

$$y'' + 4y = \sin(x)$$

$$\lambda_0 = i$$

$$\begin{cases} y'' + 4y = 0 \\ \lambda^2 + 4 = 0 \end{cases}$$

$$\rightarrow \lambda_{\pm} = \pm 2i$$

$$y(x) = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

$$y_1(x) = \cos(2x)$$

$$y_2(x) = \sin(2x)$$

$$\lambda_0 \neq \lambda_{\pm}$$

$$\rightarrow y_p(x) = A \cos(x) + B \sin(x)$$

$$y_p'(x) = -A \sin(x) + B \cos(x)$$

$$y_p''(x) = -A \cos(x) - B \sin(x)$$

$$-A \cos(x) - B \sin(x) + 4(A \cos(x) + B \sin(x)) = \sin(x)$$

$$3A \cos(x) + 3B \sin(x) = \sin(x)$$

$$3A = 0$$

$$3B = 1 \quad B = \frac{1}{3}$$

$$y_p(x) = \frac{1}{3} \sin(x)$$

$$y(x) = c_1 \cos(2x) + c_2 \sin(2x) + \frac{1}{3} \sin(x)$$

$$y'' + 4y = \cos(2x)$$

$$g(x) \rightarrow \lambda_0 = 2i$$

$$\lambda_{\pm} = \pm 2i$$

$$\lambda_0 = \lambda_+$$

$$Y(x) = c_1 Y_1(x) + c_2 Y_2(x) + Y_p(x)$$

$$Y_1(x) = \cos(2x)$$

$$Y_2(x) = \sin(2x)$$

$$Y_p(x) = x (A \cos(2x) + B \sin(2x))$$

$$Y_p'(x) = A \cos(2x) + B \sin(2x) + x (-2A \sin(2x) + 2B \cos(2x))$$

$$\begin{aligned} Y_p''(x) &= 2(-2A \sin(2x) + 2B \cos(2x)) \\ &\quad + x(-4A \cos(2x) - 4B \sin(2x)); \\ &-4A \sin(2x) + 4B \cos(2x) \\ &\quad - \cancel{4Ax \cos(2x)} - \cancel{4Bx \sin(2x)} \\ &\quad + \cancel{4Ax \cos(2x)} + \cancel{4Bx \sin(2x)} \\ &= \cos(2x) \end{aligned}$$

$$-4A \sin(2x) + 4B \cos(2x) = \cos(2x)$$

$$A = 0 \quad B = \frac{1}{4}$$

$$Y_p(x) = \frac{x}{4} \sin(2x)$$

$$Y(x) = c_1 \cos(2x) + c_2 \sin(2x) + \frac{x}{4} \sin(2x)$$

$$y'' + 4y = x \cos(2x)$$

$$\lambda_0 = 2i$$

$$\lambda_{\pm} = \pm 2i$$

$$\boxed{\lambda_0 = \lambda_+}$$

$$Y_1(x) = \cos(2x), \quad Y_2(x) = \sin(2x)$$

$$Y(x) = c_1 Y_1(x) + c_2 Y_2(x) + Y_p(x)$$

$$Y_p(x) = x \left((Ax+B) \cos(2x) + (Cx+D) \sin(2x) \right)$$

$$Y_p'(x) = \dots$$

$$Y_p''(x) = \dots \quad \rightarrow \text{SOSTITUIRE in}$$

$$Y_p'' + 4 Y_p = x \cos(2x)$$

DETERMINARE A, B, C, D

$$Y_p(x) = \frac{x}{16} \cos(2x) + \frac{x^2}{8} \sin(2x)$$

$$Y'' + 3 Y' = (x^3 - 1) e^x$$

$$\boxed{\lambda_0 \neq 0, \lambda_0 \neq -3}$$

$$\lambda^2 + 3\lambda = 0$$

$$g(x) \rightarrow \lambda_0 = 1$$

$$g(x) = P_3(x) e^{\lambda_0 x}$$

$$\lambda_1 = 0$$

$$\lambda_2 = -3$$

$$y_1(x) = e^{\lambda_1 x} = 1$$

$$y_2(x) = e^{\lambda_2 x} = e^{-3x}$$

$$y'' + 3y' = 0$$

$$\begin{aligned} y(x) &= c_1 \cdot y_1(x) + c_2 y_2(x) + y_p(x) = \\ &= c_1 + c_2 e^{-3x} + y_p(x) \end{aligned}$$

$$y_p(x) = (A + Bx + Cx^2 + Dx^3) e^x$$

$$\begin{aligned} y_p'(x) &= (B + 2Cx + 3Dx^2) e^x + \\ &\quad (A + Bx + Cx^2 + Dx^3) e^x \end{aligned}$$

$$\begin{aligned} y_p''(x) &= (2C + 6D)x e^x + \\ &\quad + 2(B + 2Cx + 3Dx^2) e^x + \end{aligned}$$

$$+ (A + Bx + Cx^2 + Dx^3) e^x ;$$

$$[2C + 6Dx + 2B + 4Cx + 6Dx^2 + A + Bx + Cx^2 + Dx^3] e^x$$

$$+ 3[B + 2Cx + 3Dx^2 + A + Bx + Cx^2 + Dx^3] e^x = (x^3 - 1) e^x$$

$$2C + 2B + A + 3(B + A) = -1$$

$$6D + 4C + B + 3(2C + B) = 0$$

$$6D + C + 3(3D + C) = 0$$

$$D + 3D = 1$$

$$\begin{cases} 2C + 5B + 4A = -1 \\ 10C + 4B + 6D = 0 \\ 4C + 15D = 0 \end{cases}$$

$$10C + 4B + 6D = 0$$

$$4C + 15D = 0$$

$$D = \frac{1}{4}$$

$$\begin{cases} 4A = -1 - 5B - 2C = \dots \\ 4B = -6D - 10C = -\frac{6}{4} + \frac{10 \cdot 15}{16} \\ C = -\frac{15}{4}D = -\frac{15}{16} \\ D = \frac{1}{4} \end{cases}$$

$$B = \frac{63}{32}$$

$$A = -\frac{287}{128}$$

$$Y(x) = c_1 + c_2 e^{-3x} + \left(-\frac{287}{128} + \frac{63}{32}x - \frac{15}{16}x^2 + \frac{x^3}{4} \right) e^x$$

$$Y'' + 3Y' = 0$$

$$\begin{aligned} Y_1 &= 1 \\ Y_2 &= e^{-3x} \end{aligned}$$

Si può
DIMINUIRE IL GRADO
DELL' EQUAZIONE DIFFERENZIALE
PERCHÉ NON C'È TERMINE Y .

$$z(x) = y'(x) \rightarrow z' + 3z = 0 \rightarrow$$

$$z(x) = \bar{c}_2 e^{-3x}$$

$$y(x) = \int \bar{c}_2 e^{-3x} dx = -\frac{\bar{c}_2}{3} e^{-3x} + c_1$$

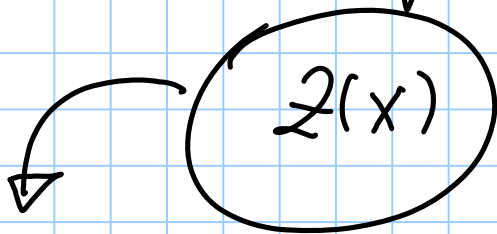
$$y(x) = c_1 + c_2 e^{-3x}$$

$$y'' + ay' = f(x)$$

$$z(x) = y'(x) \rightarrow z'(x) + az(x) = f(x)$$

1° ORDINE

NON OMogenea



$$y(x) = \int z(x) dx$$

$$y'' - y = x + 2e^{-x}$$

$$\lambda_{0,1} = 0$$

$$\lambda_{0,2} = -1$$

Equazioni LINEARI
(NON OMogenee)

$$y(x) = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

$$\lambda_{\pm} = \pm 1; \quad y_1(x) = e^x, \quad y_2(x) = e^{-x}$$

$$\rightarrow y_p(x) = y_{p,1}(x) + y_{p,2}(x)$$

$$y_{p,1}'' - y_{p,1} = x$$

$$y_{p,2}'' - y_{p,2} = 2e^{-x}$$

Ex

$$y''(x) = x^2$$

$$y'(x) = \int x^2 dx = c_2 + \frac{x^3}{3}$$

$$y(x) = \int \left(c_2 + \frac{x^3}{3} \right) dx =$$

$$c_1 + c_2 x + \frac{x^4}{12} =$$

$$c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

$$y'' = x^2, \quad \lambda_0 = 0$$

$$\lambda^2 = 0 \quad \lambda_1 = 0 = \lambda_2$$

$$y_1(x) = 1, \quad y_2(x) = x y_1(x) = x$$

$$y(x) = c_1 + c_2 x + y_p(x)$$

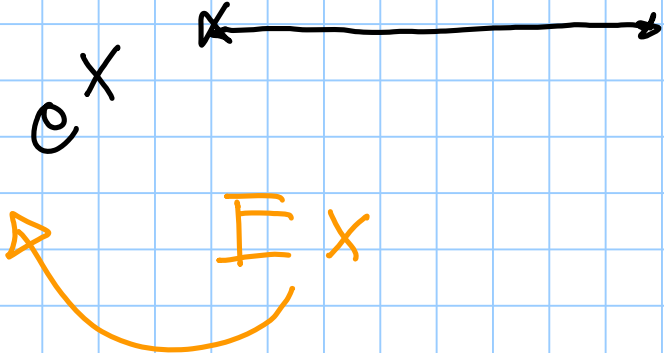
$$y_p(x) = x^2 (Ax^2 + Bx + C)$$

$$Y_p(x) = Ax^4 + Bx^3 + Cx^2$$

$$Y_p'(x) = 4Ax^3 + 3Bx^2 + 2Cx$$

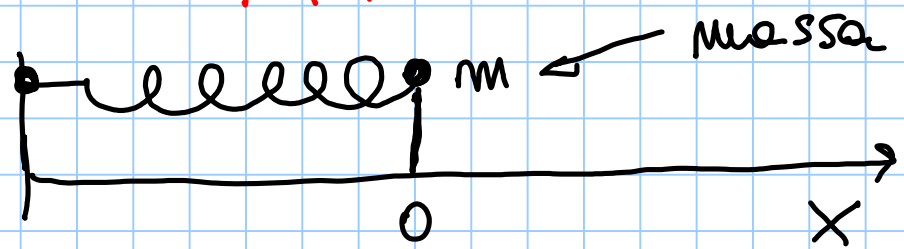
$$Y_p''(x) = 12Ax^2 + 6Bx + 2C.$$

$$12Ax^2 + 6Bx + 2C = x^2 \Rightarrow A = \frac{1}{12}$$

$$Y'' - 2Y' + Y = x e^x$$


Ex

OSCILLATORE ARMONICO



$x(t)$ = Posizione della TESTA
della molla al Tempo t

$x=0$: Posizione di RIPOSO

Se $x \neq 0$ la molla ESERCITA

una forza di richiamo

PROPORZIONALE ad x ,

$$F(x) = -Kx, K > 0$$

K COSTANTE (DIPENDE DALLA MOLLA)

LEGGE di NEWTON

$$m \ddot{X}(t) = F(X(t))$$

$\ddot{X}(t)$ = ACCELERAZIONE
 al Tempo t

$$\ddot{X}(t) = \frac{d^2}{dt^2} X(t)$$

$$m \frac{d^2}{dt^2} X(t) = -kX(t)$$

$$\begin{cases} \ddot{X}(t) + \frac{k}{m} X(t) = 0 \\ X(0) = X_0 \\ \dot{X}(0) = \gamma_0 \end{cases}$$

Equazione
 CARATTERISTICA

$$\lambda^2 = -\frac{k}{m}, \quad \lambda = \pm i \sqrt{\frac{k}{m}}$$

$$\omega := \sqrt{\frac{k}{m}}$$

PULSAZIONE

$$X(t) = A \cos(\omega t) + B \sin(\omega t)$$

$$\dot{X}(t) = -\omega A \sin(\omega t) + \omega B \cos(\omega t)$$

$$\begin{cases} A = X_0 \\ \omega B = Y_0 \end{cases} \rightarrow \begin{cases} A = X_0 \\ B = \frac{Y_0}{\omega} \end{cases}$$

$$X(t) = X_0 \cos(\omega t) + \frac{Y_0}{\omega} \sin(\omega t)$$

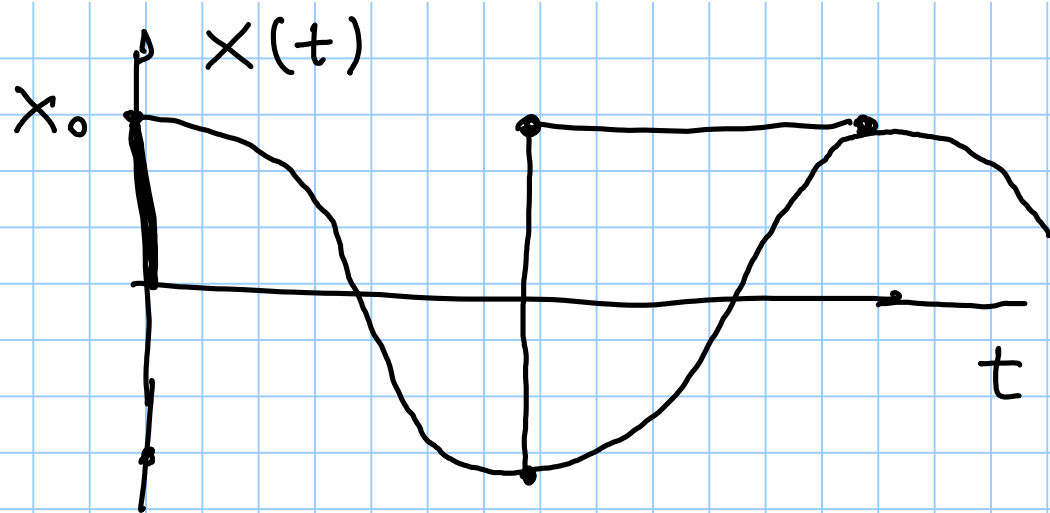
MOTO ARMONICA

Se $Y_0 = 0 \Rightarrow \dot{X}(0) = 0$ VELOCITÀ INIZIALE NULLA

$$X(t) = X_0 \cos(\omega t) = X_0 \cdot \cos\left(\sqrt{\frac{k}{m}} t\right)$$

Amplitude dell'oscillazione =

$$2 \max_{\mathbb{R}} |X(t)| = 2 |X_0|$$



OSCILLATORE ARMONICO SMORZATO

$$F(x) = -kx - \beta \dot{x},$$

$\nearrow \beta > 0$

FORZA DI ATTRITO

$$\begin{cases} m \ddot{x} = -kx - \beta \dot{x} \\ \ddot{x} + \frac{\beta}{m} \dot{x} + \frac{k}{m} x = 0 \\ x(0) = x_0 \\ \dot{x}(0) = v_0 \end{cases}$$

$$\lambda^2 + \frac{\beta}{m} \lambda + \omega^2 = 0, \quad \omega = \sqrt{\frac{k}{m}}$$

$$2\lambda_{\pm} = -\frac{\beta}{m} \pm \sqrt{\left(\frac{\beta}{m}\right)^2 - 4\omega^2}$$

$$\bullet \left(\frac{\beta}{m}\right)^2 > 4\omega^2; \quad \bullet \left(\frac{\beta}{m}\right)^2 < 4\omega^2$$

$$\left(\frac{\beta}{m}\right)^2 > 4\omega^2, \quad \frac{\beta^2}{m^2} > 4\frac{k}{m}$$

$$\Delta > 0$$

$$\beta^2 > 4mk$$

$$\boxed{\beta > \sqrt{4mk}}$$

$$\lambda_1 = \frac{1}{2} \left(-\frac{\beta}{m} + \sqrt{\Delta} \right)$$

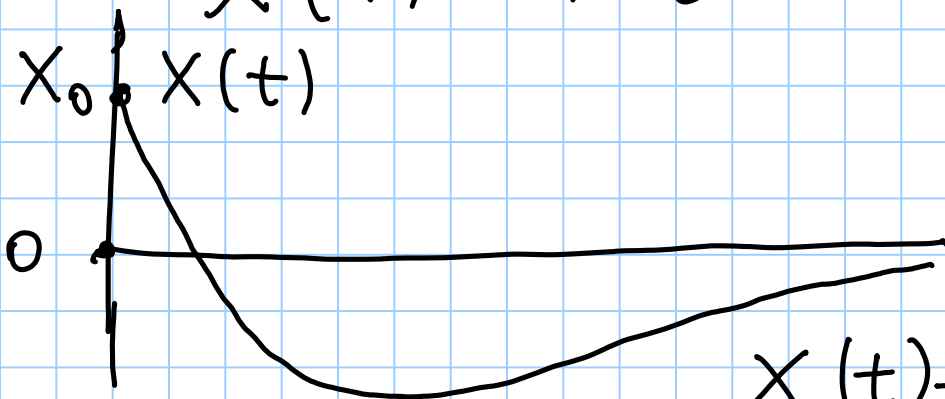
$$\lambda_2 = \frac{1}{2} \left(-\frac{\beta}{m} - \sqrt{\Delta} \right)$$

$$0 < \Delta = \left(\frac{B}{m}\right)^2 - 4\omega^2 < \left(\frac{B}{m}\right)^2$$

$$\sqrt{\Delta} < \frac{B}{m}$$

$$\lambda_2 < \lambda_1 < 0$$

$$X(t) = A e^{\lambda_1 t} + B e^{\lambda_2 t}$$



$$X(t) \rightarrow 0, t \rightarrow +\infty$$

NON CI SONO OSCILLAZIONI

$$\left(\frac{B}{m}\right)^2 < 4\omega^2$$

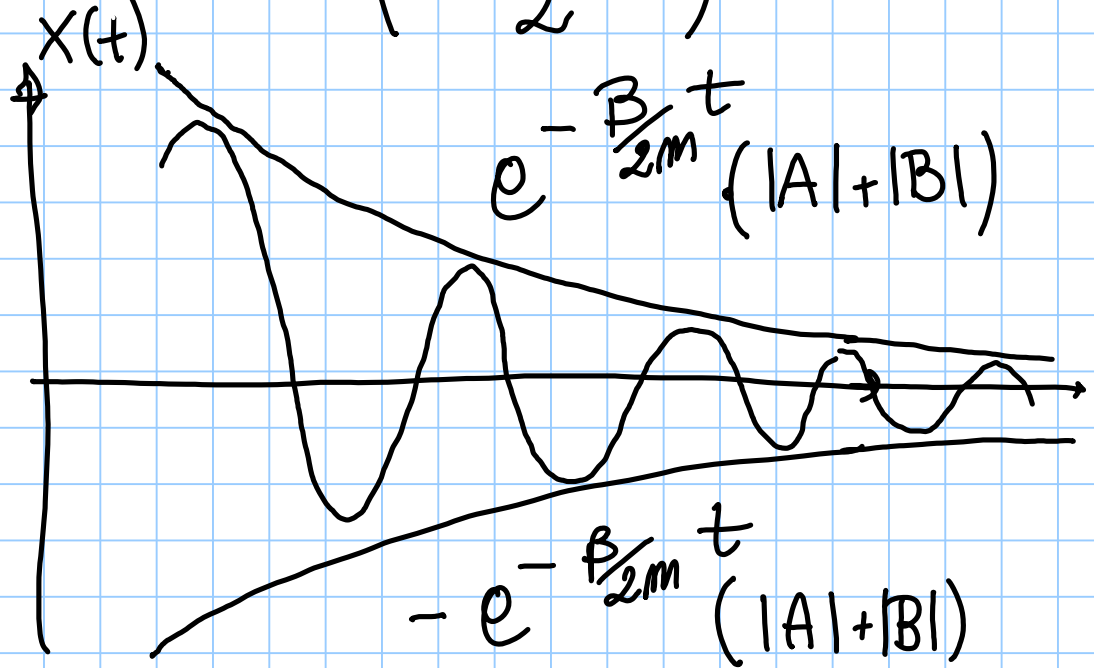
$$\Delta < 0$$

$$B < \sqrt{4mk}$$

$$\lambda_{\pm} = \frac{1}{2} \left(-\frac{\beta}{m} \pm i\sqrt{|\Delta|} \right)$$

$$X(t) = A e^{-\frac{\beta}{2m}t} \cos\left(\frac{\sqrt{|\Delta|}}{2}t\right) +$$

$$B e^{-\frac{\beta}{2m}t} \sin\left(\frac{\sqrt{|\Delta|}}{2}t\right)$$



OSCILLATORE ARMONICO FORZATO (RISONANZA)

$$\ddot{X} + \omega^2 X = \cos(\mu t), \quad \mu > 0$$

$$F(X) = -KX + m \cos(\mu t)$$

$$\begin{array}{l} \nearrow \mu \neq \omega \\ \searrow \mu = \omega \end{array}$$

$$\mu \neq \omega; X_p(t) = A_1 \cos(\mu t) + B_1 \sin(\mu t)$$

$$X(t) = c_1 X_1(t) + c_2 X_2(t) + X_p(t)$$

$$|X(t)| \leq |c_1| + |c_2| + |A_1| + |B_1|$$

$$\mu = \omega$$

$$X_p(t) = t A_1 \cos(\omega t) + t B_1 \sin(\omega t)$$

