

7. NETWORK FLOW II

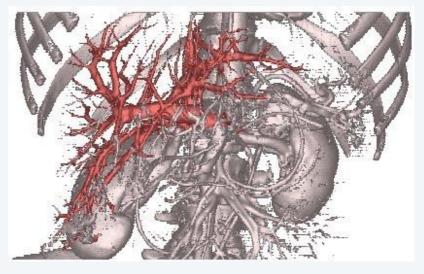
- bipartite matching
- disjoint paths
- image segmentation
- baseball elimination

Lecture slides by Kevin Wayne Copyright © 2005 Pearson-Addison Wesley

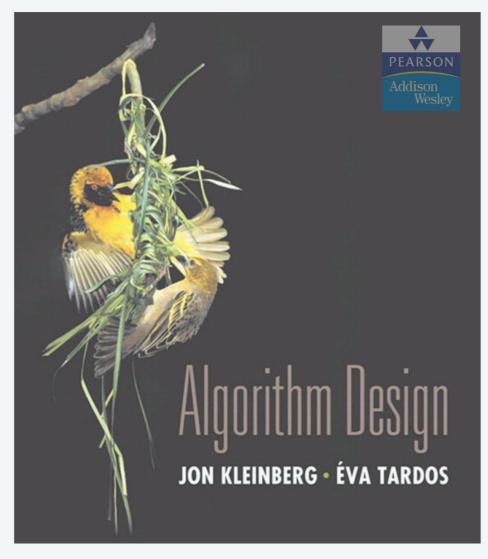
http://www.cs.princeton.edu/~wayne/kleinberg-tardos

Max-flow and min-cut problems are widely applicable model.

- Data mining.
- Open-pit mining.
- Bipartite matching.
- Network reliability.
- Baseball elimination.
- Image segmentation.
- Network connectivity.
- Markov random fields.
- Distributed computing.
- Security of statistical data.
- Egalitarian stable matching.
- Network intrusion detection.
- Multi-camera scene reconstruction.
- Sensor placement for homeland security.
- Many, many, more.



liver and hepatic vascularization segmentation



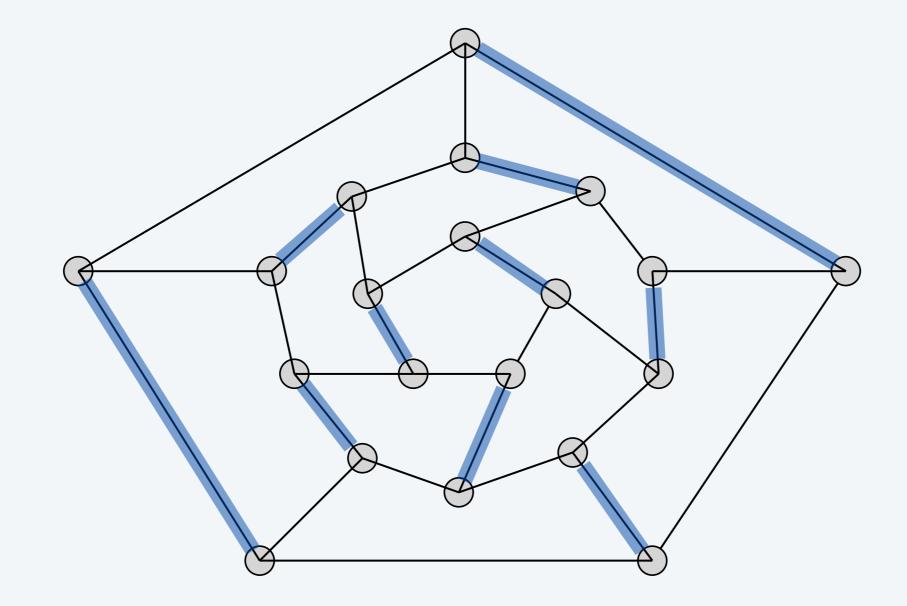
SECTION 7.5

7. NETWORK FLOW II

- bipartite matching
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- image segmentation
- baseball elimination

Def. Given an undirected graph G = (V, E), subset of edges $M \subseteq E$ is a matching if each node appears in at most one edge in M.

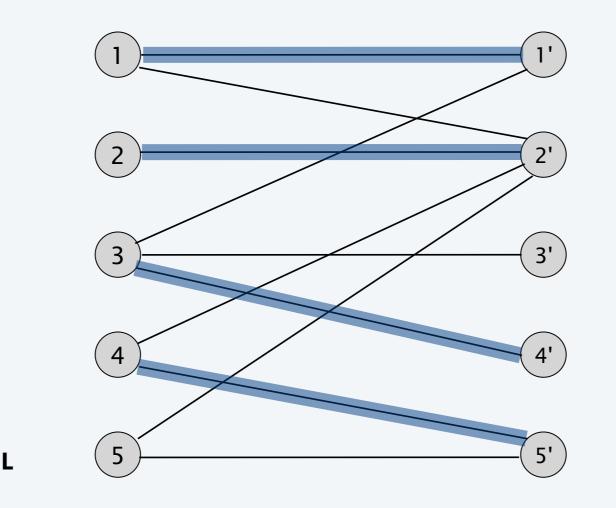
Max matching. Given a graph G, find a max-cardinality matching.



Bipartite matching

Def. A graph *G* is **bipartite** if the nodes can be partitioned into two subsets *L* and *R* such that every edge connects a node in *L* with a node in *R*.

Bipartite matching. Given a bipartite graph $G = (L \cup R, E)$, find a maxcardinality matching.



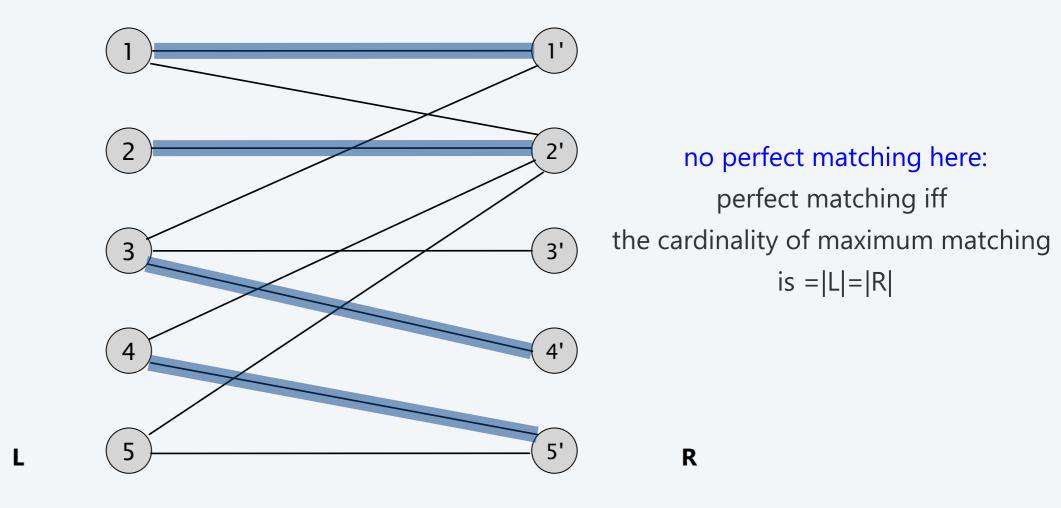
R

matching: 1-1', 2-2', 3-4', 4-5'

Perfect matching (in bipartite graphs)

Def. Given a graph G = (V, E), a subset of edges $M \subseteq E$ is a perfect matching if each node appears in exactly one edge in M.

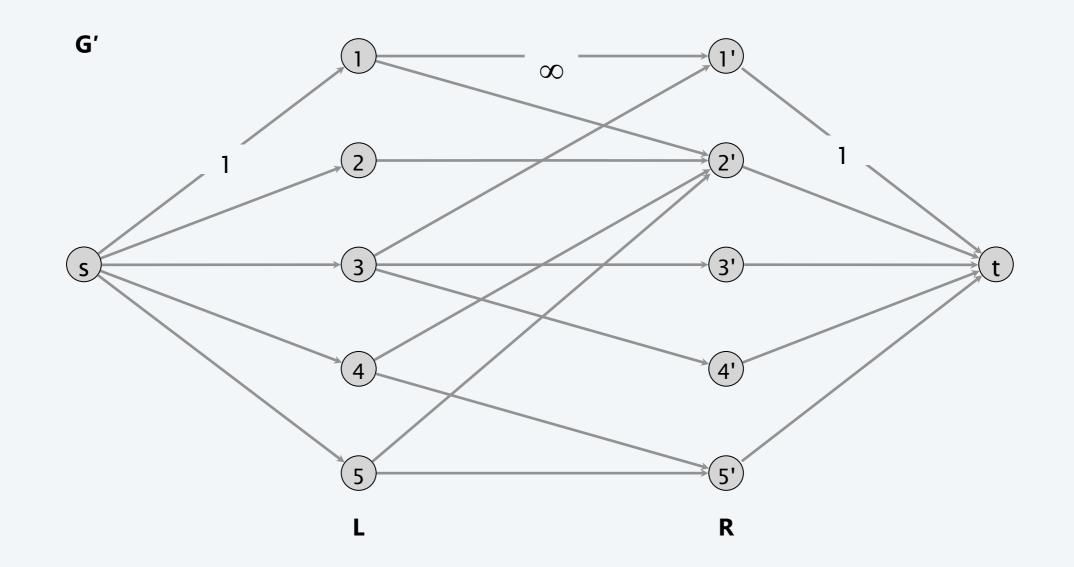
Perfect matching problem. Given a bipartite graph $G = (L \cup R, E)$, find a perfect matching or correctly report it does not exist.



matching: 1-1', 2-2', 3-4', 4-5'

Formulation.

- Create digraph $G' = (L \cup R \cup \{s, t\}, E')$.
- Direct all edges from *L* to *R*, and assign infinite (or unit) capacity.
- Add unit-capacity edges from s to each node in L.
- Add unit-capacity edges from each node in *R* to *t*.

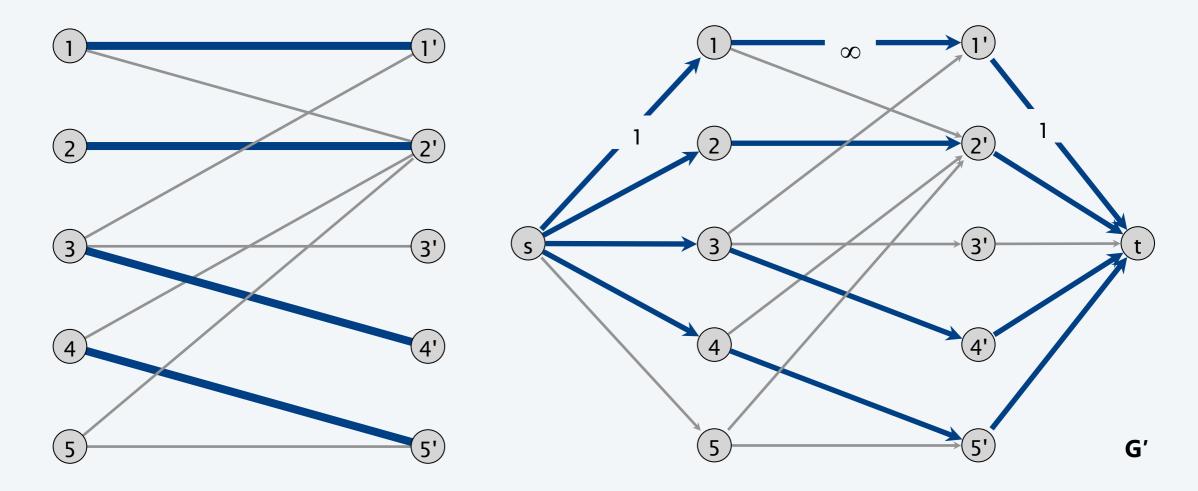


Theorem. 1–1 correspondence between matchings of cardinality k in G and integral flows of value k in G'.

Pf. \Rightarrow

for each edge $e: f(e) \in \{0, 1\}$

- Let *M* be a matching in *G* of cardinality *k*.
- Consider flow *f* that sends 1 unit on each of the *k* corresponding paths.
- *f* is a flow of value *k*. ■

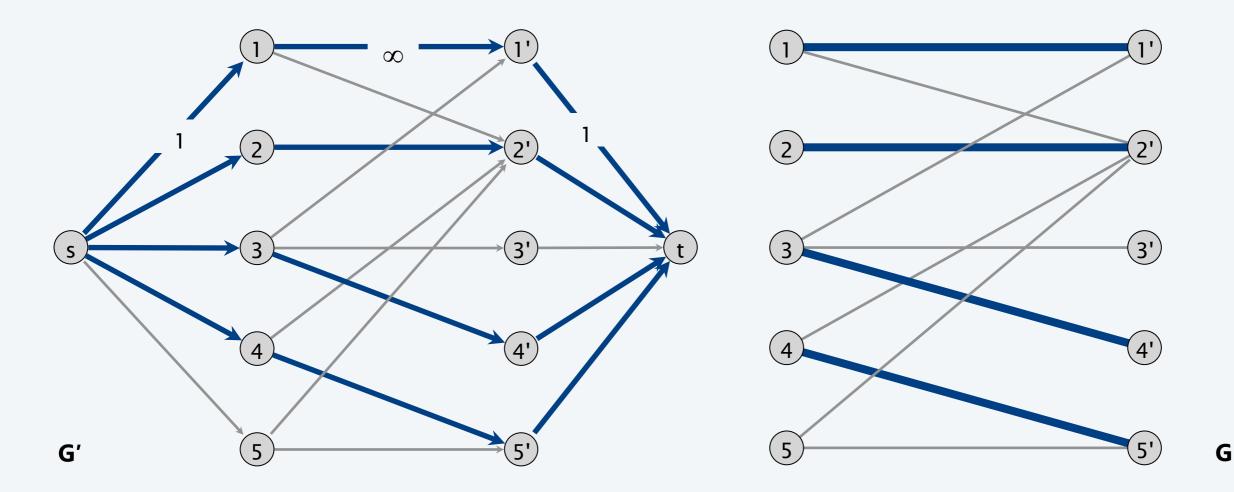


Theorem. 1–1 correspondence between matchings of cardinality k in G and integral flows of value k in G'.

Pf. ⇐

for each edge $e: f(e) \in \{0, 1\}$

- Let *f* be an integral flow in *G*' of value *k*.
- Consider M = set of edges from L to R with f(e) = 1.
 - each node in L and R participates in at most one edge in M
 - |M| = k: apply flow-value lemma to cut $(L \cup \{s\}, R \cup \{t\})$ •

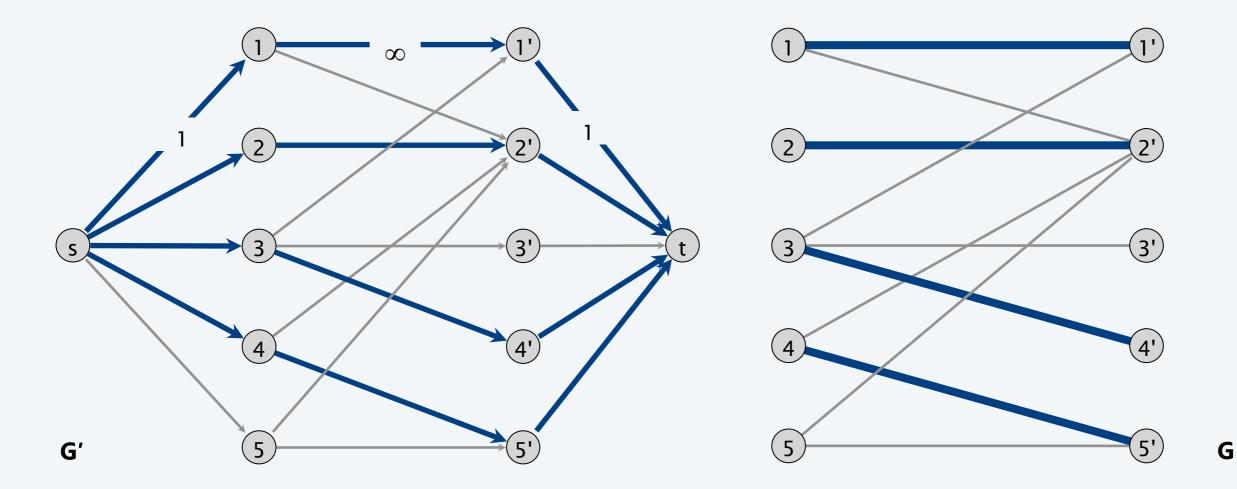


Max-flow formulation: proof of correctness

Theorem. 1–1 correspondence between matchings of cardinality k in G and integral flows of value k in G'.

Corollary. Can solve bipartite matching problem via max-flow formulation. Pf.

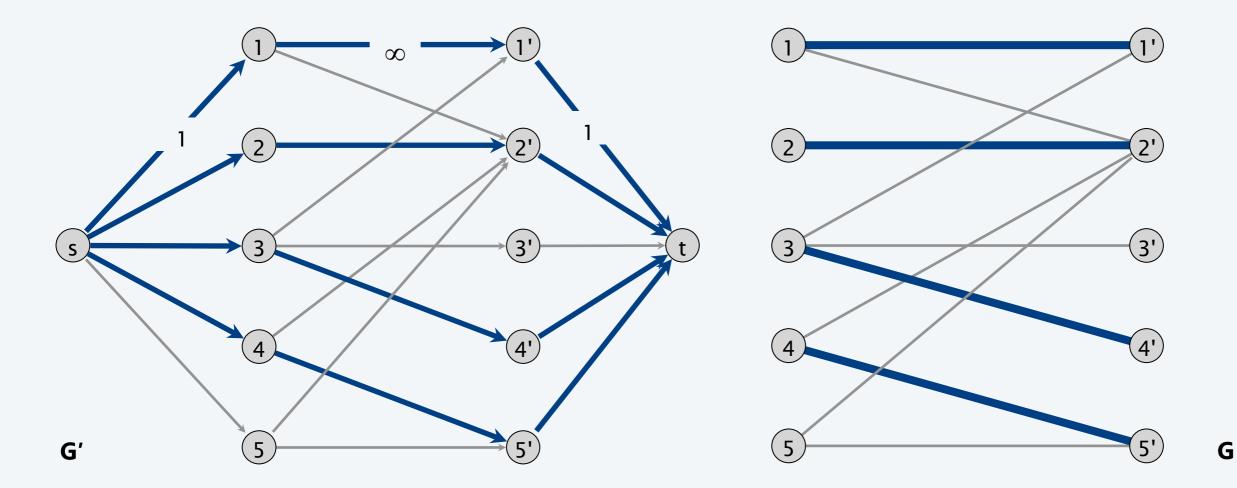
- Integrality theorem \Rightarrow there exists a max flow f^* in G' that is integral.
- 1-1 correspondence $\Rightarrow f^*$ corresponds to max-cardinality matching. •

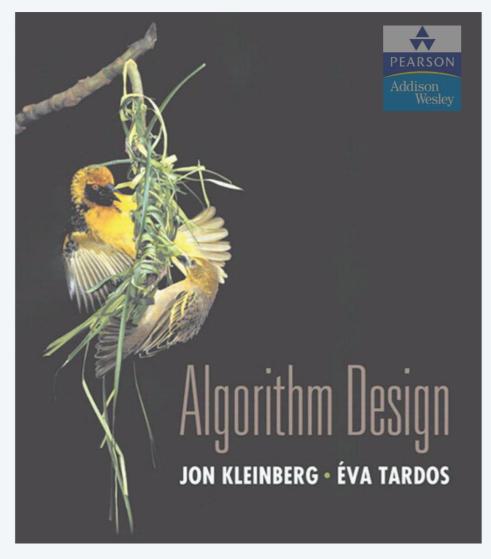


Theorem. 1–1 correspondence between matchings of cardinality k in G and integral flows of value k in G'.

Corollary. Can solve bipartite matching problem via max-flow formulation. Running time:

- Using Ford-Fulkerson:
- $\leq n$ augmentations $\Rightarrow O(mn)$ time.





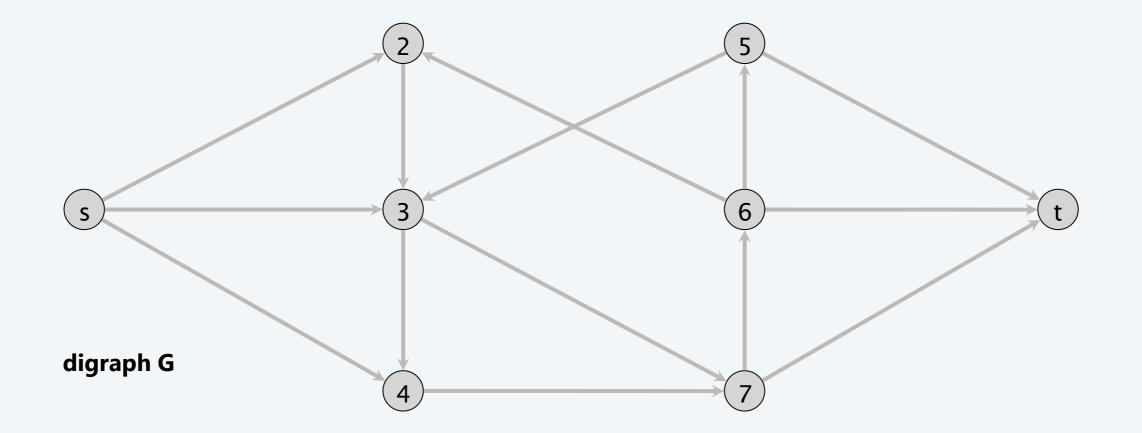
SECTION 7.6

7. NETWORK FLOW II

- bipartite matching
- disjoint paths
- image segmentation
- baseball elimination

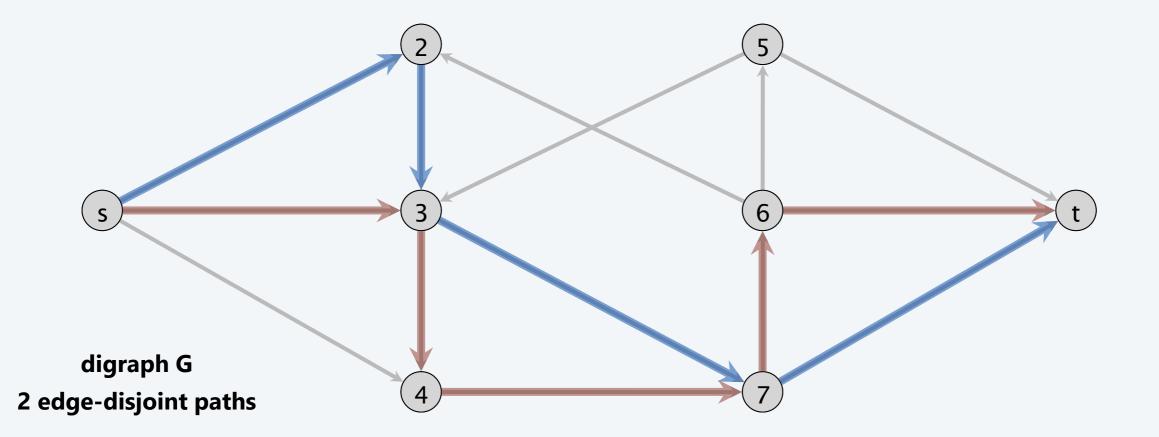
Edge-disjoint paths problem. Given a digraph G = (V, E) and two nodes s and t, find the max number of edge-disjoint $s \sim t$ paths.

Ex. Communication networks.



Edge-disjoint paths problem. Given a digraph G = (V, E) and two nodes s and t, find the max number of edge-disjoint $s \sim t$ paths.

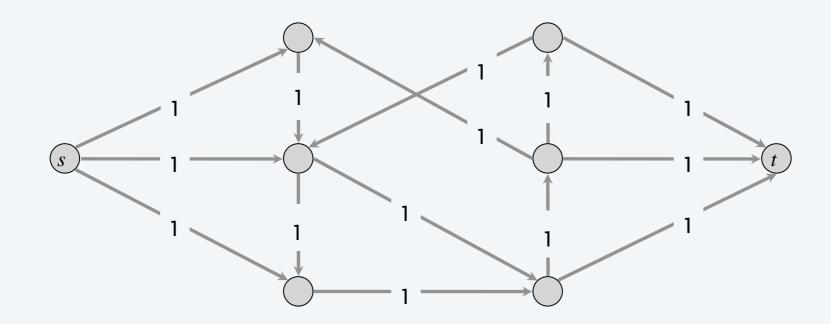
Ex. Communication networks.



Theorem. 1–1 correspondence between k edge-disjoint $s \sim t$ paths in G and integral flows of value k in G'.

Pf. \Rightarrow

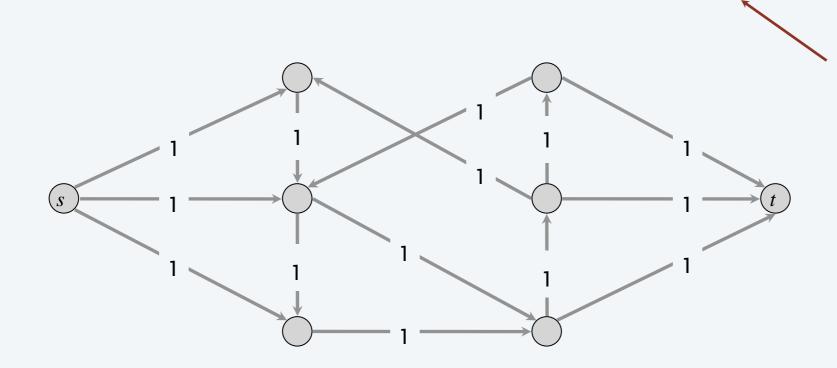
- Let $P_1, ..., P_k$ be k edge-disjoint $s \sim t$ paths in G.
- Set $f(e) = \begin{cases} 1 & \text{edge } e \text{ participates in some path } P_j \\ 0 & \text{otherwise} \end{cases}$
- Since paths are edge-disjoint, f is a flow of value k.



Theorem. 1–1 correspondence between k edge-disjoint $s \sim t$ paths in G and integral flows of value k in G'.

Pf. ⇐

- Let *f* be an integral flow in *G*' of value *k*.
- Consider edge (s, u) with f(s, u) = 1.
 - by flow conservation, there exists an edge (u, v) with f(u, v) = 1
 - continue until reach t, always choosing a new edge
- Produces k (not necessarily simple) edge-disjoint paths.

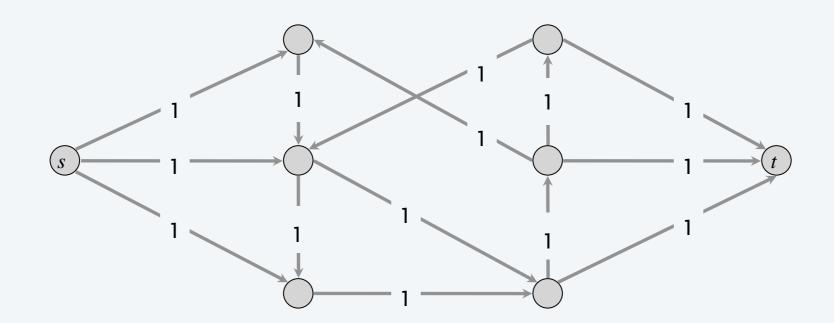


can eliminate cycles to get simple paths in O(mn) time if desired (flow decomposition)

Theorem. 1–1 correspondence between k edge-disjoint $s \sim t$ paths in G and integral flows of value k in G'.

Corollary. Can solve edge-disjoint paths problem via max-flow formulation. Pf.

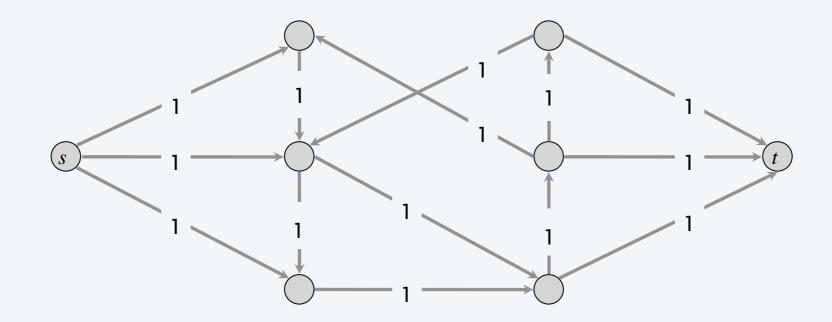
- Integrality theorem \Rightarrow there exists a max flow f^* in G' that is integral.
- 1-1 correspondence \Rightarrow f^* corresponds to max number of edge-disjoint $s \sim t$ paths in G. ■



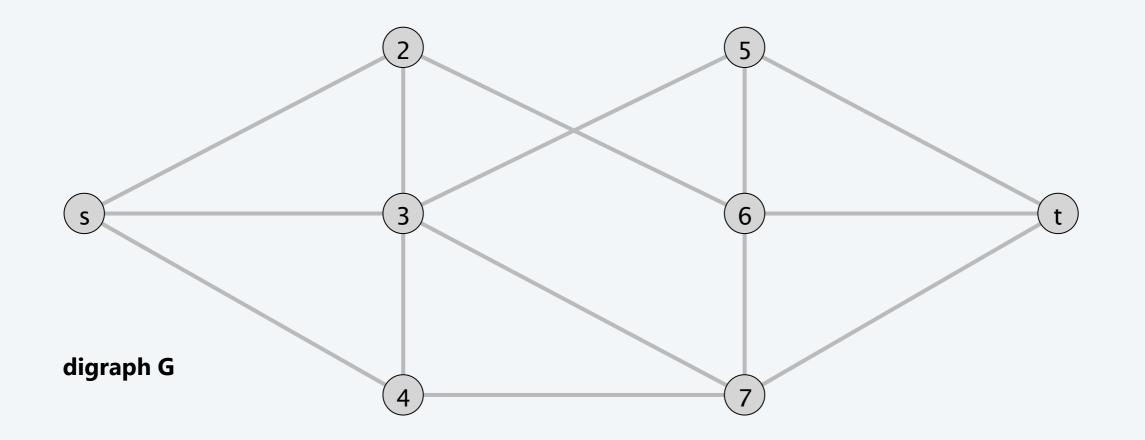
Theorem. 1–1 correspondence between k edge-disjoint $s \sim t$ paths in G and integral flows of value k in G'.

Corollary. Can solve edge-disjoint paths problem via max-flow formulation. Running time:

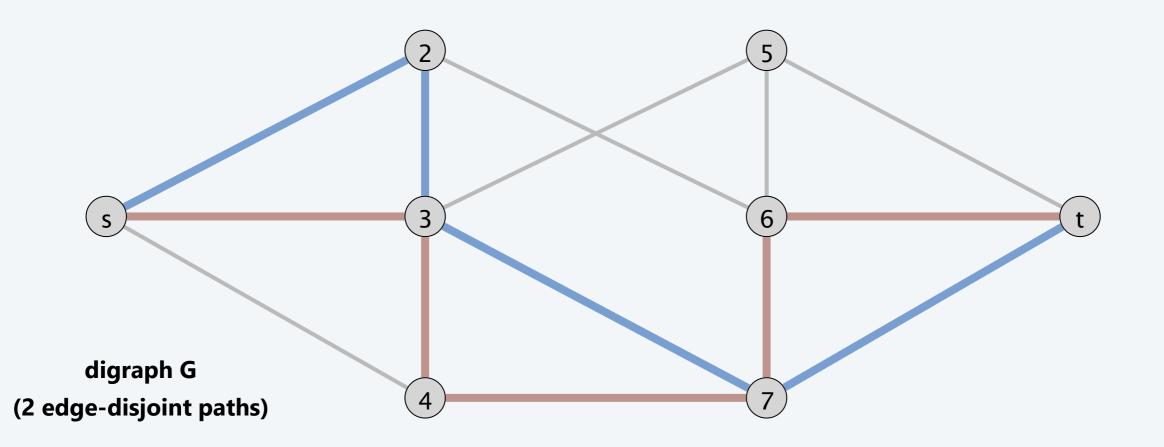
- Using Ford-Fulkerson:
- $\leq n$ augmentations $\Rightarrow O(mn)$ time.



Edge-disjoint paths problem in undirected graphs. Given a graph G = (V, E) and two nodes *s* and *t*, find the max number of edge-disjoint *s*–*t* paths.

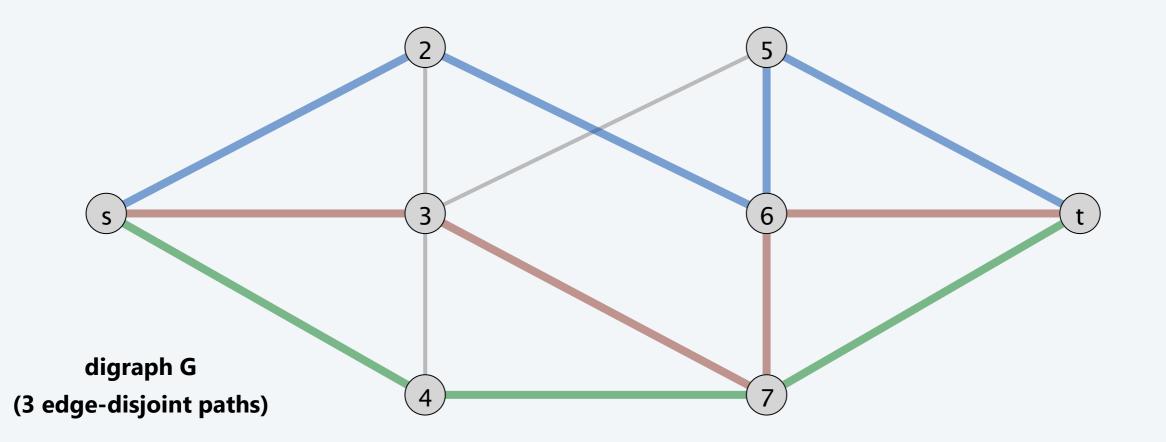


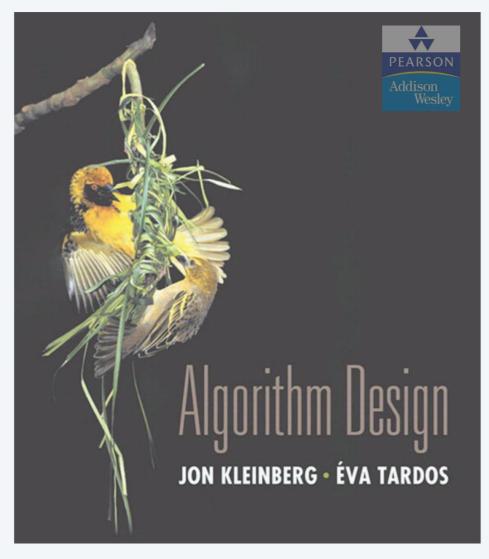
Edge-disjoint paths problem in undirected graphs. Given a graph G = (V, E) and two nodes *s* and *t*, find the max number of edge-disjoint *s*–*t* paths.



Edge-disjoint paths problem in undirected graphs. Given a graph G = (V, E) and two nodes *s* and *t*, find the max number of edge-disjoint *s*–*t* paths.

Exercise: design a max-flow-based algorithm for the problem.





SECTION 7.10

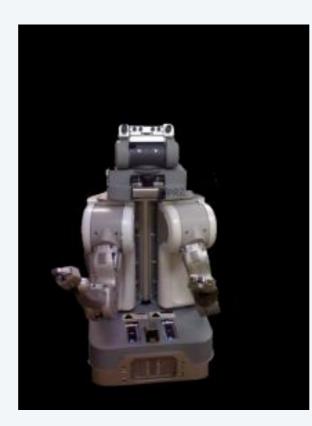
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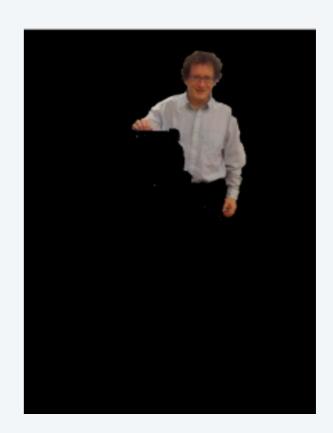
- bipartite matching
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Image segmentation.

- Divide image into coherent regions.
- Central problem in image processing.
- Ex. Separate human and robot from background scene.

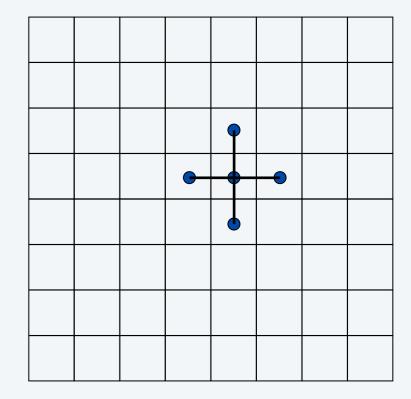






Foreground / background segmentation.

- Label each pixel in picture as belonging to foreground or background.
- V = set of pixels, E = pairs of neighboring pixels.
- $a_i \ge 0$ is likelihood pixel *i* in foreground.
- $b_i \ge 0$ is likelihood pixel *i* in background.
- *p_{ij}* ≥ 0 is separation penalty for labeling one of *i* and *j* as foreground, and the other as background.



Goals.

- Accuracy: if $a_i > b_i$ in isolation, prefer to label *i* in foreground.
- Smoothness: if many neighbors of *i* are labeled foreground, we should be inclined to label *i* as foreground.
- Find partition (A, B) that maximizes: $\sum_{i \in A} a_i + \sum_{j \in B} b_j \sum_{\substack{(i,j) \in E \\ |A \cap \{i,j\}| = 1}} p_{ij}$

Image segmentation

Formulate as min-cut problem.

Maximization.

a

- No source or sink.
- Undirected graph.

Turn into minimization problem.

Maximizing
$$\sum_{i \in A} a_i + \sum_{j \in B} b_j - \sum_{\substack{(i,j) \in E \\ |A \cap \{i,j\}| = 1}} p_{ij}$$

is equivalent to minimizing

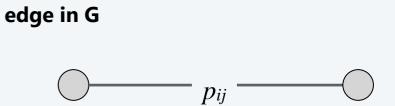
$$\left(\sum_{i \in V} a_i + \sum_{j \in V} b_j\right) - \sum_{i \in A} a_i - \sum_{j \in B} b_j + \sum_{\substack{(i,j) \in E \\ |A \cap \{i,j\}| = 1}} p_{ij}$$

• or alternatively $\sum_{j \in B} a_j + \sum_{i \in A} b_i + \sum_{\substack{(i,j) \in E \\ |A \cap \{i,j\}|=1}} p_{ij}$

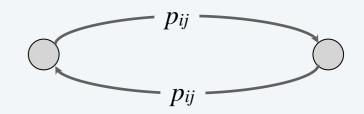
Image segmentation

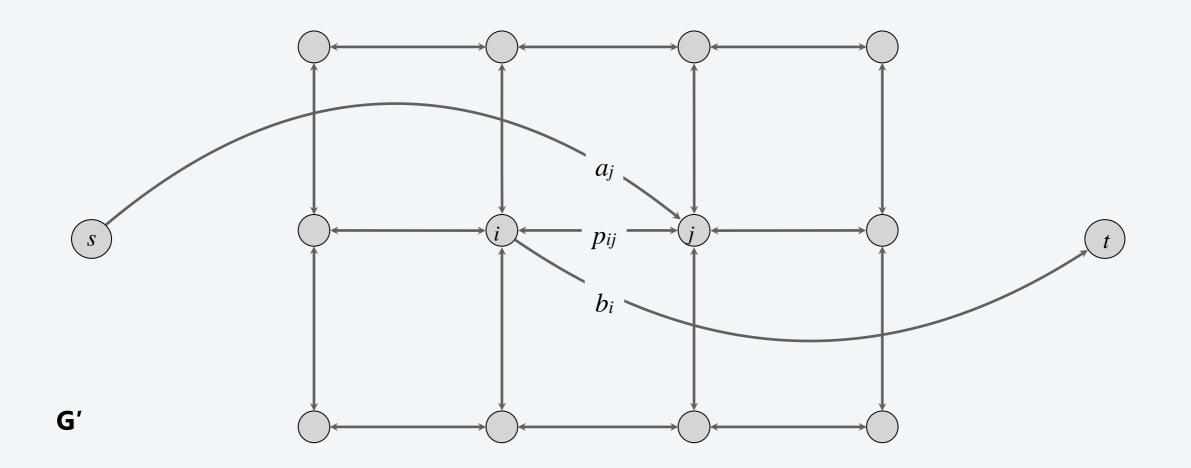
Formulate as min-cut problem G' = (V', E').

- Include node for each pixel.
- Use two antiparallel edges instead of undirected edge.
- Add source s to correspond to foreground.
- Add sink t to correspond to background.



two antiparallel edges in G'



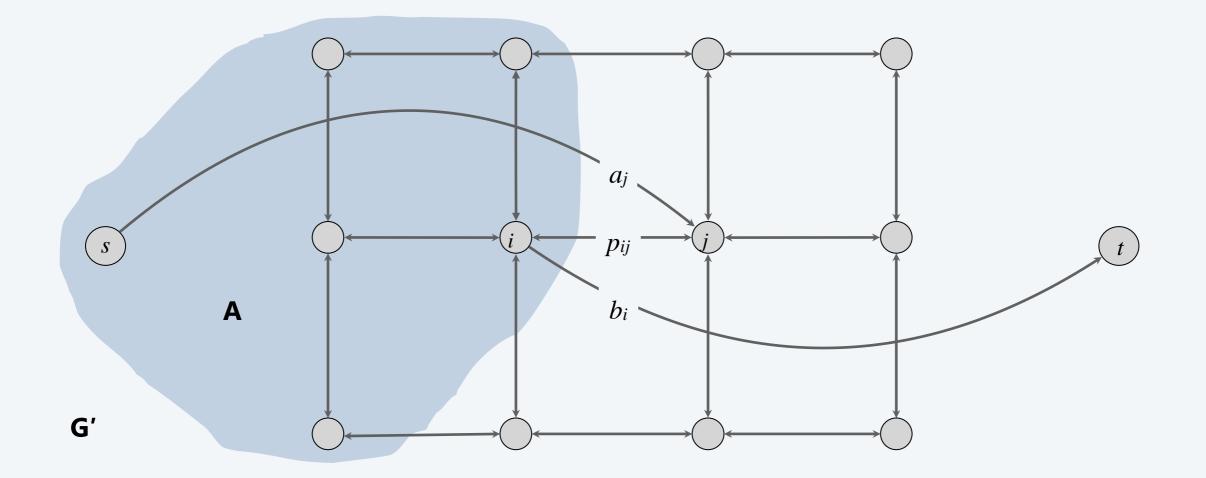


Consider min cut (A, B) in G'.

• A =foreground.

$$cap(A,B) = \sum_{j \in B} a_j + \sum_{i \in A} b_i + \sum_{\substack{(i,j) \in E \\ i \in A, j \in B}} p_{ij} \quad \text{if } i \text{ and } j \text{ on different sides,}$$

Precisely the quantity we want to minimize.



Grabcut image segmentation

Grabcut. [Rother-Kolmogorov-Blake 2004]

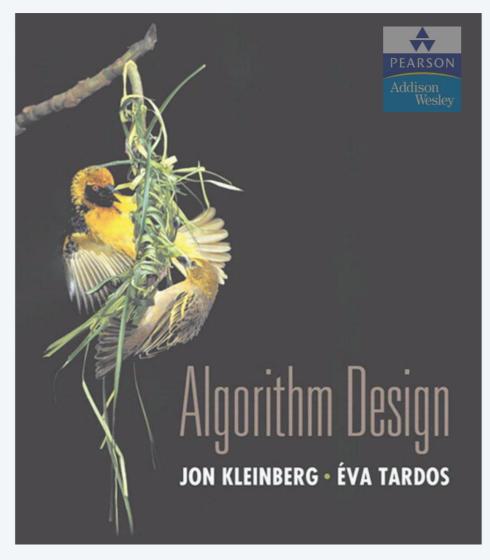
"GrabCut" — Interactive Foreground Extraction using Iterated Graph Cuts

Carsten Rother*

Vladimir Kolmogorov[†] Microsoft Research Cambridge, UK Andrew Blake[‡]



Figure 1: Three examples of GrabCut. The user drags a rectangle loosely around an object. The object is then extracted automatically.



SECTION 7.12

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- bipartite matching
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- baseball elimination

Baseball elimination



Q. Which teams have a chance of finishing the season with the most wins?

i	team		wins	losses	to play	ATL	РНІ	NYM	MON
0	A	Atlanta	83	71	8	-	1	6	1
1	Phillips	Philly	80	79	3	1	-	0	2
2	Kets	New York	78	78	6	6	0	-	0
3	EXPOS.	Montreal	77	82	3	1	2	0	-

Montreal is mathematically eliminated.

- Montreal finishes with ≤ 80 wins.
- Atlanta already has 83 wins.

Remark. This is the only reason sports writers appear to be aware of — conditions are sufficient but not necessary!

Q. Which teams have a chance of finishing the season with the most wins?

i	team		wins	losses	to play	ATL	РНІ	NYM	MON
0	A	Atlanta	83	71	8	-	1	6	1
1	Phillips	Philly	80	79	3	1	-	0	2
2	Met	New York	78	78	6	6	0	-	0
3		Montreal	77	82	3	1	2	0	-

Philadelphia is mathematically eliminated.

- Philadelphia finishes with ≤ 83 wins.
- Either New York or Atlanta will finish with ≥ 84 wins.

Observation. Answer depends not only on how many games already won and left to play, but on whom they're against.

Current standings.

- Set of teams S.
- Distinguished team $z \in S$.
- Team x has won w_x games already.
- Teams x and y play each other r_{xy} additional times.

Baseball elimination problem. Given the current standings, is there any outcome of the remaining games in which team z finishes with the most (or tied for the most) wins?

SIAM REVIEW Vol. 8, No. 3, July, 1966

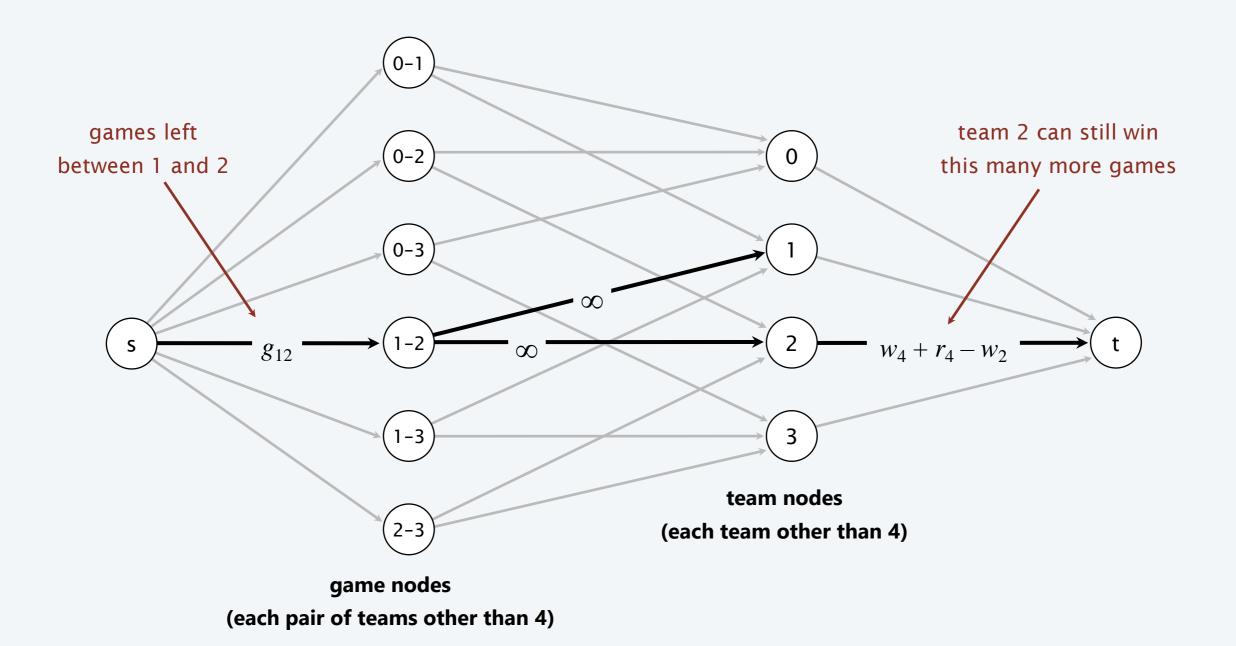
POSSIBLE WINNERS IN PARTIALLY COMPLETED TOURNAMENTS*

BENJAMIN L. SCHWARTZ†

1. Introduction. In this paper, we shall investigate certain questions in tournament scheduling. For definiteness, we shall use the terminology of baseball. We shall be concerned with the categorization of teams into three classes during the closing days of the season. A team may be definitely eliminated from pennant possibility; it may be in contention, or it may have clinched the championship. It will be our convention that a team that can possibly tie for the pennant is considered still in contention. In this paper necessary and sufficient conditions are developed to classify any team properly into the appropriate category.

Can team 4 finish with most wins?

- W.I.o.g. assume team 4 wins all remaining games $\Rightarrow w_4 + r_4$ wins.
- Divvy remaining games so that all teams have $\leq w_4 + r_4$ wins.



Baseball elimination problem: max-flow formulation

Theorem. Team 4 not eliminated iff max flow saturates all edges leaving *s*. Pf.

- Integrality theorem \Rightarrow each remaining game between x and y added to number of wins for team x or team y.
- Capacity on (x, t) edges ensure no team wins too many games.

