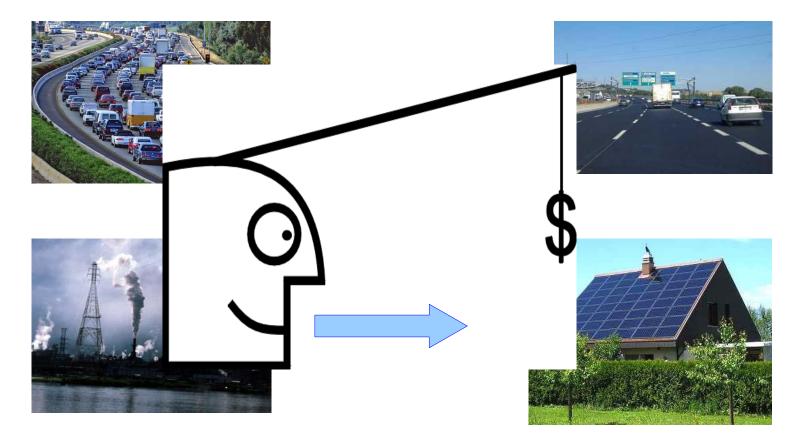
SECOND PART: Algorithmic Mechanism Design

# Mechanism Design



#### Find correct rules/incentives

## The implementation problem

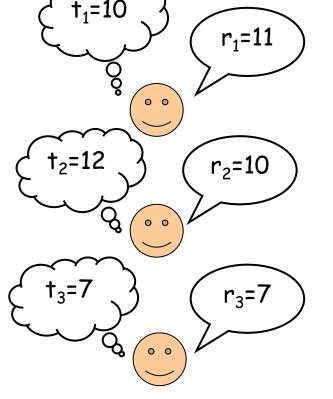
- Imagine you are a planner who develops criteria for social welfare, but you lack information about preferences of individuals. Which social-choice functions (i.e., aggregation of players' preferences w.r.t. to a certain outcome) can be implemented in such a strategic distributed system?
- Why strategic setting?
  - participants act rationally and selfishly
  - Preferences of players (i.e., their opinion about a social status) are private and can be used to manipulate the system

## Designing a Mechanism

- Informally, designing a mechanism means to define a game in which a desired outcome must be reached (in equilibrium)
- However, games induced by mechanisms are different from games in standard form:
  - Players hold independent private values
  - The payoff matrix is a function of these types
- $\Rightarrow$  Games with incomplete information

### An example: auctions

Social-choice function: the winner should be the guy having in mind the highest value for the painting



r<sub>i</sub>: is the amount of money player i **bids** (in a sealed envelope) for the painting

t<sub>i</sub>: is the **maximum** amount of money player i is willing to pay for the painting

If player i wins and has to pay p its utility is  $u_i=t_i-p$ 

The mechanism tells to players: (1) How the item will be allocated (i.e., who will be the winner), depending on the received bids (2) The payment the winner has to return, as a function of the received bids Mechanism degree of freedom

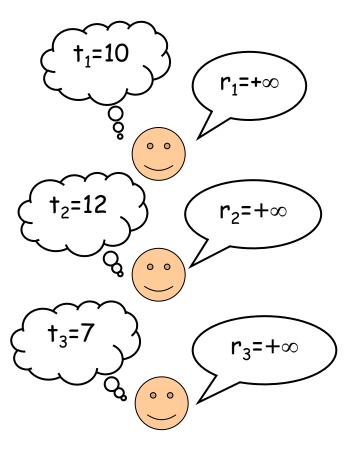
#### The mechanism has to decide:

- The allocation of the item
- The payment by the winner

## …in a way that cannot be manipulated

 the mechanism designer wants to obtain/compute a specific outcome (defined in terms of the real and private values held by the players)

### A simple mechanism: no payment

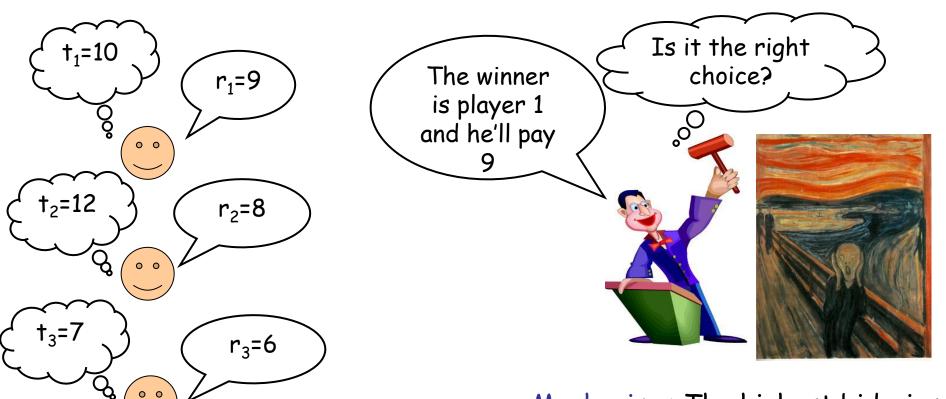




#### The highest bid wins and the price of the item is 0

...it doesn't work...

#### Another simple mechanism: pay your bid



Mechanism: The highest bid wins and the winner will pay his bid

Player i will bid  $r_i < t_i$  (in this way he is guaranteed not to incur a negative utility)

...and so the winner could be the wrong one ...

...it doesn't work...

#### An elegant solution: Vickrey's second price auction



every player has convenience to declare the truth! (we prove it in the next slide) The highest bid wins and the winner will pay the second highest bid In the Vickrey auction, for every player i,  $r_i=t_i$  is a dominant strategy

proof Fix i and t<sub>i</sub>, and look at strategies for player i. Let R= max<sub>j≠i</sub> {r<sub>j</sub>} Case t<sub>i</sub> ≥ R (observe that R is unknown to player i) declaring r<sub>i</sub>=t<sub>i</sub> gives utility u<sub>i</sub>= t<sub>i</sub>-R ≥ 0 (player wins if t<sub>i</sub> > R, while if t<sub>i</sub> = R then player can either win or lose, depending on the tie-breaking rule, but its utility would be 0) declaring any r<sub>i</sub> > R, r<sub>i</sub>≠t<sub>i</sub>, yields again utility u<sub>i</sub>= t<sub>i</sub>-R ≥ 0 (player wins) declaring any r<sub>i</sub> < R yields u<sub>i</sub>=0 (player loses)

R

In the Vickrey auction, for every player i,  $r_i=t_i$  is a dominant strategy

proof Fix i and  $t_i$ , and look at strategies for player i. Let  $R = \max_{j \neq i} \{r_j\}$ Case  $t_i \ge R$  (observe that R is unknown to player i) declaring  $r_i = t_i$  gives utility  $u_i = t_i - R \ge 0$ (player wins if  $t_i > R$ , while if  $t_i = R$  then player can either win or lose, depending on the tie-breaking rule, but its utility would be 0) declaring any  $r_i > R$ ,  $r_i \neq t_i$ , yields again utility  $u_i = t_i - R \ge 0$ (player wins)

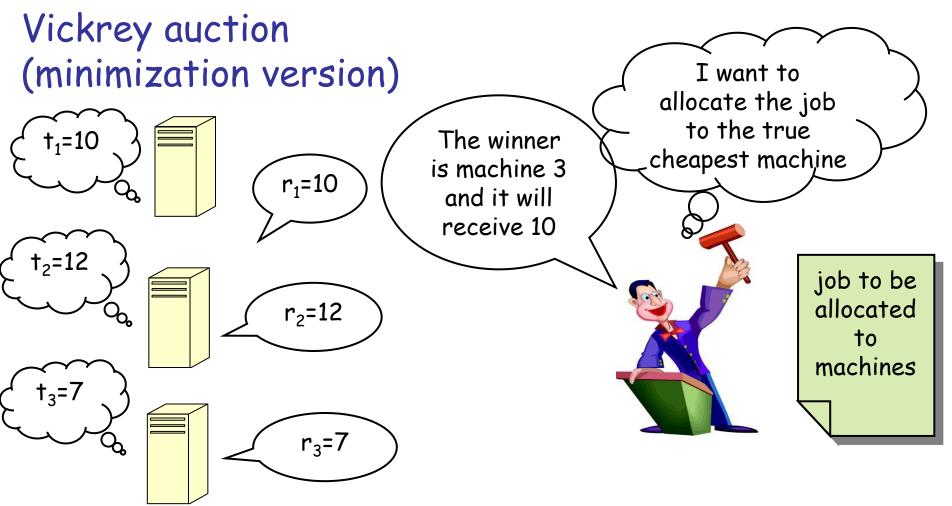
declaring any r<sub>i</sub> < R yields u<sub>i</sub>=0 (player loses)

#### Case $t_i < R$

declaring  $r_i=t_i$  yields utility  $u_i=0$  (player loses) declaring any  $r_i < R$ ,  $r_i \neq t_i$ , yields again utility  $u_i=0$  (player loses) declaring any  $r_i > R$  yields  $u_i=t_i-R < 0$  (player wins)

R

 $\Rightarrow$  In all the cases, reporting a false type produces a not better utility, and so telling the truth is a dominant strategy!



t<sub>i</sub>: cost incurred by i if i does the job

if machine i is selected and receives a payment of p its utility is  $p-t_i$ 

The cheapest bid wins and the winner will get the second cheapest bid Mechanism Design Problem: ingredients (1/2)

- N agents; each agent has some private information t<sub>i</sub>∈T<sub>i</sub> (actually, the only private info) called type
- A set of feasible outcomes F
- For each vector of types t=(t<sub>1</sub>, t<sub>2</sub>, ..., t<sub>N</sub>), a social-choice function f(t)∈F specifies an output that should be implemented (the problem is that types are unknown...)
- Each agent has a strategy space S<sub>i</sub> and performs a strategic action; we restrict ourself to direct revelation mechanisms, in which the action is reporting a value r<sub>i</sub> from the type space (with possibly r<sub>i</sub> ≠ t<sub>i</sub>), i.e., S<sub>i</sub> = T<sub>i</sub>

## Example: the Vickrey Auction

- The set of feasible outcomes is given by all the bidders
- The social-choice function is to allocate to the bidder with lowest true cost:

 $f(t)=arg min_i (t_1, t_2, ..., t_N)$ 

## Mechanism Design Problem: ingredients (2/2)

- For each feasible outcome x∈F, each agent makes a valuation v<sub>i</sub>(†<sub>i</sub>,x) (in terms of some common currency), expressing its preference about that output
- For each reported vector r, each agent receives a payment p<sub>i</sub>(r) in terms of the common currency; payments are used by the system to incentive agents to be collaborative. Then, the utility of the agent if the outcome for r is x(r) will be:

$$u_i(t_i,x(r)) = p_i(r) - v_i(t_i,x(r))$$

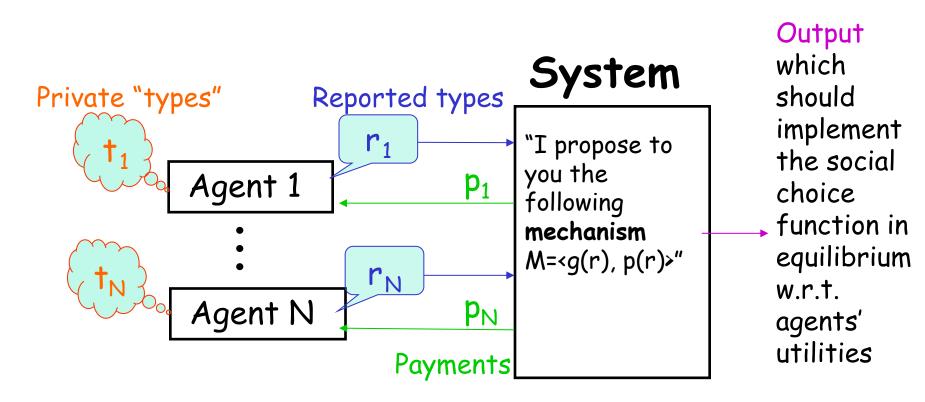
# Mechanism Design Problem: the goal

Implement (according to a given equilibrium concept) the social-choice function, i.e., provide a **mechanism** M=<g(r), p(r)>, where:

- g(r) is an algorithm which computes an outcome x=g(r) as a function of the reported types r
- p(r) is a payment scheme specifying a payment (to each agent) w.r.t. the reported types r

such that x=g(r)=f(t) is provided in equilibrium w.r.t. to the utilities of the agents.

## Mechanism Design: a picture



Each agent reports strategically to maximize its utility...

...which depends (also) on the payment... ...which is a function of the reported types!

# Implementation with dominant strategies

Def.: A mechanism  $M=\langle g(),p() \rangle$  is an *implementation* with dominant strategies if there exists a reported type vector  $r^*=(r_1^*, r_2^*, ..., r_N^*)$  such that  $f(t)=g(r^*)$  in dominant strategy equilibrium, i.e., for each agent i and for each reported type vector  $r = (r_1, r_2, ..., r_N)$ , it holds:  $u_i(t_i, (r_{-i}, r_i^*)) \ge u_i(t_i, (r_{-i}, r_i))$ 

# Strategy-Proof Mechanisms

- If truth telling is the dominant strategy in a mechanism then the mechanism is called Strategy-Proof or truthful or incentive compatible ⇒ r\*=t.
  - ⇒ Agents report their true types instead of strategically manipulating it
  - $\Rightarrow$  The algorithm of the mechanism runs on the true input

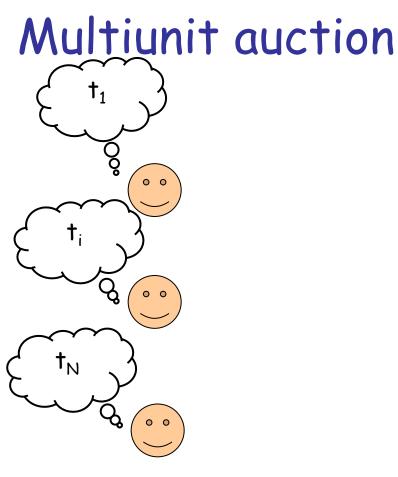
## Truthful Mechanism Design: Economics Issues

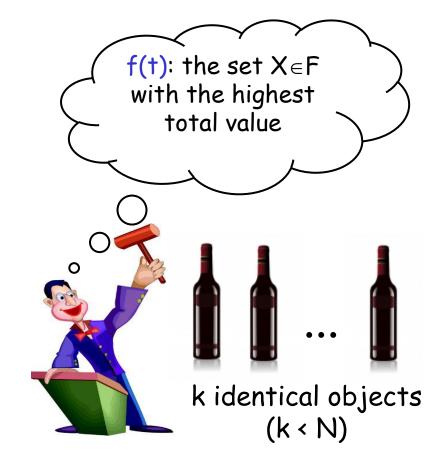
QUESTION: How to design a truthful mechanism? Or, in other words:

- 1. How to design g(r), and
- 2. How to define the payment scheme

in such a way that the underlying socialchoice function is implemented truthfully? Under which conditions can this be done?

## Some examples





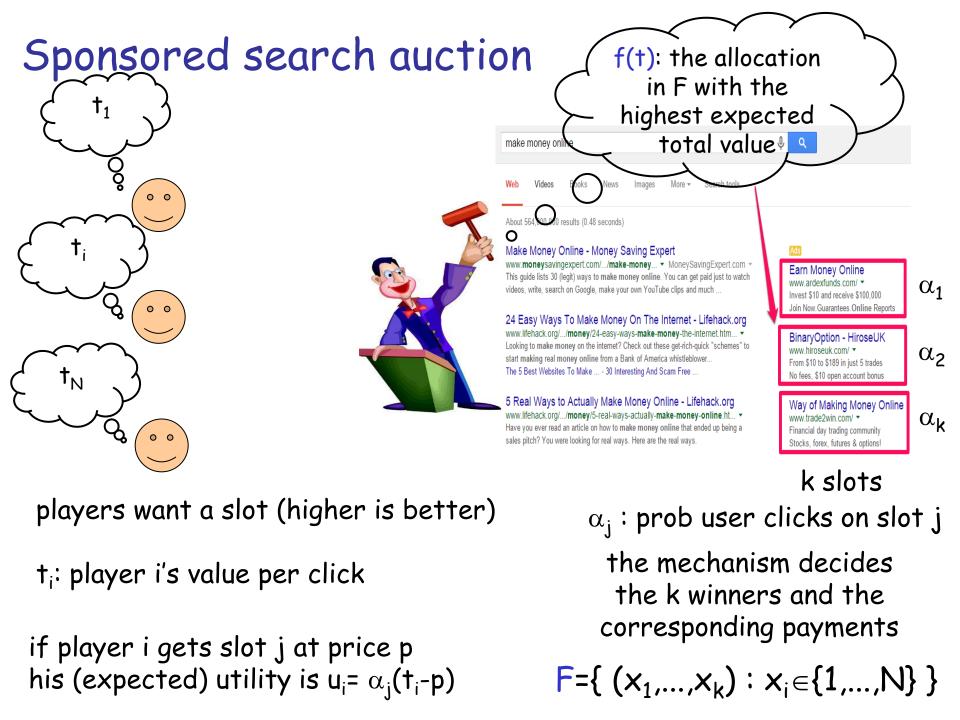
Each of N players wants an object

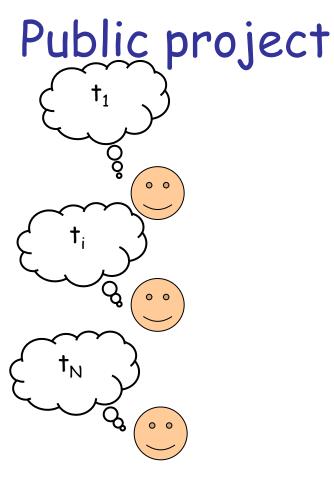
t<sub>i</sub>: value player i is willing to pay

if player i gets an object at price p his utility is  $u_i=t_i-p$ 

the mechanism decides the set of k winners and the corresponding payments

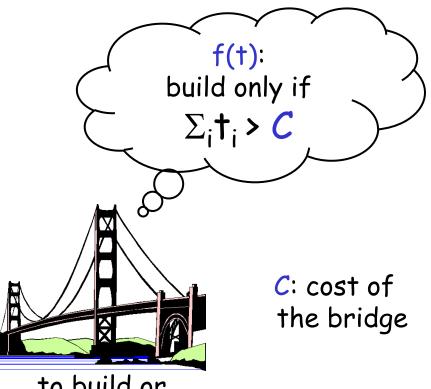
 $F=\{ X \subseteq \{1,...,N\} : |X|=k \}$ 





t<sub>i</sub>: value of the bridge for citizen i

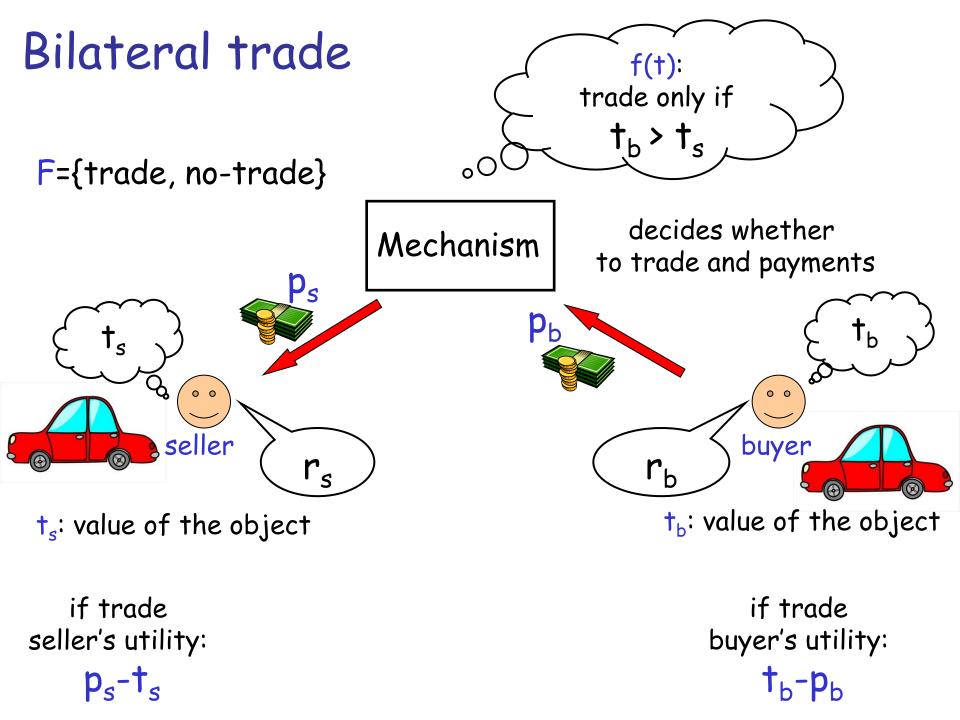
if the bridge is built and citizen i has to pay p<sub>i</sub> his utility is u<sub>i</sub>=t<sub>i</sub>-p<sub>i</sub>

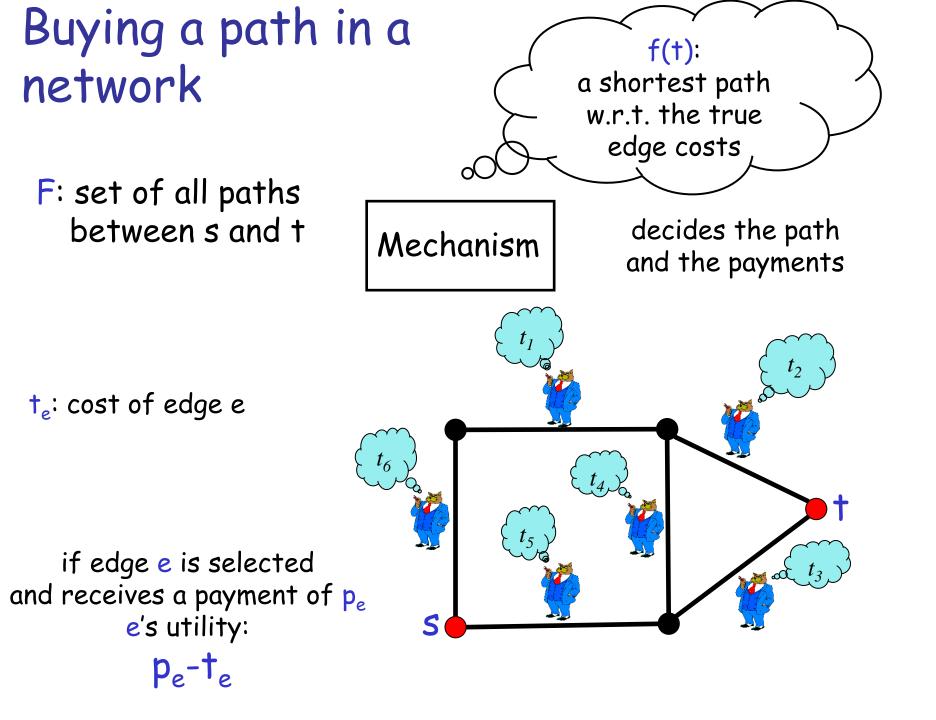


to build or not to build?

> the mechanism decides whether to build and the payments from citizens

F={build, not-build}







# How to design truthful mechanisms?

## Some remarks

- we'll describe results for minimization problems (maximization problems are similar)
- We have:
  - for each x∈F, valuation function v<sub>i</sub>(t<sub>i</sub>,x) represents a cost incurred by player i in the solution x
  - the social function f(t) maps the type vector t into a solution x which minimizes some measure of x
  - payments are from the mechanism to agents

#### • Utilitarian Problems: A problem is utilitarian if its objective function is such that $f(t) = \arg \min_{x \in F} \sum_i v_i(t_i, x)$

notice: the auction problem is utilitarian

...for utilitarian problems there is a class of truthful mechanisms...

Vickrey-Clarke-Groves (VCG) Mechanisms

A VCG-mechanism is (the only) strategy-proof mechanism for utilitarian problems:

Algorithm g(r) computes:

 $x = arg \min_{y \in F} \sum_{i} v_i(r_i, y)$ 

 Payment function for player i: p<sub>i</sub>(r) = h<sub>i</sub>(r<sub>-i</sub>) - ∑<sub>j≠i</sub> v<sub>j</sub>(r<sub>j</sub>,g(r)) where h<sub>i</sub>(r<sub>-i</sub>) is an arbitrary function of the reported types of players other than player i.
What about non-utilitarian problems? General strategy-proof mechanisms are known only when the type is a single parameter. (We'll see.)

#### Theorem

#### VCG-mechanisms are truthful for utilitarian problems

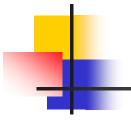
#### proof

- Fix i,  $r_{-i}$ ,  $t_i$ . Let  $\check{r}=(r_{-i},t_i)$  and consider a strategy  $r_i \neq t_i$
- $\mathbf{x}=g(\mathbf{r}_{-i},\mathbf{t}_{i})=g(\check{\mathbf{r}}) \qquad \mathbf{x}'=g(\mathbf{r}_{-i},\mathbf{r}_{i})$

$$\begin{aligned} u_i(t_i, (r_{-i}, t_i)) &= [h_i(r_{-i}) - \Sigma_{j\neq i} v_j(r_j, x)] - v_i(t_i, x) &= h_i(r_{-i}) - \Sigma_j v_j(\check{r}_j, x) \\ u_i(t_i, (r_{-i}, r_i)) &= [h_i(r_{-i}) - \Sigma_{j\neq i} v_j(r_j, x')] - v_i(t_i, x') = h_i(r_{-i}) - \Sigma_j v_j(\check{r}_j, x') \end{aligned}$$

but x is an optimal solution w.r.t.  $\check{r} = (r_{-i}, t_i)$ , i.e., x = arg min<sub>y \in F</sub>  $\sum_i v_i(\check{r}, y)$ 

 $\Sigma_{j} \mathbf{v}_{j}(\check{\mathbf{r}}_{j}, \mathbf{x}) \leq \Sigma_{j} \mathbf{v}_{j}(\check{\mathbf{r}}_{j}, \mathbf{x}') \implies \mathbf{u}_{i}(\mathsf{t}_{i}, (\mathsf{r}_{-i}, \mathsf{t}_{i})) \geq \mathbf{u}_{i}(\mathsf{t}_{i}, (\mathsf{r}_{-i}, \mathsf{r}_{i})).$ 



# How to define $h_i(r_i)$ ?

notice: not all functions make sense

what happens if we set  $h_i(r_{-i})=0$ in the Vickrey auction?

#### The Clarke payments

solution minimizing the sum of valuations when i doesn't play

This is a special VCG-mechanism in which  $h_i(\mathbf{r}_{-i}) = \sum_{j \neq i} v_j(\mathbf{r}_j, g(\mathbf{r}_{-i}))$   $\Rightarrow p_i(\mathbf{r}) = \sum_{j \neq i} v_j(\mathbf{r}_j, g(\mathbf{r}_{-i})) - \sum_{j \neq i} v_j(\mathbf{r}_j, g(\mathbf{r}))$ 

 With Clarke payments, one can prove that agents' utility are always non-negative
agents are interested in playing the game Clarke mechanism for the Vickrey auction (minimization version)

- The VCG-mechanism is:
  - $x=g(r):= arg min_{x \in F} \sum_i v_i(r_i,x)$ 
    - allocate to the bidder with lowest reported cost

• 
$$\mathbf{p}_i = \sum_{j \neq i} \mathbf{v}_j(\mathbf{r}_j, g(\mathbf{r}_{-i})) - \sum_{j \neq i} \mathbf{v}_j(\mathbf{r}_j, \mathbf{x})$$

...pay the winner the second lowest offer, and pay 0 the losers Mechanism Design: Algorithmic Issues

QUESTION: What is the time complexity of the mechanism? Or, in other words:

- What is the time complexity of g(r)?
- What is the time complexity to calculate the N payment functions?
- What does it happen if it is NP-hard to compute the underlying social-choice function?

Algorithmic mechanism design for graph problems

 Following the Internet model, we assume that each agent owns a single edge of a graph G=(V,E), and establishes the cost for using it

 $\Rightarrow$  The agent's type is the true weight of the edge

- Classic optimization problems on G become mechanism design optimization problems!
- Many basic network design problems have been faced: shortest path (SP), single-source shortest paths tree (SPT), minimum spanning tree (MST), minimum Steiner tree, and many others

## Summary of main results

|     | Centralized<br>algorithm   | Selfish-edge<br>mechanism |
|-----|----------------------------|---------------------------|
| SP  | O(m+n log n)               | O(m+n log n)              |
| SPT | O(m+n log n)               | O(m+n log n)              |
| MST | <b>Ο(m</b> α <b>(m,n))</b> | <b>Ο(m</b> α(m,n))        |

 $\Rightarrow$  For all these basic problems, the time complexity of the mechanism equals that of the canonical centralized algorithm!