

SCIENCE PASSION TECHNOLOGY

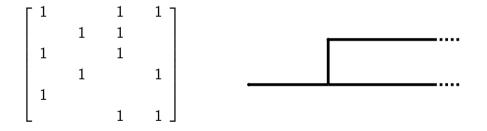
Fantastic barcode algorithms and where to find them

Barbara Giunti

Topology of Data in Rome, 15-16 September 2022



Matrices and interval spheres





Motivation





Motivation



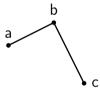
http://www.zotero.org/groups/TDA-Applications



а

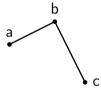
n-simplex: collection of n + 1 points





n-simplex: collection of n + 1 points Simplicial complex: collection of simplices





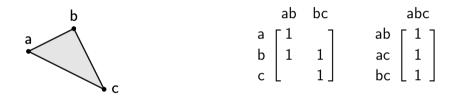
n-simplex: collection of n + 1 points Simplicial complex: collection of simplices Boundary of a *n*-simplex: all (n - 1)-simplices without one of its points





n-simplex: collection of n + 1 points Simplicial complex: collection of simplices Boundary of a *n*-simplex: all (n - 1)-simplices without one of its points (*n*)-boundary matrix: boundary of all the (*n*)-simplices

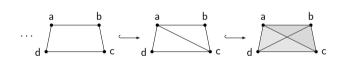




n-simplex: collection of n + 1 points Simplicial complex: collection of simplices Boundary of a *n*-simplex: all (n - 1)-simplices without one of its points (*n*)-boundary matrix: boundary of all the (*n*)-simplices



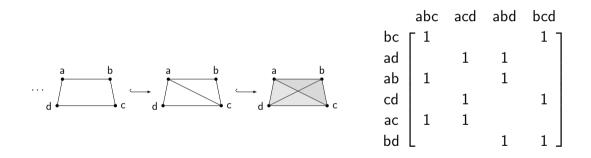
Filtrations



Filtration: nested sequence of simplicial complexes



Filtrations



Filtration: nested sequence of simplicial complexes (Total) boundary matrix: boundary matrix of the final complex



Chain complex: sequence of (boundary) maps of vector spaces such that the composition of two consecutive maps is 0



Chain complex: sequence of (boundary) maps of vector spaces such that the composition of two consecutive maps is 0

degree *n* k



Chain complex: sequence of (boundary) maps of vector spaces such that the composition of two consecutive maps is 0

degree
$$n + 1$$
 k
degree n k k



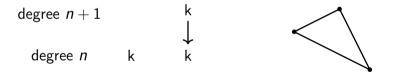
Chain complex: sequence of (boundary) maps of vector spaces such that the composition of two consecutive maps is 0

degree n + 1 k degree n k k

Homology: the quotient of the kernel of a map by the image of the previous one



Chain complex: sequence of (boundary) maps of vector spaces such that the composition of two consecutive maps is 0



Homology: the quotient of the kernel of a map by the image of the previous one



Chain complex: sequence of (boundary) maps of vector spaces such that the composition of two consecutive maps is 0



Homology: the quotient of the kernel of a map by the image of the previous one



Decomposition into interval spheres

Theorem (Chachólski, G., Landi, HHA 2020)

Every filtration decomposes uniquely into direct sum of interval spheres.



Decomposition into interval spheres

Theorem (Chachólski, G., Landi, HHA 2020)

Every filtration decomposes uniquely into direct sum of interval spheres.

Remark (Chachólski, G., Jin, Landi, CGTA, 2022)

The generators of the interval spheres give the birth and death times of the barcode. Any barcode algorithm is actually computing the interval sphere decomposition.



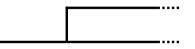
Decomposition into interval spheres

Theorem (Chachólski, G., Landi, HHA 2020)

Every filtration decomposes uniquely into direct sum of interval spheres.

Remark (Chachólski, G., Jin, Landi, CGTA, 2022)

The generators of the interval spheres give the birth and death times of the barcode. Any barcode algorithm is actually computing the interval sphere decomposition.

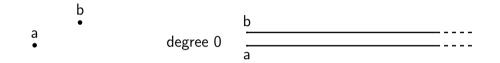




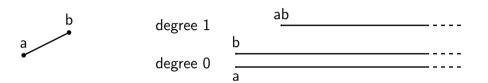
b •

а

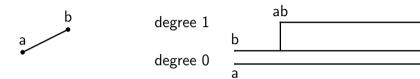








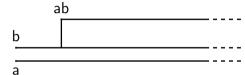






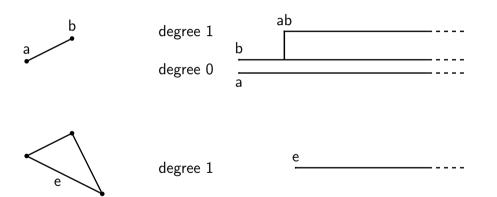




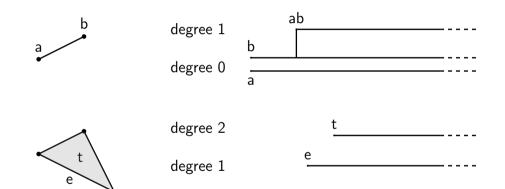




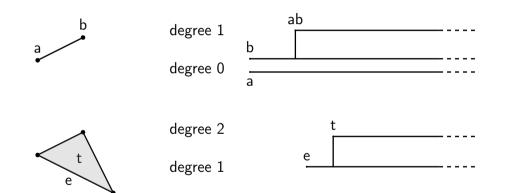




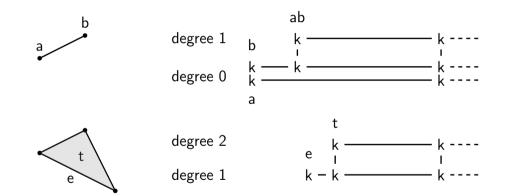














abc **acd** abd bcd bc ad ab cd **ac** bd



-



	_abc	acd	abd	bcd
bc	1			1
bc ad ab cd ac		1	1	
ab	1		1	
cd		1		1
ac	1	1		
bd			1	1



	_abc	acd	abd	bcd
bc	1			1
bc ad ab cd ac		1	1	
ab	1		1	
cd		1		1
	1	1		
bd			1	1

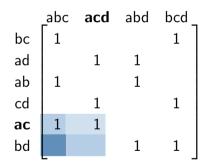


	_abc	acd	abd	bcd
bc	1			1
bc ad ab cd ac		1	1	
ab	1		1	
cd		1		1
ac	1	1		
bd			1	1



abc	acd	abd	bcd _
1			1
	1	1	
1		1	
	1		1
1	1		
		1	1
	_abc 1 1	_abc acd 1 1 1 1 1 1 1	abc acd abd 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1



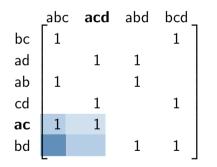


Two elements are paired if and only if the sum of the differences of the ranks is 1

Topological persistence and simplification, Edelsbrunner, Letscher, Zomorodian, *FOCS*, 2000



Pairing



Two elements are paired if and only if the sum of the differences of the ranks is 1

 \implies Any reduction that preserves these ranks is legit

Topological persistence and simplification, Edelsbrunner, Letscher, Zomorodian, *FOCS*, 2000

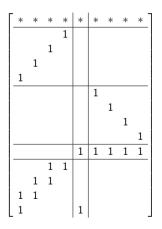


Standard barcode algorithm

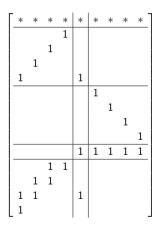
Pivot low(j): index of lowest nonzero element of column j

```
Input: Boundary matrix D
Output: Reduced matrix R
1 R = D
2 for j = 1, ..., \# of simplices do
3 while low(j) = low(i) \neq 0 for i < j do
4 add column i to column j
```

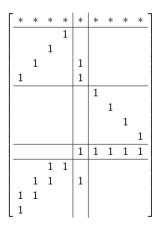
Topological persistence and simplification, Edelsbrunner, Letscher, Zomorodian, FOCS, 2000













*	*	*	*	*	*	*	*	*
			1	1				
		1		1				
	1			1				
1				1				
					1			
						1		
							1	
								1
				1	1	1	1	1
		1	1					
	1	1						
1	1							
1								_





*	*	*	*	*	*	*	*	* -
			1	1	1	1	1	1
		1		1	1	1	1	1
	1			1	1	1	1	1
1				1	1	1	1	1
					1			
						1		
							1	
								1
				1				
		1	1					
	1	1						
1	1							
1								



```
Input: Boundary matrix D
Output: Reduced matrix R
```

 $\mathbf{1} \ R = D$

2 for $j=1,\ldots,\#$ of simplices do

3 while
$$low(j) = low(i) \neq 0$$
 for $i < j$ do
4 add column i to column j

5if the column j is nonzero then6 $\sin Set$ column i to 0 for i = low(j)

Each interval sphere has two generators:

- If we find the "upper", we can remove the "lower"
- If we find the "lower", we can remove the "upper"

Persistent homology computation with a twist, Chen, Kerber, EuroCG, 2011





```
Input: Boundary matrix D
Output: Reduced matrix R
```

R = D

2 for $j=1,\ldots,\#$ of simplices do

3 while
$$low(j) = low(i) \neq 0$$
 for $i < j$ do
4 add column i to column j

5 if the column j is nonzero then 6 Set column i to 0 for i = low(j)

Each interval sphere has two generators:

If we find the "upper", we can remove the "lower" CLEAR

If we find the "lower", we can remove the "upper"

Persistent homology computation with a twist, Chen, Kerber, EuroCG, 2011



```
Input: Boundary matrix D
Output: Reduced matrix R
```

 $\mathbf{1} \ R = D$

2 for $j=1,\ldots,\#$ of simplices do

3 while
$$low(j) = low(i) \neq 0$$
 for $i < j$ do
4 add column i to column j

5if the column j is nonzero then6 $\sin Set$ column i to 0 for i = low(j)

Each interval sphere has two generators:

- If we find the "upper", we can remove the "lower" CLEAR
- If we find the "lower", we can remove the "upper"

Persistent homology computation with a twist, Chen, Kerber, EuroCG, 2011



```
Input: Boundary matrix D
Output: Reduced matrix R
```

 $\mathbf{1} \ R = D$

2 for $j=1,\ldots,\#$ of simplices do

3 while
$$low(j) = low(i) \neq 0$$
 for $i < j$ do
4 add column i to column j

5 if the column j is nonzero then 6 Set column i to 0 for i = low(j)

Each interval sphere has two generators:

- If we find the "upper", we can remove the "lower" CLEAR
- If we find the "lower", we can remove the "upper" COMPRESS
 Persistent homology computation with a twist, Chen, Kerber, *EuroCG*, 2011





The coboundary of a (n-1)-simplex *s* is the collection of all *n*-simplices that have *s* in their boundary.



The coboundary of a (n - 1)-simplex s is the collection of all *n*-simplices that have s in their boundary.

The anti-transpose of a boundary matrix is (almost) the coboundary matrix of the filtration and its pairing is in bijection with the pairing of the boundary matrix¹.

¹Dualities in persistent (co)homology, de Silva, Morozov, Vejdemo-Johansson, *Inverse Problems*, 2011



The coboundary of a (n-1)-simplex s is the collection of all *n*-simplices that have s in their boundary.

The anti-transpose of a boundary matrix is (almost) the coboundary matrix of the filtration and its pairing is in bijection with the pairing of the boundary matrix¹.

On some inputs, the standard barcode algorithm with clear is much more efficient on the coboundary than on the boundary matrix.

¹Dualities in persistent (co)homology, de Silva, Morozov, Vejdemo-Johansson, *Inverse Problems*, 2011



The coboundary of a (n-1)-simplex s is the collection of all *n*-simplices that have s in their boundary.

The anti-transpose of a boundary matrix is (almost) the coboundary matrix of the filtration and its pairing is in bijection with the pairing of the boundary matrix¹.

On some inputs, the standard barcode algorithm with clear is much more efficient on the coboundary than on the boundary matrix. Nothing comparable happens for the compress optimisation.

¹Dualities in persistent (co)homology, de Silva, Morozov, Vejdemo-Johansson, *Inverse Problems*, 2011

Row barcode algorithm

Pivot *left* (*i*): index of leftmost nonzero element of row *i*

```
Input: Boundary matrix D

Output: Reduced matrix R

1 R = D

2 for i = \# of simplices, ..., 1 do

3 | while left (i) = left (j) \neq 0 for j > i do

4 | add row j to row i
```

Tripartitions and bases of an ordered complex, Edelsbrunner, Ölsböck, *Discrete & Computational Geometry*, 2020





Row barcode algorithm with compress

Pivot *left* (*i*): index of leftmost nonzero element of row *i*

```
Input: Boundary matrix DOutput: Reduced matrix R1 R = D2 for i = \# of simplices,..., 1 do3 while left (i) = left (j) \neq 0 for j > i do4 d row j to row i5 if the row i is nonzero then6 Set row j to 0 for j = left(i)
```

Tripartitions and bases of an ordered complex, Edelsbrunner, Ölsböck, *Discrete & Computational Geometry*, 2020 / Notes on pivot pairings, G., *EuroCG*, 2021



Row barcode algorithm with compress

Pivot *left* (*i*): index of leftmost nonzero element of row *i*

```
Input: Boundary matrix D<br/>Output: Reduced matrix R1R = D2for i = \# of simplices, ..., 1 do3while left (i) = left (j) \neq 0 for j > i do4\_ add row j to row i5if the row i is nonzero then6\_ Set row j to 0 for j = left (i)
```

If the filtration is full, then # of column operations with clear on the coboundary matrix is equal to # of row operations with the compress on the boundary matrix.



Implementations

- JAVAPLEX
- Dionysus
- Gudhi
- Phat
- Ripser
- GIOTTO-PH

A roadmap for the computation of persistent homology, Otter, Porter, Tillmann, Grindrod, Harrington, *EPJ Data Science*, 2017



The choice of how to store the boundary matrix has big impact on the performances, as boundary matrices are initially sparse¹.



The choice of how to store the boundary matrix has big impact on the performances, as boundary matrices are initially sparse¹.

 \implies use data types whose size is proportional to the number of nonzero entries in a column



The choice of how to store the boundary matrix has big impact on the performances, as boundary matrices are initially sparse¹.

 \implies use data types whose size is proportional to the number of nonzero entries in a column

- The cost of adding column i to column j is #i;
- The cost of a matrix reduction is the added cost of all column additions;
- The fill-up of is the number of entries in the reduced matrix.



The choice of how to store the boundary matrix has big impact on the performances, as boundary matrices are initially sparse¹.

 \implies use data types whose size is proportional to the number of nonzero entries in a column

- The cost of adding column i to column j is #i;
- The cost of a matrix reduction is the added cost of all column additions;
- The fill-up of is the number of entries in the reduced matrix.



The choice of how to store the boundary matrix has big impact on the performances, as boundary matrices are initially sparse¹.

 \implies use data types whose size is proportional to the number of nonzero entries in a column

- The cost of adding column i to column j is #i;
- The cost of a matrix reduction is the added cost of all column additions;
- The **fill-up** of is the number of entries in the reduced matrix.



*	*	*	*	*	*	*	*	*
			1	1	1	1	1	1
		1		1	1	1	1	1
	1			1	1	1	1	1
1				1	1	1	1	1
					1			
						1		
							1	
								1
				1				
		1	1					
	1	1						
1	1							
1								_



*	*	*	*	*	*	*	*	*
			1	1	1	1	1	1
		1		1	1	1	1	1
	1			1	1	1	1	1
1				1	1	1	1	1
					1			
						1		
							1	
								1
				1				
		1	1					
	1	1						
1	1							
1								_

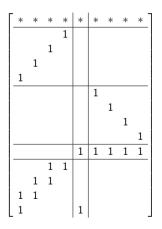
What if we try to keep the matrix sparse during the reduction?

Swap barcode algorithm **Input:** Boundary matrix D **Output:** Reduced matrix R 1 R = D2 for $j = 1, \ldots, \#$ of simplices do while $low(j) = low(i) \neq 0$ for i < j do 3 if #i < #i then 4 swap *j* and *i* 5 add column *i* to *j* 6 if column *j* is nonzero then 7 Set *i* to 0 for i = low(j)8

Keeping it sparse: Computing Persistent Homology revised, Bauer, Bin Masood, G., Houry, Kerber, Rathod, *to appear*









*	*	*	*	*	*	*	*	*
			1	1				
		1		1				
	1			1				
1				1				
					1			
						1		
							1	
								1
				1	1	1	1	1
		1	1					
	1	1						
1	1							
1								





*	*	*	*	*	*	*	*	*]
			1		1			
		1			1			
	1				1			
1					1			
				1	1	1	1	1
						1		
							1	
								1
				1				
		1	1					
	1	1						
1	1							
1								

*	*	*	*	*	*	*	*	*
			1	1	1	1	1	1
		1		1	1	1	1	1
	1			1	1	1	1	1
1				1	1	1	1	1
					1			
						1		
							1	
								1
				1				
		1	1					
	1	1						
1	1							
1								



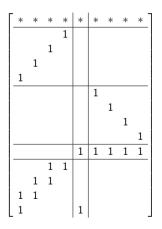
Retrospective barcode algorithm

Input: Boundary matrix *D* **Output:** Reduced boundary matrix *R*

1 R = D

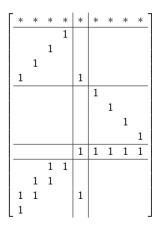
- 2 for $j=1,\ldots,\#$ of simplices do
- 3Remove the negative entries from j4while column j is nonzero and $R_j^{low(i)} \neq 0$ for i < j do5add column i to column j

Keeping it sparse: Computing Persistent Homology revised, Bauer, Bin Masood, G., Houry, Kerber, Rathod, *to appear*





T G



*	*	*	*	*	*	*	*	*
			1					
		1						
1	1			1				
1				1				
					1			
						1		
							1	
								1
				1	1	1	1	1
		1	1					
1	1	1		1				
	1							
1								





*	*	*	*	*	*	*	*	*
1	1	1	1	1	1	1	1	1
1	1	1		1	1	1	1	1
1	1			1	1	1	1	1
1				1	1	1	1	1
					1			
						1		
							1	
								1
				1				
			1					
		1						
	1							
1								_



Experiments

		Alpha sha	ре		Lower star		Vietoris–Rips			
Algorithm	Fill-up	Col.ops	Bitflips	Fill-up	Col.ops	Bitflips	Fill-up	Col.ops	Bitflips	
clear	6.35M	2.17M	62.30M	34.70M	4.90M	29.43M	14,975	5.35M	19.02M	
$clear^*$	6.90M	1.41M	84.09M	33.18M	4.91M	30.06M	0.51M	222	38,342	
swap	1.56M	1.10M	7.37M	33.61M	4.83M	26.79M	14,887	5.19M	17.29M	
swap*	2.04M	1.54M	20.72M	31.59M	4.86M	27.15M	0.51M	224	33,830	
retro	1.14M	2.34M	19.93M	8.13M	21.51M	34.70M	5,049	0.48M	0.49M	
retro*	7.94M	3.51M	40.87M	7.35M	21.94M	31.73M	6.41M	9,944	14.32M	
mix	1.04M	15.04M	140.34M	10.85M	120.02M	239.17M	5,172	0.52M	0.57M	
mix*	1.41M	14.03M	71.37M	10.79M	76.24M	150.20M	0.49M	0.22M	21.84M	

Table: "M" stands for millions. The * means via row barcode algorithm.



Experiments

	Alpha shape			Lower star			Vietoris–Rips			Shuffled		
Algorithm	40K	80K	160K	Tooth	Lobster	Skull	104	297	445	50	75	100
clear	*6.5	*18.6	*49.8	2.0	25.8	23.9	*0.0	*0.1	*0.1	*0.1	*1.3	*11.2
swap	*9.8	*28.2	*74.2	2.4	38.6	25.4	*0.0	*0.1	*0.2	0.1	0.6	2.9
retro	4.3	11.8	30.9	*4.9	*29.0	*61.6	0.1	1.4	7.2	0.0	0.1	0.3

Table: Best running times (in seconds) on various data sets. The * means via row barcode algorithm.



Experiments

	List	Vector	Set	Heap	P-Heap	P-Set	P-Full	P-Bit-Tree
clear	58.3	1.9	7.9	7.1	6.5	7.5	2.2	0.9
$clear^*$	144.6	2.8	11.9	9.5	8.9	9.8	3.2	0.9
swap	45.9	1.2	1.1	68.8	63.7	1.1	0.5	27.7
swap*	+5m	3.0	4.0	275.6	213.6	4.1	1.6	122.8
retro	2.8	0.6	2.9	6.5	6.3	9.4	4.6	3.3
retro*	72.7	2.6	20.3	128.0	167.5	182.3	103.8	54.6
mix	40.1	4.0	17.7	44.5	38.0	14.5	6.5	22.1
mix*	+5m	14.0	15.5	+5m	+5m	12.5	6.5	268.2

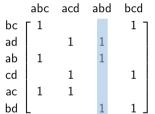
Table: Alpha filtration on 10000 points on a torus. All timings are in seconds but for the timeout (minutes). The * means via row barcode algorithm.



A clique filtration is a filtration where the *n*-simplices are added as soon as their boundary (n - 1)-simplices are added.

A clique filtration is a filtration where the *n*-simplices are added as soon as their boundary (n - 1)-simplices are added.

A **step column** is a column that is not modified during the reduction.





A clique filtration is a filtration where the *n*-simplices are added as soon as their boundary (n - 1)-simplices are added.

A **step column** is a column that is not modified during the reduction.

A **critical pivot** is a pivot that is in the reduced matrix but was not in the initial one.

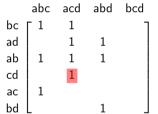
abcacdabdbcdbc111ad111ab111cd111ac111bd111



A clique filtration is a filtration where the *n*-simplices are added as soon as their boundary (n - 1)-simplices are added.

A **step column** is a column that is not modified during the reduction.

A **critical pivot** is a pivot that is in the reduced matrix but was not in the initial one.

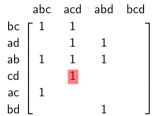




A clique filtration is a filtration where the *n*-simplices are added as soon as their boundary (n - 1)-simplices are added.

A **step column** is a column that is not modified during the reduction.

A **critical pivot** is a pivot that is in the reduced matrix but was not in the initial one.



Lemma (G., Houry, Kerber, ISSAC, 2022)

In a clique filtration, there is an critical pivot if and only if at the corresponding simplex is a "lower" generator of a new interval sphere.





Lemma (G., Houry, Kerber, ISSAC, 2022)

The cost of a matrix reduction is bounded by # of columns \times the fill-up of the reduced matrix.



Lemma (G., Houry, Kerber, *ISSAC*, 2022)

The cost of a matrix reduction is bounded by # of columns \times the fill-up of the reduced matrix.

The fill-up is bounded by
$$\Theta(\# \text{ of rows}) + \sum_{i=1}^{\# \text{of rows}} \mathbb{P}(\text{new "lower" generator}).$$



Lemma (G., Houry, Kerber, *ISSAC*, 2022)

The cost of a matrix reduction is bounded by # of columns \times the fill-up of the reduced matrix.

The fill-up is bounded by
$$\Theta(\# \text{ of rows}) + \sum_{i=1}^{\# \text{of rows}} \mathbb{P}(\text{new "lower" generator}).$$

For every random clique filtration model for which we can bound the probability of obtaining a new interval sphere, we have a bound on the average complexity of the barcode algorithm.



Theorem (G., Houry, Kerber, ISSAC, 2022)

Let *R* be the reduced 1-boundary matrix of a Vietoris–Rips filtration. Then $\mathbb{E}[\text{fill-up of } R] = O(n^2 \log^2 n)$ and $\mathbb{E}[\text{cost of matrix reduction}] = O(n^5 \log^2 n)$.



Theorem (G., Houry, Kerber, ISSAC, 2022)

Let *R* be the reduced 1-boundary matrix of a Vietoris–Rips filtration. Then $\mathbb{E}[fill-up \text{ of } R] = O(n^2 \log^2 n)$ and $\mathbb{E}[\text{cost of matrix reduction}] = O(n^5 \log^2 n)$. Let *R* be the reduced 1-boundary matrix of an Erdős–Rényi filtration. Then $\mathbb{E}[fill-up \text{ of } R] = O(n^3 \log n)$ and $\mathbb{E}[\text{cost of matrix reduction}] = O(n^6 \log n)$.



Theorem (G., Houry, Kerber, ISSAC, 2022)

Let *R* be the reduced 1-boundary matrix of a Vietoris–Rips filtration. Then $\mathbb{E}[fill-up \text{ of } R] = O(n^2 \log^2 n)$ and $\mathbb{E}[\text{cost of matrix reduction}] = O(n^5 \log^2 n)$. Let *R* be the reduced 1-boundary matrix of an Erdős–Rényi filtration. Then $\mathbb{E}[fill-up \text{ of } R] = O(n^3 \log n)$ and $\mathbb{E}[\text{cost of matrix reduction}] = O(n^6 \log n)$.

The worst-case complexities are, respectively, $O(n^4)$ and $O(n^7)$, and they are realized for the Erdős–Rényi filtration.



Take home

- The pairs links the matrices (combinatorial) to the barcode (homological/geometrical)
- Any reduction that maintains the pairs is valid
- Things can go (sort of) bad but they usually don't



Take home

- The pairs links the matrices (combinatorial) to the barcode (homological/geometrical)
- Any reduction that maintains the pairs is valid
- Things can go (sort of) bad but they usually don't

Thank you for your attention!