

Esercizio 1

①

$f \in \text{End}_{\mathbb{R}}(\mathbb{R}^3)$ t.c.

$$f(x, y, z) = (2x, -x - 3y - z, -x + 4y + z)$$

$$M_{\mathcal{B}, \mathcal{B}}(f) = A = \begin{pmatrix} 2 & 0 & 0 \\ -1 & -3 & -1 \\ -1 & 4 & 1 \end{pmatrix} \in M(3, 3; \mathbb{R})$$

$$P_f(t) = P_A(t) = \det(A - tI_3) = (2-t) \det \begin{pmatrix} -3-t & -1 \\ 4 & 1-t \end{pmatrix} =$$

$$\stackrel{\text{Laplace}}{\text{I riga}} = (2-t) [-(3+t)(1-t) + 4] = (2-t) [-(3-3t+t-t^2)+4] =$$

$$= (2-t) [-3+3t-t+t^2+4] = (2-t) [t^2+2t+1] \Rightarrow$$

$$P_f(t) = (2-t) \cdot (t+1)^2$$

$$\Rightarrow m_a(2) = 1 \quad m_a(-1) = 2$$

Spettro $(f) = \{-1, 2\} \subseteq \mathbb{R} \Rightarrow$ Ammette f.c. di Jordan su $\mathbb{R}$
(eventualmente diagonale)

Passo 1: separazione autovalori

* $\lambda = 2$ autovalore semplice $\Rightarrow E_2(f)$ ha dimensione 1

$$\Rightarrow m_g(2) = \dim(E_2(f)) = 1$$

$E_2(f) \equiv$ Autospaio generalizzato $= V_2(f)$

$$\text{Infatti } (A - 2I_3) = \begin{pmatrix} 0 & 0 & 0 \\ -1 & -5 & -1 \\ -1 & 4 & -1 \end{pmatrix} \Rightarrow$$

$$E_2(f) = \begin{cases} -x - 5y - z = 0 \\ -x + 4y - z = 0 \end{cases} \Leftrightarrow \begin{cases} -x - z = 5y \\ 9y = 0 \end{cases} \Leftrightarrow \begin{cases} x + z = 0 \\ y = 0 \end{cases}$$

$$E_2(f) = \text{Span} \left\{ \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \right\} = \text{Span} \{a\}$$

$$a := \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$$

$$A|_{E_2(f)} : t a \longrightarrow 2 \cdot t a, \forall t \in \mathbb{R} \Rightarrow E_2(f) \in \overset{\text{f-stabile}}{A\text{-stabile}}$$

$$\downarrow$$

$$A(E_2(f)) = E_2(f)$$

$$\hookrightarrow (A - 2I_3)|_{E_2(f)} = 0_{E_2(f)} \Rightarrow \text{indice di nilpotenza di}$$

$$(A - 2I_3)|_{E_2(f)} = k = 1$$

$\Rightarrow \exists !$ blocco di Jordan di ordine 1 rispetto a $\lambda = 2$

$$J_{2,1} = (2)$$

$$\text{Ricordo notazione } J_{\lambda, k} = \begin{pmatrix} \lambda & 1 & 0 & \dots & 0 \\ 0 & \lambda & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & \lambda \end{pmatrix} \in M(k \times k; \mathbb{R})$$

* $\lambda = -1$

(2)

$m_A(-1) = 2 \Rightarrow A \text{ diag.} \Rightarrow m_g(-1) = 2$

Ma $E_{-1}(f) = \ker(A + I_3) = \left\{ \begin{pmatrix} x \\ y \\ z \end{pmatrix} \in \mathbb{R}^3 \mid \begin{cases} 3x = 0 \\ -x - 2y - z = 0 \\ -x + 4y + 2z = 0 \end{cases} \right\}$

$\Rightarrow \begin{cases} x=0 \\ 2y+z=0 \\ 4y+2z=0 \end{cases} \Rightarrow \begin{cases} x=0 \\ 2y+z=0 \end{cases} \rightarrow (A+I_3) = \begin{pmatrix} 3 & 0 & 0 \\ -1 & -2 & -1 \\ -1 & 4 & 2 \end{pmatrix}$

$E_{-1}(f) = \text{Span} \left\{ \begin{pmatrix} 0 \\ -1 \\ 2 \end{pmatrix} \right\} = \text{Span} \{ \underline{b} \} \text{ dove } \underline{b} := \begin{pmatrix} 0 \\ -1 \\ 2 \end{pmatrix}$

$\Rightarrow \underline{m_g(-1) = \dim(E_{-1}(f)) = 1 < m_A(-1) = 2}$

$\Rightarrow A \text{ non diag.} \Rightarrow f \text{ ammette f.c. Jordan non diagonale}$

Poiché $\dim E_{-1}(f) = 1 \Rightarrow \exists!$ blocco Jordan rispetto a $\underline{\lambda = -1}$ e poiché $m_A(-1) = 2 \Rightarrow \dim(V_2(f)) = 2$

$\downarrow$
Autospazio generalizzato

$\Rightarrow$ il blocco di Jordan è necessariamente

$J_{-1,2} = \begin{pmatrix} -1 & 1 \\ 0 & -1 \end{pmatrix} \quad (J_{\lambda,k})$

$\Rightarrow$ Forma canonica di Jordan è (a meno di permutazione dei blocchi)

$J_f = \left(\begin{array}{c|cc} 2 & 0 & 0 \\ \hline 0 & -1 & 1 \\ 0 & 0 & -1 \end{array} \right)$

* Cerchiamo autospazio generalizzato per $\lambda = -1$

Se $k =$ indice nilpotenza di $A + I_3|_{V_1(f)} \Rightarrow \underline{k \leq m = 3}$

e sicuramente $(A + I_3|_{V_1(f)})^k = (A + I_3|_{V_1(f)})^3 = 0_{V_1(f)}$

Notiamo che

$\bullet (A + I_3)^2 = \begin{pmatrix} 9 & 0 & 0 \\ 0 & 0 & 0 \\ -9 & 0 & 0 \end{pmatrix}$

$\bullet (A + I_3)^3 = \begin{pmatrix} 3 & 0 & 0 \\ -1 & -2 & -1 \\ -1 & 4 & 2 \end{pmatrix} \cdot \begin{pmatrix} 9 & 0 & 0 \\ 0 & 0 & 0 \\ -9 & 0 & 0 \end{pmatrix} = \begin{pmatrix} 27 & 0 & 0 \\ 0 & 0 & 0 \\ -27 & 0 & 0 \end{pmatrix}$

$\rightarrow$ Matrici proporzionali

$\Rightarrow \underline{V_1(f) = \ker((A + I_3)^3) = \ker((A + I_3)^2) = \{x=0\}}$

$$V_{-1}(\neq) = \{x = 0\} = \text{Span}\{e_2, e_3\} = \text{Span}\{b, e_3\} \quad (3)$$

$\downarrow$
generatore
di $E_{-1}(\neq)$

$$\text{Su } V_{-1}(\neq): A + I_3|_{V_{-1}(\neq)} = \begin{pmatrix} 3 & 0 & 0 \\ -1 & -2 & -1 \\ -1 & 4 & 2 \end{pmatrix} \Big|_{V_{-1}(\neq)}$$

$$\begin{aligned} \text{cioè} \quad e_2 &\longrightarrow -2e_2 + 4e_3 \\ e_3 &\longrightarrow -e_2 + 2e_3 \end{aligned} \Rightarrow A + I_3|_{V_{-1}(\neq)} \neq 0_{V_{-1}(\neq)}$$

$$\text{Invece } (A + I_3|_{V_{-1}(\neq)})^2 = 0_{V_{-1}(\neq)} \Rightarrow \underline{k=2 \text{ indice nilpotenza di } (A + I_3)|_{V_{-1}(\neq)}}$$

Passo II riduzione ad autovalore nullo

$$A \text{ ha autovalore } \lambda = -1 \Leftrightarrow A v = -v \Leftrightarrow (A + I_3) v = 0$$

$$\Leftrightarrow A + I_3 \text{ ha autovalore } \lambda' = 0 \text{ ed in effetti}$$

$$A + I_3|_{V_{-1}(\neq)} \text{ nilpotente di indice 2} \Leftrightarrow A + I_3|_{V_{-1}(\neq)} \text{ ha solo autovalore nullo}$$

Notiamo che

$$\begin{aligned} \{0\} &\subset E_{-1}(\neq) \quad \text{dim}=1 \\ &\quad \parallel \\ &\quad \text{Span}(b) = \text{Span}\left\{\begin{pmatrix} 0 \\ -1 \\ 2 \end{pmatrix}\right\} \\ &\subset V_{-1}(\neq) = \text{Span}\{b, e_3\} = \text{Span}\{e_2, e_3\} \quad \text{dim}=2 \end{aligned}$$

$$\text{Se prendo } e_3 \in V_{-1}(\neq) \setminus E_{-1}(\neq)$$

$$(A + I_3)(e_3) = \begin{pmatrix} 0 \\ -1 \\ 2 \end{pmatrix} = b \in E_{-1}(\neq) \quad (\text{anzi } b \text{ generatore})$$

$$\text{In altre parole, posto } f' := f + I_3|_{V_{-1}(\neq)}$$

$$\{0\} \subset E_{-1}(\neq) \subset V_{-1}(\neq)$$

$$\text{perché } b \in \ker(f'), \quad \text{per } e_3 \in \ker(f')^2 \quad \text{infatti } f'(e_3) \in \ker(f')$$

$$0 = (f')^2(e_3) = f'(f'(e_3))$$

$\Rightarrow B = \{ \underline{b}, \underline{e}_3 \}$ base ciclica o di stringhe per $V_{-1}(f)$ (4)

Infatti

$$f'(\underline{e}_3) = \underline{b} = 1 \underline{b} + 0 \underline{e}_3$$

$$f'(\underline{b}) = (f')^2(\underline{e}_3) = \underline{0}$$

$$\Rightarrow M_{B,B}(f') = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$$M_2 \quad f' = (f + I_3)|_{V_{-1}(f)} \Rightarrow$$

$$f'(\underline{e}_3) = (f + I_3)(\underline{e}_3) = \underline{b} \Leftrightarrow f(\underline{e}_3) = \underline{b} - \underline{e}_3$$

$$f'(\underline{b}) = (f + I_3)(\underline{b}) = \underline{0} \Leftrightarrow f(\underline{b}) = -\underline{b}$$

$$\Rightarrow M_{B,B}(f|_{V_{-1}(f)}) = \begin{pmatrix} -1 & 1 \\ 0 & -1 \end{pmatrix}$$

$$\text{che } \bar{e} \text{ come fare } M_{B,B}(f') - M_{B,B}(I_3|_{V_{-1}(f)}) =$$

$$= \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} -1 & 1 \\ 0 & -1 \end{pmatrix}$$

Pertanto in base

$$\boxed{J = \{ \underline{a}, \underline{b}, \underline{e}_3 \}} \text{ per } \mathbb{R}^3 \text{ si ha}$$

$$M_{J,J}(f) = \left(\begin{array}{c|cc} 2 & 0 & 0 \\ \hline 0 & -1 & 1 \\ 0 & 0 & -1 \end{array} \right)$$

* se

$$M := M_{E,J} = \left(\begin{array}{ccc} 1 & 0 & 0 \\ 0 & -1 & 0 \\ -1 & 2 & 1 \\ \downarrow & \downarrow & \downarrow \\ \underline{a} & \underline{b} & \underline{e}_3 \end{array} \right)$$

$\Rightarrow J = \text{base di Jordan per } f$

$$\Rightarrow J_f = \left(\begin{array}{c|cc} J_{2,1} & 0 & 0 \\ \hline 0 & & \\ 0 & & J_{-1,2} \end{array} \right)$$

(5)

$$\begin{array}{ccc}
 (\mathbb{R}^3, \varepsilon) & \xrightarrow[\quad M_{\varepsilon, \varepsilon}(f) = A \quad]{f} & (\mathbb{R}^3, \varepsilon) \\
 \uparrow \text{Id} & \xrightarrow{\quad \text{red arrow} \quad} & \uparrow \text{Id} \\
 (\mathbb{R}^3, \mathcal{J}) & \xrightarrow[\quad M_{\mathcal{J}, \mathcal{J}}(f) = J_f \quad]{f} & (\mathbb{R}^3, \mathcal{J})
 \end{array}$$

$$J_f = M_{\mathcal{J}, \mathcal{J}}(f) = M_{\mathcal{J}, \mathcal{J}}(\text{Id}_{\mathbb{R}^3} \circ f \circ \text{Id}_{\mathbb{R}^3}) = M_{\mathcal{J}, \varepsilon}(\text{Id}_{\mathbb{R}^3}) \circ M_{\varepsilon, \varepsilon}(f) \circ M_{\varepsilon, \mathcal{J}}(\text{Id}_{\mathbb{R}^3})$$

$$= M_{\mathcal{J}, \varepsilon} \circ A \circ M_{\varepsilon, \mathcal{J}} = M_{\varepsilon, \mathcal{J}}^{-1} \circ A \circ M_{\varepsilon, \mathcal{J}} = M^{-1} \circ A \circ M$$

La similitudine tra J_f e A si ha con $M = M_{\varepsilon, \mathcal{J}}$

$$J_f = M^{-1} \circ A \circ M$$

Esercizio 2

$$A = \begin{pmatrix} 2 & 0 & -1 & 1 \\ 1 & 1 & -1 & 1 \\ 1 & -3 & 2 & -1 \\ 0 & -3 & 2 & -1 \end{pmatrix} \in M(4,4; \mathbb{R})$$

$$P_A(t) = (t^4 - 4t^3 + 6t^2 - 4t + 1)$$

↓
Laplace I riga

$$\text{Ricordo } \binom{4}{3} = 4 = \binom{4}{1} \binom{4}{2} = \frac{4 \cdot 3}{2} = 6 \Rightarrow$$

$$P_A(t) = (t - 1)^4$$

Se $f = L_A$

$$\text{Spettro}(f) = \{1\} \subset \mathbb{R} \Rightarrow \underline{f \text{ ammette f.c. Jordan su } \mathbb{R}}$$

Quante possibilità a priori (a meno di permutazioni)?

1! blocco

$$J_{1,4} = \begin{pmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

2 blocchi

$$\left(\begin{array}{c|ccc} J_{1,2} & 0 & 0 & 0 \\ \hline 0 & J_{1,3} \end{array} \right) = \left(\begin{array}{c|ccc} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{array} \right)$$

$$\rightarrow \left(\begin{array}{cc|cc} J_{1,2} & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ \hline 0 & 0 & J_{1,2} \end{array} \right) = \left(\begin{array}{cc|cc} 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{array} \right)$$

3 blocchi

$$\left(\begin{array}{c|cc} J_{1,1} & 0 & 0 & 0 \\ 0 & J_{1,1} & 0 & 0 \\ 0 & 0 & J_{1,2} \end{array} \right) = \left(\begin{array}{c|cc} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{array} \right)$$

4 blocchi

$$\left(\begin{array}{c|ccc} J_{1,1} & 0 & 0 & 0 \\ 0 & J_{1,1} & 0 & 0 \\ 0 & 0 & J_{1,1} & 0 \\ 0 & 0 & 0 & J_{1,1} \end{array} \right) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \rightarrow \underline{\text{diagonale}}$$

Escludiamo subito alcuni casi

Notiamo che

$$\mathbb{R}^4 = \ker((L_A - I_4)^4) = V_1(L_A) \text{ è auto spazio generalizzato perché ho solo } \lambda=1$$

$$\dim M_d(1) = 4 = \dim(V_1(L_A))$$

$$M_g(1) = ?$$

Considero

$$B := A - 1I_4 = \begin{pmatrix} 1 & 0 & -1 & 1 \\ 1 & 0 & -1 & 1 \\ 1 & -3 & 1 & -1 \\ 0 & -3 & 2 & -2 \end{pmatrix}$$

$$\Rightarrow \operatorname{rg}(B) \geq 2 \text{ perché } \det(\boxed{\begin{smallmatrix} 1 & -3 \\ 0 & -3 \end{smallmatrix}}) = -3 \neq 0$$

Pero

$$B_{\text{III}} = -B_{\text{IV}} \Rightarrow \operatorname{rg}(B) \leq 3$$

Se solo $\boxed{}$ in tutti i modi possibili $\rightarrow$ det = 0 sempre

$$\Rightarrow \boxed{\operatorname{rg}(B) = 2}$$

$$\Rightarrow \boxed{\dim(\ker(B)) = 4 - \operatorname{rg}(B) = 2}$$

$$M_d \quad \ker(B) = E_1(L_A) \Rightarrow$$

$$\boxed{M_g(1) = 2 < M_d(1) = 4}$$

$\Rightarrow$ A non diagonalizzabile e A ammette 2 blocchi di Jordan

$$\begin{array}{l} (*) \\ (**) \end{array} \begin{array}{c} \left(\begin{array}{c|ccc} J_{1,1} & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 \\ \hline & & J_{1,3} & \end{array} \right) \quad \left(\begin{array}{c|cc} J_{1,2} & 0 & 0 \\ \hline 0 & 0 & 0 \\ \hline 0 & 0 & J_{1,2} \end{array} \right) \end{array}$$

$$* \text{ Notiamo che } B^2 = B \circ B = \begin{pmatrix} 1 & 0 & -1 & 1 \\ 1 & 0 & -1 & 1 \\ 1 & -3 & 1 & -1 \\ 0 & -3 & 2 & -2 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 & 1 \\ 1 & 0 & -1 & 1 \\ 1 & -3 & 1 & -1 \\ 0 & -3 & 2 & -2 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & & & \end{pmatrix}$$

○

$$\Rightarrow \underline{k=2} \text{ NON È l'indice nilpotenza di } B$$

$$\text{Invece } \underline{k=3} \text{ è l'indice nilpotenza di } B \text{ i.e. } B^3 = 0$$

③

$\Rightarrow$ Se $f = L_A$ e $f' = L_A - I_4 = L_B$

$$\{0\} \subsetneq E_1(f) \subsetneq \ker((f')^2) \subsetneq \ker((f')^3) = \ker(0) \stackrel{||}{=} \mathbb{R}^4$$

$\underbrace{\qquad\qquad\qquad}_{\ker(f')} \quad \underbrace{\qquad\qquad\qquad}_{f'(x)} \quad \underbrace{\qquad\qquad\qquad}_{2e}$

$\Rightarrow f'$ olere avere un blocco di ordine 3 $\Rightarrow f$ olere avere un blocco di ordine 3 $\Rightarrow$ escludo la II possibilità (**)

$\Rightarrow J_f = \left(\begin{array}{c|ccc} J_{1,1} & 0 & 0 & 0 \\ \hline 0 & & & \\ 0 & & & \\ 0 & & & \end{array} \right) = \left(\begin{array}{c|ccc} 1 & 0 & 0 & 0 \\ \hline 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{array} \right)$

Prendo

$$\ker(f') = \{B \cdot x = 0\} = \begin{cases} x_1 - x_3 + x_4 = 0 \\ x_1 - x_3 + x_4 = 0 \\ x_1 - 3x_2 + x_3 - x_4 = 0 \\ -3x_2 + 2x_3 + 2x_4 = 0 \end{cases}$$

$$\Leftrightarrow \begin{cases} x_1 - x_3 + x_4 = 0 \\ 3x_2 - 2x_3 + 2x_4 = 0 \end{cases} \rightarrow \begin{cases} x_4 = t \\ x_3 = s \\ x_2 = \frac{2}{3}s - \frac{2}{3}t \\ x_1 = s - t \end{cases}$$

$$\ker(f') = E_1(f) = \text{Span} \left\{ v_1 = \begin{pmatrix} 2 \\ 2 \\ 3 \\ 0 \end{pmatrix}, v_2 = \begin{pmatrix} 3 \\ 2 \\ 0 \\ -3 \end{pmatrix} \right\}$$

Nota che

$$B^2 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ -1 & 0 & 1 & -1 \\ -1 & 0 & 1 & -1 \end{pmatrix}$$

$\Rightarrow \ker((f')^2) = \ker(B^2) = \{x_1 - x_3 + x_4 = 0\}$
iperpiano intermedio

Visto che

(4)

$$\{0\} \subsetneq \text{Span}\{\underline{v}_1, \underline{v}_2\} \subsetneq \{x_1 - x_3 + x_4 = 0\} \subsetneq \mathbb{R}^4$$

$\parallel$ $\parallel$ $\parallel$
 $\ker(B)$ $\ker(B^2)$ $\ker(B^3)$

Nota che eg. $\underline{e}_3 \in \mathbb{R}^4 \setminus \ker(B^2) = \ker(B^3) \setminus \ker(B^2)$
 $\hookrightarrow$ non soddisfa eq. cartesiana di iperpiano

$\Rightarrow$

$$\begin{array}{ccccccc} 0 & \xleftarrow{B=f'} & B^2(\underline{e}_3) & \xleftarrow{B=f'} & B(\underline{e}_3) & \xleftarrow{B=f'} & \underline{e}_3 \end{array}$$

Sistema ciclico o stringa per $\mathbb{R}^4$

$$\underline{e}_3 \rightarrow B(\underline{e}_3) = \text{III colonna di } B = \begin{pmatrix} -1 \\ -1 \\ 1 \\ 2 \end{pmatrix} \sim \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\rightarrow B^2(\underline{e}_3) = \text{III colonna di } B^2 = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix} = \frac{1}{3} \underline{v}_1 - \frac{1}{3} \underline{v}_2 \in \ker(B)$$

$E_1(f)$

* Pertanto prendiamo ad esempio

$$J = \left\{ \underline{j}_1 = \underline{v}_1, \underline{j}_2 = B^2(\underline{e}_3) = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 1 \end{pmatrix}, \underline{j}_3 = B(\underline{e}_3) = \begin{pmatrix} -1 \\ -1 \\ 1 \\ 2 \end{pmatrix}, \underline{j}_4 = \underline{e}_3 \right\}$$

In base J

$$B(\underline{j}_1) = B(\underline{v}_1) = 0, \quad \underline{v}_1 \in \ker(B) = E_1(L_A)$$

$$B(\underline{j}_2) = B(B^2(\underline{e}_3)) = B^3(\underline{e}_3) = 0_{\mathbb{R}^4}(\underline{e}_3) = 0$$

$$B(\underline{j}_3) = B(B(\underline{e}_3)) = B^2(\underline{e}_3) = \underline{j}_2$$

$$B(\underline{j}_4) = B(\underline{e}_3) = \underline{j}_3$$

$\Rightarrow$

$$M_{J,J}(f') = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \quad \begin{array}{l} \downarrow \\ f' = L_B \end{array}$$

$$\begin{array}{l} \Rightarrow \\ B = A - I_4 \\ f' = f - I_{\mathbb{R}^4} \end{array}$$

$$M_{J,J}(f) = M_{J,J}(f') + I_4 \quad \begin{array}{l} \downarrow \\ f = L_A \end{array}$$

$$M_{J,J}(\mathcal{P}) = \left(\begin{array}{c|ccc} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{array} \right) = J_{\mathcal{P}}$$

(5)

Pertanto la matrice che fornisce la similitudine $\bar{e}$

$$M := M_{E,J} = \left(\begin{array}{cccc} 3 & 0 & -1 & 0 \\ 2 & 0 & -1 & 0 \\ 3 & 1 & 1 & 0 \\ 0 & 1 & 2 & 1 \end{array} \right)$$

$\downarrow \quad \quad \downarrow \quad \quad \downarrow \quad \quad \downarrow$
 $\underline{e}_1 = \underline{1}_1 \quad B(\underline{e}_2) = \underline{1}_2 \quad B(\underline{e}_3) = \underline{1}_3 \quad \underline{e}_3$

i.e.

$$M^{-1} \circ A \circ M = J_{\mathcal{P}}$$