored 1-2-...-k



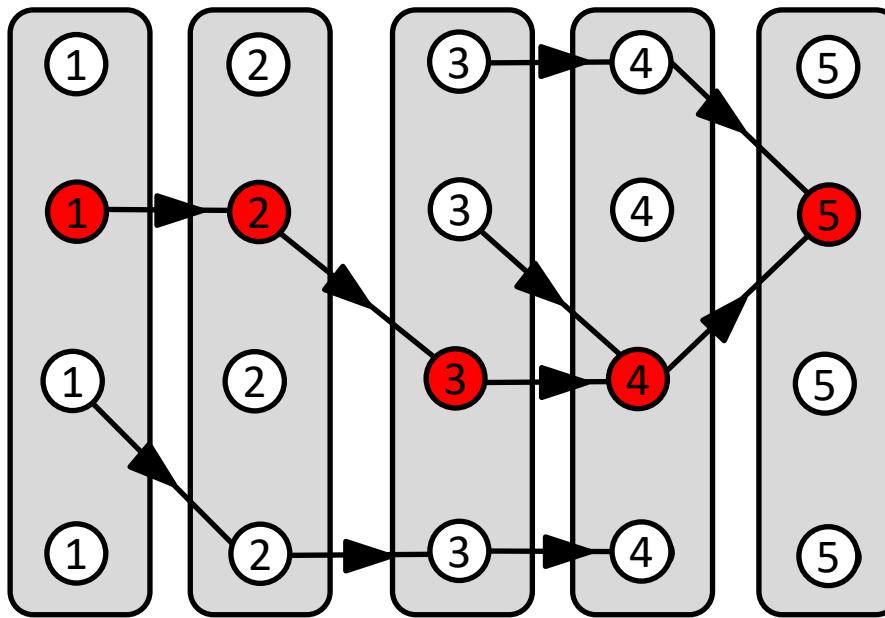
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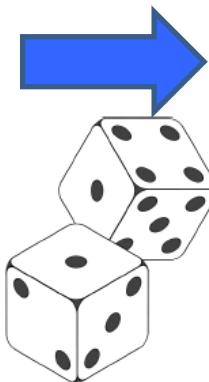
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color coding

k-Path

color coding  
success probability

$k^{-k}$

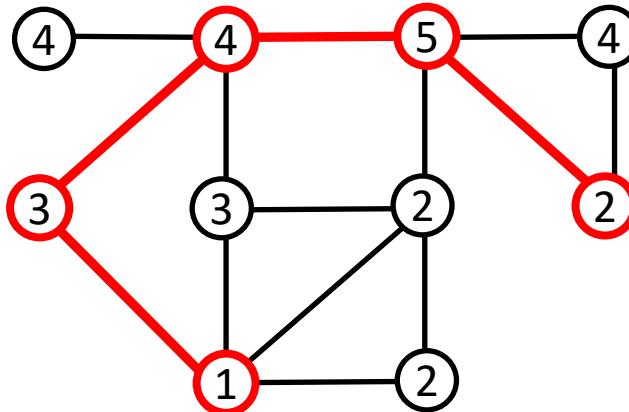


finding a  
1-...-k  
colored path

polynomial time  
solvable

## improved color coding

- assign colors from  $\{1, \dots, k\}$  to vertices  $V(G)$  uniformly and independently at random.



- check if there is a **colorful path** (each color appears exactly once) and output YES or NO

**obs1:** if there is no  $k$ -path: no colorful path exists



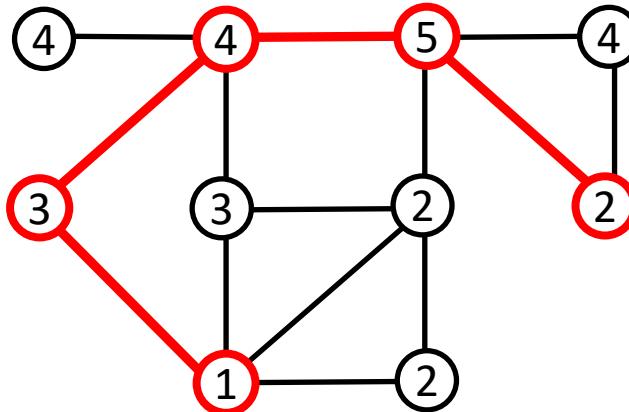
NO

**obs2:** if there is a  $k$ -path: there is some probability that it is colorful  
probability of success:

$$\frac{k! k^{n-k}}{k^n} = \frac{k!}{k^k} \geq \frac{(k/e)^k}{k^k} = e^{-k} \quad \Rightarrow \text{YES with probability } e^{-k}.$$

## improved color coding

- assign colors from  $\{1, \dots, k\}$  to vertices  $V(G)$  uniformly and independently at random.



- repeating the algorithm  $100 e^k$  times, the probability of a wrong answer is at most  $(1/e)^{100}$ .

how to find a colorful path?

- try all permutations:  $k! n^{O(1)}$  time
- dynamic programming:  $2^k n^{O(1)}$  time

# finding a colorful path

subproblems:

$v \in V$ , non-empty subset  $S \subseteq \{1, \dots, k\}$

$\text{Path}(v, S)$ : is there a path  $P$  ending at  $v$  such that each color of  $S$  appears in  $P$  exactly once and no other color appears in  $P$ ?

**obs1:** There is a colorful path iff  $\text{Path}(v, \{1, \dots, k\}) = \text{TRUE}$  for some  $v$

**obs2:** # of subproblems  $2^k n$

# finding a colorful path

subproblems:

$v \in V$ , non-empty subset  $S \subseteq \{1, \dots, k\}$

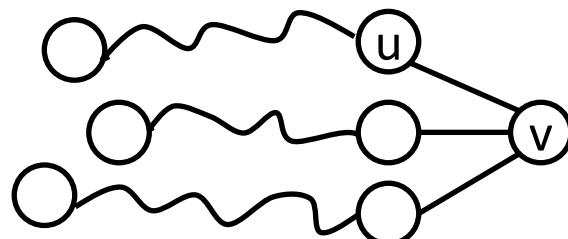
$\text{Path}(v, S)$ : is there a path  $P$  ending at  $v$  such that each color of  $S$  appears in  $P$  exactly once and no other color appears in  $P$ ?

$|S|=1$  (base case)

$\text{Path}(v, S) = \text{TRUE}$  iff  $S = \{\text{col}(v)\}$

$|S| > 1$

$\text{Path}(v, S) = \begin{cases} \text{OR}_{(u,v) \in E} \text{Path}(u, S - \{\text{col}(v)\}) & \text{if } \text{col}(v) \in S \\ \text{FALSE} & \text{otherwise} \end{cases}$

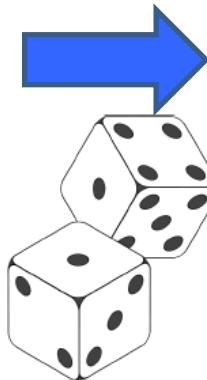


# color coding

k-Path

color coding  
success probability

$$e^{-k}$$



finding a  
colorful path

solvable in  
 $2^k n^{O(1)}$  time

## Theorem

There is a randomized algorithm for k-Path that runs in time  $(e2)^k n^{O(1)}$  that either reports a failure or find a path of k vertices. Moreover, the algorithm finds a solution of a YES-instance with constant probability.

# Kernelization

a 2k-vertex kernel for VC  
based on linear programming

# an Integer Linear Programming (ILP) formulation of VC

$$\text{minimize} \quad \sum_{v \in V} x_v$$

$$\text{subject to} \quad x_u + x_v \geq 1 \quad e = (u, v) \in E$$

$$x_v \in \{0, 1\}$$

$$v \in V$$

relax with  
 $x_v \geq 0 \quad \& \quad x_v \leq 1$

redundant

LP-relaxation

$$\text{minimize} \quad \sum_{v \in V} x_v$$

$$\text{subject to} \quad x_u + x_v \geq 1 \quad e = (u, v) \in E$$

$$x_v \geq 0$$

$$v \in V$$

a feasible solution is  
a fractional VC

$OPT_f$ : cost of the min fractional VC

$$OPT_f \leq OPT$$

Let  $x$  be an optimal fractional solution.

$$V_0 = \{ v \in V : x_v < \frac{1}{2} \}$$

$$V_{0.5} = \{ v \in V : x_v = \frac{1}{2} \}$$

$$V_1 = \{ v \in V : x_v > \frac{1}{2} \}$$

**Theorem (Nemhauser-Trotter)**

There is a minimum vertex cover  $S$  of  $G$  such that

$$V_1 \subseteq S \subseteq V_1 \cup V_{0.5}$$

Let  $S^*$  be a minimum VC      Let  $S = (S^* \setminus V_0) \cup V_1$

proof

$S$  is a VC      since every adjacent vertex of  $V_0$  must be in  $V_1$

claim:  $S$  is minimum      assume by contradiction that  $|S| > |S^*|$

$$\rightarrow |S^* \cap V_0| < |V_1 \setminus S^*|$$

$B$                                $A$

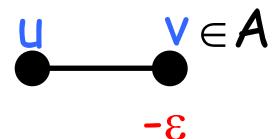
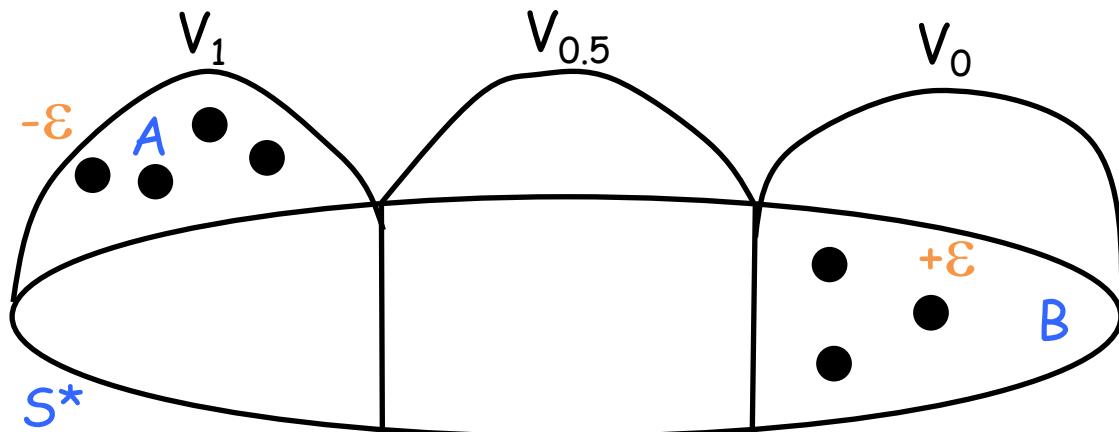
$$y_v = \begin{cases} x_v - \varepsilon & \text{if } v \in A \\ x_v + \varepsilon & \text{if } v \in B \\ x_v & \text{otherwise} \end{cases}$$

$$\varepsilon = \min\{|x_v - \frac{1}{2}| : v \in V_0 \cup V_1\}$$

claim:

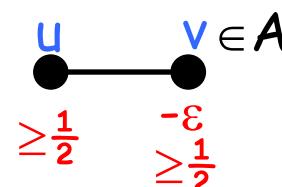
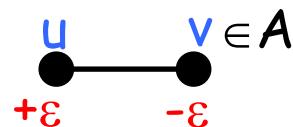
- $y$  is strictly better than  $x$
- $y$  is feasible

contradicts  
optimality of  $x$



interesting case:  
 $u$  or  $v \in A$

since  $S^*$  is a VC then       $u \in B$       or       $u \in S^* \setminus B$



## kernelization

compute an optimal fractional solution  $x$  of the LP-relaxation for the VC instance  $(G, k)$ . Define  $V_0, V_{0.5}, V_1$  as before.

if  $\sum_{v \in V} x_v > k$  conclude that  $(G, k)$  is a No-instance.

Otherwise, greedily pick  $V_1$  in the VC, delete vertices in  $V_1$  and  $V_0$  (and all their incident edges).

The new instance is  $(G' = G - (V_1 \cup V_0), k' = k - |V_1|)$ .

## Theorem

$k$ -Vertex Cover admits a kernel of at most  $2k$  vertices.

### proof

$(G, k)$  is a YES-instance iff  $(G', k')$  is a YES-instance

$$|V(G')| = |V_{0.5}| = \sum_{v \in V_{0.5}} 2x_v \leq 2 \sum_{v \in V} x_v \leq 2k$$



...in the next episode...

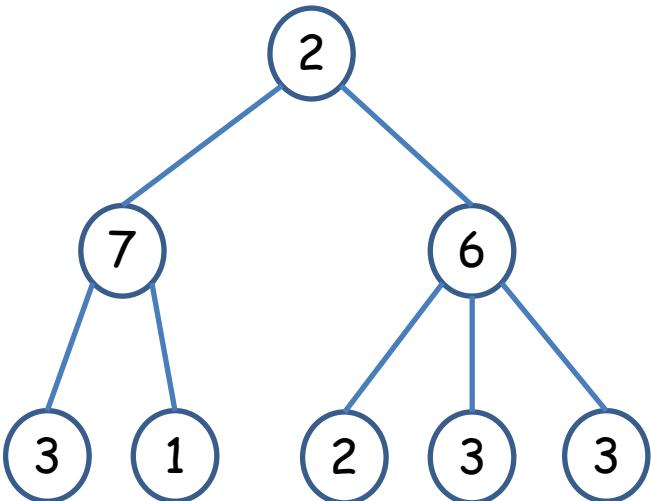
# The party problem

problem: invite people to a party

maximize: total fun factor of the invited people

constraint: everyone should be having fun

do not invite a colleague and his  
direct boss at the same time!



input: a tree with weights  
on the nodes

goal: an independent set of  
maximum total weight

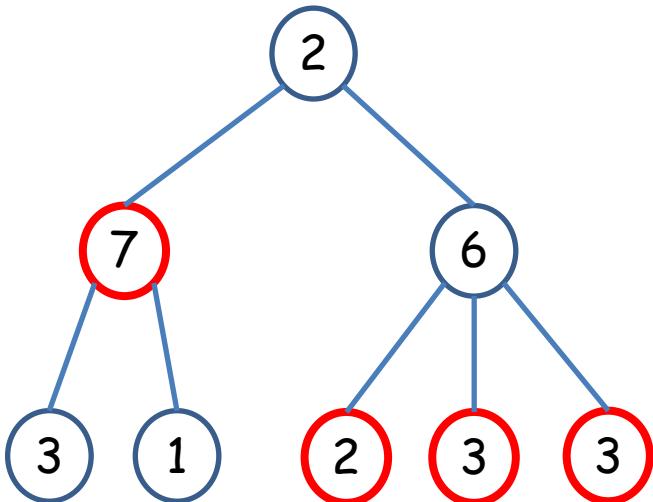
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OPT= 15

Exercise: give a polynomial time algorithm for it