

Zero Velocity Surfaces in General Three Body Problem

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Consider the planar problem.

Reduce phase space by translation ($\mathbb{R}^6 \rightarrow \mathbb{R}^4$; Jacobie coordinatges)

Next reduce the space by rotation ($\mathbb{R}^4 \rightarrow \mathbb{R}^3 : \mathcal{S}^1 \hookrightarrow \mathcal{S}^3 \rightarrow \mathcal{S}^2$; Hopf mapping):

$$\xi_1 = \mu_1 |\mathbf{Q}_1|^2 - \mu_2 |\mathbf{Q}_2|^2,$$

$$\xi_2 = 2\sqrt{\mu_1 \mu_2} \mathbf{Q}_1 \cdot \mathbf{Q}_2,$$

$$\xi_3 = 2\sqrt{\mu_1 \mu_2} \mathbf{Q}_1 \times \mathbf{Q}_2,$$

$$I = \mu_1 |\mathbf{Q}_1|^2 + \mu_2 |\mathbf{Q}_2|^2 = \sqrt{\xi_1^2 + \xi_2^2 + \xi_3^2}.$$

Here, $\mathbf{Q}_1, \mathbf{Q}_2$ – Jacobie coordinates, $\mu_1 = m_1 m_2 / (m_1 + m_2)$,
 $\mu_2 = m_3 (m_1 + m_2) / (m_1 + m_2 + m_3)$.

$$T - U = \frac{4J^2 + \dot{\xi}_1^2 + \dot{\xi}_2^2 + \dot{\xi}_3^2}{8\sqrt{\xi_1^2 + \xi_2^2 + \xi_3^2}} - U(\xi_1, \xi_2, \xi_3) = h.$$

Energy integral, Sundman inequality and zero velocity surface

$$\begin{aligned}\frac{J^2}{2I} - U(\xi_1, \xi_2, \xi_3) - h &\leq \\ \frac{J^2}{2I} + \dot{I}^2/(8I) - U(\xi_1, \xi_2, \xi_3) - h &\leq \\ \frac{4J^2 + \dot{\xi}_1^2 + \dot{\xi}_2^2 + \dot{\xi}_3^2}{8\sqrt{\xi_1^2 + \xi_2^2 + \xi_3^2}} - U(\xi_1, \xi_2, \xi_3) - h &= 0, \\ \frac{J^2}{2\sqrt{\xi_1^2 + \xi_2^2 + \xi_3^2}} - U(\xi_1, \xi_2, \xi_3) &= h, \\ U(\xi_1, \xi_2, \xi_3) &= \frac{1}{\sqrt[4]{\xi_1^2 + \xi_2^2 + \xi_3^2}} D(\varphi, \theta).\end{aligned}$$

If $\mathbf{r}_i(t)$, $i = 1, \dots, N$, is solution of N -body problem, the following expression gives the solution as well

$$\begin{aligned}\rho_i(t) &= \lambda \mathbf{r}_i(\lambda^{-3/2}t) \\ \dot{\rho}_i(t) &= \lambda^{-1/2} \mathbf{v}_i(\lambda^{-3/2}t) \\ h' &\equiv h/\lambda\end{aligned}$$

Expressions for mutual distances

$$r_{12}^2 = \frac{m_1 + m_2}{2m_1 m_2} (\sqrt{\xi_1^2 + \xi_2^2 + \xi_3^2} + \xi_1)$$

$$r_{13}^2 = \frac{m_1 + m_3}{2m_1 m_3} \sqrt{\xi_1^2 + \xi_2^2 + \xi_3^2}$$

$$+ \frac{m_2 m_3 - m_1(m_1 + m_2 + m_3)}{2m_1 m_3(m_1 + m_2)} \xi_1 + \frac{\sqrt{m_1 m_2 m_3(m_1 + m_2 + m_3)}}{m_1 m_3(m_1 + m_2)} \xi_2$$

$$r_{23}^2 = \frac{m_2 + m_3}{2m_2 m_3} \sqrt{\xi_1^2 + \xi_2^2 + \xi_3^2}$$

$$+ \frac{m_1 m_3 - m_2(m_1 + m_2 + m_3)}{2m_2 m_3(m_1 + m_2)} \xi_1 - \frac{\sqrt{m_1 m_2 m_3(m_1 + m_2 + m_3)}}{m_2 m_3(m_1 + m_2)} \xi_2$$

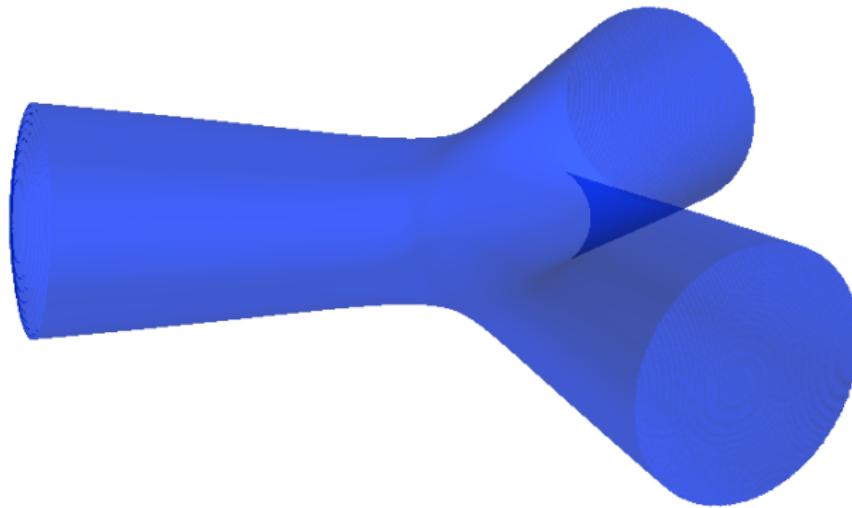
$m_1 = m_2 = m_3 = 1$: $O\xi_3$ and $O\xi_1$

$$J = 0 : \quad U(0, 0, \xi_3) = -3/\sqrt{\xi_3} = -h = \frac{1}{2}, \quad \rightarrow \quad \xi_3 = 36$$
$$U(\xi_1, 0, 0) = 1/\sqrt{2\xi_1} + 2/\sqrt{\xi_1/2}, \quad \rightarrow \quad \xi_1 = 50.$$

$$J \neq 0 : \quad U(0, 0, \xi_3) - \frac{J^2}{2\xi_3} = 3/\sqrt{\xi_3} - \frac{J^2}{2\xi_3} = \frac{1}{2} \quad \rightarrow$$
$$\xi_3 \in \left[\left(3 - \sqrt{9 - J^2} \right)^2, \left(3 + \sqrt{9 - J^2} \right)^2 \right].$$

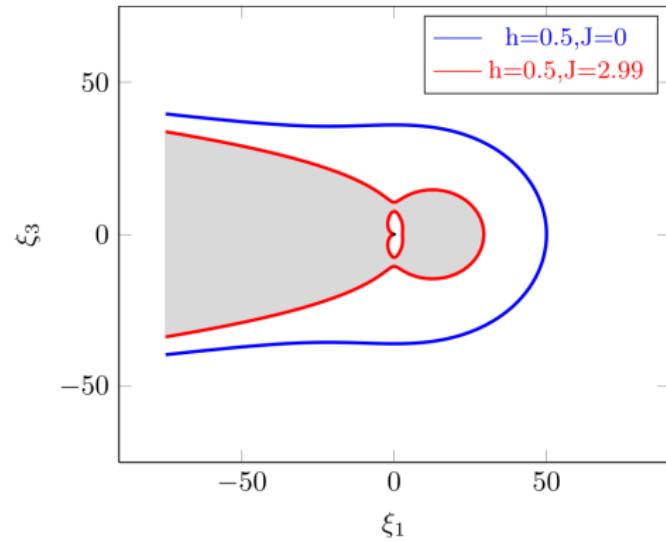
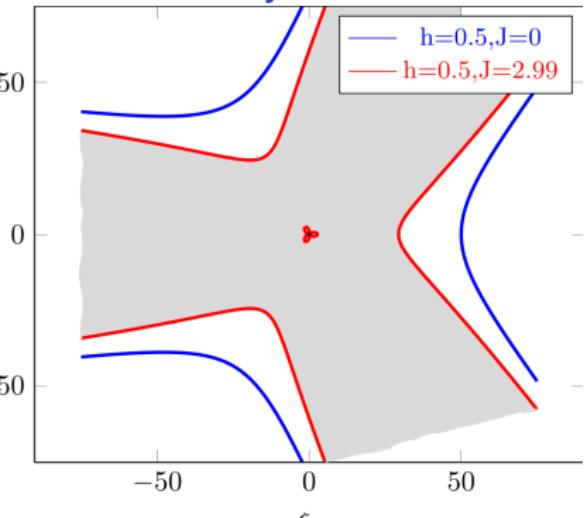
$$U(\xi_1, 0, 0) - \frac{J^2}{2\xi_1} = 1/\sqrt{2\xi_1} + 2/\sqrt{\xi_1/2} - \frac{J^2}{2\xi_1} = \frac{1}{2} \quad \rightarrow$$
$$\xi_1 \in \left[\left(5 - \sqrt{25 - 2J^2} \right)^2 / 2, \left(5 + \sqrt{25 - 2J^2} \right)^2 / 2 \right].$$

Zero velocity surface at $J = 0$ ($h = -\frac{1}{2}$)

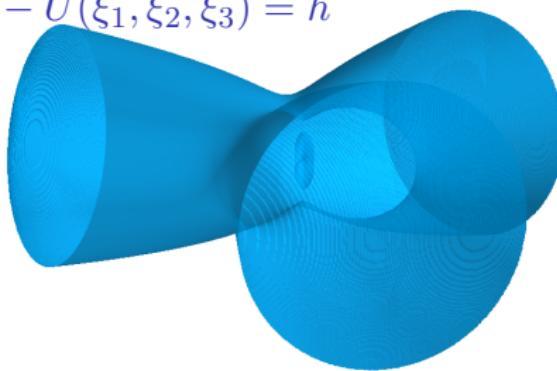


$$U(\xi_1, \xi_2, \xi_3) = -h$$

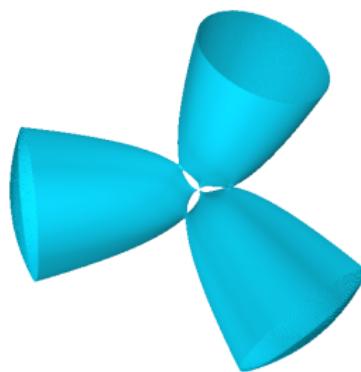
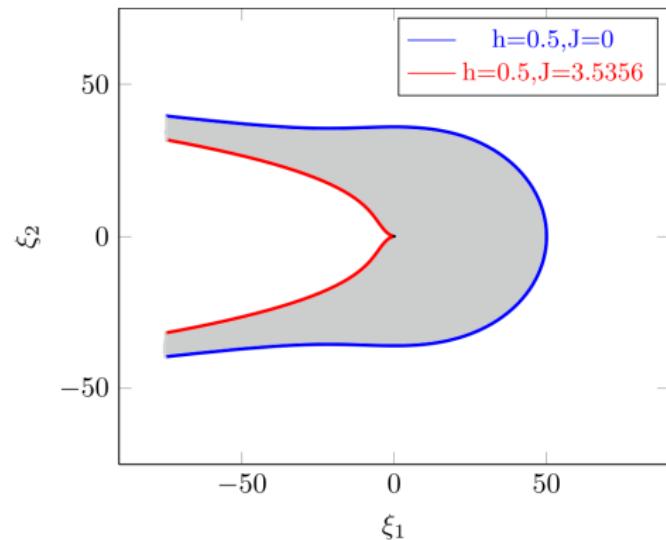
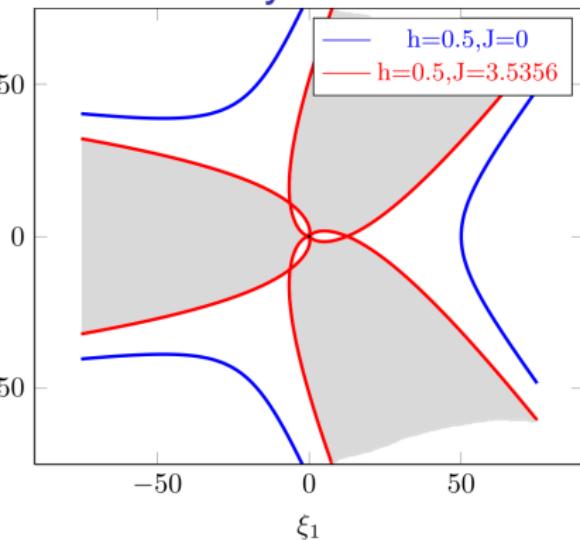
Zero velocity surface at $J = 2.99$



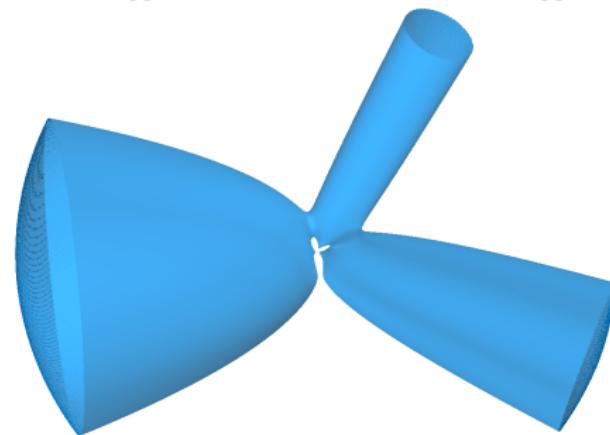
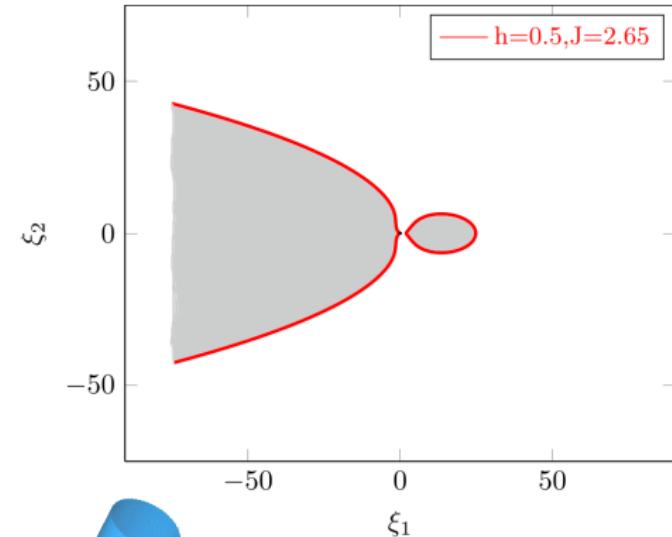
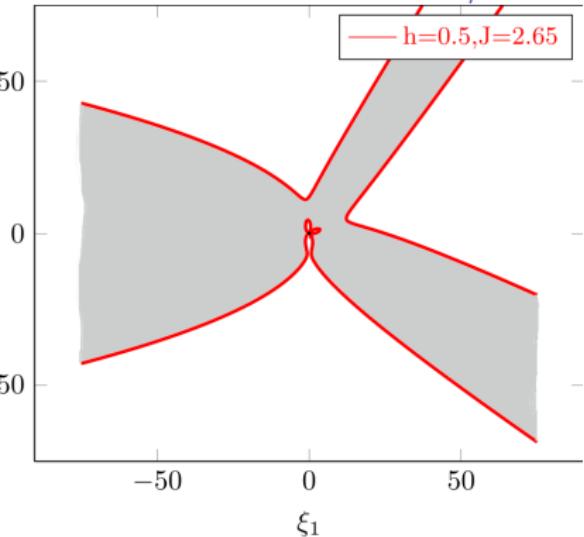
$$\frac{J^2}{2\sqrt{\xi_1^2 + \xi_2^2 + \xi_3^2}} - U(\xi_1, \xi_2, \xi_3) = h$$



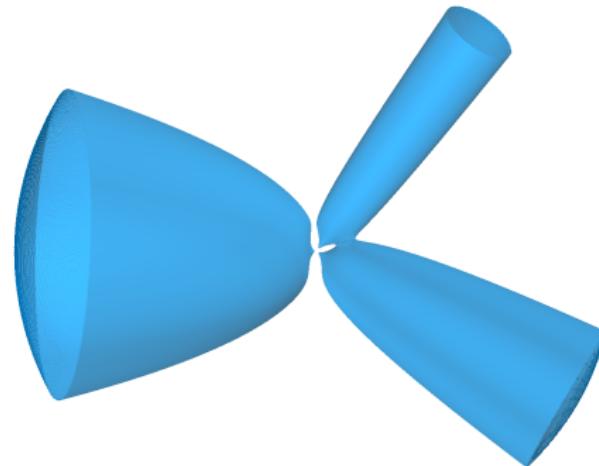
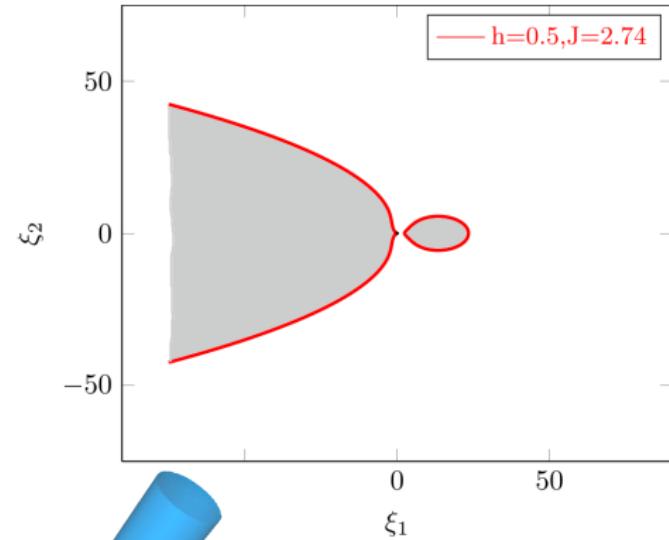
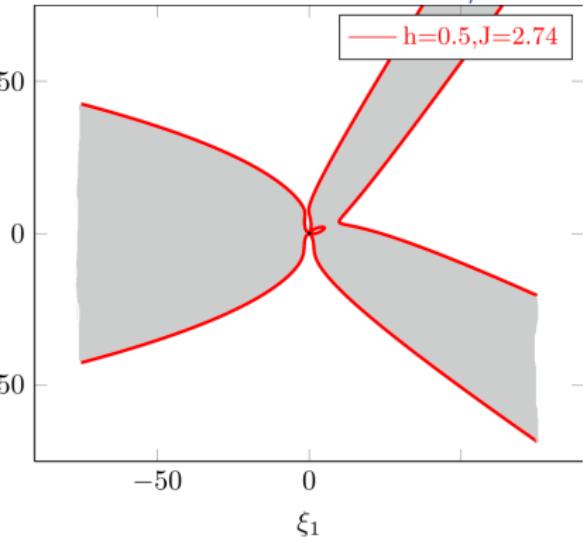
Zero velocity surface at $J = 3.53$



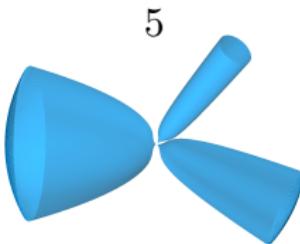
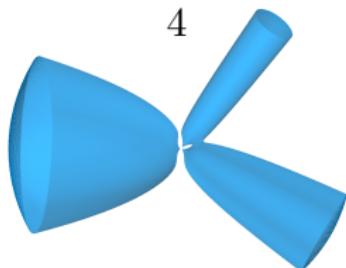
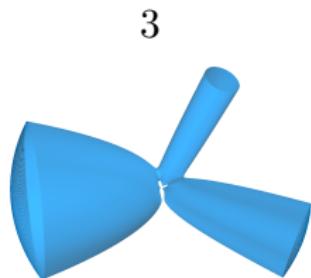
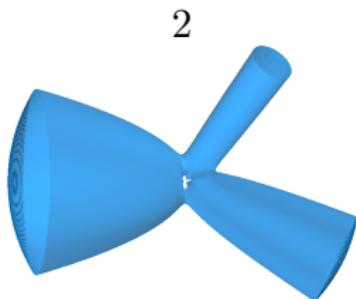
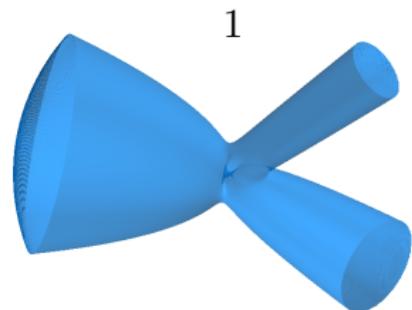
$$m_1 = 2m_2 = 4m_3 = 12/7, J = 2.65$$



$$m_1 = 2m_2 = 4m_3 = 12/7, J = 2.74$$



Zero velocity surface (general three-body problem)



Final motions, hierarchical systems