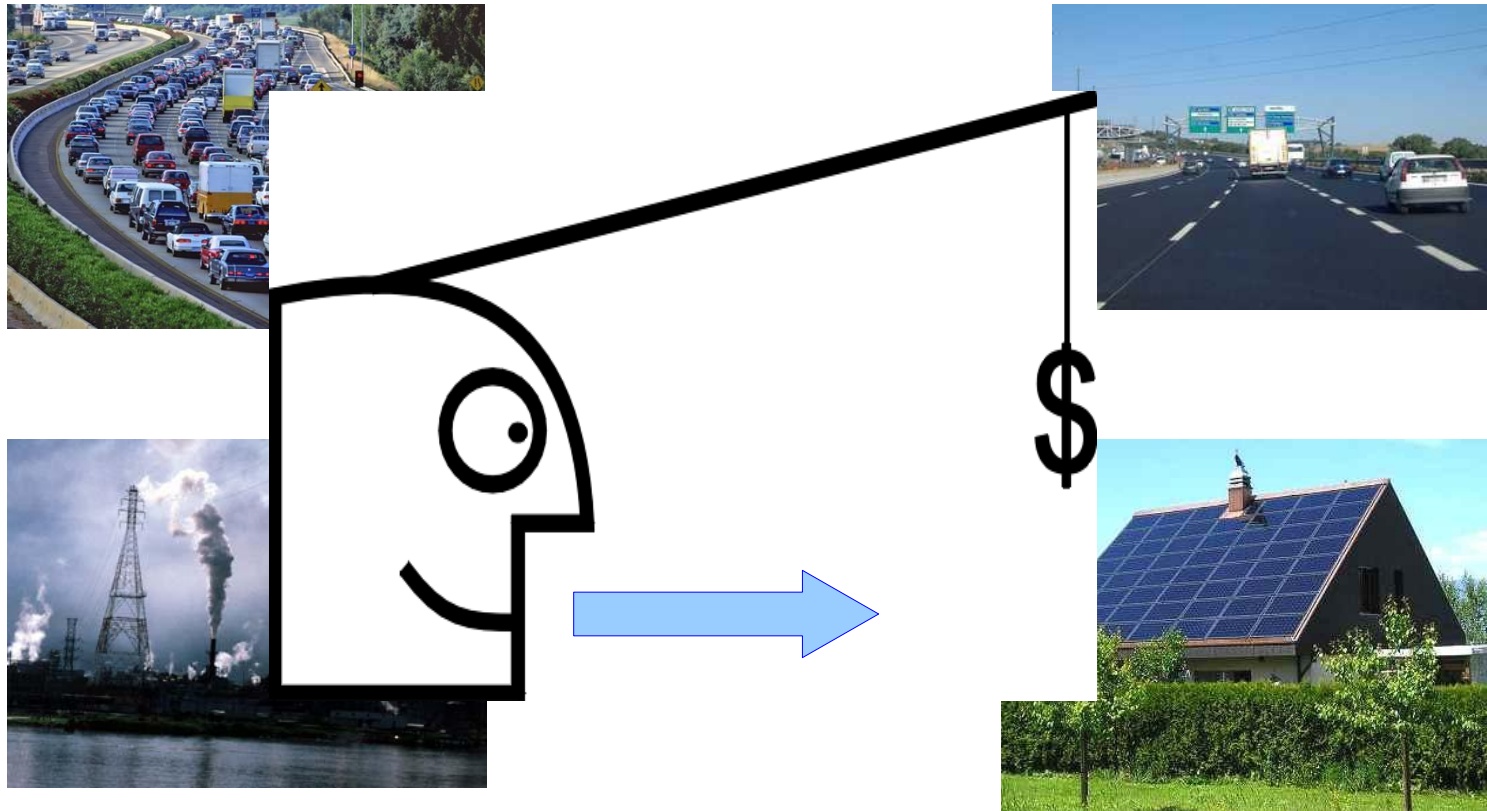


SECOND PART:

Algorithmic Mechanism Design

Mechanism Design



Find **correct** rules/incentives



The implementation problem

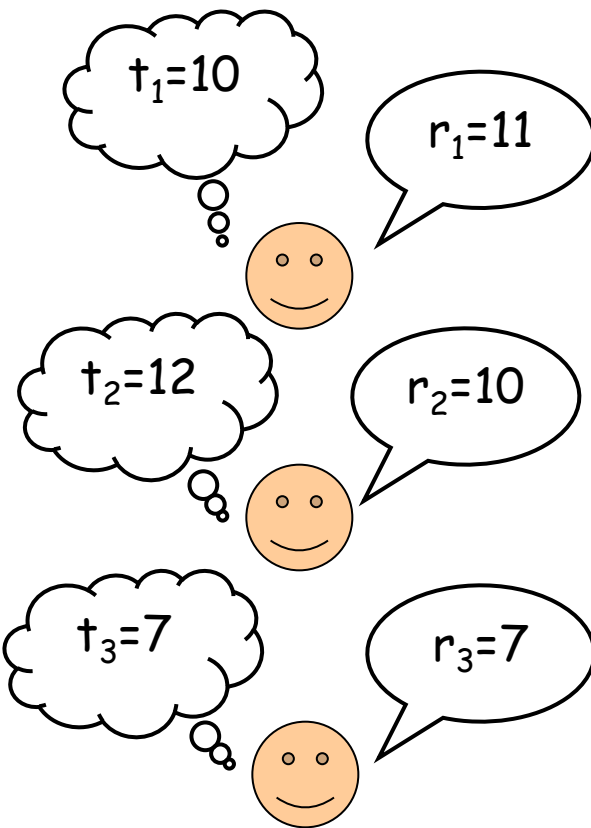
- Imagine you are a planner who develops criteria for social welfare, but **you lack information about preferences of individuals**. Which social-choice functions (i.e., aggregation of players' preferences w.r.t. to a certain outcome) can be implemented in such a strategic distributed system?
- Why **strategic** setting?
 - participants act **rationally** and **selfishly**
 - Preferences of players (i.e., their opinion about a social status) are **private** and can be used to manipulate the system



Designing a Mechanism

- Informally, designing a mechanism means to define a **game** in which a desired outcome must be reached (in equilibrium)
 - However, games induced by mechanisms are different from games in standard form:
 - Players hold independent **private values**
 - The payoff matrix is a function of these types
- ⇒ Games with **incomplete information**

An example: auctions

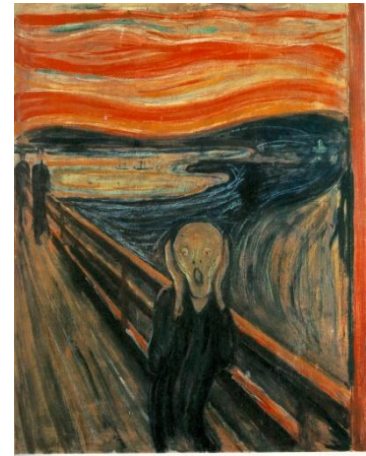


t_i is the **maximum** amount of money player i is willing to pay for the painting

If player i wins and has to pay p
its utility is $u_i = t_i - p$

r_i is the amount of money player i bids (in a sealed envelope) for the painting

Social-choice function:
the winner should be the guy **having in mind** the highest value for the painting



The mechanism tells to players:

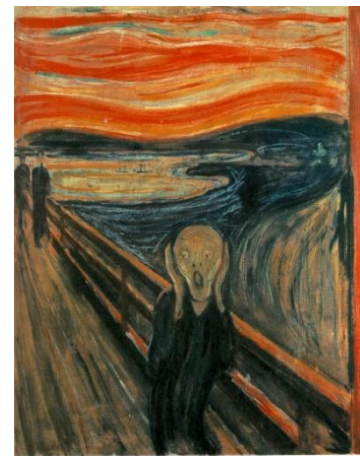
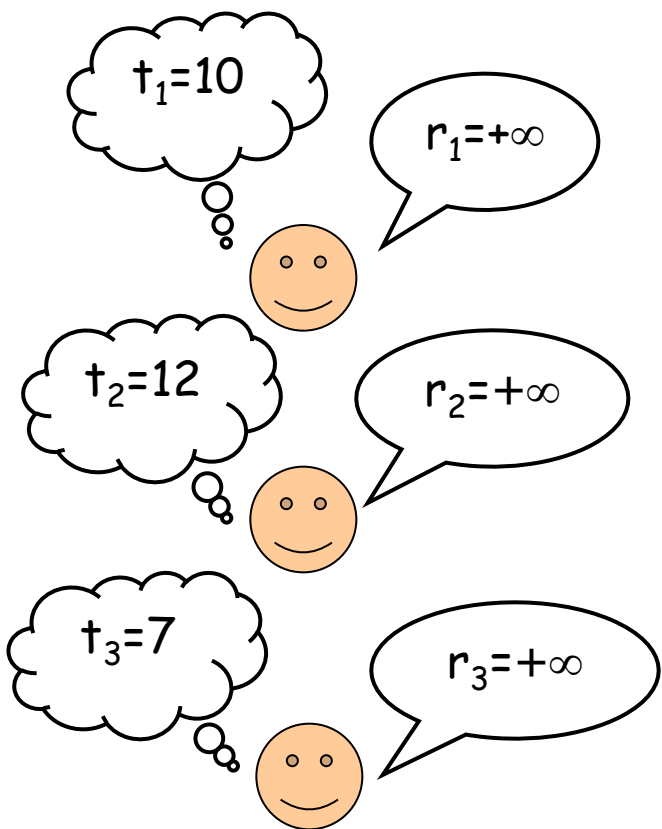
- (1) How the item will be allocated (i.e., who will be the **winner**), depending on the received bids
- (2) The payment the winner has to return, as a function of the received bids



Mechanism degree of freedom

- The mechanism has to decide:
 - The allocation of the item (social choice)
 - The payment by the winner
- ...in a way that cannot be manipulated
 - the mechanism designer wants to obtain/compute a specific outcome (defined in terms of the real and private values held by the players)

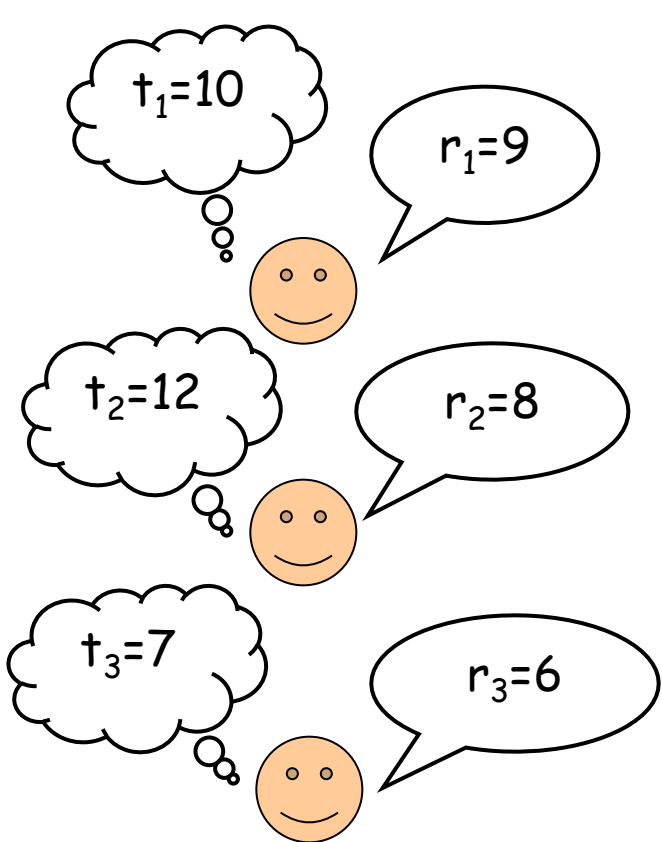
A simple mechanism: no payment



The highest bid wins
and the price of the item
is 0

...it doesn't work...

Another simple mechanism: pay your bid



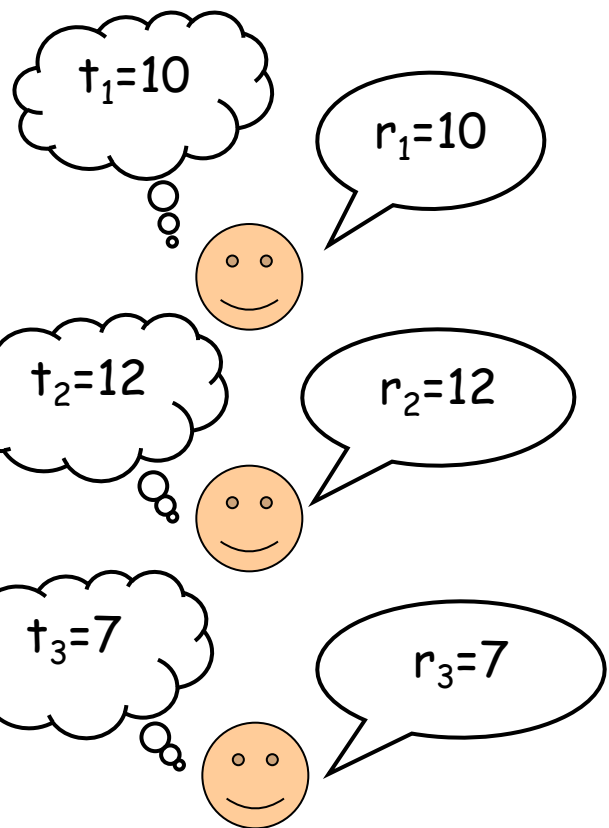
Mechanism: The highest bid wins and the winner will pay his bid

Player i may bid $r_i < t_i$ (in this way he is guaranteed not to incur a negative utility)

...and so the winner could be the wrong one...

...it doesn't work...

An elegant solution: Vickrey's second price auction



The winner is player 2 and he'll pay 10



every player has convenience
to declare the truth!
(we prove it in the next slide)

The highest bid wins
and the winner will
pay the second
highest bid

Theorem

In the Vickrey auction, for every player i , $r_i = t_i$ is a dominant strategy

proof Fix i and t_i , and look at strategies for player i . Let $R = \max_{j \neq i} \{r_j\}$

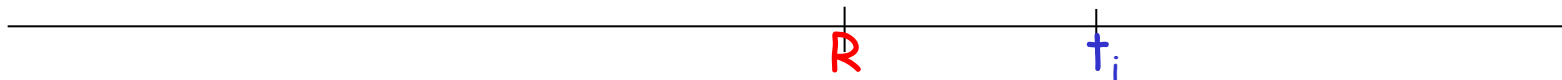
Case $t_i \geq R$ (observe that R is unknown to player i)

declaring $r_i = t_i$ gives utility $u_i = t_i - R \geq 0$

(player **wins** if $t_i > R$, while if $t_i = R$ then player can either **win** or **lose**, depending on the tie-breaking rule, but its utility would be 0)

declaring any $r_i > R$, $r_i \neq t_i$, yields again utility $u_i = t_i - R \geq 0$
(player **wins**)

declaring any $r_i < R$ yields $u_i = 0$ (player **loses**)



Theorem

In the Vickrey auction, for every player i , $r_i = t_i$ is a dominant strategy

proof Fix i and t_i , and look at strategies for player i . Let $R = \max_{j \neq i} \{r_j\}$

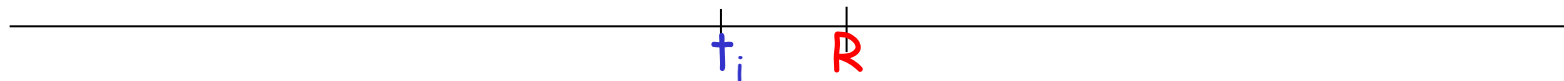
Case $t_i \geq R$ (observe that R is unknown to player i)

declaring $r_i = t_i$ gives utility $u_i = t_i - R \geq 0$

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declaring any $r_i > R$, $r_i \neq t_i$, yields again utility $u_i = t_i - R \geq 0$
(player **wins**)

declaring any $r_i < R$ yields $u_i = 0$ (player **loses**)



Case $t_i < R$

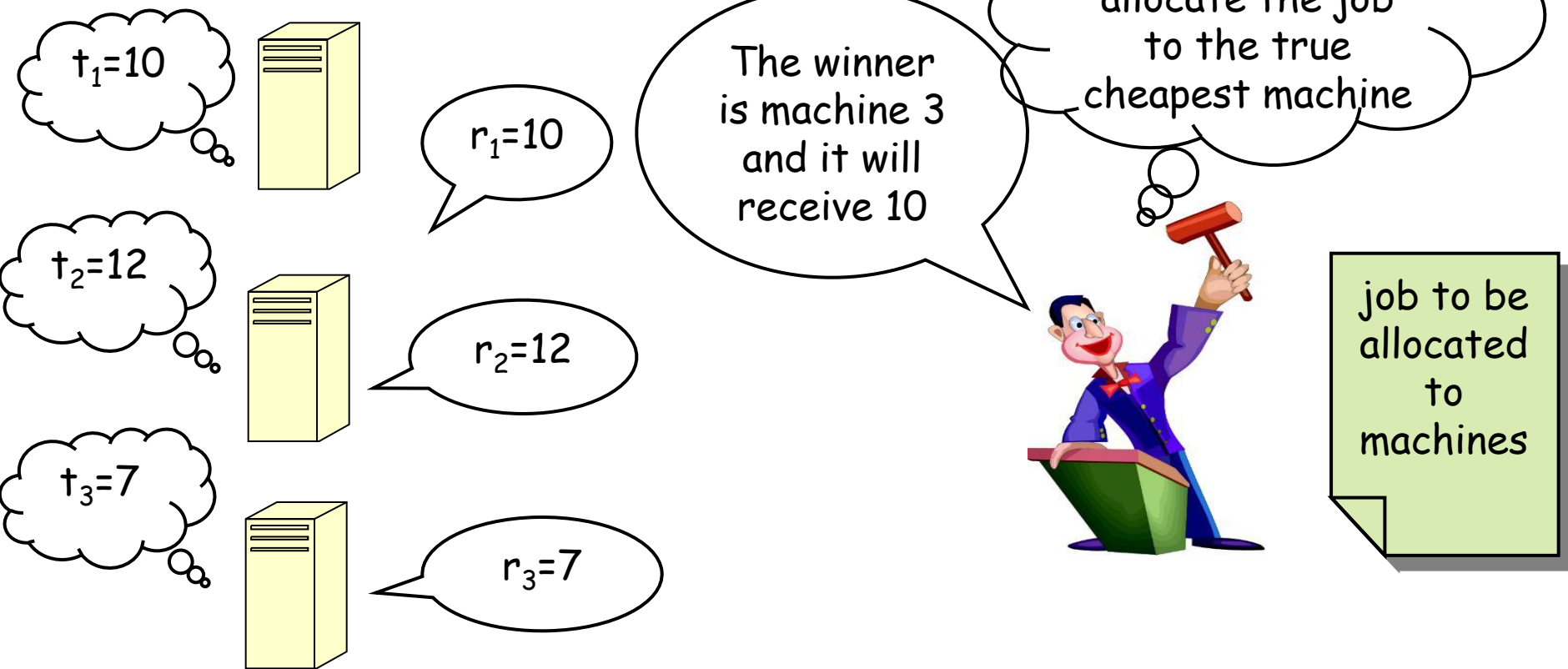
declaring $r_i = t_i$ yields utility $u_i = 0$ (player **loses**)

declaring any $r_i < R$, $r_i \neq t_i$, yields again utility $u_i = 0$ (player **loses**)

declaring any $r_i > R$ yields $u_i = t_i - R < 0$ (player **wins**)

\Rightarrow In all the cases, reporting a **false** type produces a not better **utility**, and so telling the truth is a **dominant strategy**! 

Vickrey auction (minimization version)



The cheapest bid wins
and the winner will
get the second
cheapest bid

t_i : **cost** incurred by i if i does the job
if machine i is selected and receives
a payment of p its **utility** is $p - t_i$

Mechanism Design Problem: ingredients (1/2)

- N agents; each agent has some **private** information $t_i \in T_i$ (actually, the **only** private info) called **type**
- A set of **feasible outcomes** F
- For each vector of types $t = (t_1, t_2, \dots, t_N)$, a **social-choice function** $f(t) \in F$ specifies an output that should be implemented (the problem is that types are unknown...)
- Each agent has a **strategy space** S_i and performs a strategic action; we restrict ourselves to *direct revelation mechanisms*, in which the action is **reporting a value** r_i from the type space (with possibly $r_i \neq t_i$), i.e., $S_i = T_i$

Example: the Vickrey Auction

- The set of feasible outcomes is given by all the bidders
- The social-choice function is to allocate to the bidder with lowest **true cost**:

$$f(t) = \arg \min_i (t_1, t_2, \dots, t_N)$$

- Each agent knows its cost for doing the job (**type**), but not the others' one:
 - $T_i = [0, +\infty]$: The agent's cost may be any positive amount of money
 - $t_i = 80$: Minimum amount of money the agent i is willing to be paid
 - $r_i = 85$: Exact amount of money the agent i bids to the system for doing the job (not known to other agents)

Mechanism Design Problem: ingredients (2/2)

- For each feasible outcome $x \in F$, each agent makes a **valuation** $v_i(t_i, x)$ (in terms of some common currency), expressing its preference about that output
 - Vickrey Auction: If agent i wins the auction then its valuation is equal to its **actual cost** $= t_i$ for doing the job, otherwise it is 0
- For each reported vector r , each agent receives a **payment** $p_i(r)$ in terms of the common currency; payments are used by the system to incentive agents to be collaborative. Then, the **utility** of the agent if the outcome for r is $x(r)$ will be:

$$u_i(t_i, r) = p_i(r) - v_i(t_i, x(r))$$

- Vickrey Auction: If agent's cost for the job is **80**, and it gets the contract for **100** (i.e., it is paid **100**), then its utility is **20**

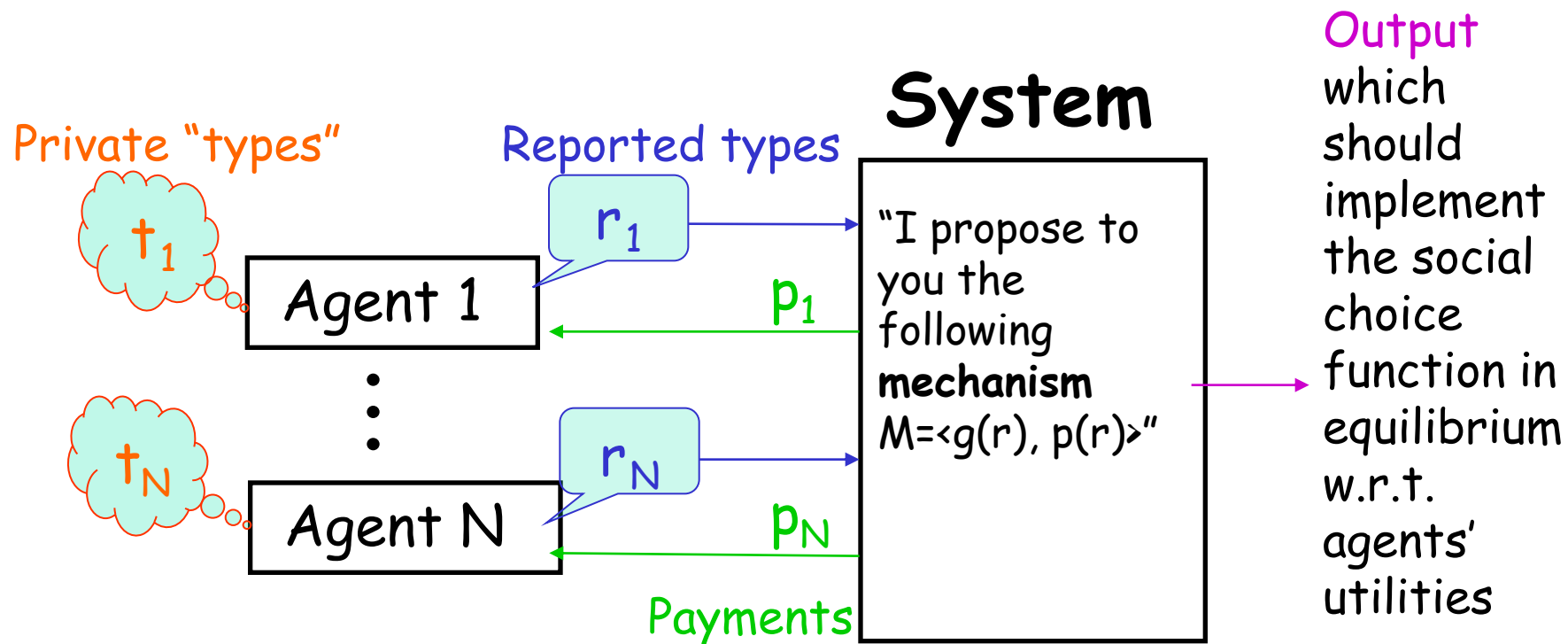
Mechanism Design Problem: the goal

Implement (according to a given equilibrium concept) the social-choice function, i.e., provide a mechanism $M = \langle g(r), p(r) \rangle$, where:

- $g(r)$ is an **algorithm** which computes an outcome $x = g(r)$ as a function of the reported types r
- $p(r)$ is a **payment scheme** specifying a payment (to each agent) w.r.t. the reported types r

such that $x = g(r) = f(t)$ is provided in equilibrium w.r.t. to the utilities of the agents.

Mechanism Design: a picture



Each agent reports strategically to maximize its utility...
...which depends (also) on the payment...
...which is a function of the reported types!

Game induced by a MD problem

This is a game in which:

- The N agents are the players
- The payoff matrix is given (in implicit form) by the utility functions

Implementation with dominant strategies

Def.: A mechanism $M=\langle g(),p()\rangle$ is an *implementation with dominant strategies* if there exists a reported type vector $r^*=(r_1^*, r_2^*, \dots, r_N^*)$ such that $f(t)=g(r^*)$ in dominant strategy equilibrium, i.e., for each agent i and for each reported type vector $r=(r_1, r_2, \dots, r_N)$, it holds:

$$u_i(t_i, (r_{-i}, r_i^*)) \geq u_i(t_i, (r_{-i}, r_i))$$

Strategy-Proof Mechanisms

- If *truth telling* is the dominant strategy in a mechanism then the mechanism is called *Strategy-Proof* or *truthful* or *incentive compatible*
 - ⇒ $r^* = t$.
 - ⇒ Agents report their true types instead of strategically manipulating it
 - ⇒ The algorithm of the mechanism runs on the true input

Truthful Mechanism Design: Economics Issues

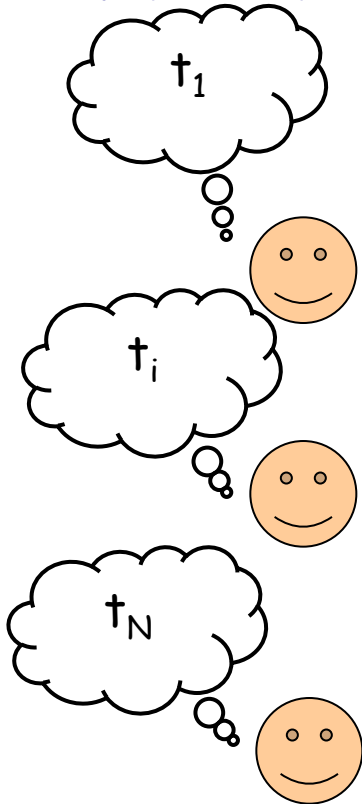
QUESTION: How to design a truthful mechanism? Or, in other words:

1. How to design $g(r)$, and
2. How to define the **payment scheme**

in such a way that the underlying social-choice function is implemented truthfully? Under which conditions can this be done?

Some examples

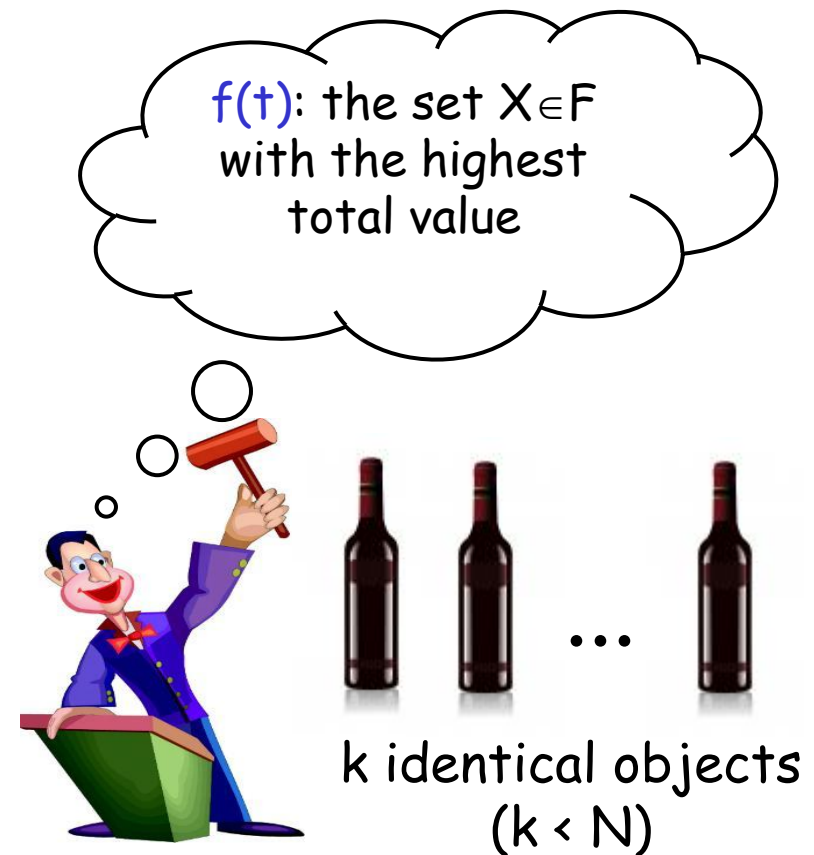
Multiunit auction



Each of N players wants an object

t_i : value player i is willing to pay

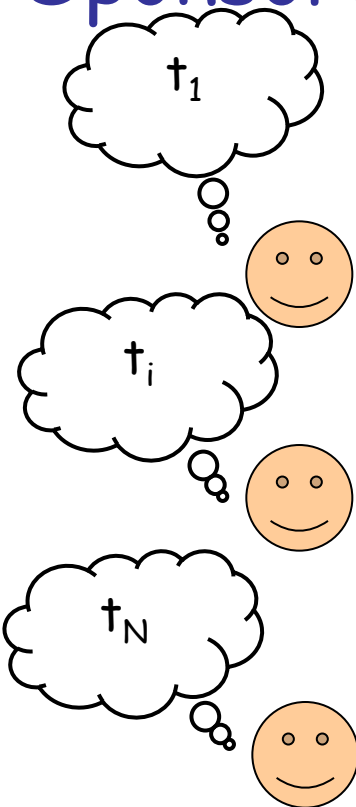
if player i gets an object at price p
his utility is $u_i = t_i - p$



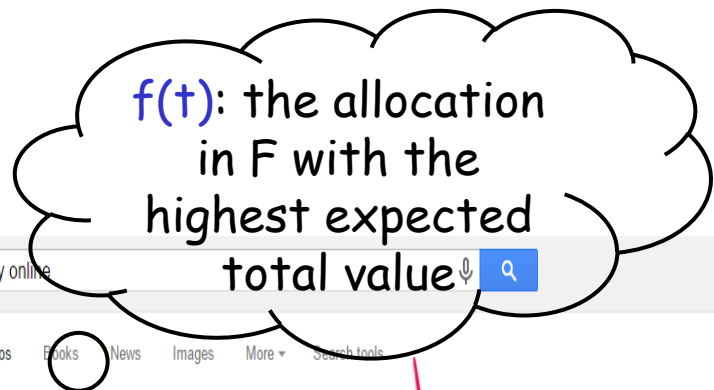
the mechanism decides
the set of k winners and the
corresponding payments

$$F = \{ X \subseteq \{1, \dots, N\} : |X| = k \}$$

Sponsored search auction



A screenshot of a Google search results page for the query "make money online". The search bar shows the query and a magnifying glass icon. Below the search bar, there are tabs for Web, Videos, Books, News, Images, and More. The search results show "About 564,000 results (0.48 seconds)". The first organic result is "Make Money Online - Money Saving Expert" from www.moneysavingexpert.com. Below the organic results, there are three sponsored ads highlighted with pink boxes. The first ad is "Earn Money Online" from www.ardextfunds.com, the second is "BinaryOption - HiroseUK" from www.hiroseuk.com, and the third is "Way of Making Money Online" from www.trade2win.com. A pink arrow points from the text $f(t)$ in the cloud to the sponsored ads section.



players want a slot (higher is better)

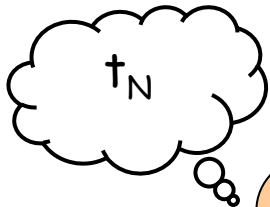
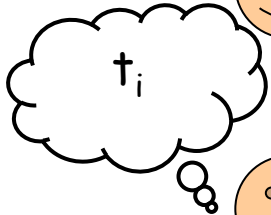
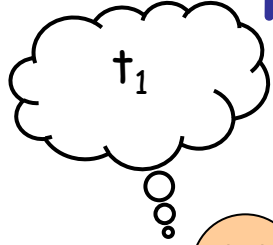
t_i : player i 's value per click

if player i gets slot j at price p
his (expected) utility is $u_i = \alpha_j(t_i - p)$

k slots
 α_j : prob user clicks on slot j
the mechanism decides
the k winners and the
corresponding payments

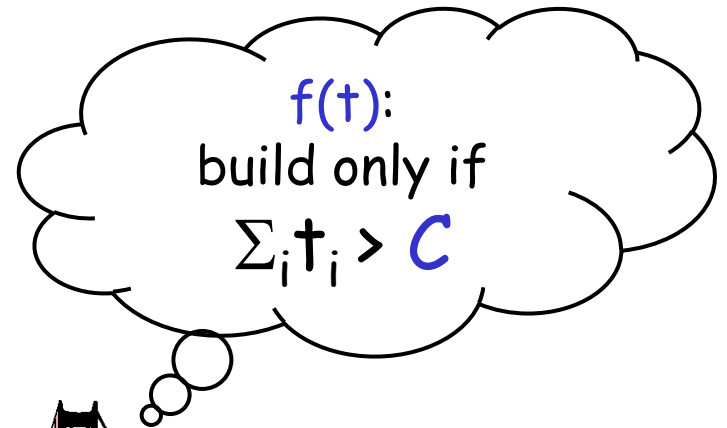
$$F = \{ (x_1, \dots, x_k) : x_i \in \{1, \dots, N\} \}$$

Public project



t_i : value of the bridge
for citizen i

if the bridge is built and
citizen i has to pay p_i
his utility is $u_i = t_i - p_i$



to build or
not to build?

C : cost of
the bridge

the mechanism decides
whether to build and the
payments from citizens

$F = \{\text{build, not-build}\}$

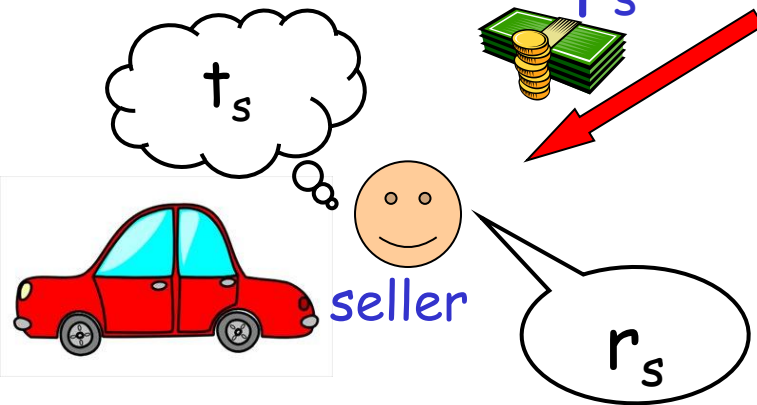
Bilateral trade

$F = \{\text{trade, no-trade}\}$

$f(t)$:
trade only if
 $t_b > t_s$

Mechanism

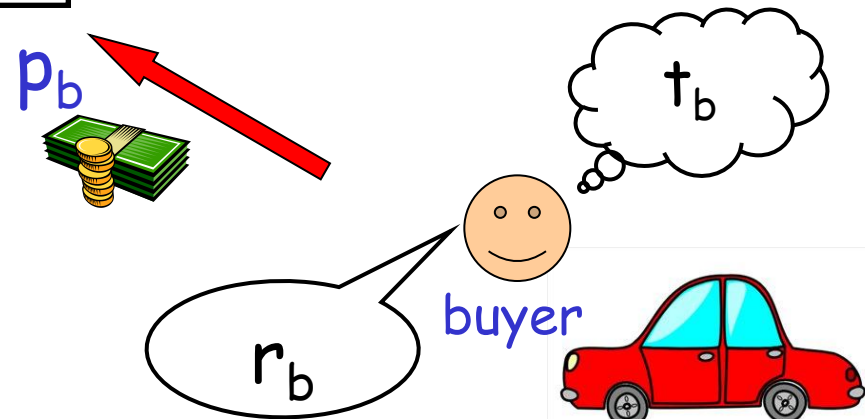
decides whether
to trade and payments



t_s : value of the object

if trade
seller's utility:

$$p_s - t_s$$



t_b : value of the object

if trade
buyer's utility:

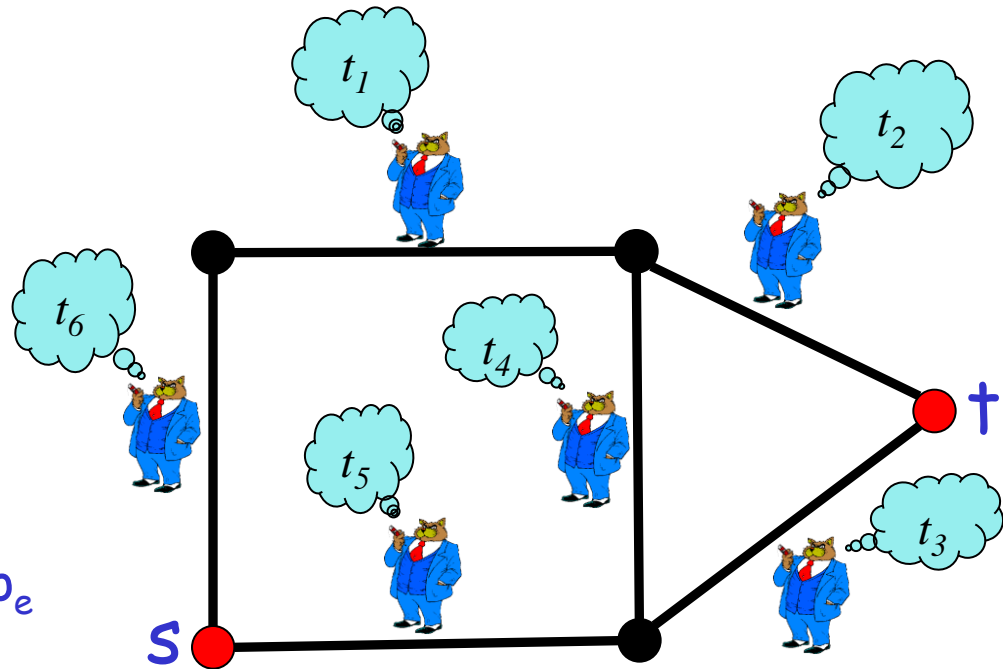
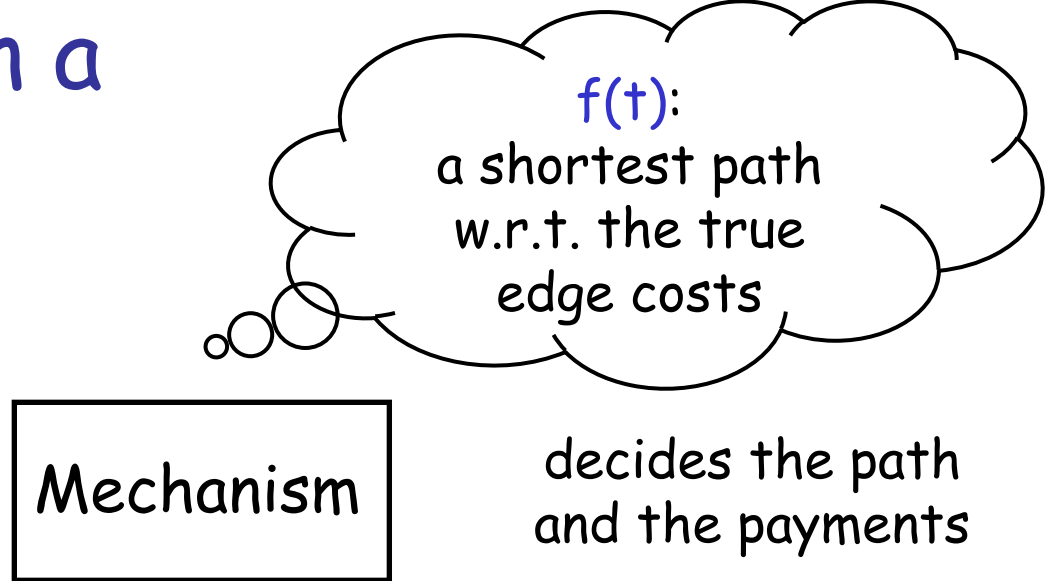
$$t_b - p_b$$

Buying a path in a network

F : set of all paths between s and t

t_e : cost of edge e

if edge e is selected and receives a payment of p_e
 e 's utility:
 $p_e - t_e$



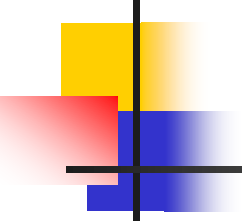


How to design truthful
mechanisms?



Some remarks

- we'll describe results for minimization problems (maximization problems are similar)
- We have:
 - for each $x \in F$, valuation function $v_i(t_i, x)$ represents a cost incurred by player i in the solution x
 - the social function $f(t)$ maps the type vector t into a solution x which minimizes some measure of x
 - payments are from the mechanism to agents

- 
-
- **Utilitarian Problems:** A problem is *utilitarian* if its objective function is such that $f(\mathbf{t}) = \arg \min_{x \in F} \sum_i v_i(\mathbf{t}_i, x)$

notice: the auction problem is utilitarian

...for utilitarian problems there is a class
of truthful mechanisms...



Vickrey-Clarke-Groves (VCG) Mechanisms

- A VCG-mechanism is (the only) strategy-proof mechanism for **utilitarian** problems:
 - Algorithm $g(r)$ computes:
$$x = \arg \min_{y \in F} \sum_i v_i(r_i, y)$$
 - Payment function for player i :
$$p_i(r) = h_i(r_{-i}) - \sum_{j \neq i} v_j(r_j, g(r))$$
where $h_i(r_{-i})$ is an arbitrary function of the reported types of players other than player i .
- What about **non-utilitarian** problems? Strategy-proof mechanisms are known only when the type is a **single** parameter.

Theorem

VCG-mechanisms are truthful for utilitarian problems

proof

Fix i , r_{-i} , t_i . Let $\check{r} = (r_{-i}, t_i)$ and consider a strategy $r_i \neq t_i$

$$x = g(r_{-i}, t_i) = g(\check{r}) \quad x' = g(r_{-i}, r_i)$$

$$u_i(t_i, (r_{-i}, t_i)) = [h_i(r_{-i}) - \sum_{j \neq i} v_j(r_j, x)] - v_i(t_i, x) = h_i(r_{-i}) - \sum_j v_j(\check{r}_j, x)$$

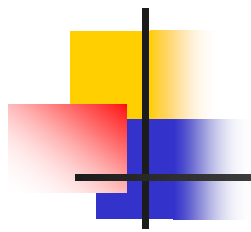
$$u_i(t_i, (r_{-i}, r_i)) = [h_i(r_{-i}) - \sum_{j \neq i} v_j(r_j, x')] - v_i(t_i, x') = h_i(r_{-i}) - \sum_j v_j(\check{r}_j, x')$$

but x is an optimal solution w.r.t. $\check{r} = (r_{-i}, t_i)$, i.e.,

$$x = \arg \min_{y \in F} \sum_i v_i(\check{r}, y)$$

$$\Rightarrow \sum_j v_j(\check{r}_j, x) \leq \sum_j v_j(\check{r}_j, x') \Rightarrow u_i(t_i, (r_{-i}, t_i)) \geq u_i(t_i, (r_{-i}, r_i)).$$





How to define $h_i(r_{-i})$?

notice: not all functions make sense

what happens if we set $h_i(r_{-i})=0$
in the Vickrey auction?

The Clarke payments

solution minimizing the sum
of valuations when i doesn't play

- This is a special VCG-mechanism in which

$$h_i(r_{-i}) = \sum_{j \neq i} v_j(r_j, g(r_{-i}))$$

$$\Rightarrow p_i(r) = \sum_{j \neq i} v_j(r_j, g(r_{-i})) - \sum_{j \neq i} v_j(r_j, g(r))$$

- With Clarke payments, one can prove that agents' utility are always non-negative

\Rightarrow agents are interested in playing the game

Clarke mechanism for the Vickrey auction (minimization version)

- The VCG-mechanism is:
 - $x=g(r):=\arg \min_{x \in F} \sum_i v_i(r_i, x)$
 - allocate to the bidder with **lowest reported cost**
 - $p_i = \sum_{j \neq i} v_j(r_j, g(r_{-i})) - \sum_{j \neq i} v_j(r_j, x)$

...pay the winner the second lowest offer,
and pay 0 the losers



Mechanism Design: Algorithmic Issues

QUESTION: What is the **time complexity** of the mechanism? Or, in other words:

- What is the time complexity of $g(\mathbf{r})$?
- What is the time complexity to calculate the N **payment functions**?
- What does it happen if it is **NP-hard** to compute the underlying social-choice function?



Algorithmic mechanism design for graph problems

- Following the Internet model, we assume that each agent owns a **single edge** of a graph $G=(V,E)$, and establishes the **cost** for using it
⇒ The agent's type is the **true weight** of the edge
- Classic optimization problems on G become mechanism design optimization problems!
- Many basic network design problems have been faced: shortest path (SP), single-source shortest paths tree (SPT), minimum spanning tree (MST), minimum Steiner tree, and many others



Summary of main results

	Centralized algorithm	Selfish-edge mechanism
SP	$O(m+n \log n)$	$O(m+n \log n)$
SPT	$O(m+n \log n)$	$O(m+n \log n)$
MST	$O(m \alpha(m,n))$	$O(m \alpha(m,n))$

⇒ For all these basic problems, the time complexity of the mechanism equals that of the canonical centralized algorithm!