

Svolgimenti Esercitazione IV  
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Esercizio 1

(i) Metodo scatti successivi

- $1-x \neq 0 \Rightarrow 1-x$  è vettore l.i. in  $V$
- $1-x, 1+x$  non proporzionali  $\Rightarrow \{1-x, 1+x\}$  sistema l.i. in  $V$
- $1-x^2$  non può essere comb. lin. di  $1-x$  e  $1+x$  per quanti mi si fissa  
 $\Rightarrow \{1-x, 1+x, 1-x^2\}$  sistema l.i. in  $V$
- $\exists \alpha_1, \alpha_2, \alpha_3 \in \mathbb{R}$  t.c.  $\alpha_1(1-x) + \alpha_2(1+x) + \alpha_3(1-x^2) = x - x^2$ ?

Tali scambi  $\nexists$  se e solo se volesse

$$(\alpha_1 + \alpha_2 + \alpha_3) \cdot 1 + (\alpha_2 - \alpha_1) x - \alpha_3 x^2 = x - x^2 \quad \text{identità polinomiale}$$

cioè se e solo se volesse:

$$\begin{cases} \alpha_1 + \alpha_2 + \alpha_3 = 0 \\ -\alpha_1 + \alpha_2 = 1 \\ \alpha_3 = 1 \end{cases}$$

$$\left( \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ -1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{array} \right) \xrightarrow{R_2 \rightarrow R_2 + R_1} \left( \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 2 & 1 & 1 \\ 0 & 0 & 1 & 1 \end{array} \right)$$

$$\# \text{ pivots} = 3 \Rightarrow \exists! \alpha_1, \alpha_2, \alpha_3 \in \mathbb{R} \text{ t.c. } x - x^2 = \alpha_1(1-x) + \alpha_2(1+x) + \alpha_3(x-x^2)$$

$\Rightarrow \{1-x, 1+x, 1-x^2, x-x^2\}$  non è sistema lin. indip.

$\Rightarrow$  anche  $S$  non può essere indipendente.

(ii) Da (i), poiché  $x - x^2 \in \text{Span}(\{1-x, 1+x, 1-x^2\}) \subseteq \text{Span}(S)$   
 posso già considerare

$$S \setminus \{x - x^2\} := \{1-x, 1+x, 1-x^2, x+x^2, 1+x^2+x^3\}$$

- $x+x^2 \in \text{Span} \{1-x, 1+x, 1-x^2\}$ ? I.e.  $\exists \beta_1, \beta_2, \beta_3 \in \mathbb{R}$  t.c.  
 $\beta_1(1-x) + \beta_2(1+x) + \beta_3(1-x^2) = x+x^2$ ?

Come prima  $\begin{cases} \beta_1 + \beta_2 + \beta_3 = 0 \\ -\beta_1 + \beta_2 = 1 \\ -\beta_3 = 1 \end{cases}$

la sesta trasformazione elementare precedente fornisce che (d)  
 $\exists!$  soli  $\beta_1, \beta_2, \beta_3 \Rightarrow$  anche  $x+x^2$  si può scrivere cioè

$$\text{Span}(S) = \text{Span}(S \setminus \{x-x^2\}) = \text{Span}(S \setminus \{x-x^2, x+x^2\})$$

e  $x+x^2$  dipende linearmente da  $\{1-x, 1+x, 1-x^2\}$

- infine  $1+x^2+x^3$  è lin. indip. da  $\{1-x, 1+x, 1-x^2\}$   
per quest'ultima si trova

$$\Rightarrow S' := \{1-x, 1+x, 1-x^2, 1+x^2+x^3\}$$

solo  $\text{Span}(S) = \text{Span}(S')$  ma  $S'$  sistema linearmente indipend.

(iii) Però  $a_0 + a_1 x + a_2 x^2 + a_3 x^3 \in V$  arbitrario,  $\exists$

$$\gamma_0, \gamma_1, \gamma_2, \gamma_3 \in \mathbb{R} \text{ t.c.}$$

$$\gamma_0(1-x) + \gamma_1(1+x) + \gamma_2(1-x^2) + \gamma_3(1+x^2+x^3) = a_0 + a_1 x + a_2 x^2 + a_3 x^3$$

$$\Leftrightarrow \begin{cases} \gamma_0 + \gamma_1 + \gamma_2 + \gamma_3 = a_0 \\ -\gamma_0 + \gamma_1 = a_1 \\ -\gamma_2 + \gamma_3 = a_2 \\ \gamma_3 = a_3 \end{cases}$$

$$\left( \begin{array}{cccc|c} 1 & 1 & 1 & 1 & a_0 \\ -1 & 1 & 0 & 0 & a_1 \\ 0 & 0 & -1 & 1 & a_2 \\ 0 & 0 & 0 & 1 & a_3 \end{array} \right) \xrightarrow{R_2 \rightarrow R_2 + R_1} \left( \begin{array}{cccc|c} 1 & 1 & 1 & 1 & a_0 \\ 0 & 2 & 1 & 1 & a_0 + a_1 \\ 0 & 0 & -1 & 1 & a_2 \\ 0 & 0 & 0 & 1 & a_3 \end{array} \right)$$

$$\# \text{ pivots} = 4 \Rightarrow \exists! \gamma_0, \gamma_1, \gamma_2, \gamma_3 \in \mathbb{R} \Rightarrow$$

$$\text{Span}(S') = V \quad e \quad S' \text{ sist. lin. indipendente}$$

$$(iv) P(x) = 10 - 7x - x^2 + x^3 = \gamma_0(1-x) + \gamma_1(1+x) + \gamma_2(1-x^2) + \gamma_3(1+x^2+x^3)$$

$$\Leftrightarrow \begin{cases} \gamma_0 + \gamma_1 + \gamma_2 + \gamma_3 = 10 \\ -\gamma_0 + \gamma_1 = -7 \\ -\gamma_2 + \gamma_3 = -1 \\ \gamma_3 = 1 \end{cases} \Leftrightarrow \begin{cases} \gamma_0 + \gamma_1 + \gamma_2 + \gamma_3 = 10 \\ 2\gamma_1 + \gamma_2 + \gamma_3 = 3 \\ -\gamma_2 + \gamma_3 = -1 \\ \gamma_3 = 1 \end{cases}$$

$$\boxed{\gamma_3 = 1} \Rightarrow \boxed{\gamma_2 = 2} \Rightarrow 2\gamma_1 = 3 - (2) - (1) = 0 \Rightarrow \boxed{\gamma_1 = 0}$$

$$\gamma_0 = 10 - (0) - (2)(1) = 7 \Rightarrow \boxed{\gamma_0 = 7}$$

$$P(x) = 7 \cdot (1-x) + 0 \cdot (1+x) + 2 \cdot (1-x^2) + 1 \cdot (1+x^2+x^3),$$

$$(v) W = \{ q_1(x) \in V \mid q_1(2) = 0 \}$$

$\forall q_1(x), q_2(x) \in W \text{ e } \forall \alpha_1, \alpha_2 \in \mathbb{R}$

$$(\alpha_1 q_1 + \alpha_2 q_2)(2) = \alpha_1 \cancel{q_1(2)} + \alpha_2 \cancel{q_2(2)} = 0$$

$\Rightarrow W$  è sottospazio di  $V$ .

Poiché  $1 \in V \setminus W \Rightarrow W$  è sottospazio proprio di  $V$ .

$$P(x) \in W \Leftrightarrow P(x) = (x-2)(b_0 + b_1 x + b_2 x^2), \quad b_i \in \mathbb{R}, \quad 0 \leq i \leq 2$$

Pertanto

$$\begin{aligned} P(x) \in W &\Leftrightarrow P(x) = b_0 \cancel{x} + b_1 \cancel{x^2} + b_2 \cancel{x^3} - 2b_0 - 2b_1 x - 2b_2 x^2 \\ &= b_0(x-2) + b_1(x^2-2x) + b_2(x^3-2x^2) \end{aligned}$$

$$b_0, b_1, b_2 \in \mathbb{R}$$

$$\text{Quindi } W = \text{Span}\left\{x-2, x^2-2x, x^3-2x^2\right\}$$

ed è un sist. lin. indip. per questioni di grado.

$$\begin{aligned} \text{Esercizio 2)} \\ (i) \quad T_{\text{sup}_{2,2}} &\ni A = \begin{pmatrix} a_{11} & a_{12} \\ 0 & a_{22} \end{pmatrix} = a_{11} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + a_{12} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} + a_{22} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \\ &= a_{11} E_{11} + a_{12} E_{12} + a_{22} E_{22} \end{aligned}$$

$$T_{\text{sup}_{2,2}} = \text{Span} \{ E_{11}, E_{12}, E_{22} \} \quad \text{ist. lin. indipendente}$$

Analogamente

$$T_{\text{inf}_{2,2}} = \text{Span} \{ E_{11}, E_{21}, E_{22} \}$$

$$\begin{aligned} (ii) \quad \text{Poiché } \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \in V \text{ è } & \quad \begin{pmatrix} a_{11} & a_{12} \\ 0 & a_{22} \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ a_{21} & a_{22} \end{pmatrix} \\ \Rightarrow V = T_{\text{sup}_{2,2}} + T_{\text{inf}_{2,2}} \end{aligned}$$

Ma la somma non è diretta, in quanto (4)

$$T_{\text{Sup}_{2,2}} \cap T_{\text{Inv}_{2,2}} = \left\{ \begin{pmatrix} a_{11} & 0 \\ 0 & a_{22} \end{pmatrix} \right\} = \text{Diag}_{2,2} \subset V.$$

(ii)  $A = \begin{pmatrix} 1 & 2 \\ 3 & 0 \end{pmatrix} \in V$  ma  $A \notin T_{\text{Sup}_{2,2}}$  e  $A \notin T_{\text{Inv}_{2,2}}$

$$\begin{pmatrix} 1 & 2 \\ 3 & 0 \end{pmatrix} = \begin{pmatrix} a_{11} & a_{12} \\ 0 & a_{22} \end{pmatrix} + \begin{pmatrix} b_{11} & 0 \\ b_{21} & b_{22} \end{pmatrix} \Leftrightarrow$$

$$\begin{cases} a_{11} + b_{11} = 1 & \text{se } b_{11} = t \in \mathbb{R} \Rightarrow a_{11} = 1 - t \\ a_{12} = 2 \\ b_{21} = 3 \\ a_{22} + b_{22} = 0 & \text{se } b_{22} = s \in \mathbb{R} \Rightarrow a_{22} = -s \end{cases}$$

Quindi

$$\begin{pmatrix} 1 & 2 \\ 3 & 0 \end{pmatrix} = \begin{pmatrix} 1-t & 2 \\ 0 & -s \end{pmatrix} + \begin{pmatrix} t & 0 \\ 3 & s \end{pmatrix} \quad \forall t, s \in \mathbb{R} \Rightarrow$$

$A$  ha  $\infty^2$  modi di essersi scritto come vettore in  $T_{\text{Sup}_{2,2}} + T_{\text{Inv}_{2,2}}$  (in particolare scritture non uniche)

$$(iv) \text{ Sym}_{2,2} \ni A = \begin{pmatrix} a_{11} & a_{12} \\ a_{12} & a_{22} \end{pmatrix} = a_{11} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + a_{12} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + a_{22} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$$

$$= a_{11} E_{11} + a_{12} (E_{12} + E_{21}) + a_{22} E_{22}$$

$$\Rightarrow \text{Sym}_{2,2} = \text{Span} \left\{ E_{11}, E_{12} + E_{21}, E_{22} \right\}$$

$$\text{Antisym}_{2,2} \ni A = \begin{pmatrix} 0 & a_{12} \\ -a_{12} & 0 \end{pmatrix} = a_{12} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

sist. lin. indipendente

$$\text{Antisym}_{2,2} = \text{Span} \left\{ E_{12} - E_{21} \right\}$$

$$(v) \text{ Antisym}_{2,2} \cap \text{Sym}_{2,2} = \{ O = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \}$$

$\forall A \in V$

$$A = \underbrace{\frac{1}{2} (A + A^t)}_{\text{Sym}_{2,2}} + \underbrace{\frac{1}{2} (A - A^t)}_{\text{Antisym}_{2,2}}$$

$\Rightarrow V = \text{Sym}_{2,2} \oplus \text{Antisym}_{2,2}$  e scritture uniche

$$A = \begin{pmatrix} 1 & 2 \\ 3 & 0 \end{pmatrix} \Rightarrow A^t = \begin{pmatrix} 1 & 3 \\ 2 & 0 \end{pmatrix} \quad (5)$$

$$\begin{aligned} A + A^t &= \begin{pmatrix} 2 & 5 \\ 5 & 0 \end{pmatrix} & \Rightarrow A &= \frac{1}{2} \begin{pmatrix} 2 & 5 \\ 5 & 0 \end{pmatrix} + \frac{1}{2} \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \\ A - A^t &= \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} & &= \begin{pmatrix} 1 & 5/2 \\ 5/2 & 0 \end{pmatrix} + \begin{pmatrix} 0 & -1/2 \\ 1/2 & 0 \end{pmatrix} \\ &&&\text{Sym}_{2,2} \qquad\qquad\qquad \text{Antisym}_{2,2} \end{aligned}$$

Schriftweise  
Unic.

### Esercizio 3

- (i) •  $\underline{v}_1$  e  $\underline{v}_2$  sono proporzionali
- $\underline{v}_3 \notin \text{Span}\{\underline{v}_1, \underline{v}_2\}$  infatti

$$\alpha_1 \underline{v}_1 + \alpha_2 \underline{v}_2 = \underline{v}_3 \Leftrightarrow \alpha_1 \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} + \alpha_2 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix} \Leftrightarrow$$

$$\begin{cases} \alpha_2 = 1 \\ \alpha_1 = -1 \\ -\alpha_1 + \alpha_2 = 3 \end{cases} \quad \cancel{\text{sistema incompatibile}}$$

Alternativamente per verificare che  $\{\underline{v}_1, \underline{v}_2, \underline{v}_3\}$  sist. lin. indip.

$$\beta_1 \underline{v}_1 + \beta_2 \underline{v}_2 + \beta_3 \underline{v}_3 = \underline{0} \quad \Leftrightarrow$$

$$\beta_1 \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} + \beta_2 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \beta_3 \begin{pmatrix} 1 \\ 0 \\ 3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \quad \Leftrightarrow$$

$$\begin{cases} \beta_2 + \beta_3 = 0 \\ \beta_1 - \beta_3 = 0 \\ -\beta_1 + \beta_2 + \beta_3 = 0 \end{cases}$$

$$\begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & -1 \\ -1 & 1 & 1 \end{pmatrix} \xrightarrow{R_1 \leftrightarrow R_3} \begin{pmatrix} -1 & 1 & 1 \\ 1 & 0 & -1 \\ 0 & 1 & 1 \end{pmatrix} \xrightarrow{R_2 \rightarrow R_2 + R_1}$$

$$\begin{pmatrix} -1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix} \xrightarrow{R_3 \rightarrow R_3 - R_2} \begin{pmatrix} \boxed{-1} & \boxed{1} & \boxed{1} \\ \boxed{0} & \boxed{1} & \boxed{0} \\ 0 & 0 & \boxed{1} \end{pmatrix}$$

Il sistema omogeneo ha soluzioni banali

$$(\beta_1, \beta_2, \beta_3) = (0, 0, 0) \Rightarrow \{\underline{v}_1, \underline{v}_2, \underline{v}_3\} \text{ sist. lin. indipendente}$$

$$\forall \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = c_1 \underline{E}_1 + c_2 \underline{E}_2 + c_3 \underline{E}_3 \in \mathbb{R}^3 \quad (6)$$

$$\exists \beta_1, \beta_2, \beta_3 \in \mathbb{R} \text{ t.c. } \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \beta_1 \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} + \beta_2 \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + \beta_3 \begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix}$$

equivolentemente

$$c_1 \underline{E}_1 + c_2 \underline{E}_2 + c_3 \underline{E}_3 = \beta_1 (\underline{E}_2 - \underline{E}_3) + \beta_2 (\underline{E}_1 + \underline{E}_3) + \beta_3 (\underline{E}_1 - \underline{E}_2 + 3\underline{E}_3)$$

Eutrambi i metodi forniscono

$$\left\{ \begin{array}{l} \beta_2 + \beta_3 = c_1 \\ \beta_1 - \beta_3 = c_2 \\ -\beta_1 + \beta_2 + 3\beta_3 = c_3 \end{array} \right.$$

$$\left( \begin{array}{ccc|c} 0 & 1 & 1 & c_1 \\ 1 & 0 & -1 & c_2 \\ -1 & 1 & 1 & c_3 \end{array} \right) \xrightarrow{R_1 \leftrightarrow R_3} \left( \begin{array}{ccc|c} -1 & 1 & 1 & c_3 \\ 1 & 0 & -1 & c_2 \\ 0 & 1 & 1 & c_1 \end{array} \right) \xrightarrow{R_2 \rightarrow R_2 + R_1}$$

$$\left( \begin{array}{ccc|c} -1 & 1 & 1 & c_3 \\ 0 & 1 & 0 & c_3 + c_2 \\ 0 & 1 & 1 & c_1 \end{array} \right) \xrightarrow{R_3 \rightarrow R_3 - R_2} \left( \begin{array}{ccc|c} -1 & 1 & 1 & c_3 \\ 0 & 1 & 0 & c_3 + c_2 \\ 0 & 0 & 1 & c_1 - c_2 + c_3 \end{array} \right)$$

$$\Rightarrow \boxed{\beta_3 = c_1 - c_2 + c_3 \quad \& \quad \beta_2 = c_2 + c_3}$$

$$\begin{aligned} -\beta_1 &= c_3 - (c_2 + c_3) - (c_1 - c_2 + c_3) = \cancel{c_3} - \cancel{c_2} - \cancel{c_3} - c_1 + \cancel{c_2} - c_3 \\ &= -c_1 - c_3 \end{aligned}$$

$$\Rightarrow \boxed{\beta_1 = c_1 + c_3}$$

Quindi

$$\begin{aligned} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} &= (c_1 + c_3) \underline{U}_1 + (c_2 + c_3) \underline{U}_2 + (c_1 - c_2 + c_3) \underline{U}_3 \\ &= (c_1 + c_3) \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} + (c_2 + c_3) \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} + (c_1 - c_2 + c_3) \begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix} \end{aligned}$$

(iii) Poiché  $\underline{w} = \begin{pmatrix} 1 \\ 0 \\ 2 \end{pmatrix} = 1 \underline{E}_1 + 2 \underline{E}_3$ , dai conti precedenti si ha

$$\underline{w} = 3 \underline{U}_1 + 2 \underline{U}_2 + 3 \underline{U}_3$$

(+)

$$\begin{aligned} \text{(iv)} \quad \underline{w} &= \underline{v}_1 - 2 \underline{v}_2 + \underline{v}_3 = (\underline{e}_2 - \underline{e}_3) - 2(\underline{e}_1 + \underline{e}_3) + (\underline{e}_1 - \underline{e}_2 + 3\underline{e}_3) \\ &= -\underline{e}_1 + 0\underline{e}_2 + 0\underline{e}_3 = -\underline{e}_1 \end{aligned}$$

### Esercizio 4

- (i) • 1 è la funzione identicamente uguale ad 1 mentre  $\sin(x)$  è periodica di periodo  $2\pi$   $\Rightarrow \{1, \sin(x)\}$  è sist. lin. indip.
- $\cos(x) \notin \text{Span}\{1, \sin(x)\}$ , altrimenti  $\exists \alpha_1, \alpha_2 \in \mathbb{R}$  t.c.

$$\cos(x) = \alpha_1 + \alpha_2 \sin(x)$$

$$\text{Poiché } \cos(0) = 1 \Rightarrow \alpha_1 = 1 \text{ visto che } \sin(0) = 0$$

$$\cos(\pi/2) = 0 \Rightarrow 0 = 1 + \alpha_2 \cdot \sin(\pi/2) \Leftrightarrow 0 = 1 + \alpha_2$$

quindi  $\alpha_2 = -1$

Se fosse

$$\cos x = 1 - \sin(x)$$

$$x = \pi/4 \quad \text{ovvero} \quad \frac{\sqrt{2}}{2} = 1 - \frac{\sqrt{2}}{2} \quad \cancel{\cancel{X}}$$

$\Rightarrow \{1, \sin(x), \cos(x)\}$  è sist. lin. indipendente

$$\bullet \quad \alpha_1 \cdot 1 + \alpha_2 \sin x + \alpha_3 \cos x + \alpha_4 \sin x \cdot \cos x \stackrel{?}{=} 0$$

$\downarrow$   
f.m.e identicamente nulla

$$x = 0 \quad \alpha_1 + \alpha_3 = 0$$

$$x = \pi/2 \quad \alpha_1 + \alpha_2 = 0$$

$$x = \frac{\pi}{4} \quad \alpha_1 + \frac{\sqrt{2}}{2} \alpha_2 + \frac{\sqrt{2}}{2} \alpha_3 + \frac{1}{2} \alpha_4 = 0$$

$$x = \frac{3}{4}\pi \quad \alpha_1 + \frac{\sqrt{2}}{2} \alpha_2 - \frac{\sqrt{2}}{2} \alpha_3 - \frac{1}{2} \alpha_4 = 0$$

$$\left\{ \begin{array}{l} \alpha_1 + \alpha_3 = 0 \\ \alpha_1 + \alpha_2 = 0 \\ 2\alpha_1 + \sqrt{2}\alpha_2 + \sqrt{2}\alpha_3 + \alpha_4 = 0 \\ 2\alpha_1 + \sqrt{2}\alpha_2 - \sqrt{2}\alpha_3 - \alpha_4 = 0 \end{array} \right. \Rightarrow \left\{ \begin{array}{l} \alpha_3 = -\alpha_1 \\ \alpha_2 = -\alpha_1 \\ 2\alpha_1 - 2\sqrt{2}\alpha_1 + \alpha_4 = 0 \\ 2\alpha_1 - \alpha_4 = 0 \end{array} \right.$$

$$\begin{cases} \alpha_3 = -\alpha_1 \\ \alpha_2 = -\alpha_1 \\ (2 - 2\sqrt{2})\alpha_1 + \alpha_4 = 0 \\ 2\alpha_1 - \alpha_4 = 0 \end{cases}$$

(8)

sistema con unica soluz.  
buone  
 $(\alpha_1, \alpha_2, \alpha_3, \alpha_4) = (0, 0, 0, 0)$

$\Rightarrow \{1, \sin(x), \cos(x), \sin(x) \cdot \cos(x)\}$  sist. lin. indipendente

• Ora, poiché  $\sin(2x) = 2 \sin(x) \cdot \cos(x) \Rightarrow$

$$\sin(2x) \in \text{Span} \{1, \sin(x), \cos(x), \sin(x) \cdot \cos(x)\}$$

visto che

$$\sin(2x) = 0 \cdot 1 + 0 \cdot \sin(x) + 0 \cdot \cos(x) + 2 \cdot (\sin(x) \cdot \cos(x))$$

$\Downarrow$

$$S' = \{1, \sin(x), \cos(x), \sin(x) \cdot \cos(x)\}.$$

(ii) Poiché  $\cos(2x) = \cos^2(x) - \sin^2(x)$  constatato  
simile alla precedente si verifica che  $\cos(2x) \notin \text{Span}(S')$

(iii) Analogamente per  $\operatorname{tg}(x)$  che non è definita su  $\mathbb{R}$ .  
differenza degli elementi in  $S'$ .