Eli Maor, *e* the story of a number, among references: George F. Simmons, Calculus with Analytic Geometry, NY, McGraw Hill, 1985, pp. 734–739

How Chebycev polynomials arise

Set $y(x) = x^n - p_{n-1}^{ott}(x)$ where p_{n-1}^{ott} is the unique polynomial of degree at most n-1 solving the minimum problem

$$\min_{p \in \mathbb{P}_{n-1}} \max_{[-1,1]} |x^n - p(x)|$$

where \mathbb{P}_{n-1} is the set of all polynomials of degree less than or equal to n-1. Moreover, set $\mu = \max_{[-1,1]} |y(x)|$.

Graphical considerations let us find such p_{n-1}^{ott} , for n = 1, 2, 3:

For n = 1 the given problem $\min_{p \in \mathbb{P}_0} \max_{[-1,1]} |x - p(x)|$ has the obvious solution $p_0^{ott}(x) = 0$. Moreover, observe that $y(x_i) = (-1)^i \mu$, $\mu = 1$, $x_1 = -1$, $x_0 = 1$.

For n = 2 the problem $\min_{p \in \mathbb{P}_1} \max_{[-1,1]} |x^2 - p(x)|$ is solved by $p_1^{ott}(x) = \frac{1}{2}$. Moreover, $y(x_i) = (-1)^i \mu$, $\mu = \frac{1}{2}$, $x_2 = -1$, $x_1 = 0$, $x_0 = 1$. For n = 3 the solution p_2^{ott} of the problem $\min_{p \in \mathbb{P}_2} \max_{[-1,1]} |x^3 - p(x)|$ must

For n = 3 the solution p_2^{ott} of the problem $\min_{p \in \mathbb{P}_2} \max_{[-1,1]} |x^3 - p(x)|$ must be a straight line with positive slope which intersects x^3 in three distinct points whose abscissas are $\xi_2 \in (-1,0)$, $\xi_1 = 0$, $\xi_0 = -\xi_2 \in (0,1)$, i.e. $p_2^{ott} = \alpha x$ with $0 < \alpha < 1$. Consider the function $g(x) = x^3 - \alpha x$ in the interval [-1,1]and notice that $g'(x) = 3x^2 - \alpha$ and thus $g'(\pm \sqrt{\frac{\alpha}{3}}) = 0$, $g(\pm \sqrt{\frac{\alpha}{3}}) = \pm \frac{\alpha}{3}\sqrt{\frac{\alpha}{3}} - \alpha(\pm \sqrt{\frac{\alpha}{3}}) = \pm \frac{2}{3}\alpha\sqrt{\frac{\alpha}{3}}$. Moreover, $g(\pm 1) = \pm 1 - \alpha(\pm 1)$. So, we have to choose $\alpha \in (0,1)$ so that $\max\{1 - \alpha, \frac{2}{3}\alpha\sqrt{\frac{\alpha}{3}}\}$ is minimum, i.e. $\alpha \in (0,1)$ such that

$$1 - \alpha = \frac{2}{3\sqrt{3}}\alpha\sqrt{\alpha} \Rightarrow \alpha = \frac{3}{4}.$$

Thus, $p_2^{ott}(x) = \frac{3}{4}x$. Moreover, observe that $y(x_i) = (-1)^i \mu$, $\mu = \frac{1}{4}$, $x_3 = -1$, $x_2 = -\frac{1}{2}$, $x_1 = \frac{1}{2}$, $x_0 = 1$. In general, Chebycev-Tonelli theory states that $y(x) = x^n - p_{n-1}^{ott}(x)$ must

In general, Chebycev-Tonelli theory states that $y(x) = x^n - p_{n-1}^{ott}(x)$ must assume the values μ and $-\mu$ alternately in n+1 points x_j of $[-1,1], -1 \leq x_n < x_{n-1} < \ldots < x_2 < x_1 < x_0 \leq 1$: $y(x_j) = (-1)^j \mu$. Obviously $y'(x_i) = 0$, $i = 1, \ldots, n-1$, whereas $y'(x_0)y'(x_n) \neq 0$ since y'(x) is a polynomial of degree n-1. Thus $x_n = -1, x_0 = 1$. Consider now the function $y(x)^2 - \mu^2$. It is zero in all the x_i and its derivative, 2y(x)y'(x), is zero in $x_1, x_2, \ldots, x_{n-1}$. It follows that $y(x)^2 - \mu^2 = c(x^2 - 1)y'(x)^2$ for some real constant c. Noting that the coefficient of x^{2n} is on the left 1 and on the right cn^2 , we conclude that

$$\frac{n^2}{1-x^2} = \frac{y'(x)^2}{\mu^2 - y(x)^2}, \quad \frac{n}{\sqrt{1-x^2}} = \pm \frac{y'(x)}{\sqrt{\mu^2 - y(x)^2}}.$$

The latter equality is solved by $y(x) = \mu \cos(n \arccos x + c), c \in \mathbb{R}$. Then the identity $y(1) = \mu$ implies $c = 2k\pi$, and thus

$$y(x) = x^n - p_{n-1}^{ott}(x) = \mu \cos(n \arccos x), \quad 1 - x^2 \ge 0.$$

Finally, observe that

$$\begin{aligned} \cos(0 \arccos x) &= 1|_{[-1,1]} =: T_0(x)|_{[-1,1]},\\ \cos(\arccos x) &= x|_{[-1,1]} =: T_1(x)|_{[-1,1]},\\ \cos(2 \arccos x) &= 2 \cos(\arccos x) \cos(\arccos x) - \cos(0 \arccos x) \\ &= 2x^2 - 1|_{[-1,1]} =: T_2(x)|_{[-1,1]},\\ \cos((j+1) \arccos x) &= 2 \cos(\arccos x) \cos(j \arccos x) - \cos((j-1) \arccos x) \\ &= 2xT_j(x) - T_{j-1}(x)|_{[-1,1]} =: T_{j+1}(x)|_{[-1,1]}. \end{aligned}$$

Thus, $\mu = \frac{1}{2^{n-1}}$ because $T_n(x) = 2^{n-1}x^n + \cdots$. So, we have the important result:

$$y(x) = x^n - p_{n-1}^{ott}(x) = \frac{1}{2^{n-1}}\cos(n\arccos x) = \frac{1}{2^{n-1}}T_n(x), \quad 1 - x^2 \ge 0.$$

Let us see two examples. The already studied specific case n = 3 is now immediately obtained:

$$y(x) = x^3 - p_2^{ott}(x) = \frac{1}{4}\cos(3\arccos x) = \frac{1}{4}(4x^3 - 3x) = x^3 - \frac{3}{4}x,$$

$$y(x_j) = (-1)^j \frac{1}{4}, \quad p_2^{ott}(x) = x^3 - (x^3 - \frac{3}{4}x) = \frac{3}{4}x.$$

The cases n > 3 are analogously easily solved. In particular, for n = 4 we have

$$y(x) = x^4 - p_3^{ott}(x) = \frac{1}{8}\cos(4\arccos x) = \frac{1}{8}(8x^4 - 8x^2 + 1) = x^4 - x^2 + \frac{1}{8},$$

$$y(x_j) = (-1)^j \frac{1}{8}, \quad p_3^{ott}(x) = x^4 - (x^4 - x^2 + \frac{1}{8}) = x^2 - \frac{1}{8}.$$

Deflation

Le *A* be a $n \times n$ matrix. Denote by λ_i , i = 1, ..., n, the eigenvalues of *A* and by \mathbf{y}_i the corresponding eigenvectors. So, we have $A\mathbf{y}_i = \lambda_i \mathbf{y}_i$, i = 1, ..., n.

Assume that λ_1, \mathbf{y}_1 are given and that $\lambda_1 \neq 0$. Choose $\mathbf{w} \in \mathbb{C}^n$ such that $\mathbf{w}^* \mathbf{y}_1 \neq 0$ (given \mathbf{y}_1 choose \mathbf{w} not orthogonal to \mathbf{y}_1) and set

$$W = A - \frac{\lambda_1}{\mathbf{w}^* \mathbf{y}_1} \mathbf{y}_1 \mathbf{w}^*.$$

It is known that the eigenvalues of W are

$$0, \lambda_2, \ldots, \lambda_j, \ldots, \lambda_n$$

i.e. they are the same of A except λ_1 which is replaced with 0. Let us prove this fact. Consider a matrix S whose first column is \mathbf{y}_1 and whose remaining columns $\mathbf{x}_2, \ldots, \mathbf{x}_n$ are chosen such that S is non singular. Observe that

$$S^{-1}AS = S^{-1}[A\mathbf{y}_1 A\mathbf{x}_2 \cdots A\mathbf{x}_n] = [\lambda_1 \mathbf{e}_1 S^{-1}A\mathbf{x}_2 \cdots S^{-1}A\mathbf{x}_n]$$

So, if we call B the $(n-1) \times (n-1)$ lower right submatrix of $S^{-1}AS$, then $p_A(\lambda) = (\lambda - \lambda_1)p_B(\lambda)$. But we also have

$$S^{-1}WS = S^{-1}AS - S^{-1}\frac{\lambda_1}{\mathbf{w}^*\mathbf{y}_1}\mathbf{y}_1\mathbf{w}^*S$$

= $\begin{bmatrix} \lambda_1 & \mathbf{c}^T \\ \mathbf{0} & B \\ \lambda_1 & \mathbf{c}^T \\ \mathbf{0} & B \end{bmatrix} - \frac{\lambda_1}{\mathbf{w}^*\mathbf{y}_1}\mathbf{e}_1[\mathbf{w}^*\mathbf{y}_1\,\mathbf{w}^*\mathbf{x}_2\cdots\mathbf{w}^*\mathbf{x}_n]$
= $\begin{bmatrix} \lambda_1 & \mathbf{c}^T \\ \mathbf{0} & B \end{bmatrix} - \begin{bmatrix} \lambda_1 & \mathbf{d}^T \\ \mathbf{0} & O \end{bmatrix}$
= $\begin{bmatrix} 0 & \mathbf{c}^T - \mathbf{d}^T \\ \mathbf{0} & B \end{bmatrix},$

and thus the identity $p_W(\lambda) = \lambda p_B(\lambda)$, from which the thesis.

Let $\mathbf{w}_1, \mathbf{w}_2, \ldots, \mathbf{w}_j, \ldots, \mathbf{w}_n$ be the corresponding eigenvectors ($W\mathbf{w}_1 = \mathbf{0}$, $W\mathbf{w}_j = \lambda_j \mathbf{w}_j \ j = 2, \dots, n$). Is it possible to obtain the \mathbf{w}_j from the \mathbf{y}_j ? First observe that

$$A\mathbf{y}_1 = \lambda_1 \mathbf{y}_1 \Rightarrow W\mathbf{y}_1 = \mathbf{0}: \mathbf{w}_1 = \mathbf{y}_1.$$
 (a)

Then, for $j = 2, \ldots, n$,

$$W\mathbf{y}_j = A\mathbf{y}_j - \frac{\lambda_1}{\mathbf{w}^* \mathbf{y}_1} \mathbf{y}_1 \mathbf{w}^* \mathbf{y}_j = \lambda_j \mathbf{y}_j - \lambda_1 \frac{\mathbf{w}^* \mathbf{y}_j}{\mathbf{w}^* \mathbf{y}_1} \mathbf{y}_1.$$
 (1)

If we impose $\mathbf{y}_j = \mathbf{w}_j + c\mathbf{y}_1$, $j = 2, \dots, n$, then (1) becomes,

$$W\mathbf{w}_{j} + cW\mathbf{y}_{1} = \lambda_{j}\mathbf{w}_{j} + c\lambda_{j}\mathbf{y}_{1} - \lambda_{1}\frac{\mathbf{w}^{*}\mathbf{w}_{j}}{\mathbf{w}^{*}\mathbf{y}_{1}}\mathbf{y}_{1} - c\lambda_{1}\mathbf{y}_{1}$$
$$= \lambda_{j}\mathbf{w}_{j} + \mathbf{y}_{1}[c\lambda_{j} - \lambda_{1}\frac{\mathbf{w}^{*}\mathbf{w}_{j}}{\mathbf{w}^{*}\mathbf{y}_{1}} - \lambda_{1}c]$$

So, if $\lambda_j \neq \lambda_1$ and

$$\mathbf{w}_j = \mathbf{y}_j - \frac{\lambda_1}{\lambda_j - \lambda_1} \frac{\mathbf{w}^* \mathbf{w}_j}{\mathbf{w}^* \mathbf{y}_1} \mathbf{y}_1,$$
(2)

then $W\mathbf{w}_j = \lambda_j \mathbf{w}_j$. If, moreover, $\lambda_j \neq 0$, then $\mathbf{w}^* \mathbf{y}_j = \mathbf{w}^* \mathbf{w}_j + \frac{\lambda_1}{\lambda_j - \lambda_1} \mathbf{w}^* \mathbf{w}_j \Rightarrow$ $\mathbf{w}^*\mathbf{y}_j = \mathbf{w}^*\mathbf{w}_j \frac{\lambda_j}{\lambda_j - \lambda_1} \Rightarrow \mathbf{w}^*\mathbf{w}_j = \frac{\lambda_j - \lambda_1}{\lambda_j}\mathbf{w}^*\mathbf{y}_j. \text{ So, by (2),}$

for all
$$j \in \{2...n\} \mid \lambda_j \neq \lambda_1, 0$$
:
 $A\mathbf{y}_j = \lambda_j \mathbf{y}_j \Rightarrow$
 $W(\mathbf{y}_j - \frac{\lambda_1}{\lambda_j} \frac{\mathbf{w}^* \mathbf{y}_j}{\mathbf{w}^* \mathbf{y}_1} \mathbf{y}_1) = \lambda_j (\mathbf{y}_j - \frac{\lambda_1}{\lambda_j} \frac{\mathbf{w}^* \mathbf{y}_j}{\mathbf{w}^* \mathbf{y}_1} \mathbf{y}_1)$: $\mathbf{w}_j = \mathbf{y}_j - \frac{\lambda_1}{\lambda_j} \frac{\mathbf{w}^* \mathbf{y}_j}{\mathbf{w}^* \mathbf{y}_1} \mathbf{y}_1$.
(b)

Note that a formula for \mathbf{y}_j in terms of \mathbf{w}_j holds: see (2).

As regards the case $\lambda_j = \lambda_1$, it is simple to show that

for all
$$j \in \{2...n\} \mid \lambda_j = \lambda_1$$
:
 $A\mathbf{y}_j = \lambda_j \mathbf{y}_j \Rightarrow$

$$W(\mathbf{y}_j - \frac{\mathbf{w}^* \mathbf{y}_j}{\mathbf{w}^* \mathbf{y}_1} \mathbf{y}_1) = \lambda_j (\mathbf{y}_j - \frac{\mathbf{w}^* \mathbf{y}_j}{\mathbf{w}^* \mathbf{y}_1} \mathbf{y}_1): \mathbf{w}_j = \mathbf{y}_j - \frac{\mathbf{w}^* \mathbf{y}_j}{\mathbf{w}^* \mathbf{y}_1} \mathbf{y}_1.$$
(c)

Note that the vectors $\mathbf{y}_j - \frac{\mathbf{w}^* \mathbf{y}_j}{\mathbf{w}^* \mathbf{y}_1} \mathbf{y}_1$ are orthogonal to \mathbf{w} . Is it possible to find from (c) an expression of \mathbf{y}_j in terms of \mathbf{w}_j ?

It remains the case $\lambda_j = 0$: find ? in

for all
$$j \in \{2...n\} \mid \lambda_j = 0$$
:
 $A\mathbf{y}_j = \lambda_j \mathbf{y}_j = \mathbf{0} \Rightarrow W(?) = \lambda_j(?) = \mathbf{0}: \mathbf{w}_j = ?$

$$(d?)$$

 $(\mathbf{y}_j = \mathbf{w}_j - \frac{\mathbf{w}^* \mathbf{w}_j}{\mathbf{w}^* \mathbf{y}_1} \mathbf{y}_1 \Rightarrow \mathbf{w}^* \mathbf{y}_j = 0) \dots$

Choices of w. Since $\mathbf{y}_1^*\mathbf{y}_1 \neq 0$ one can set $\mathbf{w} = \mathbf{y}_1$. In this way, if A is hermitian also W is hermitian. If i is such that $(\mathbf{y}_1)_i \neq 0$ then $\mathbf{e}_i^T A \mathbf{y}_1 =$ $\lambda_1(\mathbf{y}_1)_i \neq 0$. So one can set $\mathbf{w}^* = \mathbf{e}_i^T A = \text{row } i \text{ of } A$. In this way the row i of Wis null and therefore we can introduce a matrix of order n-1 whose eigenvalues are $\lambda_2, \ldots, \lambda_n$ (the unknown eigenvalues of A).

Exercise on deflation

The matrix

$$G = \begin{bmatrix} \frac{1}{4} & \frac{1}{4} & \frac{1}{2} \\ \frac{3}{4} & \frac{1}{8} & \frac{1}{8} \\ \frac{11}{16} & \frac{1}{4} & \frac{1}{16} \end{bmatrix}$$

satisfies the identity $G\mathbf{e} = \mathbf{e}, \mathbf{e} = [1 \ 1 \ 1]^T$. So, G has the eigenvalue 1 with corresponding eigenvector **e**. Moreover, since $\rho(G) \leq ||G||_{\infty} = 1$, all the eigenvalues of G have modulus less than or equal to 1.

Let 1, λ_2 , λ_3 be the eigenvalues of G. It is known that the matrix

$$W = G - \frac{1}{\mathbf{w}^* \mathbf{e}} \mathbf{e} \mathbf{w}^* = G - \frac{1}{\mathbf{e}_i^T G \mathbf{e}} \mathbf{e} \mathbf{e}_i^T G = G - \mathbf{e} \mathbf{e}_i^T G$$

for any i = 1, 2, 3 has $0, \lambda_2, \lambda_3$ as eigenvalues. For i = 1 we obtain

$$W = \begin{bmatrix} 0 & 0 & 0\\ \frac{1}{2} & -\frac{1}{8} & -\frac{3}{8}\\ \frac{7}{16} & 0 & -\frac{7}{16} \end{bmatrix},$$

thus the remaining eigenvalues of G are $-\frac{1}{8}$ and $-\frac{7}{16}$. Now observe that 1, $\lambda_2 = -\frac{1}{8}$, $\lambda_3 = -\frac{7}{16}$ are eigenvalues also of G^T . In particular, there exists **p** such that G^T **p** = **p**, but **p** has to be computed. The following inverse power iterations

$$\mathbf{v}_0, \|\mathbf{v}_0\|_1 = 1, \ \mathbf{a}_k = (G^T - (1 + \varepsilon)I)^{-1}\mathbf{v}_k, \ \mathbf{v}_{k+1} = a_k/\|\mathbf{a}_k\|_1, \dots$$

generate \mathbf{v}_k convergent to \mathbf{p} , $\|\mathbf{p}\|_1 = 1$, with a convergence rate $O(\frac{1+\varepsilon-1}{1+\varepsilon+\frac{1}{3}})$.

One eigenvalue at a time with power iterations

Assume A diagonalizable with eigenvalues λ_i such that $|\lambda_1| > |\lambda_k|, k =$ $2, \ldots, n$. Let $\mathbf{v} \neq \mathbf{0}$ be a vector. Then

$$A^{k}\mathbf{v} = \sum_{j} \alpha_{j} A^{k} \mathbf{x}_{j} = \sum_{j} \alpha_{j} \lambda_{j}^{k} \mathbf{x}_{j}, \ \frac{1}{\lambda_{1}^{k}} A^{k} \mathbf{v} = \alpha_{1} \mathbf{x}_{1} + \sum_{j \neq 1} \alpha_{j} \frac{\lambda_{j}^{k}}{\lambda_{1}^{k}} \mathbf{x}_{j}.$$

Thus

$$\begin{aligned} \frac{1}{\lambda_1^k} \mathbf{z}^* A^k \mathbf{v} &= \alpha_1 \mathbf{z}^* \mathbf{x}_1 + \sum_{j \neq 1} \alpha_j \frac{\lambda_j^k}{\lambda_1^k} \mathbf{z}^* \mathbf{x}_j, \\ \frac{1}{\lambda_1^{k+1}} \mathbf{z}^* A^{k+1} \mathbf{v} &= \alpha_1 \mathbf{z}^* \mathbf{x}_1 + \sum_{j \neq 1} \alpha_j \frac{\lambda_j^{k+1}}{\lambda_1^{k+1}} \mathbf{z}^* \mathbf{x}_j, \\ \frac{\mathbf{z}^* A^{k+1} \mathbf{v}}{\mathbf{z}^* A^k \mathbf{v}} &\to \lambda_1, \quad k \to \infty. \end{aligned}$$

So, if an eigenvalue dominates the other eigenvalues, then such eigenvalue can be approximated better and better by computing the quantities:

$$A\mathbf{v}, \ \frac{\mathbf{z}^*A\mathbf{v}}{\mathbf{z}^*\mathbf{v}}, \ A^2\mathbf{v} = A(A\mathbf{v}), \ \frac{\mathbf{z}^*A^2\mathbf{v}}{\mathbf{z}^*A\mathbf{v}}, \ A^3\mathbf{v} = A(A^2\mathbf{v}), \ \frac{\mathbf{z}^*A^3\mathbf{v}}{\mathbf{z}^*A^2\mathbf{v}}, \ \dots$$

It is clear that each new approximation requires a multiplication $A\mathbf{w}$.

Positive definite matrices and the choice $\mathbf{w} = \mathbf{y}_1^*$

Let A be a positive definite $n \times n$ matrix and let λ_j , \mathbf{y}_j be such that $A\mathbf{y}_j = \lambda_j \mathbf{y}_j$. Assume that $0 < \lambda_n < \lambda_{n-1} < \cdots < \lambda_2 < \lambda_1$. Then compute λ_1 via power iterations, and \mathbf{y}_1 from a weak approximation λ_1^* of λ_1 via inverse power iterations, both applied to A. Then the eigenvalues of

$$A - \frac{\lambda_1}{\|\mathbf{y}_1\|^2} \mathbf{y}_1 \mathbf{y}_1^*$$
 are $0, \lambda_n, \lambda_{n-1}, \cdots, \lambda_2$.

Compute λ_2 via power iterations, and \mathbf{y}_2 from a weak approximation λ_2^* of λ_2 via inverse power iterations, both applied to $A - \frac{\lambda_1}{\|\mathbf{y}_1\|^2} \mathbf{y}_1 \mathbf{y}_1^*$. Then the eigenvalues of

$$(A - \frac{\lambda_1}{\|\mathbf{y}_1\|^2} \mathbf{y}_1 \mathbf{y}_1^*) - \frac{\lambda_2}{\|\mathbf{y}_2\|^2} \mathbf{y}_2 \mathbf{y}_2^* \text{ are } 0, 0, \lambda_n, \cdots, \lambda_3.$$

$$(\cdots (A - \frac{\lambda_1}{\|\mathbf{y}_1\|^2} \mathbf{y}_1 \mathbf{y}_1^*) - \frac{\lambda_2}{\|\mathbf{y}_2\|^2} \mathbf{y}_2 \mathbf{y}_2^* \cdots) - \frac{\lambda_n}{\|\mathbf{y}_n\|^2} \mathbf{y}_n \mathbf{y}_n^* \text{ are } 0, 0, \dots, 0.$$

It follows that $A = \sum_{j=1}^{n} \frac{\lambda_j}{\|\mathbf{y}_j\|^2} \mathbf{y}_j \mathbf{y}_j^* = QDQ^*, Q = \begin{bmatrix} \frac{1}{\|\mathbf{y}_1\|_2} \mathbf{y}_1 & \frac{1}{\|\mathbf{y}_2\|_2} \mathbf{y}_2 & \cdots & \frac{1}{\|\mathbf{y}_n\|_2} \mathbf{y}_n \end{bmatrix}$. Note that the matrix Q is unitary (eigenvectors corresponding to distinct eigenvalues of a hermitian matrix must be orthogonal).

The QR method for 2×2 matrices

 Set

. . .

$$A = \left[\begin{array}{cc} x & y \\ z & w \end{array} \right], \quad x, y, w, z \in \mathbb{R}.$$

Choose $\alpha, \beta \in \mathbb{R}$ such that $\alpha^2 + \beta^2 = 1$ and $[Q_1 A]_{21} = 0$, where

$$Q_1 = \left[\begin{array}{cc} \alpha & -\beta \\ \beta & \alpha \end{array} \right],$$

i.e. $\alpha = \frac{x}{\sqrt{x^2 + z^2}}, \ \beta = \frac{-z}{\sqrt{x^2 + z^2}}$. Then

$$Q_1 A = \begin{bmatrix} \sqrt{x^2 + z^2} & \frac{xy + zw}{\sqrt{x^2 + z^2}} \\ 0 & \frac{-zy + xw}{\sqrt{x^2 + z^2}} \end{bmatrix} =: R.$$

Now define the matrix $B = RQ_1^T$:

$$B = \left[\begin{array}{cc} x + \frac{z(xy+zw)}{x^2+z^2} & -z + \frac{x(xy+zw)}{x^2+z^2} \\ \frac{z(xw-zy)}{x^2+z^2} & \frac{x(xw-zy)}{x^2+z^2} \end{array} \right].$$

Note that $B = Q_1 A Q_1^T$, $Q_1^T = Q_1^{-1}$, so that B has the same eigenvalues of A. (Moreover, B is real symmetric if A is real symmetric).

So, by setting $x_0 = x$, $y_0 = y$, $w_0 = w$, $z_0 = z$ we can define the four sequences

$$\begin{aligned} x_{k+1} &= x_k + \frac{z(x_k y_k + z_k w_k)}{x_k^2 + z_k^2}, \quad y_{k+1} &= -z_k + \frac{x_k (x_k y_k + z_k w_k)}{x_k^2 + z_k^2}, \\ z_{k+1} &= \frac{z(x_k w_k - z_k y_k)}{x_k^2 + z_k^2}, \quad w_{k+1} &= \frac{x_k (x_k w_k - z_k y_k)}{x_k^2 + z_k^2}, \\ k &= 0, 1, 2, \dots, \end{aligned}$$

which satisfy (by the theory on QR method) the properties:

 $z_k \to 0, \quad x_k, w_k \to \text{ eigenvalues of } A, \quad k \to +\infty$

provided the eigenvalues of A are distinct in modulus (try to prove this assertion). For example, if x = w = 2 and y = z = -1, then $x_1 = \frac{14}{5}$, $y_1 = -\frac{3}{5}$, $w_1 = \frac{6}{5}$, $z_1 = -\frac{3}{5}$, $x_2 = \frac{122}{41}$, $y_2 = -\frac{9}{41}$, $w_2 = \frac{42}{41}$, $z_2 = -\frac{9}{41}$, It is clear that x_k and w_k tend to 3 and 1, the eigenvalues of A.

Some results on matrix algebras

Given a $n \times n$ matrix X, set

$$K_X = \{A : AX - XA = 0\}, \quad \mathcal{P}(X) = \{p(X) : p \text{ polynomials}\}.$$

Note that $\mathcal{P}(X) \subset K_X$, and

$$\mathcal{P}(X) = K_X$$
 iff $\dim \mathcal{P}(X) = \dim K_X = n$.

Let Z denote the $n \times n$ shift-forward matrix, i.e. $[Z]_{ij} = 1$ if i = j + 1, and $[Z]_{ij} = 0$ otherwise. Note that

 $K_Z = \mathcal{P}(Z) = \{ \text{lower triangular Toeplitz matrices} \},$ $K_{Z^{T}} = \mathcal{P}(Z) = \{\text{nower triangular Toephez Interfect}\},\$ $K_{Z^{T}} = \mathcal{P}(Z^{T}) = \{\text{upper triangular Toephez matrices}\},\$ $K_{Z^{T} + \varepsilon \mathbf{e}_{n} \mathbf{e}_{1}^{T}} = \mathcal{P}(Z^{T} + \varepsilon \mathbf{e}_{n} \mathbf{e}_{1}^{T}) = \{\varepsilon \text{ circulant matrices}\},\$ $K_{Z^{T} + Z} = \mathcal{P}(Z^{T} + Z) = \{\tau \text{ matrices}\},\$ $\{\text{symmetric circulant matrices}\} = \mathcal{P}(Z^{T} + Z + \mathbf{e}_{n} \mathbf{e}_{1}^{T} + \mathbf{e}_{1} \mathbf{e}_{n}^{T})\$ $\subset K_{Z^T+Z+\mathbf{e}_n\mathbf{e}_1^T+\mathbf{e}_1\mathbf{e}_n^T} = \{A+JB: A, B \text{ circulant matrices }\}$

 $(\mathbf{e}_i^T J = \mathbf{e}_{n-i+1} \ i = 1, \dots, n, \ J = \text{counteridentity}).$ Set $X = Z + Z^T$. Then the condition $AX = XA, \ A = (a_{ij})_{i,j=1}^n$, is equivalent to the n^2 conditions:

$$a_{i,j-1} + a_{i,j+1} = a_{i-1,j} + a_{i+1,j}, \quad 1 \le i, j \le n,$$

 $a_{i,0} = a_{i,n+1} = a_{0,j} = a_{n+1,j} = 0$. Thus a generic matrix of τ has the form (in the case n = 5:

a	b	c	d	e	
b	a + c	b+d	c + e	d	
c	b+d	a + c + e	b+d	c	.
d	c + e	b+d	a + c	b	
e	d	c	b	a	
-				_	•

Since XS = SD, $S_{ij} = \sqrt{\frac{2}{n+1}} \sin \frac{ij\pi}{n+1}$ $(S^2 = I)$, $D = \text{diag}(2 \cos \frac{j\pi}{n+1})$, and matrices from τ are determined from their first row \mathbf{z}^T , we have the representation:

$$\tau(\mathbf{z}) = Sd(S\mathbf{z})d(S\mathbf{e}_1)^{-1}S$$

 $(\tau(\mathbf{z}) = \text{matrix of } \tau \text{ whose first row is } \mathbf{z}^T).$

Given a generic non singular matrix M, we have the representation

$$\{Md(\mathbf{z})M^{-1}:\,\mathbf{z}\in\mathbb{C}^n\}=\{Md(\mathbf{z})d(M^T\mathbf{v})^{-1}M^{-1}:\,\mathbf{z}\in\mathbb{C}^n\}$$

for any vector \mathbf{v} such that $(M^T \mathbf{v})_i \neq 0, \forall j$ (note that $\mathbf{v}^T M d(\mathbf{z}) d(M^T \mathbf{v})^{-1} M^{-1} =$ \mathbf{z}^{T}). For M =Fourier, sine matrices, one can choose $\mathbf{v} = \mathbf{e}_{1}$ (so circulants and

 τ matrices are determined by their first row). But there are significant matrices M (associated to fast discrete transforms) for which **v** cannot be chosen equal to **e**₁ (i.e. matrices diagonalized by M are not determined by their first row).

An example of matrix algebra which is not commutative is $\mathcal{L} = \{A + JB : A, B \text{ circulants}\}$. The best approximation (in the Frobenius norm) in \mathcal{L} of a given matrix A, call it \mathcal{L}_A , is well defined. It is known that \mathcal{L}_A is hermitian any time A is hermitian. But it is not known if (in case A hermitian) $\mathbf{z}^* A \mathbf{z} > 0$ $\forall \mathbf{z} \neq \mathbf{0}$ implies $\mathbf{z}^* \mathcal{L}_A \mathbf{z} > 0 \ \forall \mathbf{z} \neq \mathbf{0}$.

Assume $\{t_k\}_{k=0}^{+\infty}, t_k \in \mathbb{R}$, such that

$$\sum_{k=0}^{+\infty} |t_k| < +\infty.$$
(1)

Set $t(\theta) = \sum_{k=-\infty}^{+\infty} t_{|k|} e^{ik\theta}$, $t_{\min} = \min t(\theta)$, $t_{\max} = \max t(\theta)$. Then the eigenvalues of $T^{(n)} = (t_{|i-j|})_{j,j=1}^n$ are in the interval $[t_{\min}, t_{\max}]$ for all n (proof omitted). Let $C_{T^{(n)}}$ be the best circulant approximation of $T^{(n)}$. Since

$$C_{T^{(n)}} = F \operatorname{diag}\left((F^*T^{(n)}F)_{ii}\right)F^*, \ F_{ij} = \frac{1}{\sqrt{n}}\omega_n^{(i-1)(j-1)}, \ \omega_n = e^{-\mathbf{i}2\pi/n},$$

we have

 $t_{\min} \le \min \lambda(T^{(n)}) \le \min \lambda(C_{T^{(n)}}), \ \max \lambda(C_{T^{(n)}}) \le \max \lambda(T^{(n)}) \le t_{\max}.$

In particular, if

$$t_{\min} > 0, \tag{2}$$

then the $T^{(n)}$ and the $C_{T^{(n)}}$ are positive definite, and $\mu_2(C_{T^{(n)}}) \leq \mu_2(T^{(n)}) \leq \frac{t_{\max}}{t_{\min}}$; moreover, if $E_n E_n^T = C_{T^{(n)}}$, and $\alpha_j^{(n)}$ and $\beta_j^{(n)}$ are the eigenvalues, respectively, of $I - E_n^{-1}T^{(n)}E_n^{-T}$ and $C_{T^{(n)}} - T^{(n)}$ in nondecreasing order, then

$$\frac{1}{t_{\max}}|\beta_j^{(n)}| \le \frac{1}{\max\lambda(C_{T^{(n)}})}|\beta_j^{(n)}| \le |\alpha_j^{(n)}| \le \frac{1}{\min\lambda(C_{T^{(n)}})}|\beta_j^{(n)}| \le \frac{1}{t_{\min}}|\beta_j^{(n)}|$$
(2.5)

(apply the Courant-Fisher minimax characterization of the eigenvalues of a real symmetric matrix to $I - E_n^{-1}T^{(n)}E_n^{-T}$).

Theorem. If (1) holds, then the eigenvalues of $C_{T^{(n)}} - T^{(n)}$ are clustered around 0. If (1) and (2) hold, then the eigenvalues of $I - C_{T^{(n)}}^{-1} T^{(n)}$ are clustered around 0.

Proof. For the sake of simplicity, set $T = T^{(n)}$. Fix a number N, n > 2N, and let $W^{(N)}$ and $E^{(N)}$ be the $n \times n$ matrices defined by

$$[W^{(N)}]_{ij} = \begin{cases} [C_T - T]_{ij} & i, j \le n - N \\ 0 & \text{otherwise} \end{cases}$$

and

$$C_T - T = E^{(N)} + W^{(N)}.$$
(3)

Note that $[C_T]_{1j} = ((n-j+1)t_{j-1} + (j-1)t_{n-j+1})/n$, j = 1, ..., n, and thus, for i, j = 1, ..., n, we have

$$[C_T - T]_{ij} = -\frac{s_{|i-j|}|i-j|}{n}, \ s_k = t_k - t_{n-k}.$$

Now observe that the rank of $E^{(N)}$ is less than or equal to 2N, so $E^{(N)}$ has at least n - 2N null eigenvalues. Also observe that $C_T - T$, $E^{(N)}$ and $W^{(N)}$ are all real symmetric matrices. In the following we prove that, for any fixed $\varepsilon > 0$, there exist N_{ε} and $\nu_{\varepsilon} \geq 2N_{\varepsilon}$ such that

$$\|W^{(N_{\varepsilon})}\|_{1} < \varepsilon \quad \forall n > \nu_{\varepsilon}.$$

$$\tag{4}$$

As a consequence of this fact and of the identity (3) for $N = N_{\varepsilon}$, we shall have that for all $n > \nu_{\varepsilon}$ at least $n - 2N_{\varepsilon}$ eigenvalues of $C_T - T$ are in $(-\varepsilon, \varepsilon)$. Moreover, if $t_{\min} > 0$, then, by (2.5), we shall also obtain the clustering around 0 of the eigenvalues of $I - C_T^{-1}T$.

So, let us prove (4). First we have

$$\|W^{(N)}\|_{1} \leq \frac{2}{n} \sum_{j=1}^{n-N-1} j|s_{j}| \leq 2 \sum_{j=N+1}^{n-1} |t_{j}| + \frac{2}{n} \sum_{j=1}^{N} j|t_{j}|.$$
(5)

Then, for any $\varepsilon > 0$ choose N_{ε} such that $2\sum_{j=N_{\varepsilon}+1}^{+\infty} |t_j| < \frac{\varepsilon}{2}$ and set $N = N_{\varepsilon}$ in (5) and in the previous arguments. If ν_{ε} , $\nu_{\varepsilon} \ge 2N_{\varepsilon}$, is such that, $\forall n > \nu_{\varepsilon}$, $\frac{2}{n}\sum_{j=1}^{N_{\varepsilon}} j|t_j| < \frac{\varepsilon}{2}$ (the sequence $\frac{1}{n}\sum_{j=1}^{n-1} j|t_j|$ tends to 0 if (1) holds), then by (5) we have the thesis (4).

Stai usando il seguente algoritmo (il primo a p.18 dell'articolo) che calcola direttamente una successione di e vettori \mathbf{x}_k convergente a \mathbf{x} tale che $\mathbf{p} = \frac{1}{\|\mathbf{x}\|_1}\mathbf{x}$? Se non lo stai usando, allora leggilo attentamente ed implementalo accuratamente, rispondendomi alle domande che troverai.

$$\mathbf{x}_{k+1} = \mathbf{x}_k + F(I - \alpha \sqrt{n}d(\overline{Fc}))^{-1}F^*(\mathbf{v} - A^T\mathbf{x}_k)$$

$$F_{s,j} = \frac{1}{\sqrt{n}}\omega_n^{(s-1)(j-1)}, \ s, j = 1, \dots, n, \ \omega_n = e^{-\mathbf{i}2\pi/n}$$

$$d(\mathbf{z}) = \begin{bmatrix} z_1 & & \\ & \ddots & \\ & & z_n \end{bmatrix}$$

$$= [c_0 \ c_1 \ \cdots \ c_{n-1}]^T, \ c_0 = s_0/n = 0, \ c_i = (s_i + s_{-n+i})/n, \ i = 1, \dots, n-1$$

$$s_1 = \sum_{i=1}^{n-1} [P]_{i,i+1}, \ s_{-1} = \sum_{i=1}^{n-1} [P]_{i+1,i}, \dots$$

Quindi, ogni volta che *n* e' una potenza di 2: calcolo dei c_j , j = 0, ..., n-1($c_0 = 0$); calcolo di $F\mathbf{c}$; calcolo dei $\overline{F\mathbf{c}}$ (il vettore coniugato di $F\mathbf{c}$); calcolo della matrice diagonale $D = (I - \alpha \sqrt{nd}(\overline{F\mathbf{c}}))^{-1}$. Poi, per ogni k = 0, 1, ..., calcolo di

$$\mathbf{x}_{k+1} = \mathbf{x}_k + FDF^*(\mathbf{v} - (I - \alpha P^T)\mathbf{x}_k)$$

(scegliendo $\mathbf{x}_0 = \mathbf{v} = [1/n \cdots 1/n]^T$).

С

Nota che esiste una matrice di permutazione Q tale che $F^* = QF$, $F = QF^*$, hai usato questo fatto per calcolare \mathbf{x}_{k+1} ? Quindi $F^*\mathbf{z}$ e' semplicemente una permutazione di $F\mathbf{z}$ (e viceversa); la FFT che hai tu calcola $F\mathbf{z}$ o $F^*\mathbf{z}$? I vettori \mathbf{x}_k dovrebbero convergere a un vettore \mathbf{x} che una volta normalizzato dovrebbe coincidere con il vettore page-rank \mathbf{p} , cioe' $\mathbf{p} = \frac{1}{\|\mathbf{x}\|_1} \mathbf{x}$.

Mi scrivi dettagliatamente i tre criteri di arresto che usi? Quello per potenze dovrebbe differire da quelli usati per RE e RE precondizionato perche' i vettori generati dal metodo delle potenze sono gia' normalizzati.

$$\begin{split} y'(t) &= -\frac{1}{2y(t)}, \ y(0) = 1 \quad (y(t) = \sqrt{1-t}) \\ \sqrt{1-t} &= \frac{1}{\sqrt{p}} \ iff \ t = 1 - \frac{1}{p} \end{split}$$

Integrate in $[0, 1 - \frac{1}{p}]$ the Cauchy problem to obtain an approximation of $\frac{1}{\sqrt{p}}$. p = 3: Eulero for $h = \frac{1}{3}$, two steps; for $h = \frac{1}{6}$, four steps.

$$\eta(x_i + h) = \eta(x_i) + hf(x_i, \eta(x_i)) = \eta(x_i) - h\frac{1}{2\eta(x_i)}$$
$$\eta(0 + \frac{1}{3}) = \eta(0) - \frac{1}{3}\frac{1}{2\eta(0)} = 1 - \frac{1}{6} = \frac{5}{6}$$
$$\eta(\frac{1}{3} + \frac{1}{3}) = \eta(\frac{1}{3}) - \frac{1}{3}\frac{1}{2\eta(\frac{1}{3})} = \frac{5}{6} - \frac{1}{5} = \frac{19}{30}$$

Idem, implicit Euler: $h = \frac{1}{3}$ not ok; $h = \frac{1}{6}$ ok?.

$$\eta(x_i + h) = \eta(x_i) + hf(x_i + h, \eta(x_i + h)) = \eta(x_i) - h\frac{1}{2\eta(x_i + h)}$$
$$\eta(x_i + h)^2 - \eta(x_i + h)\eta(x_i) + h\frac{1}{2} = 0$$
$$\eta(x_i + h) = \frac{1}{2}(\eta(x_i) \pm \sqrt{\eta(x_i)^2 - 2h})$$
$$\eta(0 + \frac{1}{3}) = \frac{1}{2}(\eta(0) \pm \sqrt{\eta(0)^2 - \frac{2}{3}}) = \frac{1}{2}(1 \pm \sqrt{1 - \frac{2}{3}}) = \frac{1}{2} \pm \frac{1}{2}\frac{1}{\sqrt{3}}\frac{\sqrt{3} + 1}{2\sqrt{3}}$$
$$\eta(\frac{1}{3} + \frac{1}{3}) = \frac{1}{2}(\eta(\frac{1}{3}) \pm \sqrt{\eta(\frac{1}{3})^2 - \frac{2}{3}})$$

not real!

The given matrix is non negative and stochastic by columns

$$\lambda^3 - \lambda^2 (1 - a - b) - \lambda b - a = (\lambda - 1)(\lambda^2 + (a + b)\lambda + a)$$

Eigenvalues:

$$1, \ -\frac{a+b}{2} \pm \frac{\sqrt{(a+b)^2 - 4a}}{2}$$

We know that their absolute value is less than or equal to 1. Question: when is it equal to 1?

Assume they are real. Then question becomes:

$$-\frac{a+b}{2} + \frac{\sqrt{(a+b)^2 - 4a}}{2} = 1$$

$$-\frac{a+b}{2} - \frac{\sqrt{(a+b)^2 - 4a}}{2} = -1$$

Assume they are not real. Then they can be rewritten as follows:

$$-\frac{a+b}{2} \pm \mathbf{i}\frac{\sqrt{4a-(a+b)^2}}{2}$$

Thus, question becomes:

$$\frac{(a+b)^2}{4} + \frac{4a - (a+b)^2}{4} = 1$$

equality which is satisfied iff a = 1

An equivalent definition of Bernoulli polynomials

The degree n Bernoulli polynomial $B_n(x)$ is uniquely determined by the conditions

$$B_n(x+1) - B_n(x) = nx^{n-1}, \quad \int_0^1 B_n(x) \, dx = 0. \tag{1}$$

Note that the first condition in (1) implies:

$$\int_{t}^{t+1} B_{n}(x+1)dx - \int_{t}^{t+1} B_{n}(x)dx = n \left[\frac{x^{n}}{n}\right]_{t}^{t+1},$$
$$\int_{t+1}^{t+2} B_{n}(y)dy - \int_{t}^{t+1} B_{n}(x)dx = (t+1)^{n} - t^{n}.$$

By writing the latter identity for t = 0, 1, ..., x - 1, taking into account the second condition in (1), and summing, we obtain:

$$\int_{x}^{x+1} B_n(y) dy = x^n, \ \forall x \in \mathbb{R}.$$
 (2)

So, (1) implies (2). Of course, (2) implies the second condition in (1) (choose x = 0). It can be shown that (2) implies also that B_n must be a polynomial of degree at least n and must satisfy the first condition in (1).

Assume that we know that (2) implies that B_n must be a polynomial. Let us show that then its degree is at least n. If, on the contrary, $B_n(y) = a_0 y^{n-1} + \ldots$ then $\int_x^{x+1} B_n(y) dy = [\frac{a_0}{n} y^n + \ldots]_x^{x+1} = \frac{a_0}{n} [(x+1)^n - x^n] + \ldots$ is a degree n-1 polynomial, and thus cannot be equal to x^n .

Finally, the fact that (2) implies the first condition in (1) can be shown by deriving (2) with respect to x, and remembering the rule:

$$\frac{d}{dx} \int_{f(x)}^{g(x)} h(x,y) dy = h(x,g(x))g'(x) - h(x,f(x))f'(x) + \int_{f(x)}^{g(x)} \frac{\partial}{\partial x} h(x,y) dy.$$